

# Noether's Theorem: #1 Introduction

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## Questions that we'll answer

- ↳ Analytical Mech {
  - Lagr.
  - Ham.
  - Ham-Jacob;
- ↳ Abstract Alg {
  - vec. spaces
  - Groups
- ↳ Field
- ↳ Gauge
- ↳ Examples
  - ↳ CM
  - ↳ QM
  - ↳  $\subseteq$  FT

# A Brief Glance of topics

- ① Functionals
- ② Extremals
- ③ Invariance
- ④ Noether's Theorem
- ⑤ What is Noether's Theorem?
- ⑥ Fields
- ⑦ Gauge Invariance
- ⑧ Invariance in Phase Space
- ⑨ The Action as a Generator

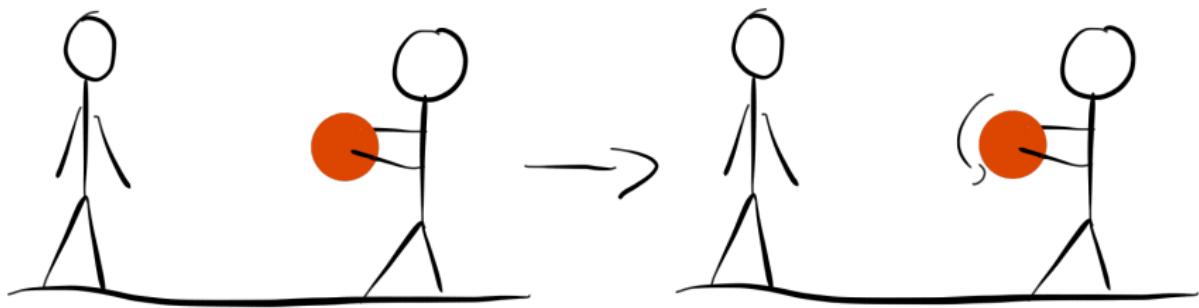
# Pedagogy

- ↳ Comments/Qs
- ↳ Eocs
- ↳ Reflective
- ↳ Problems
- } Appendices

## This Discussion

- Invariance
- Symmetry
- Passive and Active Transformations
- Global and Local Transformations
- Conservation
- What is Noether's Theorem?
- Functionals

# Invariance

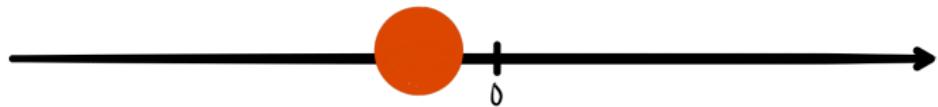


# Symmetry

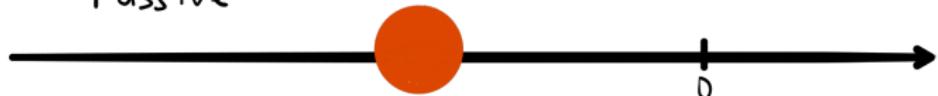
## Definition of Symmetry

The invariance of an object under a particular transformation is termed a symmetry.

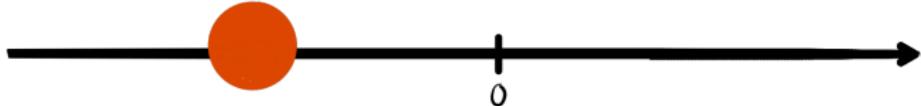
# Passive and Active Transformations



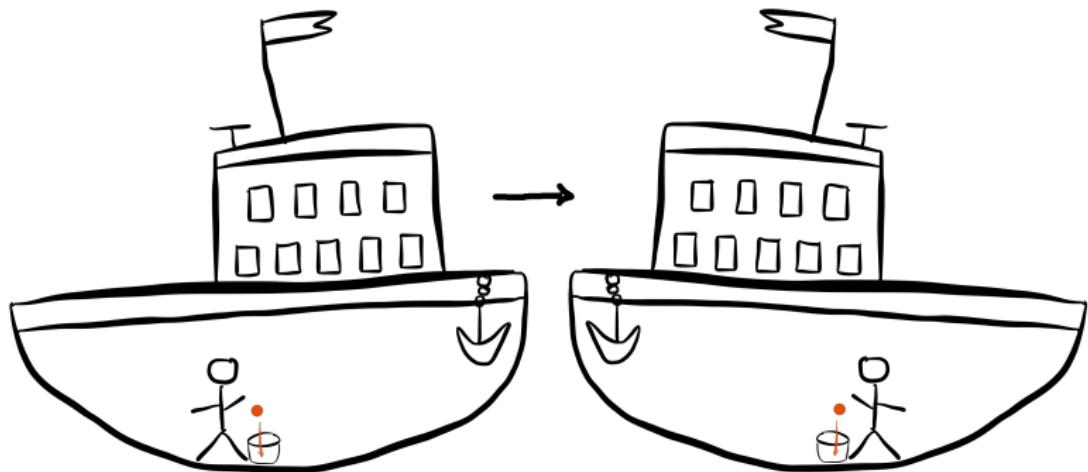
Passive



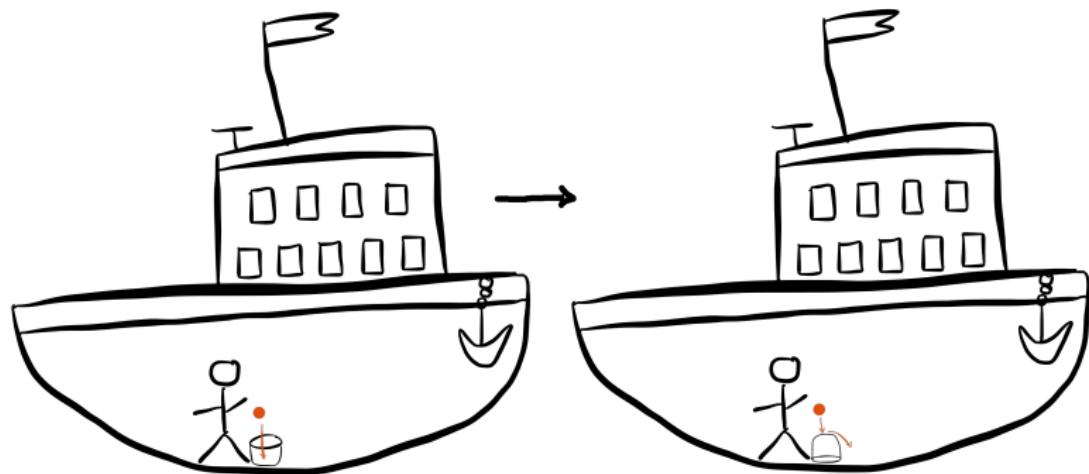
Active



# Global Transformations



## Local Transformations



## Continuous vs Discrete Transformations

$$g(\theta) = I + \underbrace{\epsilon X}_{<1} \} \text{Generator}$$

$$g(\theta) = I + \frac{\theta}{N} X$$



Continuous iff  $\prod \sum ds$

$$h(\theta) = [g(\theta)]N = \left[ I + \frac{\theta}{N} X \right]^N = e^{\theta X}$$

$\downarrow$   
Limit  
 $N \rightarrow \infty$

$= \text{Taylor Expand}$

## Conserved "Current"

$$\left. \begin{aligned} \rho &= \psi\psi^* \\ \frac{\partial\rho}{\partial t} &= 0 \end{aligned} \right\} \quad \begin{aligned} \frac{\partial\rho}{\partial t} &= -\nabla \cdot \vec{j} \\ \vec{j} &= \frac{\hbar}{e m_i} (\psi^* \nabla \psi - \psi \nabla \psi^*) \end{aligned}$$

A conserved current is an object that follows a continuity equation

## What is Noether's Theorem?

Symmetry  $\leftrightarrow$  Conserved

Transformations = Continuous

Every differentiable symmetry of the action of a physical system has a corresponding conservation law.

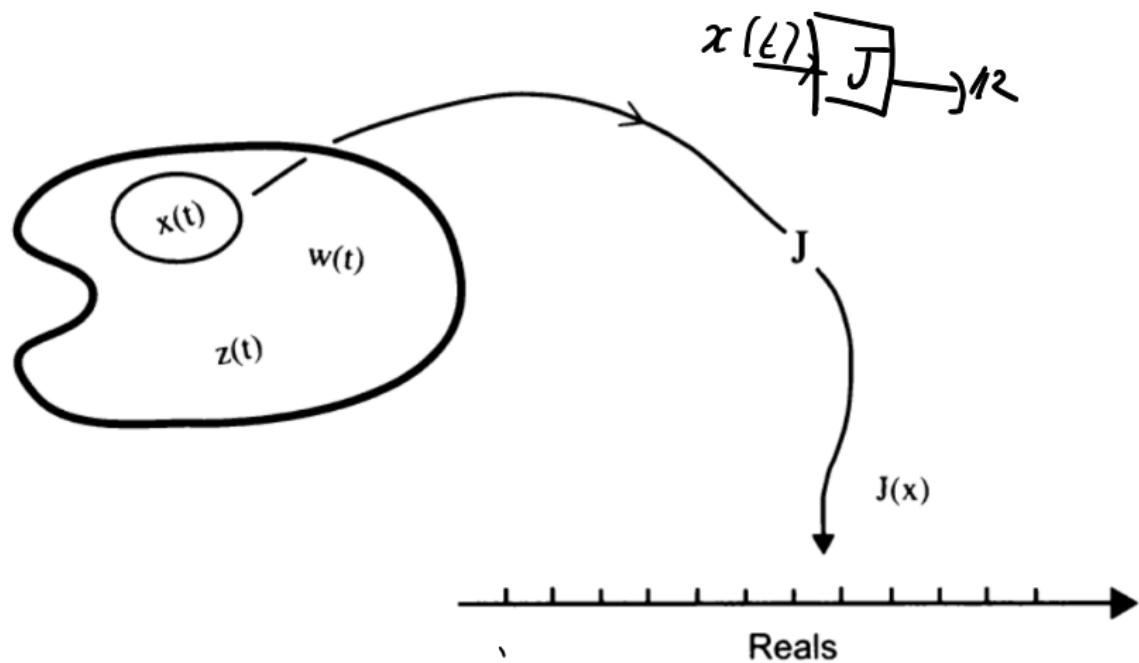
"Functional"

$$S = \int L dt \underset{\text{Extremize}}{\approx}$$

$$\int (T - V) d\ell$$



## Functionals



A functional  $J$  is a mapping from a set of well defined functions to the real number line.

## Examples

↳ Length / Distance =  $\int ds$

$$= \int \sqrt{dx^2 + dy^2} = \int \sqrt{1+y'^2} dx$$

↳ Fermat's Principle

$$\int n(x) L(x) dx = 0$$

↳ Hamilton's principle

$$\int_a^b (T - V) dt = L$$

$L(q, \dot{q}, t)$  Ostrogr.

Lagrangian

$$J(x) = \int_a^b L dx$$

Functional

$$J: V \rightarrow \mathbb{R} \quad \forall v \in V$$

## A Word About Mathematical Structures

Set + Operations + Rules

$\{ \dots \}$

$\in$

$C$

Binary  
 $(, ) \rightarrow ()$

Associative:  $AB(c) = A(Bc)$   
 $A \cdot B = B \cdot A$

# Vector Spaces

$$+ = v, w \in V \quad \vec{v}, \vec{v}'$$

## Axioms

A linear vector space or simply a vector space  $V$  is a set along with the multiplication ( $\cdot$ ) and addition ( $+$ ) operations over  $\mathbb{R}$  or  $\mathbb{C}$ , such that the following axioms hold:

- **Commutativity:**  $|U\rangle + |V\rangle = |V\rangle + |U\rangle$  Field
- **Associativity:**  $(|U\rangle + |V\rangle) + |W\rangle = |V\rangle + (|U\rangle + |W\rangle)$
- **Additive Identity:**  $\exists |0\rangle \in V \mid |V\rangle + |0\rangle = |0\rangle + |V\rangle = |V\rangle$
- **Additive Inverse:**  $\forall |V\rangle \exists |V^{-1}\rangle \mid |V\rangle + |V^{-1}\rangle = |0\rangle$  ↗
- **Multiplicative identity:**  $\exists 1 \in V \mid 1 \cdot |V\rangle = |V\rangle$
- **Multiplicative Associativity:**  $(\alpha\beta)|V\rangle = \alpha(\beta|V\rangle)$
- **Distributive Properties:**

- $(\alpha + \beta)|U\rangle = \alpha|U\rangle + \beta|U\rangle$
- $\alpha(|U\rangle + |V\rangle) = \alpha|U\rangle + \alpha|V\rangle$

Here,  $\alpha, \beta \in \mathbb{R}$  or  $\mathbb{C}$  and  $|U\rangle, |V\rangle$  and  $|W\rangle \in V$

Kets

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