

Student project survey!

Class syllabi requested!

We're crowdsourcing data from PRIOR QUARTERS' (ideally mostly prior years') classes students have taken, on a per-class basis, using two methods: A. direct syllabus submission AND/OR B. a survey with questions corresponding to policies for that class.

We're doing this to research how course logistics policies (attendance and assignment lateness, as well as providing materials like class recordings or lecture notes) correlate to student performance and satisfaction (using CAPES data).

This is for our project for this class, and we'd appreciate if you'd submit for at least one class, or ideally multiple (and try to do ones from before this year, if you can).

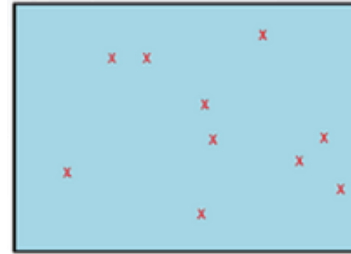
Form A: Syllabus submission – <https://docs.google.com/forms/d/e/1FAIpQLSc7iF4juanYzbRetRmfeBBVrSSWkFADa9nU50KzYLVe2dbdkA/viewform>

Form B: Direct info submission – <https://docs.google.com/forms/d/e/1FAIpQLSfL5GjmCkemxm6t6XFKc6uF3xnU8sQ7U9Zw7aAzEfsKWBU-Xw/viewform>

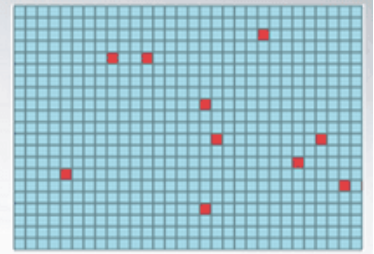
**Representing spatial data and
making maps like these**

Representing shapes on maps

- Vector data
 - Points, lines, polygons
- Raster data
 - Encodes the world as a continuous surface represented by a grid, such as the pixels of an image.



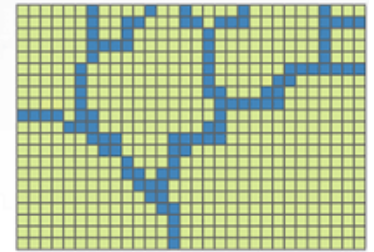
Point features



Raster point features



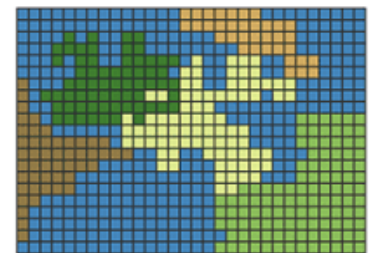
Line features



Raster line features



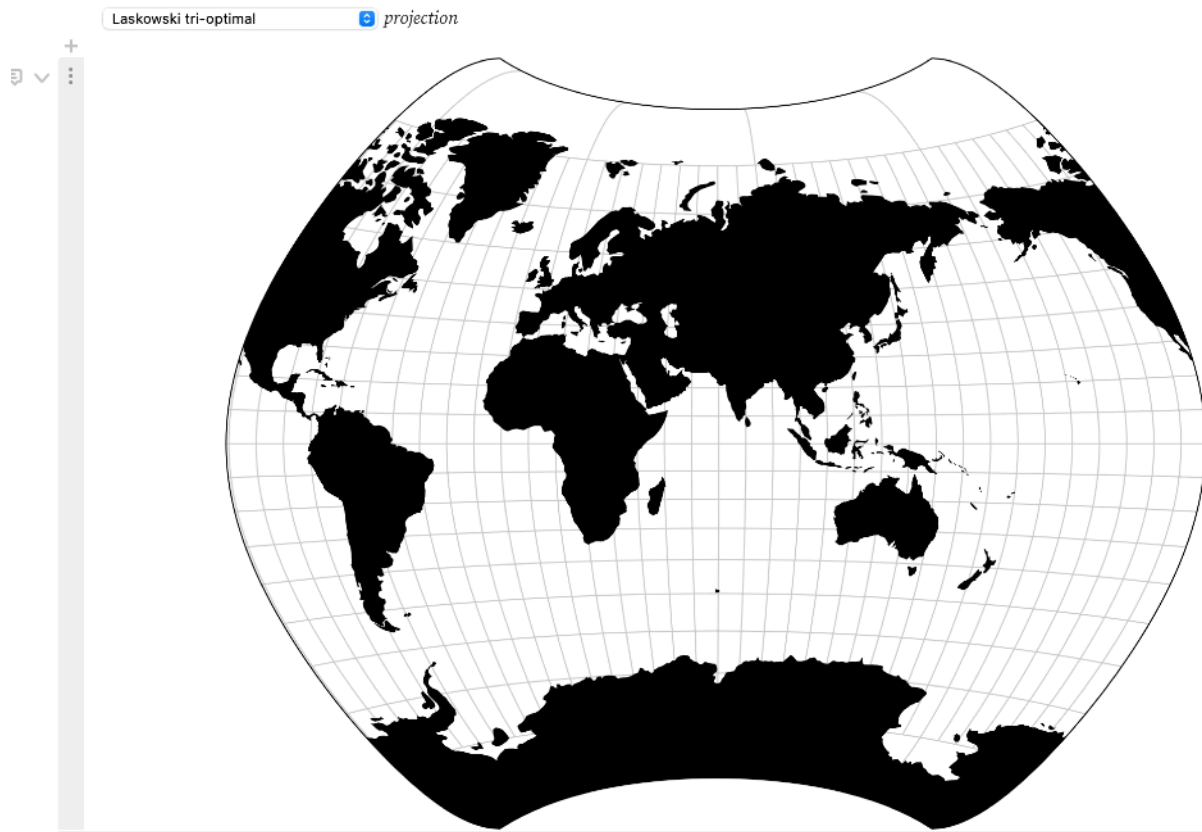
Polygon features



Raster polygon features

Projection Transitions

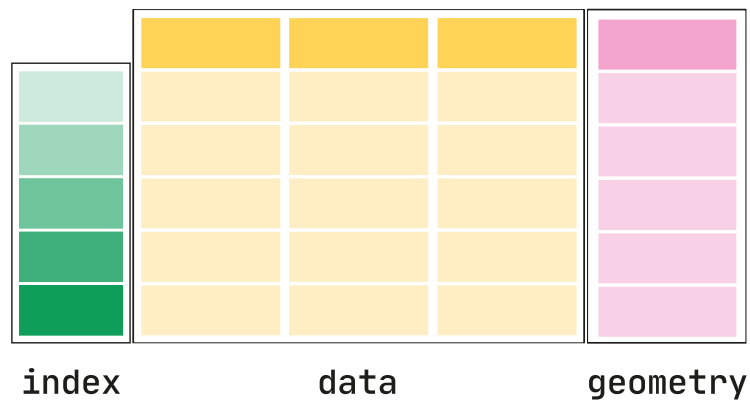
This notebook interpolates smoothly between projections; this is easiest when both projections are well-defined over the given viewport (here, the world).



Source: <https://observablehq.com/@d3/projection-transitions>

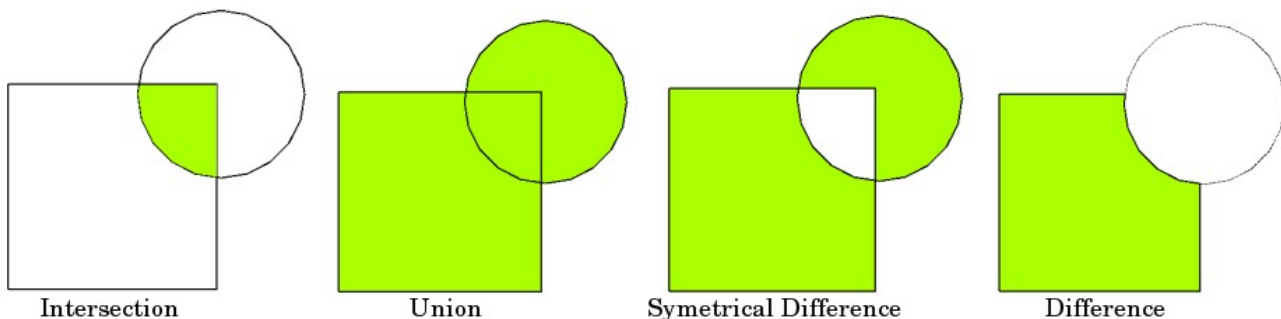
Geopandas

- Extends pandas, adds support for geospatial data
- Uses shapely library to represent vector geometry (e.g., POINT, LINE, POLYGON)
- Writes/reads shape files, GeoJSON and other formats
- Uses Coordinate Reference Systems (CRS) to represent how data aligns with the real world
- Different types of CRS: Geographic Coordinate Systems and Projected Coordinate Systems.



Geopandas skills

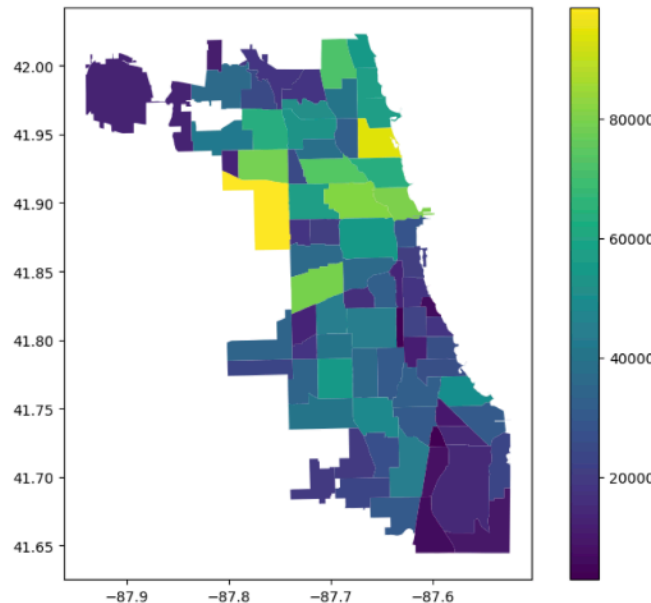
- Overlay spatial datasets: e.g. calculate what regions of Chicago are within 1km of a grocery store
- Join dataframes on shape information
- Aggregate across different subregions to get measurements at a more granular regional level



Geopandas tutorials

- https://geopandas.org/en/stable/getting_started/introduction.html
- https://geopandas.org/en/stable/docs/user_guide/mapping.html
- https://geopandas.org/en/stable/docs/user_guide/set_operations.html
- <https://geopandas.org/en/stable/gallery/index.html>

```
# Plot population estimates with an accurate legend  
In [7]: chicago.plot(column='POP2010', legend=True);
```



Spatial Statistics : The Basics

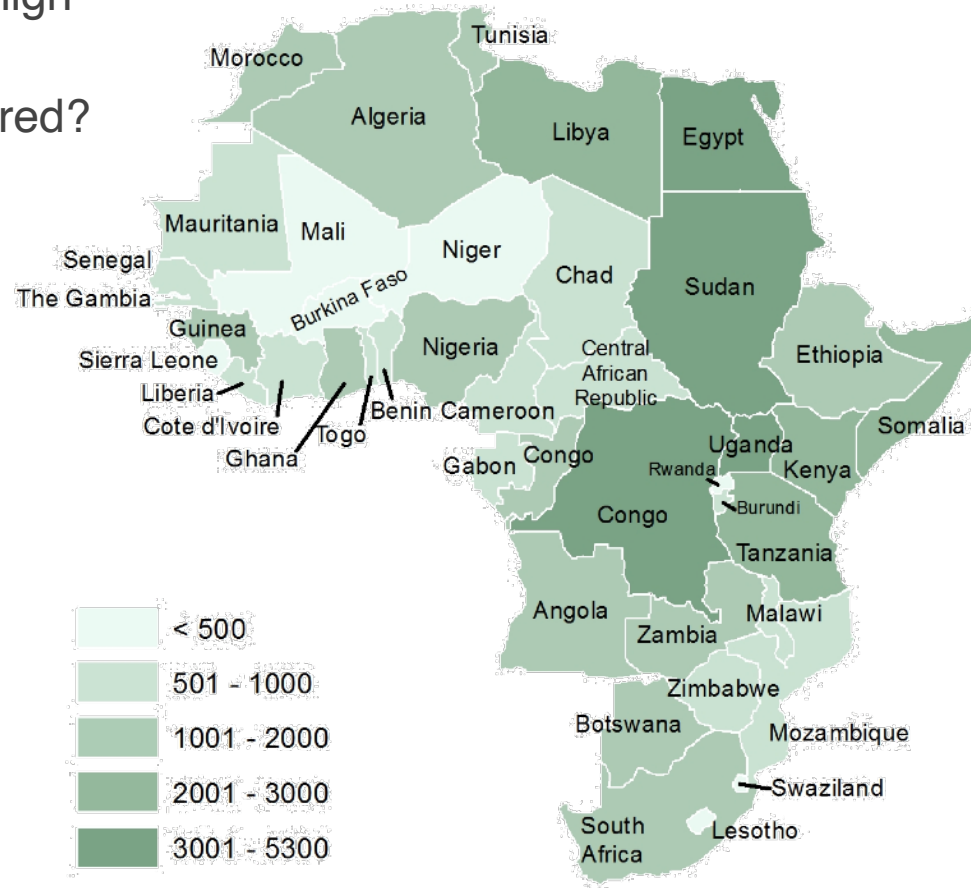
Are countries with a high conflict index score geographically clustered?

Table 1.1: Index of total African conflict for the 1966-78 period (Anselin and O'Loughlin 1992).

Country	Conflicts	Country	Conflicts
EGYPT	5246	LIBERIA	980
SUDAN	4751	SENEGAL	933
UGANDA	3134	CHAD	895
ZAIRE	3087	TOGO	848
TANZANIA	2881	GABON	824
LIBYA	2355	MAURITANIA	811
KENYA	2273	ZIMBABWE	795
SOMALIA	2122	MOZAMBIQUE	792
ETHIOPIA	1878	IVORY COAST	758
SOUTH AFRICA	1875	MALAWI	629
MOROCCO	1861	CENTRAL AFRICAN REPUBLIC	618
ZAMBIA	1554	CAMEROON	604

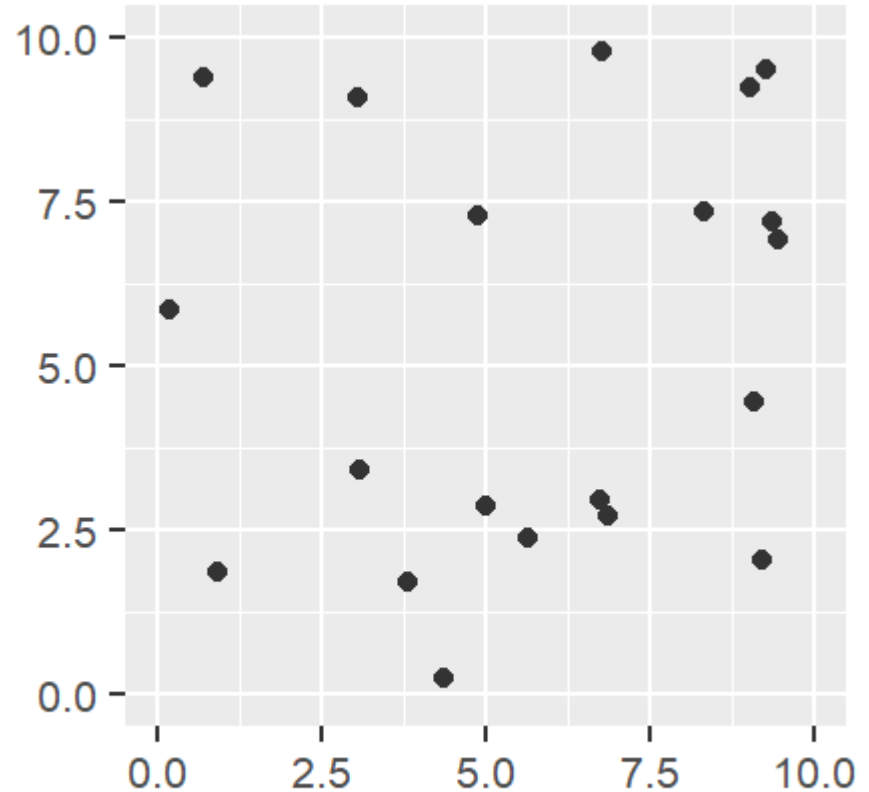
Data source: Anselin, L. and John O'Loughlin. 1992. Geography of international conflict and cooperation: spatial dependence and regional context in Africa. In The New Geopolitics, ed. M. Ward, pp. 39-75.

Are countries with a high
conflict index score
geographically clustered?



Global Point Density

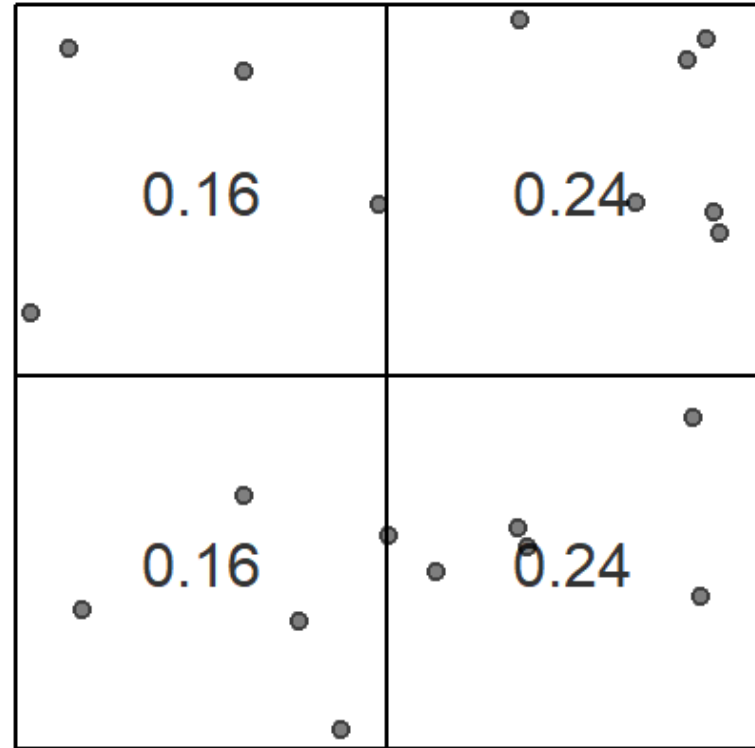
the ratio of observed
number of points to the
study region's surface area



Quadrat Density (local)

Surface is divided and then point density is calculated within quadrat

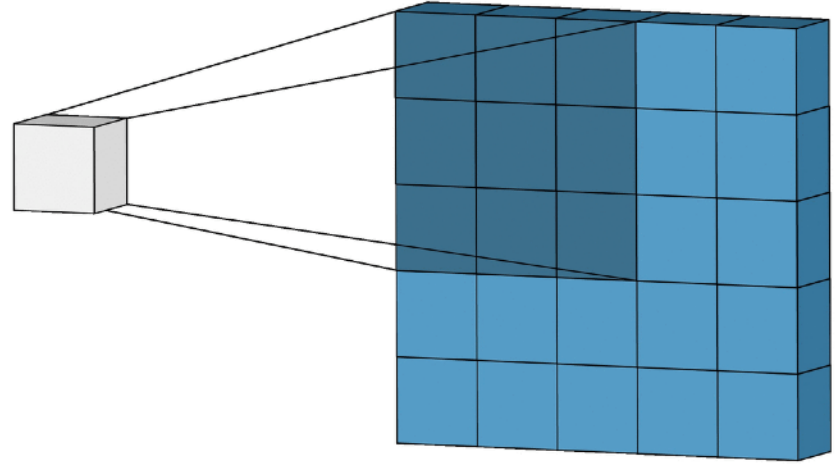
Note: quadrat number and shape will affect measurement estimate. Suffers from MAUP.



Kernel Density (local)

Point density is calculated within sliding windows (window size = kernel)

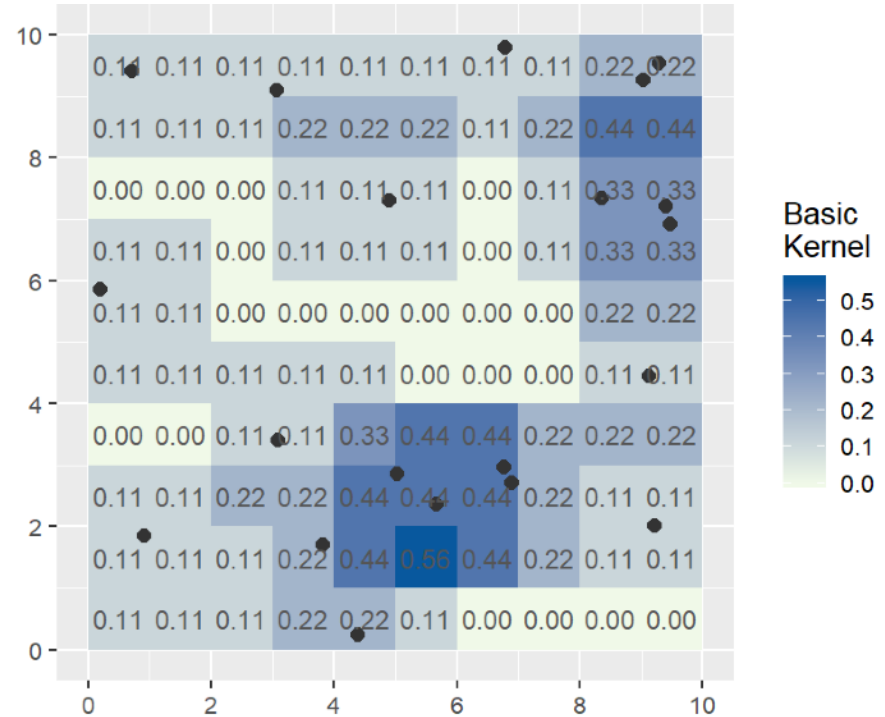
Note: kernel will affect measurement estimate, but this is less susceptible to MAUP.



Kernel Density (local)

Point density is calculated within sliding windows (window size = kernel)

Note: kernel will affect measurement estimate, but this is less susceptible to MAUP.



Modeling these data: Poisson Point Process

(Density-based Methods - - how the points are distributed relative to the study space)

$$\lambda(i) = e^{\alpha + \beta Z(i)}$$

$\lambda(i)$ is the modeled intensity at location i

e^α is the base intensity when the covariate is *zero*

e^β is the multiplier by which the intensity increases (or decreases) for each 1 unit increase in the covariate

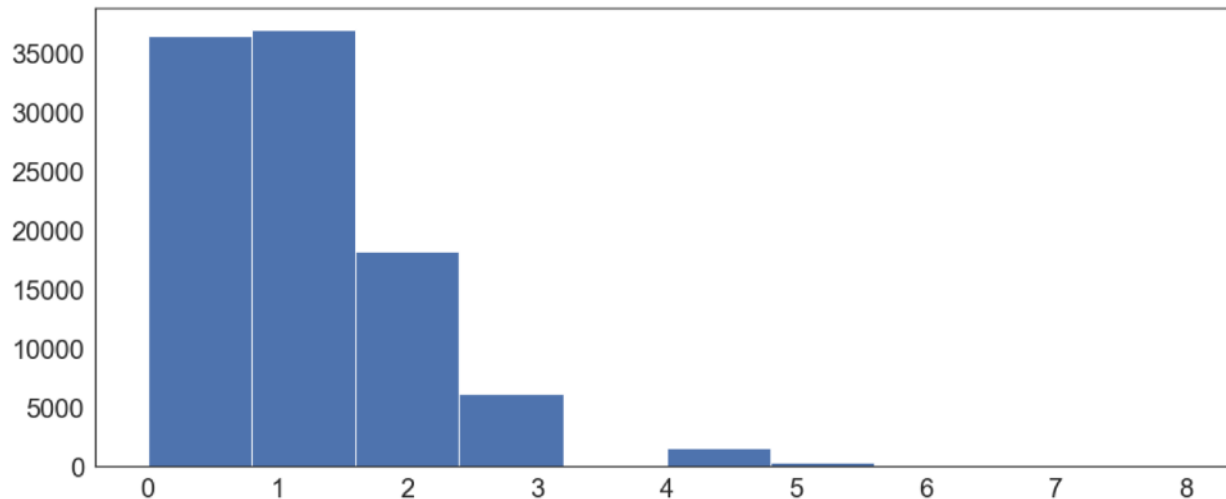
Poisson Distribution

The Poisson Distribution models events in fixed intervals of time, given a known average rate (and independent occurrences).

In [55]:

Slide Type Fragment

```
dat = poisson.rvs(mu=1, size=100000)
plt.hist(dat);
```

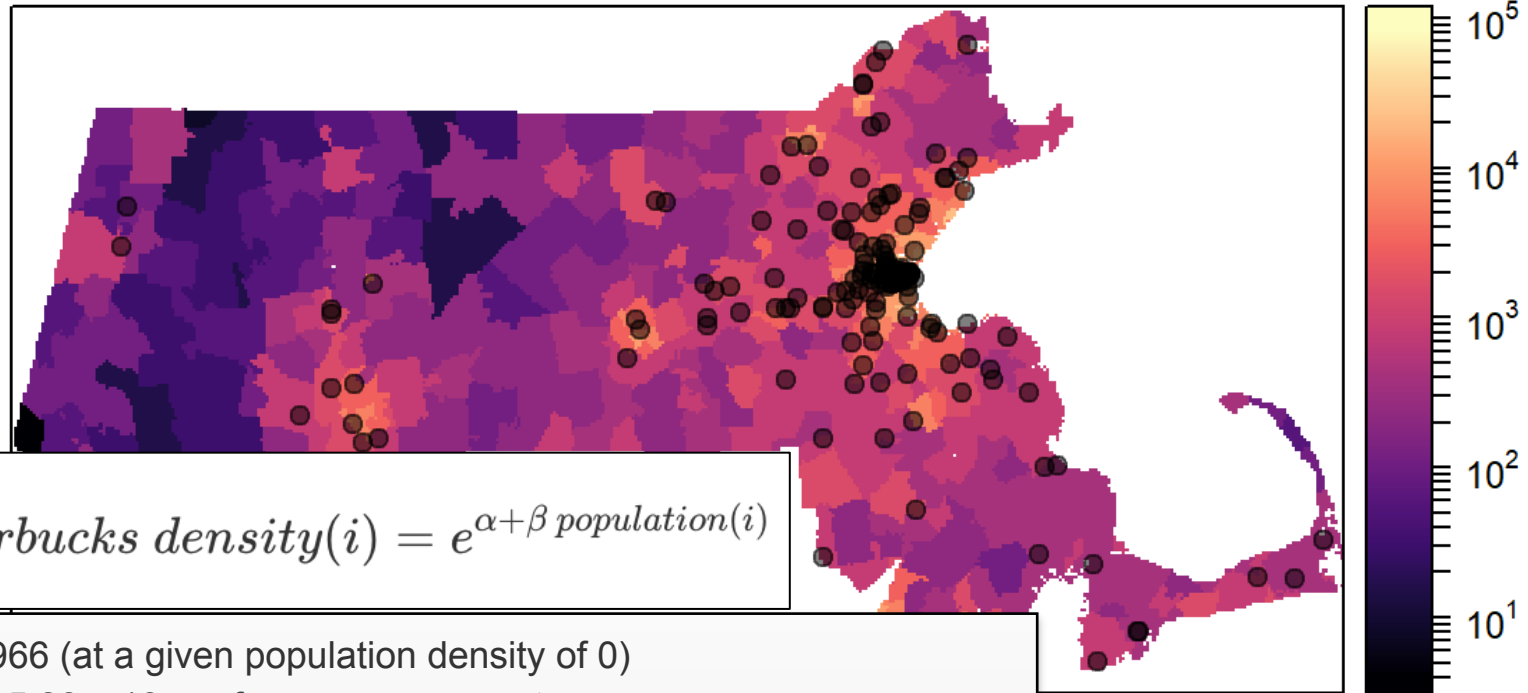


Slide Type Fragment

The **number of visitors a fast food drive-through gets each minute** follows a Poisson distribution. In this case, maybe the average is 3, but there's some variability around that number.

A Poisson distribution can help calculate the probability of various events related to customers going through the drive-through at a restaurant. It will predict lulls (0 customers) and flurry of activity (5+ customers), allowing staff to plan and schedule more precisely.

Location of Starbucks relative to population density in MA



$$\text{Starbucks density}(i) = e^{\alpha + \beta \text{ population}(i)}$$

$\alpha = -18.966$ (at a given population density of 0)

$e^{-18.966} = 5.80 \times 10^{-9}$ cafes per square meter

$\beta = 0.00017$; $e^{0.00017}$ or 1.00017

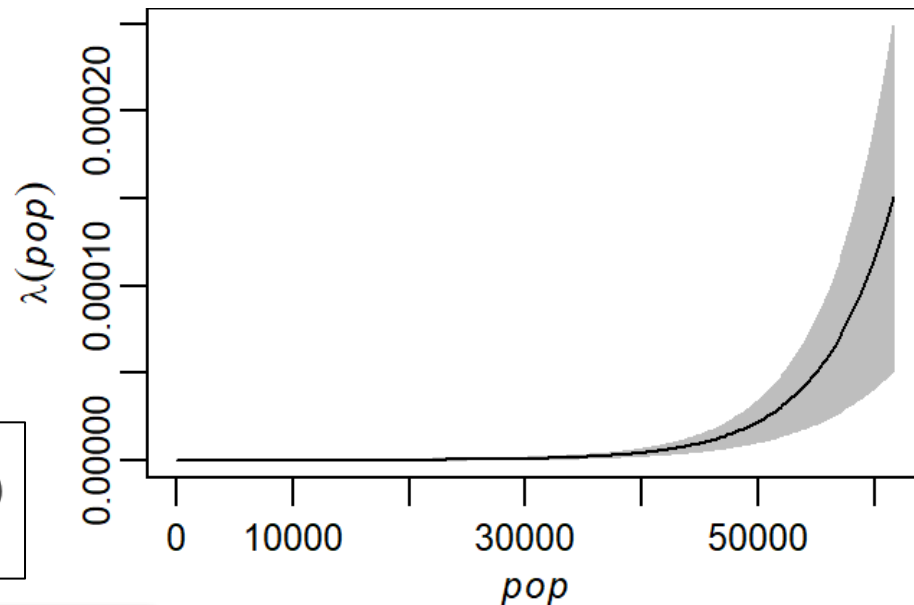
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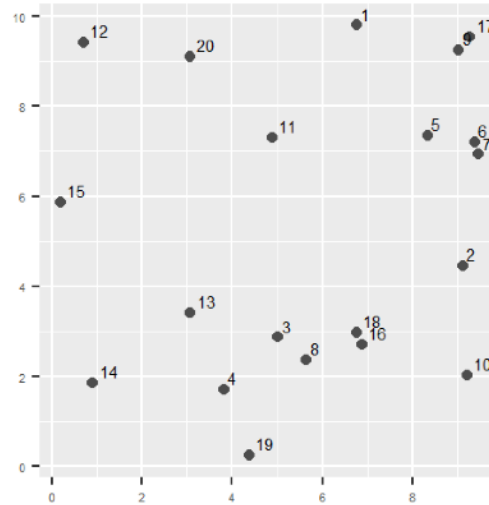
$e^{-18.966} = 5.80 \times 10^{-9}$ cafes per square meter

$\beta = 0.00017$; $e^{0.00017}$ or 1.00017



Modeling these data: Average Nearest Neighbor

(Distance-based Methods - how the points are distributed relative to one another)



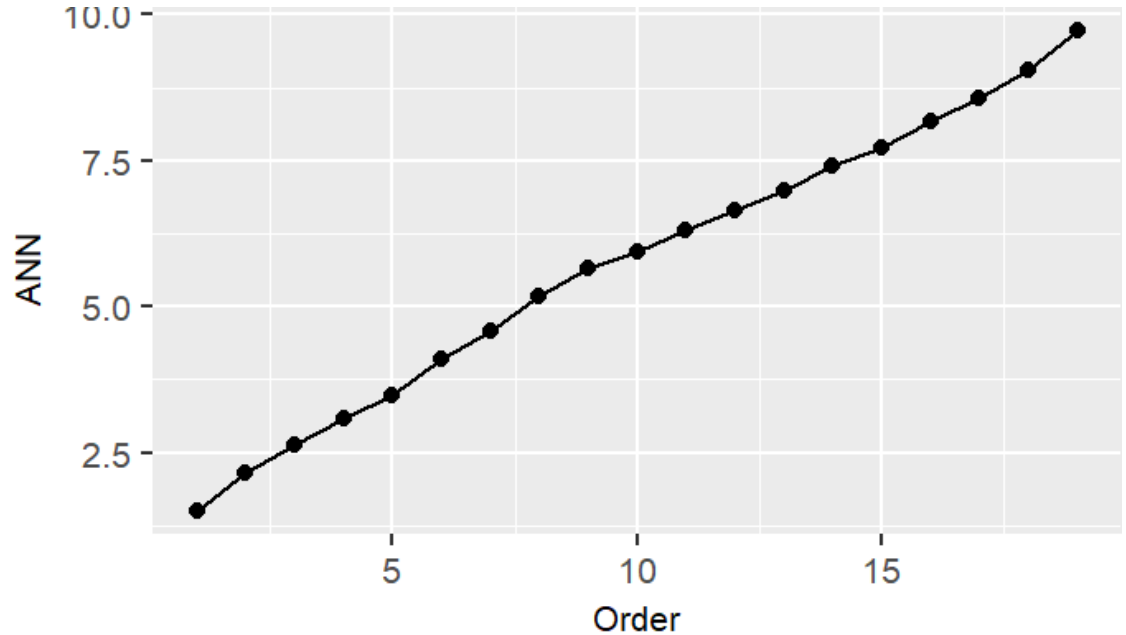
From	To	Distance	From	To	Distance
1	9	2.32	11	20	2.55
2	10	2.43	12	20	2.39
3	8	0.81	13	4	1.85
4	19	1.56	14	13	2.67
5	6	1.05	15	12	3.58
6	7	0.3	16	18	0.29
7	6	0.3	17	9	0.37
8	3	0.81	18	16	0.29
9	17	0.37	19	4	1.56
10	2	2.43	20	12	2.39

ANN = 1.52 units

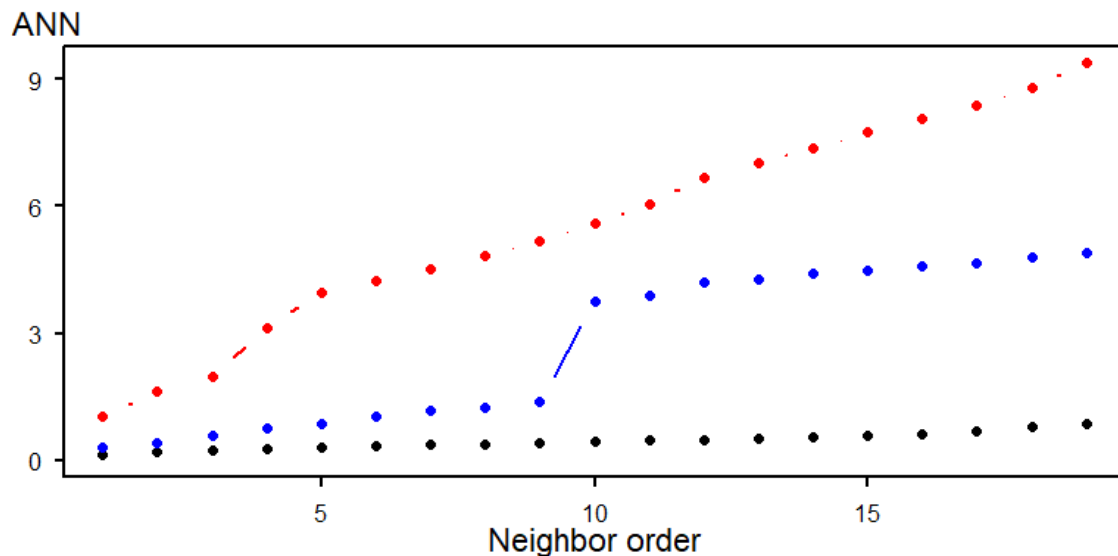
Modeling these data: Average Nearest Neighbor

(Distance-based Methods - how the points are distributed relative to one another)

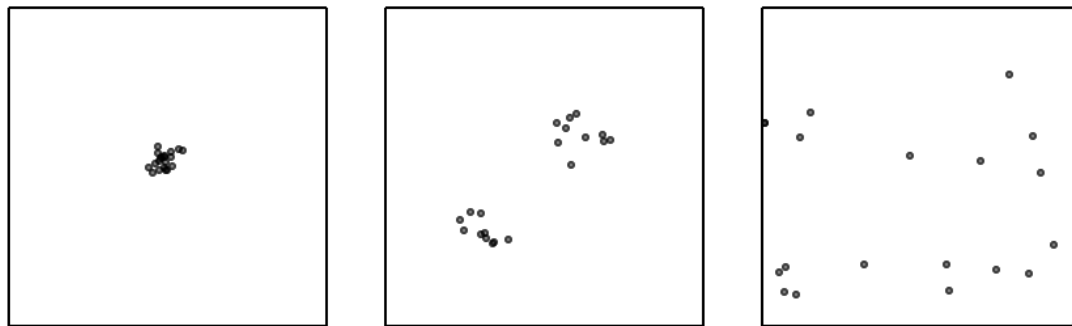
plot the ANN values for different order neighbors, that is for the first closest point, then the second closest point, and so forth.



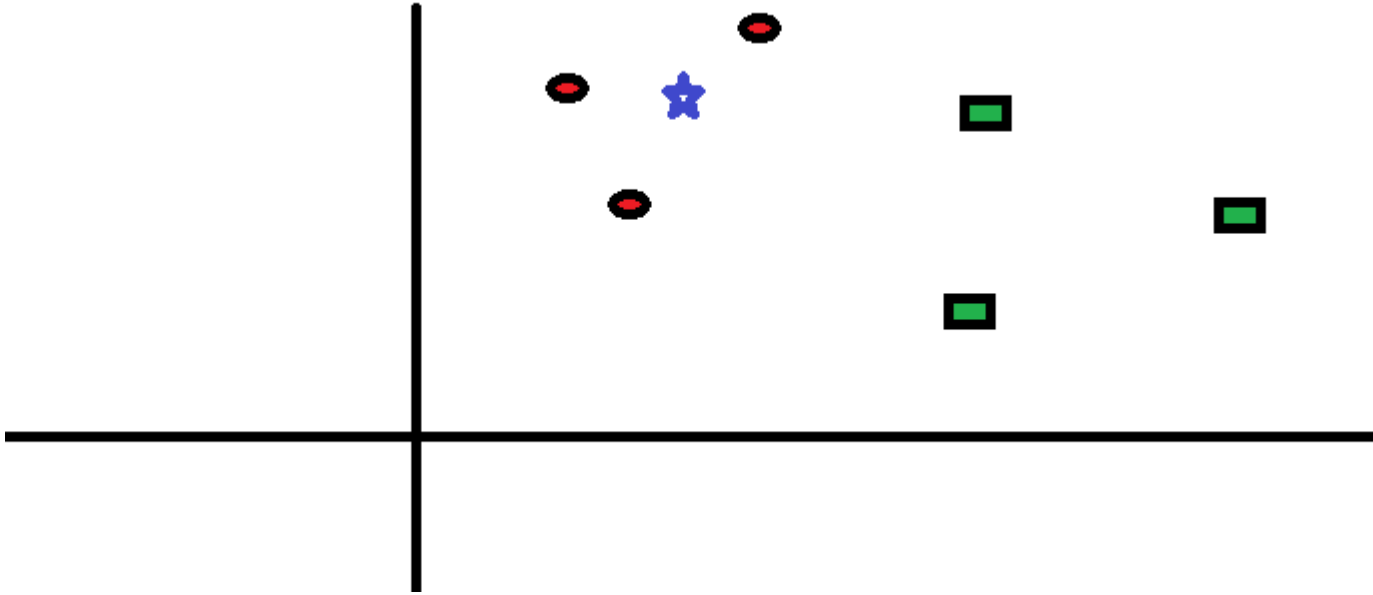
ANN vs neighbor order
offers insight into
underlying spatial
relationship



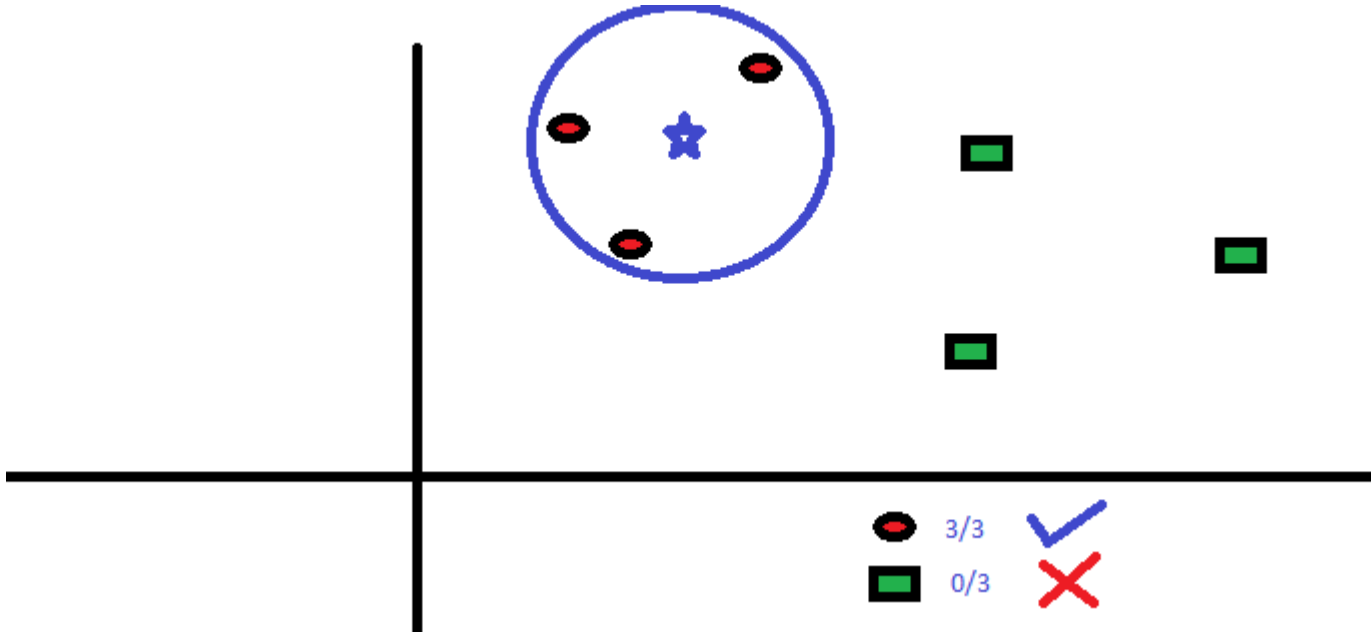
Note: study space definition
affects this measure



KNN: K Nearest Neighbor for Classification



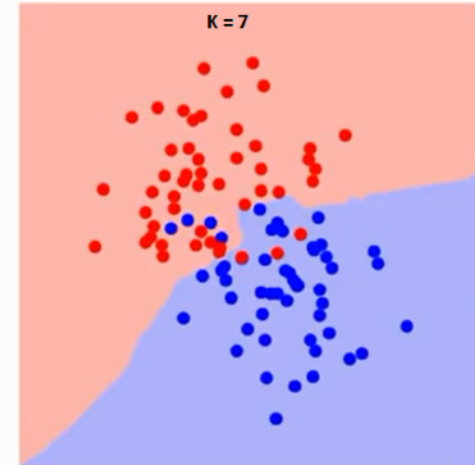
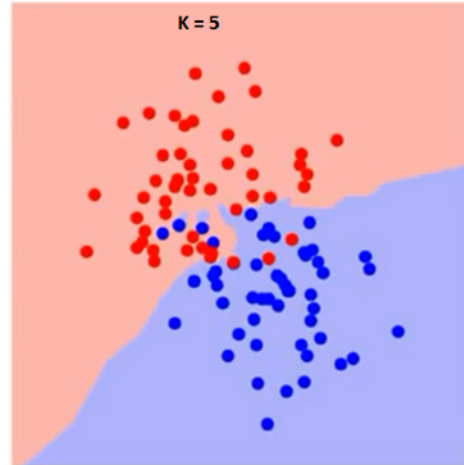
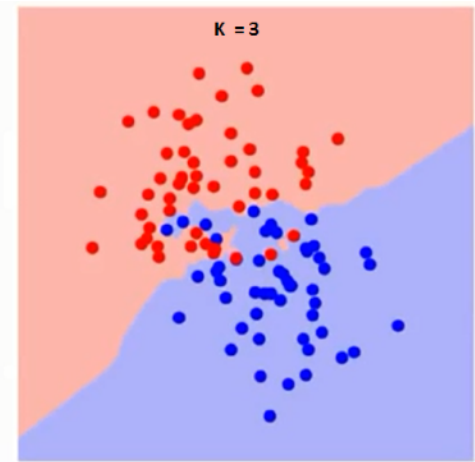
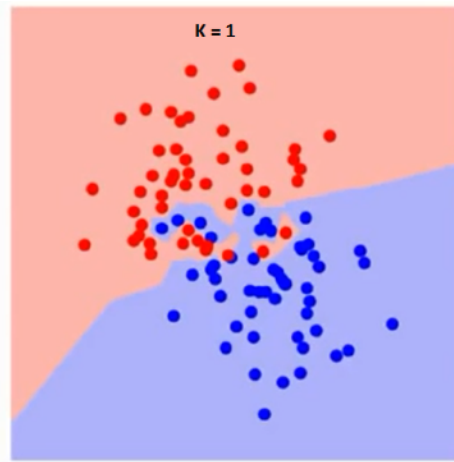
KNN: To which class does the blue star belong?



KNN: Choosing K

K specifies how many neighbors to consider.

Note that as more neighbors are considered, the boundary smooths out.



KNN: Pros & Cons

Pros:

- No assumptions about data (good for nonlinear)
- Simple and interpretable
- Relatively high accuracy
- Versatile (classification & regression)

Cons:

- Computationally intensive
- High Memory requirements
- Stores all (or most) of training data
- Prediction slow with large N
- Sensitive to outliers/irrelevant features

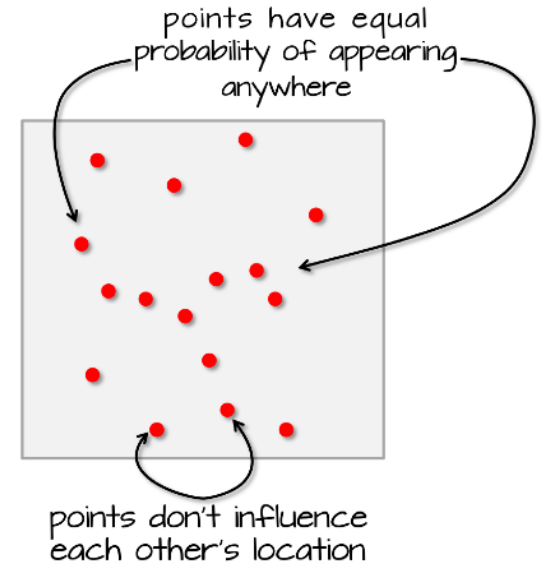
Hypothesis Testing: CSR/IPR

(Distance-based Methods - how the points are distributed relative to one another)

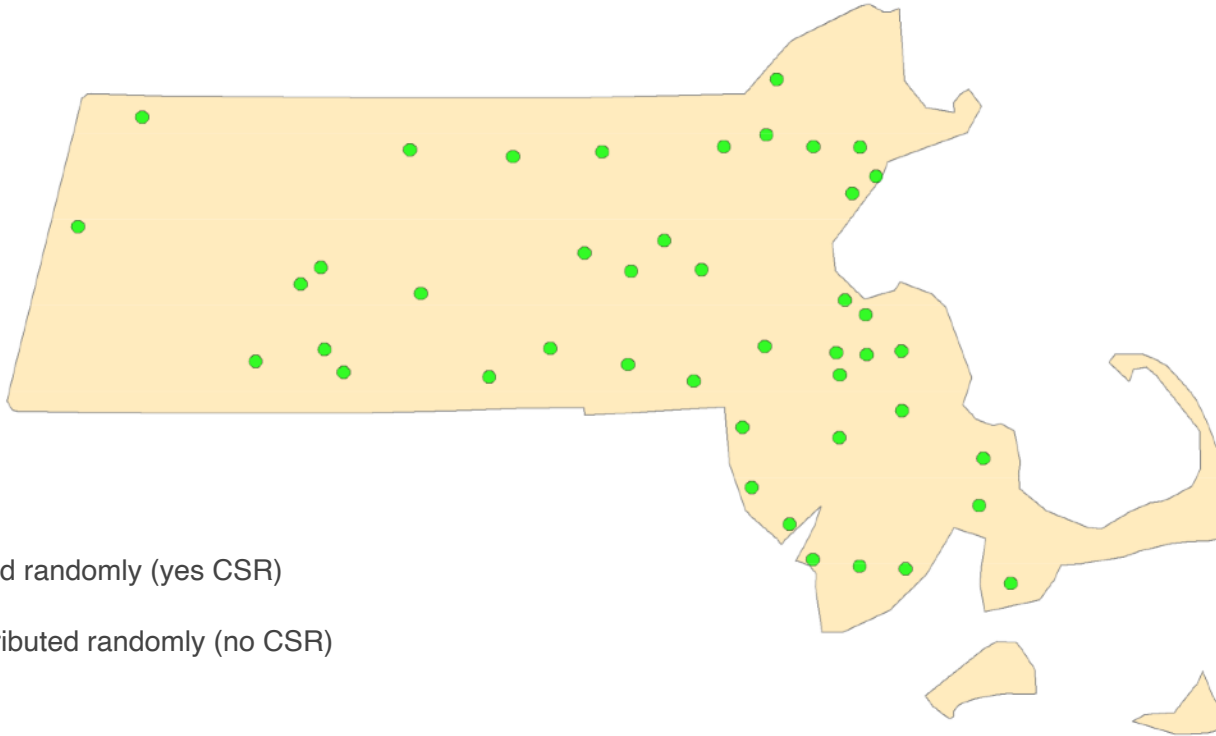
Compare observed point patterns to ones generated by an independent random process (IRP), aka complete spatial randomness (CSR).

CSR/IPR satisfy two conditions:

1. Any event has equal probability of being in any location, a 1st order effect.
2. The location of one event is independent of the location of another event, a 2nd order effect



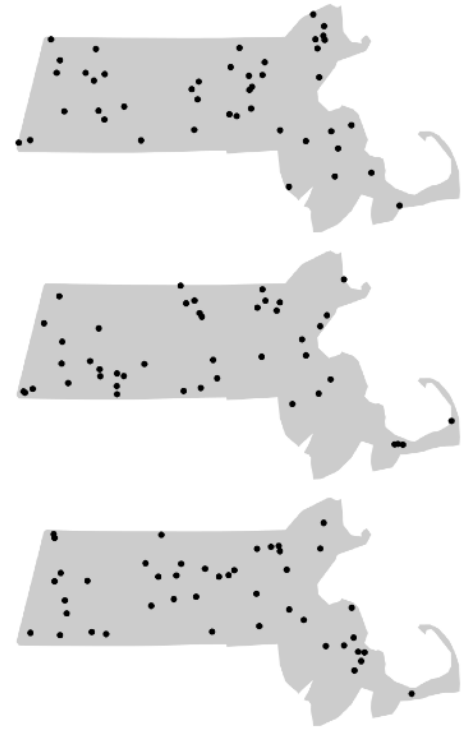
Is this distribution of Walmarts in MA the result of CSR?



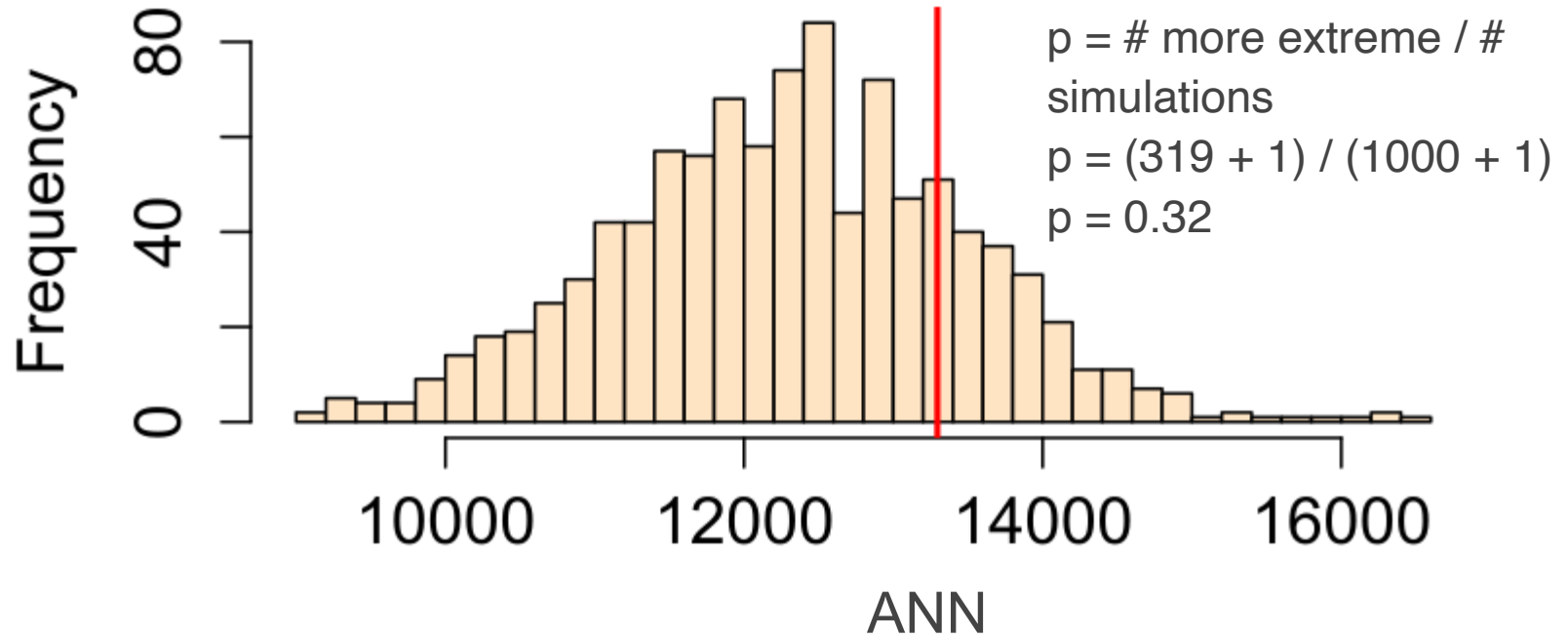
H_o : Distributed randomly (yes CSR)

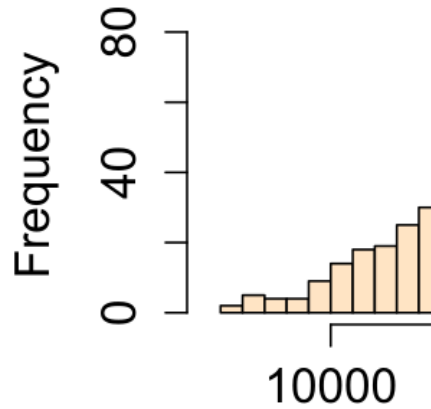
H_a : NOT distributed randomly (no CSR)

1. First, we postulate a process—our null hypothesis, H_0 .
For example, we hypothesize that the distribution of Walmart stores is consistent with a completely random process (CSR).
2. Next, we simulate many realizations of our postulated process and compute a statistic (e.g. ANN) for each realization.
3. Finally, we compare our observed data to the patterns generated by our simulated processes and assess (via a measure of probability) if our pattern is a likely realization of the hypothesized process.

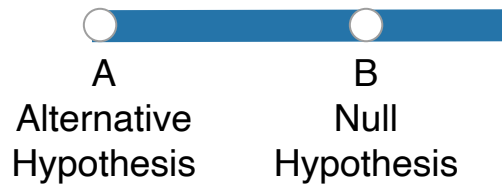


This is an example of bootstrapping!

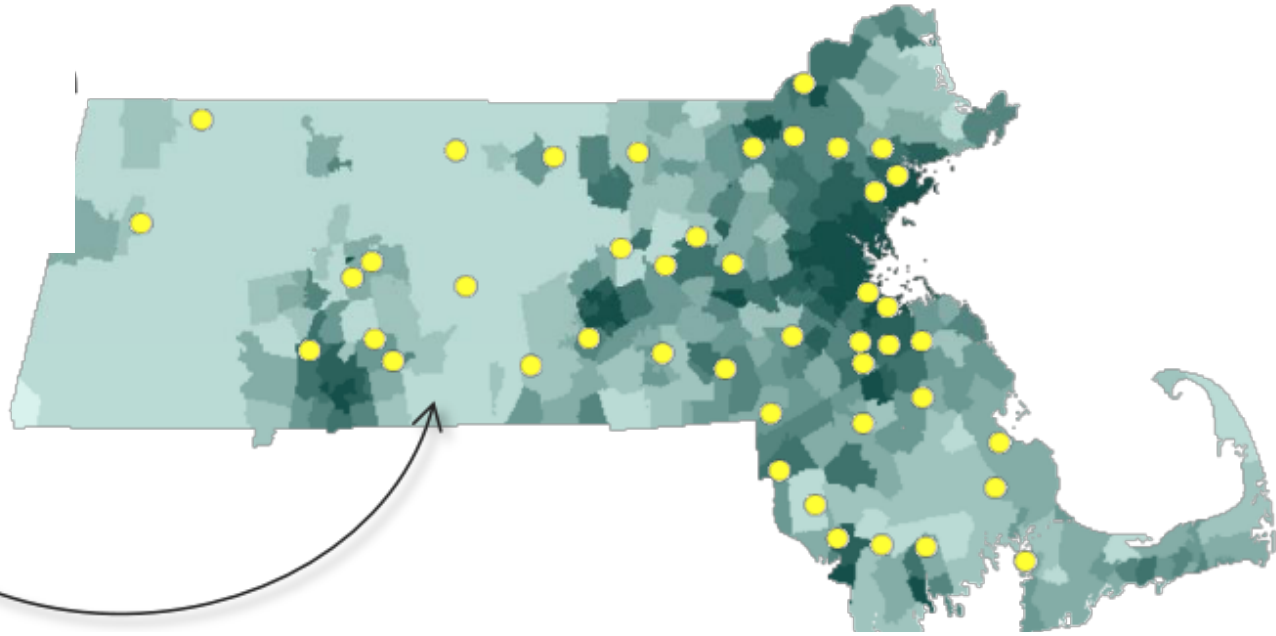




What does the histog

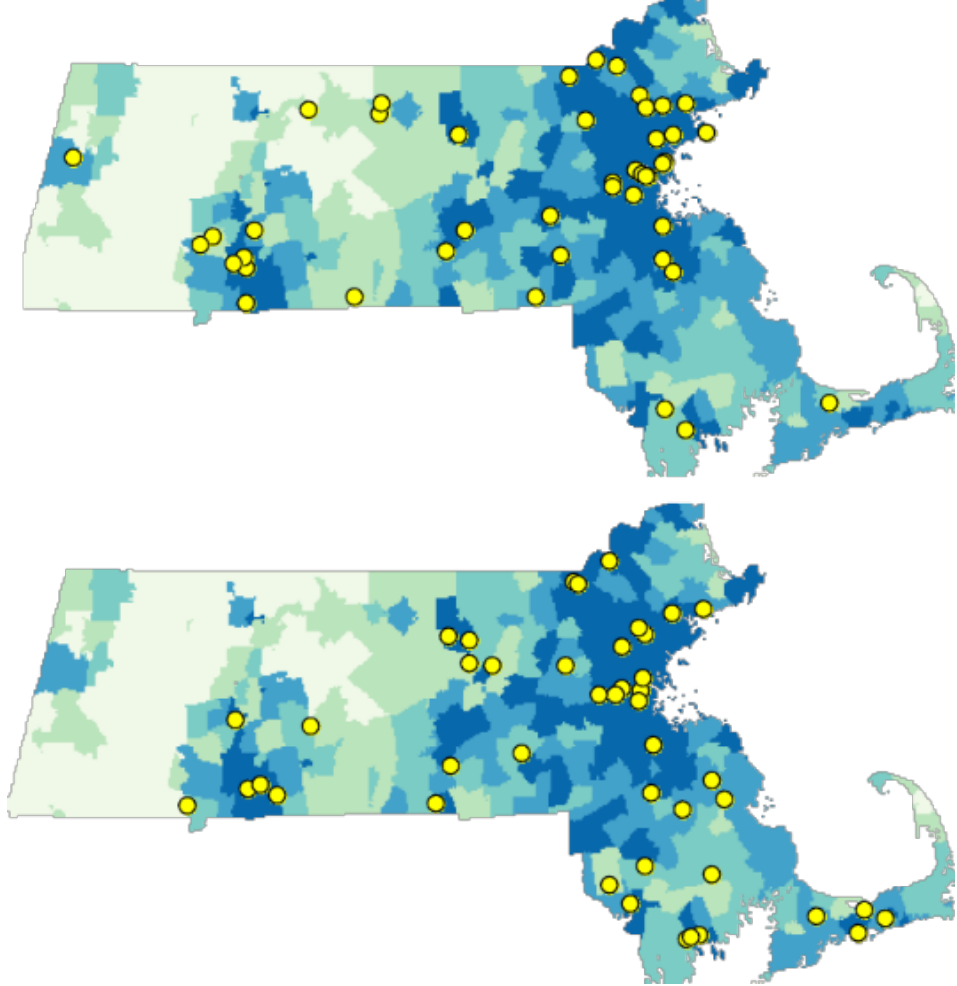


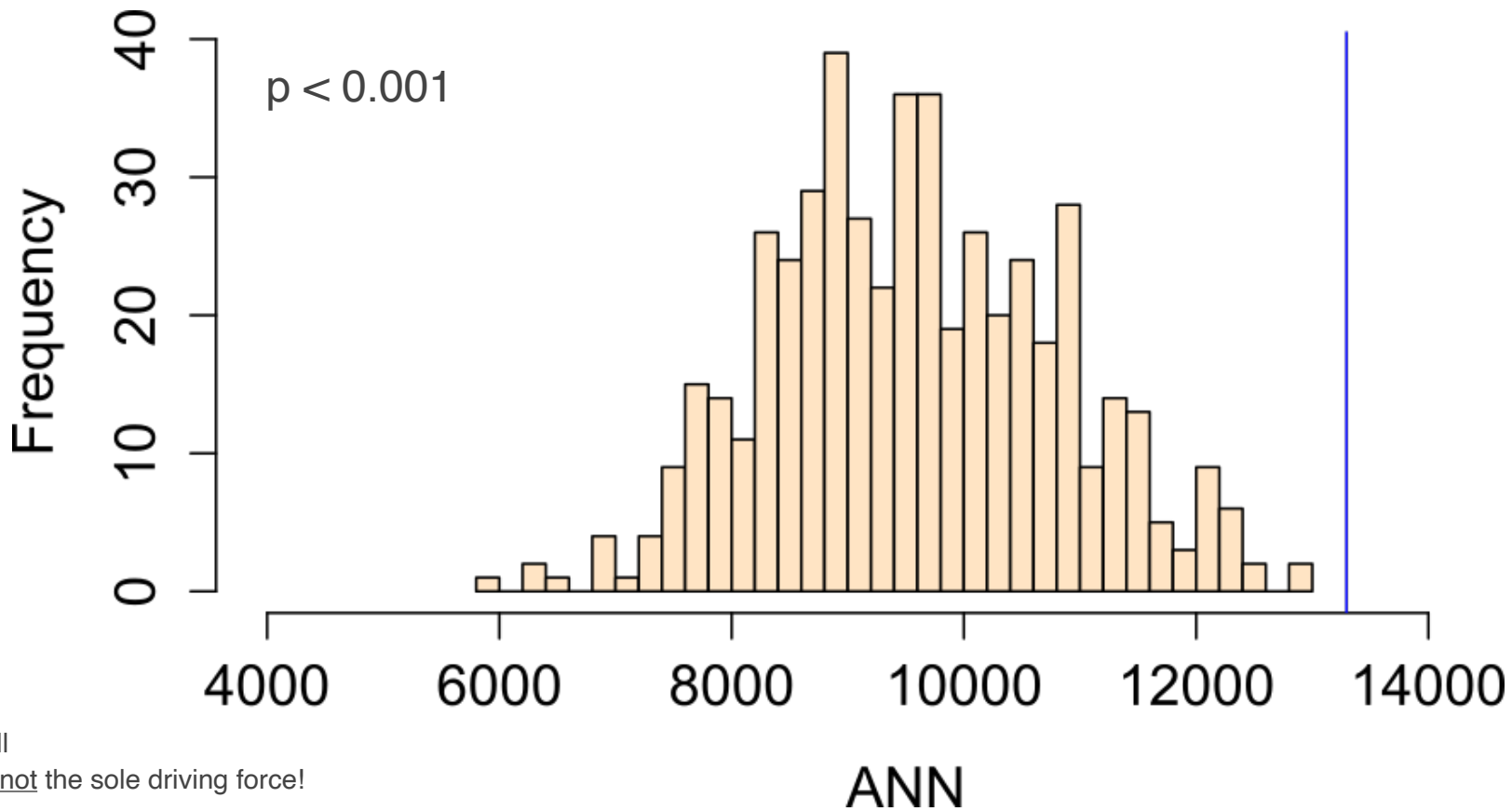
When controlling for population density, are Walmarts randomly distributed?



H_0 : Walmarts are distributed according to population density alone
 H_a : Walmarts are *not* distributed based on population density alone

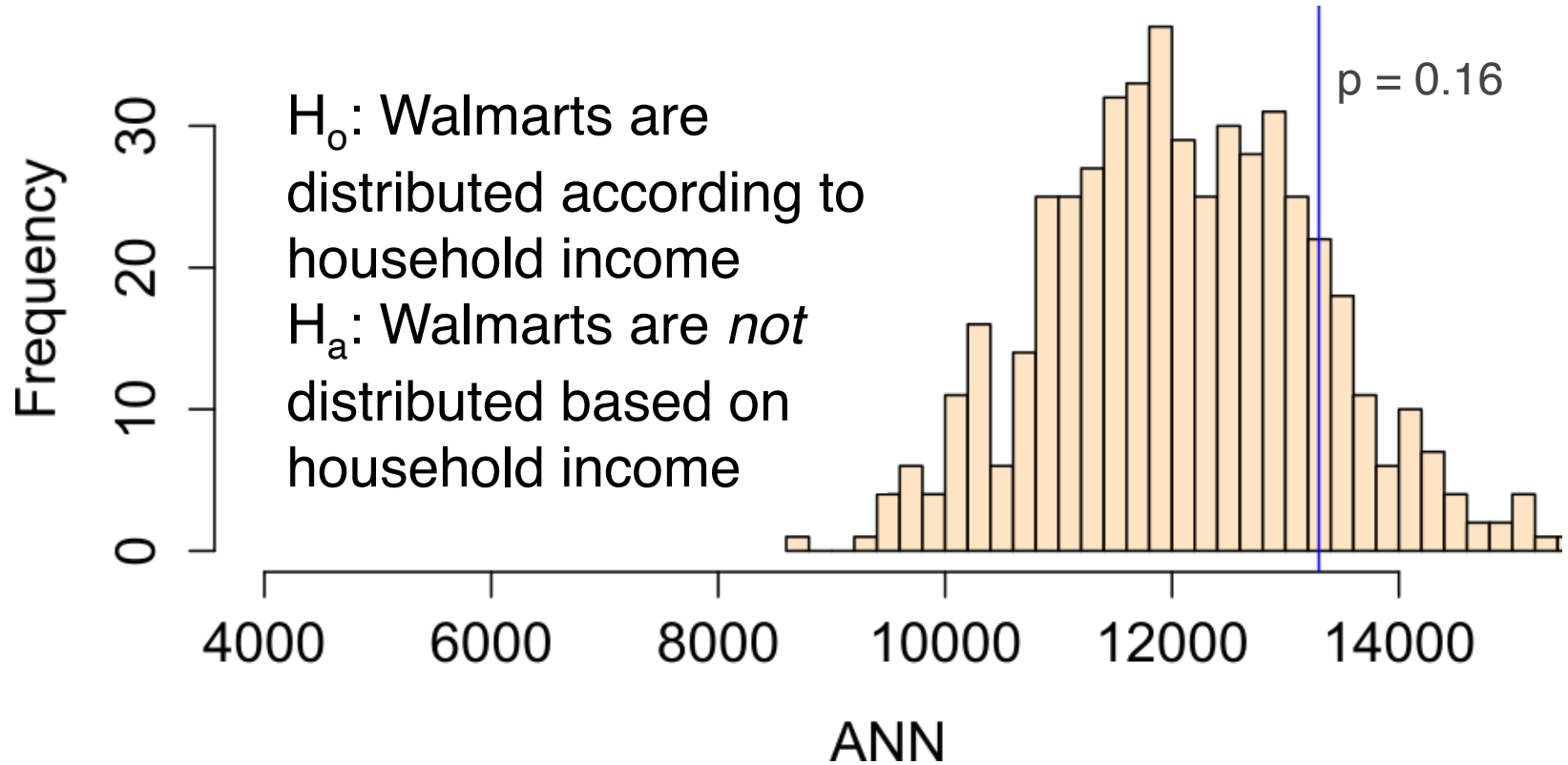
two randomly generated
point patterns using
population density as
the underlying process





Reject the null
Population is not the sole driving force!

Maybe median household income is the driving force...?



...Is it CSR or median household income?

hints at plausible scenarios, but doesn't tell us which one it is definitively.

Basic Geospatial Analysis: Summary

1. Considerations when visualizing spatial data important to conclusions drawn
 - a. values to plot?
 - b. map type?
 - c. color scale?
2. Traditional statistics fail with geospatial data:
 - a. Spatial autocorrelation
 - b. MAUP
 - c. Edge effects
 - d. Ecological fallacy
 - e. Nonuniformity of space
3. Analysis still possible
 - a. Global Point Density, Quadrat Density, Kernel Density
 - b. Poisson Point Process
 - c. K-Nearest Neighbor (KNN)
 - d. Comparison to a CRP (using simulation)