

```

1  /*****
2  MPLAB Harmony Application Source File
3
4  Company:
5      Microchip Technology Inc.
6
7  File Name:
8      app.c
9
10 Summary:
11     This file contains the source code for the MPLAB Harmony application.
12
13 Description:
14     This file contains the source code for the MPLAB Harmony application. It
15     implements the logic of the application's state machine and it may call
16     API routines of other MPLAB Harmony modules in the system, such as drivers,
17     system services, and middleware. However, it does not call any of the
18     system interfaces (such as the "Initialize" and "Tasks" functions) of any of
19     the modules in the system or make any assumptions about when those functions
20     are called. That is the responsibility of the configuration-specific system
21     files.
22 *****/
23
24 // DOM-IGNORE-BEGIN
25 /*****
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44 SUBSTITUTE GOODS, TECHNOLOGY, SERVICES, OR ANY CLAIMS BY THIRD PARTIES
45 (INCLUDING BUT NOT LIMITED TO ANY DEFENSE THEREOF), OR OTHER SIMILAR COSTS.
46 *****/
47 // DOM-IGNORE-END
48
49
50 // ****
51 // ****
52 // Section: Included Files
53 // ****
54 // ****
55
56 #include "app.h"
57 #include "Mc32_spi_sm.h"
58 #include "lcd_spi.h"
59 #include "system/devcon/src/sys_devcon_local.h"
60 #include "pec12.h"
61 #include "menu.h"
62
63
64
65 // ****
66 // ****
67 // Section: Global Data Definitions
68 // ****
69 // ****

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70
71 // *****
72 /* Application Data
73
74     Summary:
75         Holds application data
76
77     Description:
78         This structure holds the application's data.
79
80     Remarks:
81         This structure should be initialized by the APP_Initialize function.
82
83         Application strings and buffers are be defined outside this structure.
84 */
85
86 APP_DATA appData;
87 SW S1;
88
89 // *****
90 // *****
91 // Section: Application Callback Functions
92 // *****
93 // *****
94
95 /* TODO:  Add any necessary callback functions.
96 */
97
98 // *****
99 // *****
100 // Section: Application Local Functions
101 // *****
102 // *****
103
104
105 /* TODO:  Add any necessary local functions.
106 */
107
108
109 // *****
110 // *****
111 // Section: Application Initialization and State Machine Functions
112 // *****
113 // *****
114
115
116 //-----//
APP_UpdateAppState
117 void APP_UpdateAppState(APP_STATES newState){
118
119     appData.appState = newState;
120 }
121
122 //-----//
APP_Initialize
123 void APP_Initialize ( void )
124 {
125     SPI_Init();
126     /* Place the App state machine in its initial state. */
127     appData.appState = APP_STATE_INIT;
128     appData.msCounter = 0;
129     appData.backLightIntensitiy = 2500; /* 100% */
130     appData.lightIntensity = 2500; /* 100% */
131     appData.exposureDuration = 100;
132     appData.timeBetweenPictures = 1000;
133     appData.isFiveShotsSeqEnable = false;
134     appData.seqClock1_ms = 0;
135     appData.angleBwEachSeq = 10;
136     appData.nbrOfShotsPerformed = 0;

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137     appData.buzzerIntensity = 2500;
138     appData.valSeq = 0;
139
140     initMenuParam();
141     initStepperParam();
142 }
143
144
145
146 //-----//
APP_Tasks
147 void APP_Tasks ( void ){
148
149     static uint16_t counter1 = 0;
150     static uint16_t counter2 = 0;
151
152     /* Main state machine */
153     switch(appData.appState){
154         //-----//
        APP_STATE_INIT
155         case APP_STATE_INIT:
156             /* Read data from EEPROM to restore presets */
157             readDataFromEeprom(getMyStepperStruct());
158             /* Initialization of the motor */
159             initStepperMotor();
160             /* Update MCPWM Duty-cycle of other PWM with EEPROM data */
161             updateMcpwmDuty();
162             /* Turn on MCPWM */
163             PLIB_MCPWM_Enable(MCPWM_ID_0);
164             /* Initialization sequence */
165             initLcd();
166             /* Print initialization menu */
167             printLcdInit();
168             /* Start useful Timers */
169             DRV_TMR1_Start();
170             DRV_TMR2_Start();
171             /* Print main menu once all peripherals are configured */
172             printMainMenu();
173             /* States machines update */
174             APP_UpdateAppState(APP_STATE_WAIT);
175             break;
176
177         //-----//
        APP_STATE_SERVICE_TASKS
178         /* Frequency = 10'000Hz */
179         case APP_STATE_SERVICE_TASKS:
180
181             /* Process who is responsible of the sequence, motor orders and
182              * lights orders. */
183
184             //          SIGN_LED_CMDToggle();
185             sequenceManagementProcess();
186
187             if(counter2 >= 10){
188                 /* Frequency = 1'000Hz */
189                 counter2 = 0;
190                 /* Scan the activity of the rotary encoder */
191                 scanPec12();
192                 /* Scan the activity of the switch S1 */
193                 scanSwitch();
194             }
195             if(counter1 >= 1000){
196                 /* Frequency = 10Hz */
197                 counter1 = 0;
198                 menuManagementProcess();
199             }
200             counter1++;
201             counter2++;
202

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203
204         // Calls the SPI do task state machine
205         SPI_DoTasks();
206
207         /* States machines update */
208         APP_UpdateAppState(APP_STATE_WAIT);
209         break;
210     //-----//
211     APP_STATE_WAIT
212     case APP_STATE_WAIT:
213         /* Nothing is supposed to happen here */
214         break;
215     //-----// default
216     default:
217         break;
218     }
219 }
220
221
222 //-----//
223 APP_Delay_ms
224 void APP_Delay_ms(uint32_t ms){
225     DRV_TMR3_Start();
226     //     SIGN_LED_CMDToggle();
227     while(appData.msCounter < ms){
228
229     }
230     //     SIGN_LED_CMDToggle();
231
232     DRV_TMR3_Stop();
233     appData.msCounter = 0;
234 }
235
236 //-----//
237 setBlIntensity
238 void setBlIntensity(int32_t *backLightIntensity){
239
240     // Limit values to avoid problems
241     if(*backLightIntensity < BACKLIGHT_INTENSITY_MIN) *backLightIntensity
242         = BACKLIGHT_INTENSITY_MIN;
243     if(*backLightIntensity > BACKLIGHT_INTENSITY_MAX) *backLightIntensity
244         = BACKLIGHT_INTENSITY_MAX;
245
246     /* 25 = 2500 / 100 */
247     appData.backLightIntensity = *backLightIntensity * 25;
248     PLIB_MCPWM_ChannelPrimaryDutyCycleSet(MCPWM_ID_0, PWM_BL_CH,
249         appData.backLightIntensity);
250 }
251 int32_t getBlIntensity(void){
252
253     return appData.backLightIntensity / 25;
254 }
255
256 //-----//
257 scanSwitch
258 void scanSwitch(void){
259
260     // Save old states for debounce
261     S1.state[3] = S1.state[2];
262     S1.state[2] = S1.state[1];
263     S1.state[1] = S1.state[0];
264     S1.state[0] = SWITCHStateGet();
265
266     // Check if switch is pressed
267     if(S1.state[0] == 1 && S1.state[1] == 1
268         && S1.state[2] == 0 && S1.state[3] == 0){

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268         S1.isPressed = true;
269     }
270 }
271 //-----//
272 getSwitchEvent
273 bool getSwitchEvent(void){
274     bool isPressed = S1.isPressed;
275     S1.isPressed = 0;
276
277     return isPressed;
278 }
279
280 //-----//
281 initLcdSeq
282 void initLcd(void){
283     RESET_LCD_CMDOff();
284     APP_Delay_ms(1);
285     RESET_LCD_CMDOn();
286     APP_Delay_ms(10);
287     initDispl();
288     /* Create degree symbol for LCD uses */
289     CreateLcdDegreeSymbol(0x01);
290 }
291
292 void updateMcpwmDuty(void){
293     /* Update PWMs DutyCycle with data from EEPROM */
294     PLIB_MCPWM_ChannelPrimaryDutyCycleSet(MCPWM_ID_0, PWM_BL_CH,
295         appData.backLightIntensitiy);
296     PLIB_MCPWM_ChannelPrimaryDutyCycleSet(MCPWM_ID_0, PWM_BUZZER_CH,
297         appData.buzzerIntensity);
298     PLIB_MCPWM_ChannelPrimaryDutyCycleSet(MCPWM_ID_0, PWM_DIM_CH,
299         appData.lightIntensity);
300 }
301
302
303
304
305
306
307
308 /*****
309 End of File
310 */
311

```