```
2
     MPLAB Harmony Application Header File
3
4
     Company:
5
      Microchip Technology Inc.
6
    File Name:
7
8
     app.h
9
10
    Summary:
11
      This header file provides prototypes and definitions for the application.
12
1.3
    Description:
14
       This header file provides function prototypes and data type definitions for
15
       the application. Some of these are required by the system (such as the
       "APP Initialize" and "APP_Tasks" prototypes) and some of them are only used
16
       internally by the application (such as the "APP STATES" definition). Both
17
    18
19
20
21
   //DOM-IGNORE-BEGIN
    /*****************************
22
23
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2.4
25
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41 SUBSTITUTE GOODS, TECHNOLOGY, SERVICES, OR ANY CLAIMS BY THIRD PARTIES
42 (INCLUDING BUT NOT LIMITED TO ANY DEFENSE THEREOF), OR OTHER SIMILAR COSTS.
43
44 //DOM-IGNORE-END
45
46
   #ifndef _APP_H
   #define APP H
47
48
   // ****************************
49
    // ***************************
50
51
   // Section: Included Files
    // *********************
52
    // ***************************
53
54
55
   #include "stepperDriver.h"
56
   #include "lights.h"
57
   #include <stdint.h>
58
   #include <stdbool.h>
59
   #include <stddef.h>
60
   #include <stdlib.h>
61
   #include <stdio.h>
   #include "system config.h"
62
63
   #include "system definitions.h"
64
65
   // DOM-IGNORE-BEGIN
   #ifdef cplusplus // Provide C++ Compatibility
67
68
   extern "C" {
69
```

```
#endif
 71
    // DOM-IGNORE-END
 72
     // *********************
 73
     // **********************
 74
     // Section: Type Definitions
 75
     // **************************
 76
     // *********************************
 77
 78
 79
     #define SYS CLK 40000000
 80
81
    #define PWM A CMD CH MCPWM CHANNEL1
     #define PWM B CMD CH MCPWM CHANNEL1
82
     #define PWM C CMD CH MCPWM CHANNEL2
83
     #define PWM D CMD CH MCPWM CHANNEL2
84
 85
     #define PWM BL CH MCPWM CHANNEL3
     #define PWM BUZZER CH MCPWM CHANNEL4
 86
 87
     #define PWM DIM CH MCPWM CHANNEL6
 88
89
    #define MARGIN LED DELAY 50
90
 91 /* Intensity in percent */
 92
    #define BACKLIGHT INTENSITY MIN 0
    #define BACKLIGHT INTENSITY MAX 100
93
 94
 95
 96
     /* Value used to check if the EEPROM is already writent by this code */
 97
    #define CONTROL VALUE 0x11223344
98
     // ***************************
99
100
    /* Application states
101
102
      Summary:
103
        Application states enumeration
104
105
      Description:
106
        This enumeration defines the valid application states. These states
107
        determine the behavior of the application at various times.
108
109
110
     typedef enum
111
112
        /* Application's state machine's initial state. */
113
        APP STATE INIT=0,
114
        APP STATE SERVICE TASKS,
115
        APP STATE SERVICE CAPTURE,
116
        APP STATE WAIT,
117
     } APP STATES;
118
119
    typedef enum{
120
121
        SYS STATE MENU = 0,
122
        SYS STATE MANUAL,
123
        SYS STATE AUTO
124
    } SYSTEM STATES;
125
126
127
     // *********************
128
129
     /* Application Data
130
131
      Summarv:
132
       Holds application data
133
134
      Description:
135
       This structure holds the application's data.
136
137
      Remarks:
138
        Application strings and buffers are be defined outside this structure.
```

70

```
139
      * /
140
141
      typedef enum{
142
143
          ALL LED DISABLE = 0,
144
          PWR LED1,
145
          PWR LED2,
146
          PWR LED3,
147
          PWR LED4,
148
          PWR LED5,
149
150
     }LED ID;
151
152
153
      typedef struct
154
155
          /* The application's current state */
156
          APP STATES appState;
157
          SYSTEM STATES systemState;
158
          LED ID ledId;
159
          uint32 t msCounter;
160
161
          /* LED config */
162
          uint16 t lightIntensity;
          uint16 t timeBetweenPictures;
163
          uint16 t exposureDuration;
164
165
166
          /* Auto mode param */
167
          uint8 t angleBwEachSeq;
168
169
          uint32 t seqClock1 ms;
170
          uint32 t seqClock2 ms;
171
          bool isFiveShotsSeqEnable;
172
         bool isFullImaginSeqEnable;
          bool isFirstPass;
173
174
          uint16 t nbrOfShotsPerformed;
175
          uint8 t valSeq;
176
177
          uint16 t backLightIntensitiy;
178
179
          uint16 t buzzerIntensity;
180
181
      } APP DATA;
182
183
      typedef struct
184
185
          bool state[4];
186
          bool isPressed;
187
188
      } SW;
189
190
     typedef struct{
191
192
          /* Motor data */
193
          int16 t
                    stepPerSec;
194
          uint1\overline{6} t
                     stepPerTurn;
195
          uint16 t
                     gearValue;
196
          float
                      anglePerStep;
197
          /* LEDs data */
198
199
          uint16_t lightIntensity;
200
          uint16_t timeBetweenPictures;
201
          uint16 t exposureDuration;
202
203
          uint16 t backLightIntensitiy;
204
205
          /* Security value */
206
          uint32 t controlValue;
207
```

```
208
       ) DATA IN EEPROM:
    209
    // *********************
210
    // Section: Application Callback Routines
211
    // ****************************
212
    // *********************
213
214
    /* These routines are called by drivers when certain events occur.
215
216
    // *********************
217
    // ****************************
218
219
    // Section: Application Initialization and State Machine Functions
    // ***************************
220
    // **********************************
221
222
    /***********************************
223
224
      Function:
225
      void APP Initialize ( void )
226
227
      Summary:
228
       MPLAB Harmony application initialization routine.
229
230
      Description:
231
       This function initializes the Harmony application. It places the
232
       application in its initial state and prepares it to run so that its
233
       APP Tasks function can be called.
234
235
     Precondition:
236
      All other system initialization routines should be called before calling
237
       this routine (in "SYS Initialize").
238
239
     Parameters:
240
      None.
241
242
     Returns:
243
      None.
244
245
     Example:
246
       <code>
247
       APP Initialize();
248
      </code>
249
250
251
       This routine must be called from the SYS Initialize function.
252
253
254
    void APP Initialize ( void );
255
256
    /******************************
257
258
     Function:
259
      void APP Tasks ( void )
260
261
262
      MPLAB Harmony Demo application tasks function
263
264
      Description:
265
       This routine is the Harmony Demo application's tasks function. It
266
       defines the application's state machine and core logic.
267
268
     Precondition:
269
      The system and application initialization ("SYS Initialize") should be
270
       called before calling this.
271
272
     Parameters:
273
      None.
274
275
     Returns:
276
      None.
```

```
277
278
      Example:
279
       <code>
       APP_Tasks();
280
281
282
     Remarks:
283
       This routine must be called from SYS Tasks() routine.
284
285
286
287
       void APP Tasks( void );
288
        void APP Delay ms(uint32 t ms);
289
290
        void setBlIntensity(int32 t *backLightIntensitiy);
291
        int32 t getBlIntensity(void);
292
293
294
        void scanSwitch(void);
295
        bool getSwitchEvent(void);
296
297
        void initLcd(void);
298
299
        void updateMcpwmDuty(void);
300
301
302
303
    #endif /* APP H */
304
    //DOM-IGNORE-BEGIN
305
306 #ifdef cplusplus
307
308 #endif
309
    //DOM-IGNORE-END
310
311
     /***********************************
312
     End of File
313
     */
314
```