Introduction to Statistical Learning

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Clustering

- $\{x_i\}_{i=1}^n$
- $\mathbf{x}_i = (x_{i1}, ..., x_{ip})$
- Group "similar" data points together

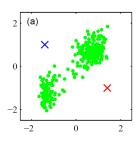


Figure: Bishop, 2013

K-means clustering

- Divide $\{\mathbf{x}_i\}_{i=1}^n$ into K clusters
- Each x_i belongs to only one of the K clusters (hard assignment)
- Define indicator variables for class membership:

$$r_{ik} = \begin{cases} 1 & \text{if} & \mathbf{x}_i \in \text{cluster } k \\ 0 & \text{if} & \mathbf{x}_i \notin \text{cluster } k \end{cases}$$

Loss function (distortion measure)

$$J = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} ||\mathbf{x}_{i} - \mu_{k}||^{2}$$

- What is μ_k ? Prototype associated with cluster k
- Find clusters such that J is minimized

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K-means clustering

An iterative procedure to minimize J:

- Step 0 (Initialization): Start with an initial set of prototype vectors $\{\mu_k\}_{k=1}^K$
- Step 1 (Expectation): Minimize J with respect to r_{ik} , i = 1, ..., n, k = 1, ..., K by fixing $\{\mu_k\}_{k=1}^K$
- Step 2 (Maximization): Minimize J with respect to $\{\mu_k\}_{k=1}^K$ by fixing r_{ik} , i = 1, ..., n, k = 1, ..., K

k-means algorithm:

Initialization $\rightarrow E \rightarrow M \rightarrow E \rightarrow M \rightarrow \cdots$ (until convergence)

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The expectation step

Problem:

Minimize

$$J = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} ||\mathbf{x}_{i} - \mu_{k}||^{2}$$

with respect to r_{ik} , i = 1, ..., n, k = 1, ..., K

Solution:

$$r_{ik} = egin{cases} 1 & ext{if} & k = arg \min_{j \in \{1, \dots, K\}} ||\mathbf{x}_i - \mu_j||^2 \\ 0 & ext{otherwise} \end{cases}$$

• Assign x_i to the cluster with the closest prototype vector!

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The maximization step

Problem:

Minimize

$$J = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} ||\mathbf{x}_{i} - \mu_{k}||^{2}$$

with respect to $\{\mu_k\}_{k=1}^K$ **Solution:**

$$\mu_k = \frac{\sum_{i=1}^n r_{ik} \mathbf{x}_i}{\sum_{i=1}^n r_{ik}}$$

- μ_k is the mean (average) of all data points \mathbf{x}_i assigned to cluster k
- This is where the name "K-means" comes from!

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Convergence of the K-means algorithm

- Does K-means converge?
- If it converges, how long does it take for it to converge?
- Where does it converge?



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A probabilistic analogue of k-means

- For each cluster j we have the following parameters: π_j, μ_j, Σ_j
- Given $\{\mathbf{x}_i\}_{i=1}^n$ find the MLE estimate of (π, μ, Σ)

Solution?

MLE:

$$L(\pi, \mu, \Sigma) = \prod_{i=1}^{n} p(\mathbf{x}_{i} | \pi, \mu, \Sigma)$$

$$I(\pi, \mu, \Sigma) = \log L(\pi, \mu, \Sigma)$$

$$= \sum_{i=1}^{n} p(\mathbf{x}_{i} | \pi, \mu, \Sigma)$$

$$= \sum_{i=1}^{n} \log \{ \sum_{k=1}^{K} \pi_{j} \mathcal{N}(\mathbf{x} | \mu_{j}, \Sigma_{j}) \}$$

$$(\hat{\pi}, \hat{\mu}, \hat{\Sigma}) = \arg \max I(\pi, \mu, \Sigma)$$

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Illustration of k-means

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Illustration of k-means

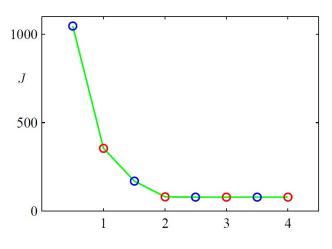


Figure: Bishop, 2013

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k-medoids algorithm

- Generalization of K-means
- $||\mathbf{X}_i \mu_k||^2 \to \mathcal{V}(\mathbf{x}_i, \mu_k)$ (a general dissimilarity measure)
- New loss function

$$\widetilde{J} = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} \mathscr{V}(\mathbf{x}_{i}, \mu_{k})$$

The same procedure applies to minimize J^{\sim} :

Initialization \rightarrow $E \rightarrow$ $M \rightarrow$ $E \rightarrow$ $M \rightarrow \cdots$ (until convergence)

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The expectation step

Problem:

Minimize

$$\widetilde{J} = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} \mathcal{V}(\mathbf{x}_i, \mu_k)$$

with respect to r_{ik} , i = 1, ..., n, k = 1, ..., K

Solution:

$$r_{ik} = egin{cases} 1 & ext{if} & k = arg \min_{j \in \{1, \dots, K\}} \mathscr{V}(\mathbf{x}_i, \mu_k) \ 0 & ext{otherwise} \end{cases}$$

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The maximization step

Problem:

Minimize

$$\widetilde{J} = \sum_{i=1}^{n} \sum_{k=1}^{K} r_{ik} \mathscr{V}(\mathbf{x}_{i}, \mu_{k})$$

with respect to $\{\mu_k\}_{k=1}^K$ such that μ_k is a datapoint that belongs to cluster k **Solution:**

- Let \mathcal{N}_k be the set of \mathbf{x}_i that belongs to cluster k
- Choose μ_k from \mathcal{N}_k such that it minimizes

$$\sum_{\mathbf{x}_i \in \mathcal{N}_k} \mathcal{V}(\mathbf{x}_i, \mu_k)$$

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Application: image segmentation and compression

- Image segmentation: partition an image into region of similar visual appearance
- Each pixel is R,G,B intensity triplet: $\mathbf{x}_i = \{x_{i1}, x_{i2}, x_{i3}\}$
- Apply K-means, represent each pixel that belongs to cluster k by its cluster center μ_k

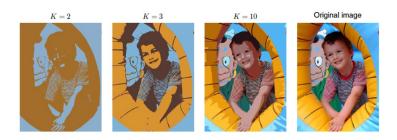


Figure: Bishop, 2013

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Application: image segmentation and compression

- Assume image has n pixels
- Assume x_{ii} stored using 8 bits of precision
- Total number of bits to transmit the original image = 24n
- What happens if we compress the image by K-means and then transmit?

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GMM

$$p(\mathbf{x}) = \sum_{j=1}^{K} \underbrace{\pi_{j}}_{ ext{mixing coefficients}} \mathscr{N}(\mathbf{x}|\mu_{j}, \Sigma_{j})$$

- What is $\int p(\mathbf{x})$?
- We must have $\sum_{j=1}^K \pi_j = 1$ and $0 \le \pi \le 1$ for all j = 1, 2, ..., K.

Compare with:

$$p(\mathbf{x}) = \sum_{j=1}^K p(j) p(\mathbf{x}|j)$$
 law of total probability



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GMM example

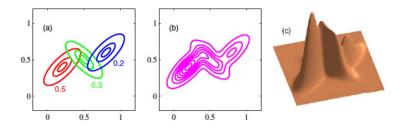


Figure: Bishop, 2013

- (a) 3 different Gaussians with mixture coefficients
- (b) contour plot of the mixture
- (c) 3D plot of the mixture

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Latent (hidden) variable

• $\mathbf{z} = (z_1, ..., z_K)$ (latent variable vector)

Properties of z:

- **1** $z_j \in \{0, 1\}$
- $\sum_{i=1}^{K} z_i = 1$
- 3 z can be viewed as an indicator vector that denotes the cluster membership.

Other properties:

- $p(\mathbf{z}) = \prod_{i=1}^K \pi_i^{z_i}$

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Conditional and marginal distribution of x

Conditional distribution of x

$$p(\mathbf{x}|\mathbf{z}) = \prod_{j=1}^{K} (\mathcal{N}(\mathbf{x}|\mu_j,]Sigma_j))^{z_j}$$

Marginal distribution of x:

$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{z}) p(\mathbf{x}|\mathbf{z}) = \sum_{j=1}^{K} \pi_{j} \mathcal{N}(\mathbf{x}|\mu_{j}, \Sigma_{j})$$

- $p(\mathbf{x})$ depends on $\{\pi_i, \mu_i, \Sigma_i\}_{i=1}^K$
- Notation:

$$\pi = \{\pi_j\}_{j=1}^K,$$

$$\mu = \{\mu_j\}_{j=1}^K,$$

$$\Sigma = \{\Sigma_j\}_{j=1}^K,$$

$$p(\mathbf{x}) = p(\mathbf{x}|\pi, \mu, \Sigma)$$

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Expectation maximization (EM) algorithm

You are given the dataset $\{\mathbf{x}\}_{j=1}^n$

- **1.** Initialize parameters: $\{\mu_j\}_{j=1}^K, \{\sum_j\}_{j=1}^K$ and $\{\pi_j\}_{j=1}^K$
- **2. E step:** Calculate responsibilities $\{z_{ij}\}$ using current parameter values:

$$\gamma(z_{ij}) = \frac{p(z_{ij} = 1|\mathbf{x})}{\sum_{k=1}^{K} \frac{\pi_{i} \mathcal{N}(\mathbf{x}_{i}|\mu_{j}, \Sigma_{j})}{\sum_{k=1}^{K} \frac{\pi_{k} \mathcal{N}(\mathbf{x}_{i}|\mu_{k}, \Sigma_{k})}{}}$$

3. M step: Re-calculate parameters using current responsibilities:

$$\mu_j^{new} = \frac{1}{N_j} \sum_{i=1}^n \gamma(z_{ij}) \mathbf{x}_i$$

$$\Sigma_j^{new} = \frac{1}{N_j} \sum_{i=1}^n \gamma(z_{ij}) (\mathbf{x}_i - \mu_j^{new}) (\mathbf{x}_i - \mu_j^{new})^T$$

$$\pi_j^{new} = \frac{N_j}{n}$$
 where $N_j = \sum_{i=1}^n \gamma(z_{ij})$

l. Repeat 2 and 3 until log-likelihood or parameters converge, 🚛 👢 🦠

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EM application - probabilistic clustering

- K = 2, Initial Gaussian centers are identical with K-means example
- Circles: one standard deviation countour plots of Gaussians
- L: Number of cycles



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References

Bishop, C. (2013). Pattern recognition and machine learning: All "just the facts 101" material. Springer (India) Private Limited. https://books.google.fr/books?id=HL4HrgEACAAJ

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