

#### University of British Columbia Electrical and Computer Engineering ELEC291/ELEC292

# Project 1 – EFM8 board, FSM, EEPROM, and tips

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## **Objectives**

- Introduction to the EFM8 board.
- Programming using Finite State Machines (FSMs) in assembly language.
- Using non-volatile memory (flash) for variable storage and initialization.
- Extra project tips.

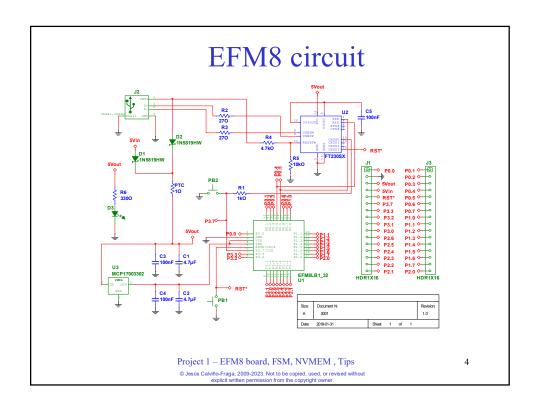
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#### The EFM8 Board

- Each student should have a EFM8 board for the second half of the course.
- Each student should assemble (or try to) a EFM8 board. Stencil + Solder Paste + SMDs + TH + Testing.
- The EFM8 board needs to be soldered in an reflow oven. You need a reflow oven controller!

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# EFM8 Bill of Materials (BOM)

Qty	Supplier's#	Reference	Man's #	Description
1	768-1135-1-ND	U2	FT230XS-R	IC USB SERIAL BASIC UART 16SSOP
1	MCP1700T3302ETTCT-ND	U3	MCP1700T-3302E/TT	IC REG LDO 3.3V 0.25A SOT23-3
1	336-3736-ND	U1	EFM8LB12F64E-B-QFP32	IC MCU 8BIT 64KB FLASH 32QFP
2	450-1759-1-ND	PB1, PB2	FSM4JSMATR	SWITCH TACTILE SPST-NO 0.05A 24V
2	A26509-16-ND	J1, J3	4-103741-0-16	CONN HEADR BRKWAY .100 16POS STR
1	ED2983-ND	J2	USB-B1HSB6	CONN USB TYPE B R/A BLACK
2	1N5819HW-FDICT-ND	D1, D2	1N5819HW-7-F	DIODE SCHOTTKY 40V 1A SOD123
3	399-1170-1-ND	C3, C4, C5	C0805C104K5RACTU	CAP CER 0.1UF 50V X7R 0805
2	311-22ARCT-ND	R2, R3	RC0805JR-0722RL	RES SMD 22 OHM 5% 1/8W 0805
1	160-1179-1-ND	D3	LTST-C170GKT	LED GREEN CLEAR 0805 SMD
1	311-330ARCT-ND	R6	RC0805JR-07330RL	RES SMD 330 OHM 5% 1/8W 0805
1	311-1.0KARCT-ND	R1	RC0805JR-071KL	RES SMD 1K OHM 5% 1/8W 0805
1	311-4.7KARCT-ND	R4	RC0805JR-074K7L	RES SMD 4.7K OHM 5% 1/8W 0805
2	478-8125-1-ND	C1, C2	F921A475MPA	CAP TANT 4.7UF 10V 20% 0805
1	507-1797-1-ND	PTC	0ZCJ0020FF2E	PTC RESTTBLE 0.20A 30V CHIP 1206
1	311-10KARCT-ND	R5	RC0805JR-0710KL	RES SMD 10K OHM 5% 1/8W 0805

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# Steps Assembling a PCB with SMDs.

- Step 1: Apply solder paste to the PCB. You will use a Mylar stencil. (The most critical step in the whole process!)
- Step 2: Place the SMT components into the PCB.
- Step 3: Reflow soldering. You will be using a toaster oven with a controller of your own design.
- Step 4: Hand soldering of TH (thru hole) components.

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## Testing the EFM8 Board

- Write a "blinky.asm" for the EFM8. Some things to take into account compared to the AT89LP51RC2 and AT89LP51RC2:
  - The default oscillator frequency is 6.000MHz.
     It can be configured for 12MHz, 24MHz,
     48MHZ, and 72MHz... or many different values in between!
  - The number cycles per instruction is different.
  - The registers used to configure the ports are different. Check the datasheet!

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### blinky\_EFM8.asm

### \$MODEFM8LB1

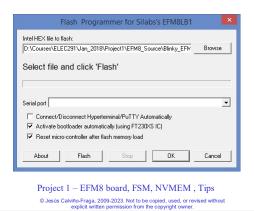
```
ljmp main
Wait_half_second:
    ;For a 6MHz clock one machine cycle takes 1/6.0000MHz=166.666ns
    mov R2, #25
L3: mov R1, #250
L2: mov R0, #120
L1: djnz R0, L1; 4 machine cycles-> 4*166.666ns*120=80us
djnz R1, L2; 80us*250=0.02s
    djnz R2, L3; 0.02s*25=0.5s
main:
    ; DISABLE WDT: provide Watchdog disable keys
    mov WDTCN, #0xDE; First key
    mov WDTCN, #0xAD ; Second key
    mov SP, #7FH
    ; Enable crossbar and weak pull-ups
    mov XBR0, #0x00
    mov XBR1, #0x00
    mov XBR2, #0x40
    mov P2MDOUT, #0x02 ; make LED pin (P2.1) output push-pull
M0: cpl P2.1 ; Led off/on
    lcall Wait_half_second
    sjmp M0
```

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## Flashing HEX file into EFM8 Board

• In CrossIDE click fLash->Silabs EFM8LB1. Select the correct HEX file, make sure settings are like shown below, and then click 'Flash'.



Testing the board with



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# Finite State Machines in Assembly Language

- A finite state machine (FSM) is a programming abstraction method that can be represented using a graph structure.
- We can draw the states as circles and the transitions as arrows.
- There is a finite number of states. The active state is called the current state.
- FSMs are easily implemented in assembly language!
- Many FMS can be run "concurrently". (One after another really!)
- FSM are in principle non-blocking.

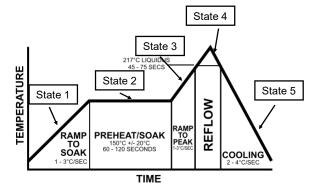
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#### Reflow Profile States

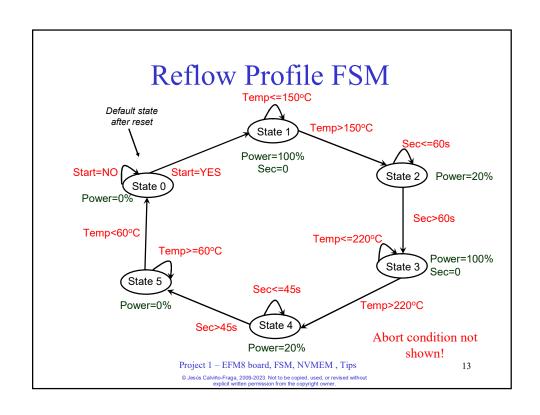
http://en.wikipedia.org/wiki/Reflow\_soldering



State 0

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#### FSM In assembly (some states only!) FSM1: mov a, FSM1\_state FSM1\_state2: cjne a, #2, FSM1\_state3 FSM1\_state0: mov pwm, #20 cjne a, #0, FSM1\_state1 mov a, #60 mov pwm, #0 jb PB6, FSM1\_state0\_done subb a, sec jnb PB6, \$ ; Wait for key release jnc FSM1\_state2\_done mov FSM1\_state, #1 mov FSM1\_state, #3 FSM1\_state0\_done: FSM1\_state2\_done: ljmp FSM1\_FSM2 ljmp FSM2 cjne a, #1, FSM1\_state2 mov pwm, #100 mov sec, #0 mov a, #150 clr c subb a, temp jnc FSM1\_state1\_done mov FSM1\_state, #2 FSM1\_state1\_done: ljmp FSM2 Project 1-EFM8 board, FSM, NVMEM , Tips 14 © Jesús Calviño-Fraga, 2009-2023. Not to be copied, used, or revised without explicit written permission from the copyright owner.

# In assembly (some states only!) using variables...

```
FSM1:
     mov a, FSM1_state
                                                          FSM1_state2:
                                                              cjne a, #2, FSM1_state3
FSM1 state0:
                                                              mov pwm, #20
    cjne a, #0, FSM1 state1
                                                              mov a, time_soak
    {\color{red} {\rm mov}} pwm, {\color{red} {\rm \#0}}
     jb PB6, FSM1_state0_done
                                                              subb a, sec
                                                              jnc FSM1_state2_done
     jnb PB6, $ ; Wait for key release
     mov FSM1 state, #1
                                                              mov FSM1 state, #3
FSM1 state0 done:
                                                         FSM1_state2_done:
    1jmp FSM2
                                                             ljmp FSM2
FSM1_state1:
    cjne a, #1, FSM2_state2
    mov pwm, #100
    mov sec, #0
    mov a, temp_soak
                                                  DSEG; Before the state machine! state: ds 1
     clr c
     subb a, temp
                                                         temp_soak: ds 1
     jnc FSM1_state1_done
                                                        Time_soak: ds 1
    mov FSM1 state, #2
                                                        Temp_refl: ds 1
FSM1 state1 done:
                                                         Time_refl: ds 1
    ljmp FSM2
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```

### **About Variables**

- Initialize variables before using them!
- It is easy to work with binary (8-bit) variables. Use "inc", "dec", to increment/decrement and 'subb' to compare.
- Small variables are easy to save and retrieve from nonvolatile memory such as FLASH or EEPROM.
- If temperature measurements are too "noisy", make several measurements and take the average!
- To convert 8-bit binary variable to decimal use either HEX2BCD (in the math32 library) or one of these smaller/faster 8051 subroutines:

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### Binary to decimal conversion of 8bit numbers in the 8051

```
; Send eight bit number via serial port, passed in 'a'.
SendToSerialPort:
        mov b, #100
        div ab
        orl a, #0x30 ; Convert hundreds to ASCII
        lcall putchar ; Send to PuTTY/Python/Matlab
                       ; Remainder is in register b
        mov a, b
        mov b, #10
        div ab
        orl a, #0x30 ; Convert tens to ASCII
        lcall putchar ; Send to PuTTY/Python/Matlab
        mov a, b
        orl a, #0x30; Convert units to ASCII
        lcall putchar ; Send to PuTTY/Python/Matlab
        ret
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```

### Binary to decimal conversion of 8bit numbers in the 8051

```
; Eight bit number to display passed in 'a'.
; Sends result to LCD
SendToLCD:
        mov b, #100
        div ab
        orl a, \#0x30; Convert hundreds to ASCII
        lcall ?WriteData ; Send to LCD
        mov a, b
                        ; Remainder is in register b
        mov b, #10
        orl a, #0x30; Convert tens to ASCII
        lcall ?WriteData; Send to LCD
        mov a, b
        orl a, #0x30; Convert units to ASCII
        lcall ?WriteData; Send to LCD
        ret
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```

#### **DIV AB**

#### **DIV AB**

Function: Divide

Description:

DIV AB divides the unsigned eight-bit integer in the accumulator by the unsigned eight-bit integer in register B. The accumulator receives the integer part of the quotient; register B receives the integer remainder. The carry and OV flags will be cleared. *Exception*: If B had originally contained 00H, the values returned in the accumulator and B register will be undefined and the overflow flag

will be set. The carry flag is cleared in any case.

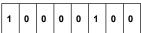
The accumulator contains 251 (0FBH or 11111011B) and B contains 18 (12H or 00010010B). The Example:

instruction DIV AB will leave 13 in the accumulator (0DH or 00001101 B) and the value 17 (11H or 00010001B) in B, since 251 = (13x18) + 17. Carry and OV will both be cleared.

Operation: DIV AB

(A), (B) ¬ (A) / (B)

Encoding:



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### Non-Volatile Memory: AT89LP51RC2 Flash as EEPROM

#### **Emulating EEPROM Using** AT89LP On-Chip Flash Data Memory

#### 1. Introduction

Many embedded systems rely on nonvolatile parameters that are preserved across reset or power-loss events. In some systems this static information is used to initialize the system to a correct state at start-up. In other systems it is used to log system history or accumulated data. Traditionally these tasks have been implemented using EEPROM; first with off-chip EEPROM and later in on-chip EEPROM as levels of system integration have increased.

This application note describes how to emulate the behavior of an on-chip EEPROM using the on-chip Flash data memory of Atmel's AT89LP series of microcontrollers. Flash data memory is an alternative to EEPROM that is well suited for large paramereast use a relative to a relative to the result of the re



AT89LP **EEPROM Emulation** 

**Application Note** 

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## Why non-volatile memory?

- To save your reflow oven controller parameters so they are available automatically the next time you use it.
- To store other useful information.

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# Example: Writing Project Data to the AT89LP51RC2 Flash

```
loadbyte mac
   mov a, %0
    movx @dptr, a
    inc dptr
endmac
Save Configuration:
   mov FCON, #0x08; Page Buffer Mapping Enabled (FPS = 1)
    mov dptr, #0x7f80 ; Last page of flash memory
    ; Save variables
    loadbyte(temp_soak) ; @0x7f80
    loadbyte(time_soak) ; @0x7f81
    loadbyte(temp_refl) ; @0x7f82
    loadbyte(time refl) ; @0x7f83
    loadbyte(#0x55) ; First key value @0x7f84
    loadbyte(#0xAA) ; Second key value @0x7f85
    mov FCON, \#0\times00; Page Buffer Mapping Disabled (FPS = 0)
    orl EECON, #0b01000000 ; Enable auto-erase on next write sequence
    mov FCON, \#0x50; Write trigger first byte
    mov FCON, #0xA0 ; Write trigger second byte
    ; CPU idles until writing of flash completes.
    mov FCON, \#0\times00; Page Buffer Mapping Disabled (FPS = 0)
    anl EECON, #0b10111111 ; Disable auto-erase
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```

# Example: Read From Flash; Get Saved Values

```
getbyte mac
    clr a
    movc a, @a+dptr
    mov %0, a
    inc dptr
Endmac
Load_Configuration:
    mov dptr, #0x7f84 ; First key value location.
    getbyte(R0) ; 0x7f84 should contain 0x55
    cjne R0, #0x55, Load Defaults
    getbyte(R0); 0x7f85 should contain 0xAA
    cjne R0, #0xAA, Load_Defaults
                                                          ; Load defaults if 'keys'
    ; Keys are good. Get stored values.
                                                          ; are incorrect
    mov dptr, #0x7f80
                                                          Load Defaults:
    getbyte(temp_soak) ; 0x7f80
                                                             mov temp_soak, #150
    getbyte(time_soak) ; 0x7f81
                                                              mov time_soak, #45
    getbyte(temp refl) ; 0x7f82
                                                              mov temp_ref1, #225
    getbyte(time_refl) ; 0x7f83
                                                              mov time_refl, #30
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```

## Extra Tips...

• Are you using macros yet?

```
Change_8bit_Variable MAC
   jb %0, %2
   Wait_Milli_Seconds(#50); de-bounce
   jb %0, %2
   jnb %0, $
   jb SHIFT_BUTTON, skip%Mb
   dec %1
   sjmp skip%Ma
skip%Mb:
   inc %1
skip%Ma:
ENDMAC
```

```
Change_8bit_Variable(MY_VARIABLE_BUTTON, my_variable, loop_c)
Set_Cursor(2, 14)
mov a, my_variable
lcall SendToLCD
lcall Save_Configuration
loop_c:
```

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# Extra tips...

• 'Noisy' measurements? Average!

```
Wait10us:
    mov R0, #74
    djnz R0, $
    ret

Average_CH0:
    Load x(0)
    mov R5, #100

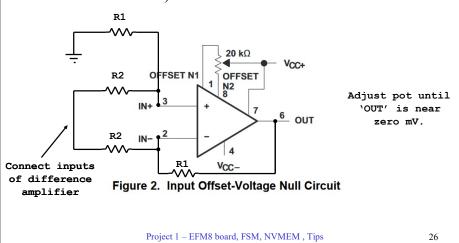
Sum_loop0:
    lcall Read ADC Channel
    mov y+3, #0
    mov y+2, #0
    mov y+1, R7
    mov y+0, R6
    lcall add32
    lcall Wait10us
    djnz R5, Sum_loop0
    load y(100)
    lcall div32
    ret

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```

# Extra tips...

 Op-amp has to much offset? Zero it! (Should not be needed for OP07)



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## Extra tip

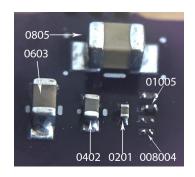
• There is 'magic' value of gain that will give you the temperature of the thermocouple (minus cold junction) directly when reading from the ADC!

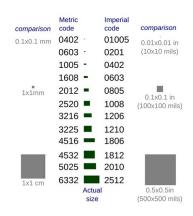
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# The smallest component we are using is '0805' size





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