

Microprocessors & Interfacing

Input/Output Devices

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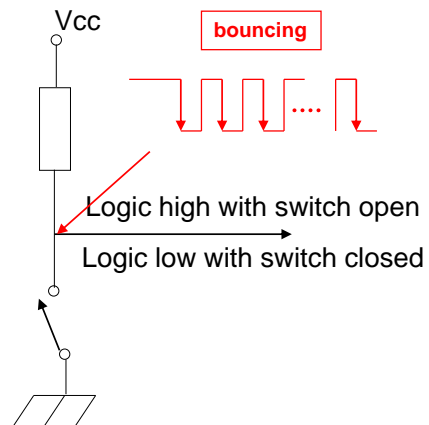
Lecture Overview

- Input devices
 - Input switch
 - Keypad
- Output devices
 - LCD

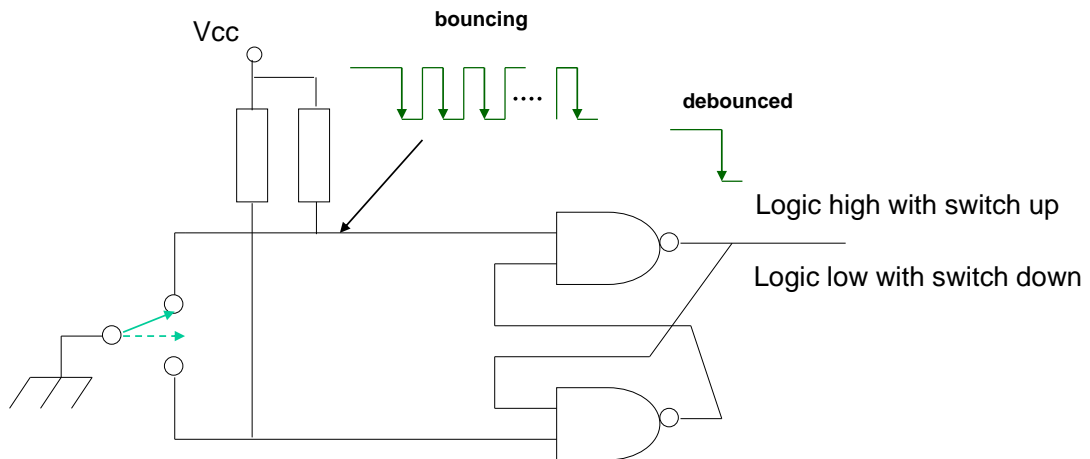
Input Switch

- A switch provides different values, depending on the switch position.
- Pull-up resistor/circuit may be necessary for the switch to provide a high logic level when the switch is open.
- Problem with switch:
 - Switch bounce
 - When a switch makes contact, its mechanical springiness will cause the contact to bounce, namely contact and break, for a few milliseconds (typically 5 to 10 ms).

Input Switch (cont.)



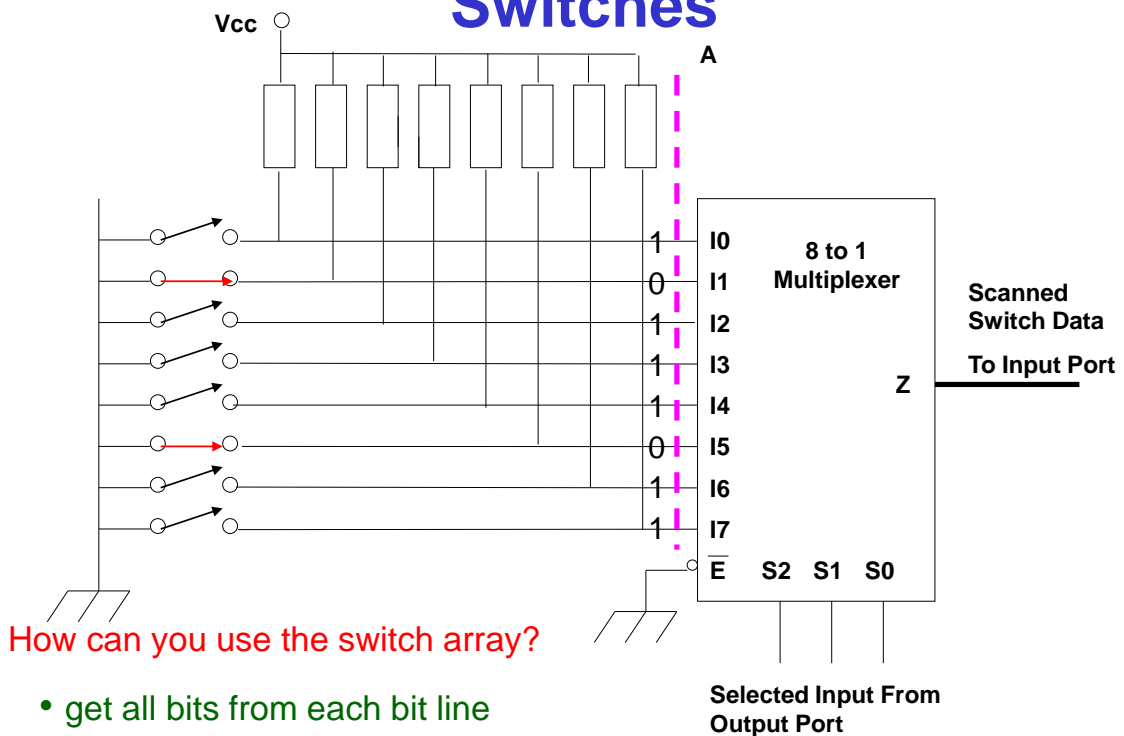
NAND Latch Debouncer*



Software Debouncing

- Basic idea: wait until the switch is stable
- For example:
 - Wait and see:
 - If the software detects a low logic level, indicating that switch has closed, it simply waits for some time, say 20 to 100ms, and then test if the switch is still low.
 - Counter-based approach:
 - Initialize a counter to 10.
 - Poll the switch every millisecond until the counter is either 0 or 20.
 - If the switch output is low, decrease the counter; otherwise, increment the counter.
 - If the counter is 0, we know that switch output has been low (closed) for at least 10 ms. If, on the other hand, the counter reaches 20, we know that the switch output has been high for at least 10 ms.

One-Dimensional Array of Switches

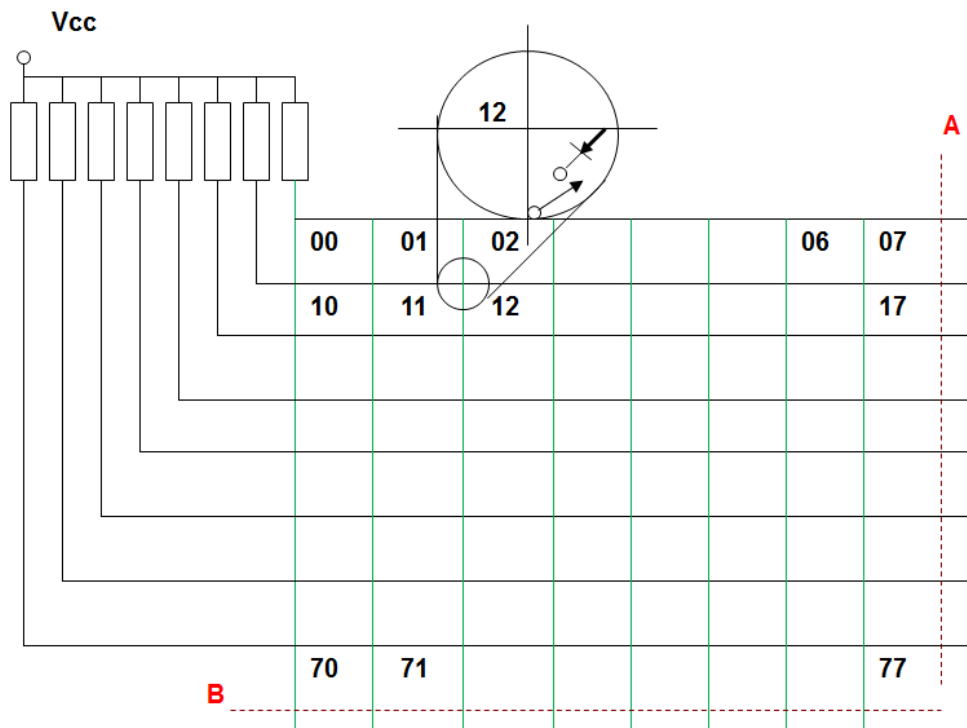


JMP9032 Week8

One-Dimensional Array of Switches (cont.)

- Switch bouncing problem must be solved
 - Either using software or hardware
- The output of switch array can be interfaced directly to an eight-bit port at point A.
- The array of switches can also be scanned by the software to find out which switches are closed or open.
 - The software outputs a 3-bit sequence from 000 to 111 and the multiplexer selects each of the switch inputs.

Keypad



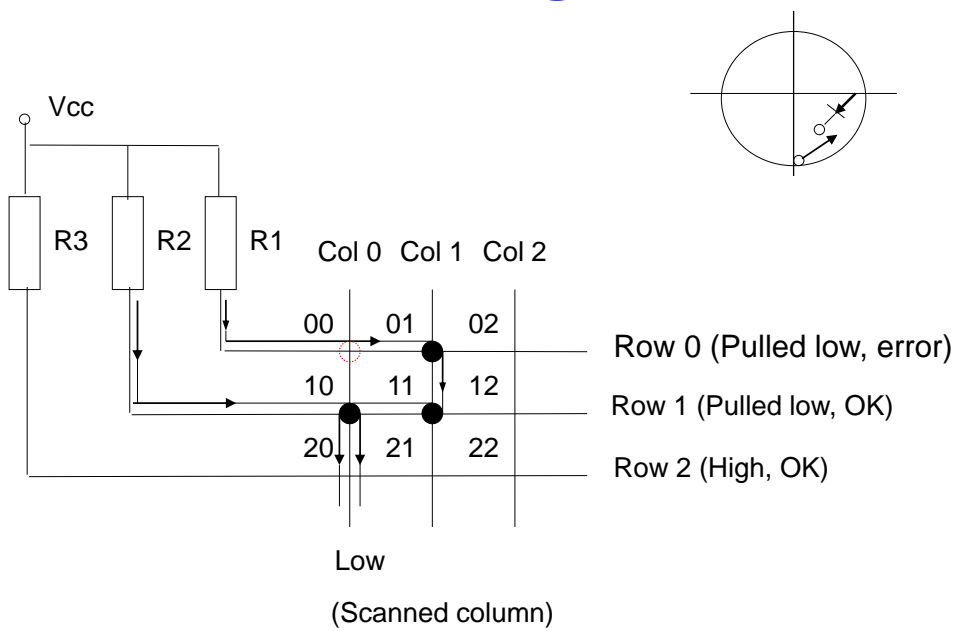
Keypad (cont.)

- A keypad is an array of switches arranged in a two-dimensional matrix, consisting of two layers
 - A layer of the horizontal lines
 - connected to the power supply via resistors
 - A layer of the vertical lines
 - normally disconnected to the horizontal layer
- Each intersection of the vertical and horizontal lines forms a switch
 - The switch can be operated by a key button
 - When the key is pressed, the switch connects both two lines.

Keypad (cont.)

- The 8*8 keypad can be interfaced directly to 8-bit output and input ports
 - at point *A (as input)* and *B (as output)*
- The output from each horizontal line
 - Normally is a logic high (1)
 - Becomes logic low (0) when a key is pressed and the related vertical line is set/connected to logic low (0)
- The diode prevents a problem called **ghosting**.

Ghosting*



Ghosting (cont.)*

- Ghosting occurs when several keys are pushed at once.
- Consider the case shown in the figure in the previous slide, where three switches 01, 10 and 11 are all closed. Column 0 is selected with a logic low and assume that the circuit does not contain the diodes. As the rows are scanned, a low is sensed on Row 1, which is true because switch 10 is closed. But, a low is also seen on Row 0, indicating switch 00 is closed, which is NOT true.
- The diodes in the switches eliminate this problem by preventing current flow from R1 through switches 01 and 11. Thus Row 0 will not be low when it is scanned.

Example

- Get an input from 4x4 keypad used in our lab board

1	2	3	A	R0
4	5	6	B	R1
7	8	9	C	R2
*	0	#	D	R3
C0	C1	C2	C3	

Example (solution)

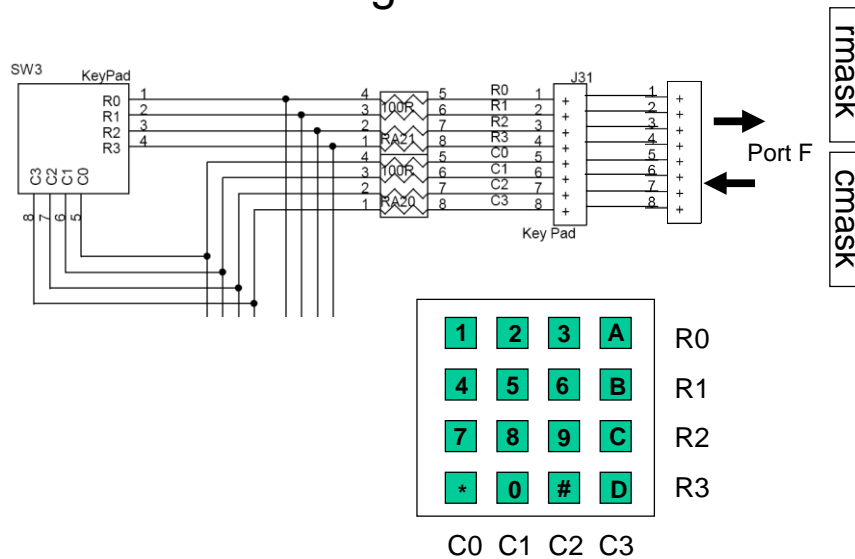
- Algorithm

```
Scan columns from left to right
  for each column, scan rows from top to bottom
    for each key being scanned
      if it is pressed
        display
        wait
      endif
    endfor
  endfor
Repeat the scan process
```

- To select a column, set the related Cx value to 0
- A mask is used to read one row at a time.

Example (solution)

- Hardware Interfacing



Code Implementation

```
; The program gets input from keypad and displays its ascii value on the  
; LED bar  
  
.include "m2560def.inc"  
  
.def row = r16                ; current row number  
.def col = r17                ; current column number  
.def rmask = r18              ; mask for current row during scan  
.def cmask = r19              ; mask for current column during scan  
.def temp1 = r20  
.def temp2 = r21  
  
.equ PORTFDIR = 0xF0          ; PF7-4: output, PF3-0, input  
.equ INITCOLMASK = 0xEF       ; scan from the leftmost column,  
.equ INITROWMASK = 0x01       ; scan from the top row  
.equ ROWMASK = 0x0F           ; for obtaining input from Port F
```

Code Implementation

RESET:

```
ldi    temp1, PORTFDIR    ; PF7:4/PF3:0, out/in
out     DDRC, temp1
ser     temp1              ; PORTC is output
out     DDRC, temp1
out     PORTC, temp1
```

main:

```
ldi     cmask, INITCOLMASK ; initial column mask
clr     col                ; initial column
```

Code Implementation

```
colloop:
    cpi    col, 4
    breq   main          ; if all keys are scanned, repeat.
    out    PORTF, cmask  ; otherwise, scan a column

    ldi    temp1, 0xFF    ; slow down the scan operation.
delay:    dec    temp1
    brne   delay

    in     temp1, PINF    ; read PORTF
    andi   temp1, ROWMASK ; get the keypad output value
    cpi    temp1, 0xF     ; check if any row is low
    breq   nextcol

                                ; if yes, find which row is low
    ldi    rmask, INITROWMASK ; initialize for row check
    clr    row
    ;
```

Code Implementation

```
rowloop:
    cpi    row, 4
    breq   nextcol           ; the row scan is over.
    mov    temp2, temp1
    and    temp2, rmask      ; check un-masked bit
    breq   convert          ; if bit is clear, the key is pressed
    inc    row               ; else move to the next row
    lsl    rmask
    jmp    rowloop

nextcol:
                                ; if row scan is over
    lsl    cmask
    inc    col               ; increase column value
    jmp    colloop          ; go to the next column
```

Code Implementation

convert:

cpi	col, 3	; If the pressed key is in col. 3
breq	letters	; we have a letter
		; If the key is not in col. 3 and
cpi	row, 3	; if the key is in row3,
breq	symbols	; we have a symbol or 0
mov	temp1, row	; Otherwise we have a number in 1-9
lsl	temp1	
add	temp1, row	;
add	temp1, col	; temp1 = row*3 + col
subi	temp1, -'1'	; Add the value of character '1'
jmp	convert_end	

Code Implementation

```
letters:
    ldi temp1, 'A'
    add temp1, row           ; Get the ASCII value for the key
    jmp convert_end

symbols:
    cpi col, 0               ; Check if we have a star
    breq star
    cpi col, 1               ; or if we have zero
    breq zero
    ldi temp1, '#'           ; if not we have hash
    jmp convert_end

star:
    ldi temp1, '*'           ; Set to star
    jmp convert_end

zero:
    ldi temp1, '0'           ; Set to zero

convert_end:
    out PORTC, temp1         ; Write value to PORTC
    jmp main                 ; Restart main loop
```

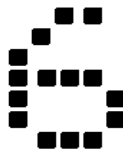
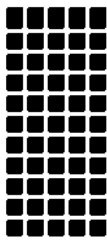
LCD

- Liquid Crystal Display
- Programmable output device

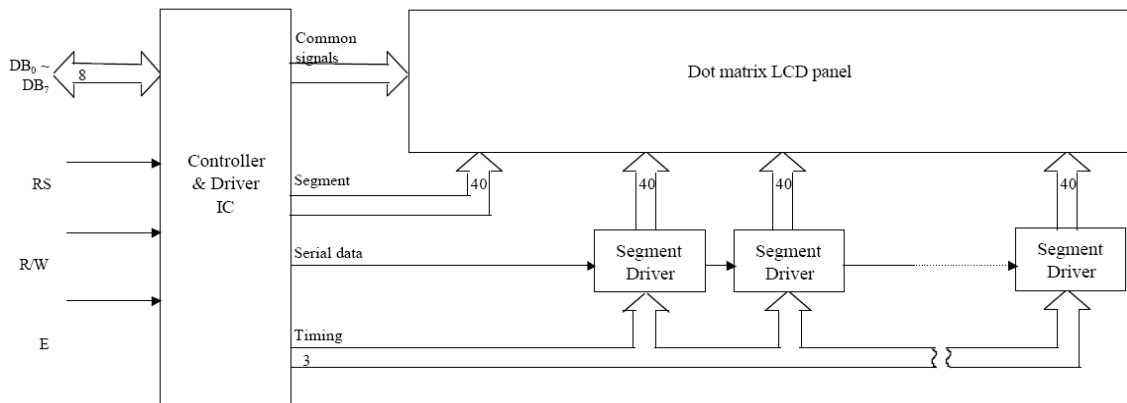


Dot Matrix LCD

- Characters are displayed using a dot matrix.
 - 5x7, 5x8, and 5x11
- A controller is used for communication between the LCD and other components, e.g. microprocessor unit (MPU)
- The controller has an internal character generator ROM. All display functions are controllable by instructions.



Dot Matrix LCD Diagram



Note: The diagram and tables are extracted from the LCD Manual available on the course website

Pin Descriptions

Signal name	No. of Lines	Input/Output	Connected to	Function
DB4 ~ DB7	4	Input/Output	MPU	4 lines of high order data bus. Bi-directional transfer of data between MPU and module is done through these lines. Also DB ₇ can be used as a busy flag. These lines are used as data in 4 bit operation.
DB0 ~ DB3	4	Input/Output	MPU	4 lines of low order data bus. Bi-directional transfer of data between MPU and module is done through these lines. In 4 bit operation, these are not used and should be grounded.
E	1	Input	MPU	Enable - Operation start signal for data read/write.
R/W	1	Input	MPU	Signal to select Read or Write "0": Write "1": Read
RS	1	Input	MPU	Register Select "0": Instruction register (Write) : Busy flag; Address counter (Read) "1": Data register (Write, Read)
V _{ee}	1		Power Supply	Terminal for LCD drive power source.
V _{cc}	1		Power Supply	+5V
V _{ss}	1		Power Supply	0V (GND)

Operations

- MPU communicates with LCD through two registers
 - Instruction Register (IR)
 - To store
 - instruction code
 - » E.g Display Clear or Cursor Shift
 - address for the Display Data RAM (DD RAM)
 - etc.
 - Data Register (DR)
 - To store
 - data to be read/written to/from the DD RAM of the display controller.

Operations (cont.)

- The register select (RS) signal determines which of these two registers is selected.

RS	R/W	Operation
0	0	IR write, internal operation (Display Clear etc.)
0	1	Busy flag (DB ₇) and Address Counter (DB ₀ ~ DB ₆) read
1	0	DR Write, Internal Operation (DR ~ DD RAM or CG RAM)
1	1	DR Read, Internal Operation (DD RAM or CG RAM)

Operations (cont.)

- When the busy flag is high or “1”, the LCD is busy with the internal operation.
- The next instruction must not be written until the busy flag is low or “0”.
- For details, refer to the LCD USER’S MANUAL.

LCD Instructions

- A list of binary instructions are available for LCD operations
- Some typical ones are explained in the next slides.

Instructions

- Function Set

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	0	0	1	DL	N	F	x	x

- Set the interface data length, the number of lines, and character font.
 - DL = “1”, 8 –bits; otherwise 4 bits
 - N: Sets the number of lines
 - N = “0” : 1 line display
 - N = “1” : 2 line display
 - F: Sets character font.
 - F = “1” : 5 x 10 dots
 - F = “0” : 5 x 7 dots

Instructions

- Entry Mode Set

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	0	0	0	0	0	1	I/D	S

- Set the Increment/Decrement and Shift modes
 - I/D = 1: increments the address counter by 1 for each DD RAM access (read or write); I/D = 0: decrements the address counter
 - S=0, no shift
 - S=1, shift the entire display
 - Shift to the left when I/D = 1
 - Shift to the right when I/D = 0

Instructions

- Display ON/OFF Control

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	0	0	0	0	1	D	C	B

- Control the display ON/OFF, Cursor ON/OFF and Cursor Blink function.
 - D: The display is ON when D = 1 and OFF when D = 0.
 - C: The cursor displays when C = 1 and does not display when C = 0.
 - B: The character indicated by the cursor blinks when B = 1.

Instructions

- Clear Display

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	0	0	0	0	0	0	0	1

- The display clears and the cursor moves to the upper left corner of the display.

Instructions

- Return Home

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	0	0	0	0	0	0	1	x

- The cursor moves to the upper left corner of the display. Text on the display remains unchanged.

Instructions

- Write Data to DD RAM

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	1	0	D	D	D	D	D	D	D	D

- Write binary 8-bit data DDDDDDDD to the CG or DD RAM.
- The previous designation determines whether the CG or DD RAM is to be written (CG RAM address set or DD RAM address set). After a write the entry mode will automatically increase or decrease the address by 1. Display shift will also follow the entry mode.

Instructions

- Set DD RAM Address

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	0	1	A	A	A	A	A	A	A

- Sets the address counter to DD RAM.
- The address range:
 - For 1-line display, 0x00-0x4F
 - For 2-line display,
 - 0x00-0x27 for the first line
 - 0x40-0x67 for the second line

Instructions

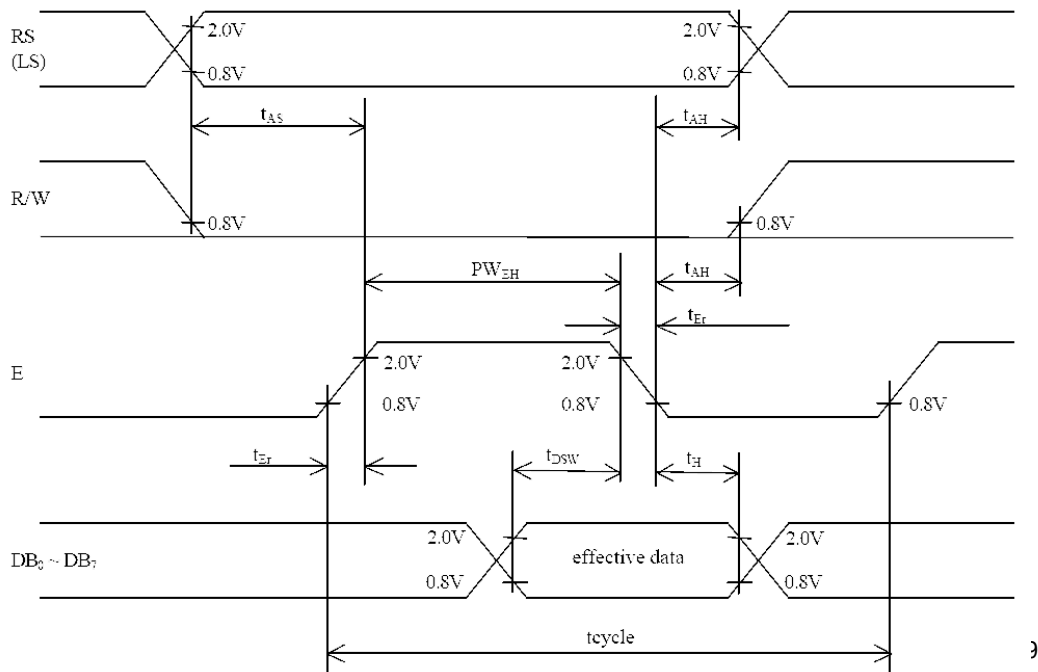
- Read Busy Flag and Address

	RS	R/W	DB7	DB6	DB5	BD4	DB3	DB2	DB1	DB0
Code	0	1	BF	A	A	A	A	A	A	A

- Read the busy flag (BF) and value of the address counter (AC). BF = 1 indicates that an internal operation is in progress and the next instruction will not be accepted until BF is set to “0”. If the display is written while BF = 1, abnormal operation will occur.

Timing Characteristics

- For write operation

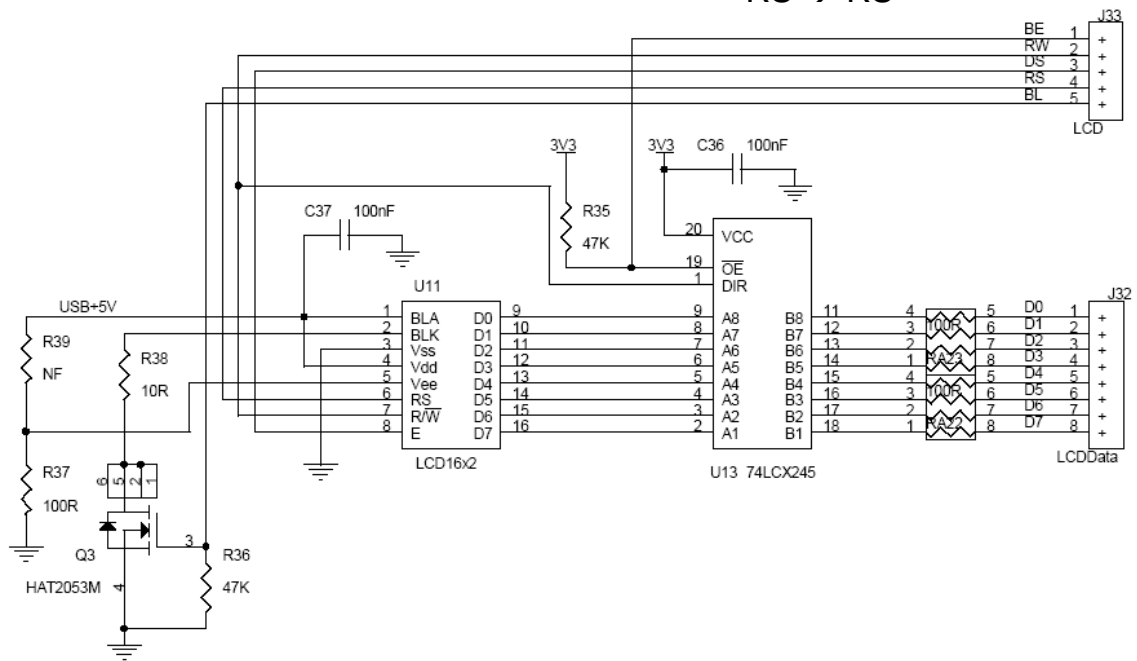


LCD Connection Diagram*

RW → R/W


DS → E

RS → RS



Examples

- Send a command to LCD



- LCD_RS: pin position for setting RS
- LCD_RW: pin position for setting RW
- LCD_RS: pin position for setting E

; General purpose register **data** stores value to be written to the LCD
; Port F is output and connects to LCD; Port A controls the LCD (Bit LCD_RS for RS and bit LCD_RW for RW, LCD_E for E). The character to be displayed is stored in register data
; Assume all labels are pre-defined.

```
.macro lcd_write_com
    out PORTF, data          ; set the data port's value up
    ldi temp, (0<<LCD_RS)|(0<<LCD_RW)
    out PORTA, temp         ; RS = 0, RW = 0 for a command write
    nop                    ; delay to meet timing (Set up time)
    sbi PORTA, LCD_E        ; turn on the enable pin
    nop                    ; delay to meet timing (Enable pulse width)
    nop
    nop
    cbi PORTA, LCD_E        ; turn off the enable pin
    nop                    ; delay to meet timing (Enable cycle time)
    nop
    nop
    nop
.endmacro
```

Examples

- Send data to display

; comments are same as in previous slide.

```
.macro lcd_write_data
    out PORTF, data           ; set the data port's value up
    ldi temp, (1 << LCD_RS) | (0 << LCD_RW)
    out PORTA, temp          ; RS = 1, RW = 0 for a data write
    nop                      ; delay to meet timing (Set up time)
    sbi PORTA, LCD_E          ; turn on the enable pin
    nop                      ; delay to meet timing (Enable pulse width)
    nop
    nop
    cbi PORTA, LCD_E          ; turn off the enable pin
    nop                      ; delay to meet timing (Enable cycle time)
    nop
    nop
.endmacro
```

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Examples

- Check LCD and wait until LCD is not busy

; comments are same as in the previous slide

```
.macro lcd_wait_busy
    clr temp
    out DDRF, temp                ; Make PORTF be an input port for now
    out PORTF, temp
    ldi temp, 1 << LCD_RW
    out PORTA, temp              ; RS = 0, RW = 1 for a command port read
busy_loop:
    nop                          ; delay to meet set-up time
    sbi PORTA, LCD_E             ; turn on the enable pin
    nop                          ; delay to meet timing (Data delay time)
    nop
    nop
    in temp, PINF                ; read value from LCD
    cbi PORTA, LCD_E             ; turn off the enable pin
    sbrc temp, LCD_BF            ; if the busy flag is set
    rjmp busy_loop              ; repeat command read
    clr temp                     ; else
    out PORTA, temp              ; turn off read mode,
    ser temp                     ;
    out DDRF, temp               ; make PORTF an output port again
.endmacro
```

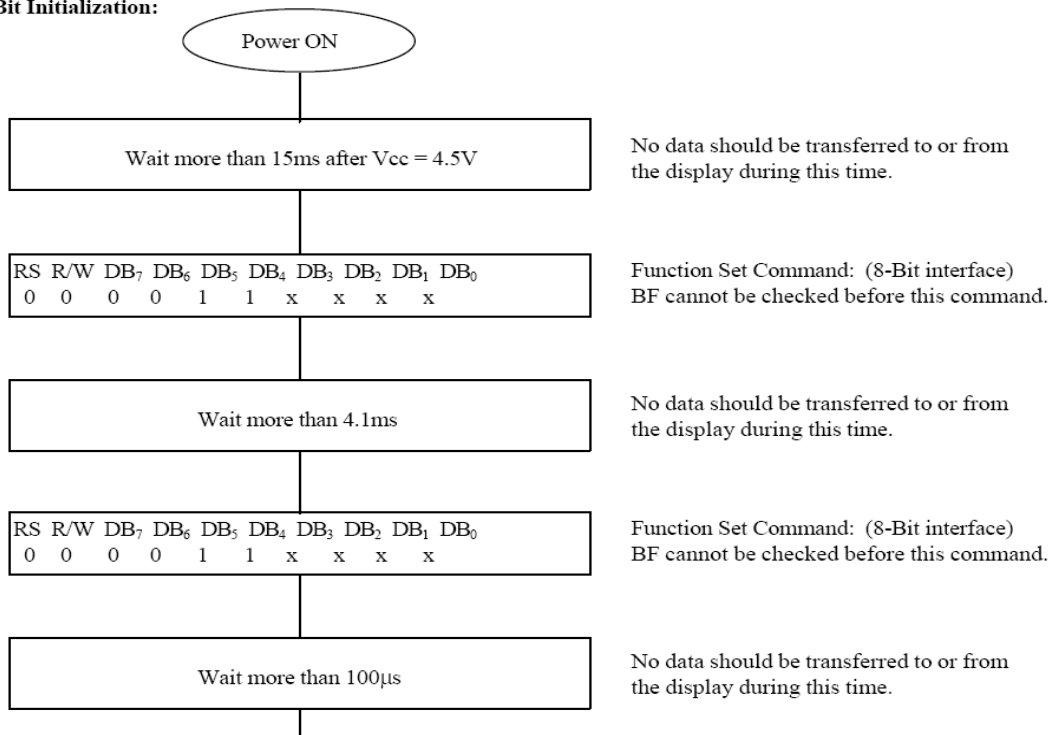
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LCD Initialization

- LCD should be initialized before use
- Internal Reset Circuit can be used, but it is related to power supply loading, may not work properly.
- Therefore, software initialization is recommended.

Software Initialization

8 - Bit Initialization:



Software Initialization

Wait more than 100µs

No data should be transferred to or from the display during this time.

RS	R/W	DB ₇	DB ₆	DB ₅	DB ₄	DB ₃	DB ₂	DB ₁	DB ₀
0	0	0	0	1	1	x	x	x	x

Function Set Command: (8-Bit interface)
After this command is written, BF can be checked.

RS	R/W	DB ₇	DB ₆	DB ₅	DB ₄	DB ₃	DB ₂	DB ₁	DB ₀
0	0	0	0	1	1	N	F	x	x
0	0	0	0	0	0	1	0	0	0
0	0	0	0	0	0	0	0	0	1
0	0	0	0	0	0	0	1	I/D	S
0	0	0	0	0	0	1	1	C	B

Function Set (Interface = 8 bits, Set No. of lines and display font)

Display OFF

Clear Display

Entry Mode Set:

Display ON (Set C and B for cursor/Blink options.)

Initialization Complete,
Display Ready.

Note: BF should be checked before each of the instructions starting with Display OFF.

Example of Initialization Code

```
.include "m2560def.inc"

; The del_hi:del_lo register pair store the loop counts
; each loop generates about 1 us delay
.macro delay
loop1:  subi del_lo, 1
        sbci del_hi, 0
        ldi r16, 0x3
loop2:  dec r16
        nop
        brne loop2
        brne loop1    ; taken branch takes two cycles.
                        ; one loop iteration time is 16 cycles = ~1.08us
.endmacro

; continued
```


Example of Initialization Code

```
ldi del_lo, low(15000)           ;delay (>15ms)
ldi del_hi, high(15000)
delay

; Function set command with N = 1 and F = 0
; for 2 line display and 5*7 font. The 1st command
ldi data, LCD_FUNC_SET | (1 << LCD_N)
lcd_write_com

ldi del_lo, low(4100)           ; delay (>4.1 ms)
ldi del_hi, high(4100)
delay

lcd_write_com                   ; 2nd Function set command

                                ; continued
```

Example of Initialization Code

```
ldi del_lo, low(100)           ; delay (>100 ns)
ldi del_hi, high(100)
delay

lcd_write_com                  ; 3rd Function set command
lcd_write_com                  ; Final Function set command

lcd_wait_busy                  ; Wait until the LCD is ready
ldi data, LCD_DISP_OFF
lcd_write_com                  ; Turn Display off

lcd_wait_busy                  ; Wait until the LCD is ready
ldi data, LCD_DISP_CLR
lcd_write_com                  ; Clear Display

                                ; continued
```

Example of Initialization Code

```
lcd_wait_busy                ; Wait until the LCD is ready
; Entry set command with I/D = 1 and S = 0
; Set Entry mode: Increment = yes and Shift = no
ldi data, LCD_ENTRY_SET | (1 << LCD_ID)
lcd_write_com

lcd_wait_busy                ; Wait until the LCD is ready
; Display On command with C = 1 and B = 0
ldi data, LCD_DISP_ON | (1 << LCD_C)
lcd_write_com
```

Reading Material

- Chapter 9: Computer Buses and Parallel Input and Output. Microcontrollers and Microcomputers by Fredrick M. Cady.
 - Simple I/O Devices
- DOT Matrix LCD User's Manual
 - Available on the course website.
 - The useful examples of instructions can be found on pages 41-46.

Homework

1. Write an assembly program to initialize LCD panel to display characters in one line with the 5x7 font.