

From econometrics to machine learning: Insights from transportation studies

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Academic and Professional Background

- ▶ 2012-2014: Biology, Mathematics
- ▶ 2014-2018: Engineering School Transport Economics
- ▶ 2018-2021: Consultant for transportation projects
- ▶ 2021-2025: PhD Student in Economics

My main research interest lies in short-term forecasting of economic demand under disturbing events. Applied to transportation, this aims to optimize transport infrastructures and understand "erratic" mobility behaviours.



A Economic theory

- A1 The concept of Utility
- A2 Consumer theory
- A3 Discrete choice theory: example from a binary setting

B Transportation problems

- B1 Application of discrete choice modeling to transportation problems
- **B2** Limitations

C Machine Learning (ML)

- C1 Supervised learning for binary classification problems
- C2 Shapley additive explaination (SHAP)

D A Funkier Example: Anomaly detection

- D1 Binary classification setting
- D2 Results



A. Economic theory

Heavily relies on Ben Akiva (1985) and Bonnel (2002)



A1. The concept of Utility

- ▶ **Utility** measures satisfaction. It can be described as a function *U* with the following (non-exhaustive) hypotheses:
 - Decision makers are economically rational.

Ex. Transitivity - For 3 different quantities of goods q_1, q_2 and q_3 if $U(q_1) > U(q_2)$ and $U(q_2) > U(q_3)$, then $U(q_1) > U(q_3)$

• Utility increases and marginal utility decreases (diminishing returns)

$$\frac{dU}{dq} \ge 0 \quad \text{and} \quad \frac{d^2U}{dq^2} \le 0 \tag{1}$$



A2. Consumer theory

- ▶ The consumer theory focuses on the quantities of goods $q_1, ..., q_n$ with prices $p_1, ..., p_n$.
- ▶ Under a constraint of income *I*, the consumer wants to maximize its utility such that

$$\max_{q_i}[U(q_1,...,q_n)] \tag{2}$$

$$\sum_{i=1}^{n} p_i q_i = I \tag{3}$$

▶ This is an optimization problem, for which we can find optimal quantities $q_1^*,...,q_n^*$. We are interested in finding explanations, i.e. why would we reach a certain optimum.



A2. Consumer theory

- ▶ Resolution in a simple case with 2 goods q_1 and q_2 :
 - We assume the utility function has a multiplicative form (Cobb-Douglas)

$$U(q_1, q_2) = \beta_0 q_1^{\beta_1} q_2^{\beta_2} \tag{4}$$

• Under the constraint of income (2), we can maximize the utility function using the Lagrangian multiplier. We obtain:

$$q_1^* = \frac{\beta_1}{\beta_1 + \beta_2} \cdot \frac{I}{p_1} \qquad q_2^* = \frac{\beta_2}{\beta_1 + \beta_2} \cdot \frac{I}{p_2}$$
 (5)

• With enough data (surveys) on prices, quantities and income levels, we can retrieve coefficients β_1 and β_2 .



A3. Discrete choice theory

- ► Two goals:
 - When we isolate economic problems by field (Strotz, 1959), we no longer chose quantities of several different goods, but we pick up one good among similar competing goods (discrete choice).
 - We want to get rid of inconsistencies due to transitivity issues, that might occur
 often with discrete choices.
- ► Therefore, we introduce new utility function with a deterministic component and a random component. For decision maker *n* and choice *i*:

$$U_{in} = V_i n + \epsilon_i n \tag{6}$$



A3. Discrete choice theory

• Let's consider a binary choice set $C = \{i, j\}$. The deterministic component is defined as a linear combination of K variables x_k ($x \in \mathbb{R}, k \in [1, K], K \in \mathbb{N}$). Utility functions are computed as:

$$U_{in} = \beta_0 + \sum_{k=1}^{K} \beta_k x_{k_{in}} + \epsilon_{in} \quad \text{and} \quad U_{jn} = \beta_0 + \sum_{k=1}^{K} \beta_k x_{k_{jn}} + \epsilon_{jn}$$
 (7)

• For decision maker *n*, the probability to make choice *i* is:

$$P_{n}(i) = P(U_{in} \ge U_{jn})$$

$$= P(\underbrace{\epsilon_{jn} - \epsilon_{in}}_{\epsilon_{n}} \le V_{in} - V_{jn})$$
(8)

• We assume ϵ_n follows a logistic distribution

$$P_n(i) = \frac{1}{1 + e^{-\sum_{k=1}^{K} \beta_k (x_{k_{in}} - x_{k_{jn}})}}$$
(9)



A3. Discrete choice theory

 \blacktriangleright We find $\beta_1, ..., \beta_K$ through Maximum Likelihood Estimation. Let's define the variable

$$y_{in} = \begin{cases} 1, & \text{if decision maker } n \text{ chose } i \\ 0, & \text{if decision maker } n \text{ chose } j \end{cases}$$
 (10)

▶ We compute the likelihood function

$$\mathcal{L}(\beta_1, ..., \beta_K) = \prod_{n=1}^N P_n(i)^{y_{in}} [1 - P_n(i)]^{1 - y_{in}}$$
(11)

▶ We linearize and seek estimates $\hat{\beta}_1, ..., \hat{\beta}_K$ by maximizing the likelihood function. This can be hard to solve, so we approximate it numerically using the Newton-Raphson algorithm.



B. Transportation problems



B1. Application of discrete choice modeling to transportation problems

- ► Mode choice few possibilities; uses socio-economic attributes and eventually landuse attributes; purpose of trip; costs...
- ▶ Route choice lots of possibilities (routes of a network); independence issues; uses access/egress time, in-vehicle time; costs; purpose of trip; congestion...

- ▶ Time focus: This econometric modeling framework is not really suitable for short term analysis (e.g. real time optimization). Research at this level relies on traffic theory.
- ▶ Data: Stated preferences (survey) vs. Revealed preferences (passive data), especially to gather data on abnornal events.
- ► **Flexibility**: Econometric tools require to specify the modeling framework beforehand, which might not be ideal in the event of disruptions.



C. Machine Learning



C1. Supervised learning for binary classification problems

- ▶ Let's consider the binary choice set $C = \{i, j\}$.
 - We have:

$$y_{in} = \begin{cases} 1, & \text{if decision maker } n \text{ chose } i \\ 0, & \text{if decision maker } n \text{ chose } j \end{cases}$$
 (12)

- Given a set of explanatory variables X = {X_k}_{k∈[1,K]}, ML models can be used to find a mapping h that will estimate new data points based on the observed distribution of the couple (y, X). These estimated values are called ŷ = h(X).
- The mapping h is found thanks to a loss function $\mathcal{L}(\hat{y}, y)$, that we want to minimize.
- ▶ The main advantage is that we don't have to specify any utility function
- ▶ But sadly, we don't have β s! :(



C2. Shapley additive explaination (SHAP)

The SHAP theory is based on game theory, where "a prediction can be viewed as a coalitional game by considering each [variable] value of an instance as a player in a game" (Molnar, 2023)

- ▶ Intuition Max and Alice are treasure hunters. Together, they find 100 gold coins with the following distribution :
 - · Alice finds 60 gold coins alone
 - Max finds 30 gold coins alone
 - Together, they find 10 gold coins
- ▶ We compute the following value functions:
 - $v(\{\}) = 0$
 - $v(\{Alice\}) = 60$
 - $v(\{Max\}) = 30$
 - $v(\{Alice, Max\}) = 100$



C2. Shapley additive explaination (SHAP)

- ▶ We compute marginal contributions of each player:
 - Alice's Marginal Contribution

Alice with Max:
$$v({Alice, Max}) - v({Max}) = 100 - 30 = 70$$

Alice alone: $v({Alice}) = 60$

Max's Marginal Contribution

Max with Alice:
$$v(\{Alice, Max\}) - v(\{Alice\}) = 100 - 60 = 40$$

Max alone: $v(\{Max\}) = 30$

 \blacktriangleright We compute the average marginal contribution ϕ of each player to all possible coalitions:

$$\phi(\text{Alice}) = \frac{70 + 60}{2} = 65$$
 $\phi(\text{Max}) = \frac{40 + 30}{2} = 35$ (13)



C2. Shapley additive explaination (SHAP)

- ► SHAP can be used as a post-hoc and model-agnostic technique to retrieve the marginal effects of variables *X* on output *y*.
- ► Tree-SHAP computes exact values when used in combination with tree-based models (Random Forest, Gradient Boosting)
- ► SHAP deals with interactions between variables
- ► SHAP has a nice additive property
- ▶ for more info on SHAP: Lundberg and Lee (2017) and Molnar (2023)



D. A Funkier Example

Based on Cottreau et al. (2025)



D1. Binary classification setting

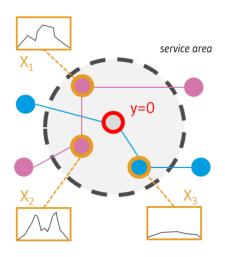
Let's consider a subway station which status is defined by the binary variable *y* at each time interval *t*, such that:

$$y_t = \begin{cases} 1, & \text{if the subway station experiences a disruption at time } t \\ 0, & \text{if not} \end{cases}$$
 (14)

- Let's define the variable $x_{k,t}$ that captures the demand levels at stop k at each time t. Stop k is selected based on its proximity to the subway station (< 600m)
- ▶ We seek a mapping h that will estimate the occurrence of disruptions based on demand levels $x_{k,t}$. These estimated values are called $\hat{y} = h(x_{k,t})$. [Random Forest]
- \blacktriangleright We also want to know the contribution of each stop k in the estimation process. **[SHAP]**

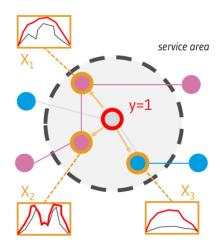


D1. Binary classification setting



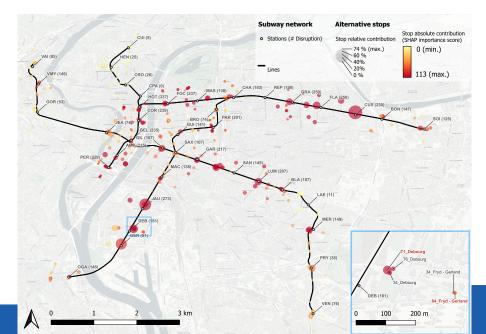


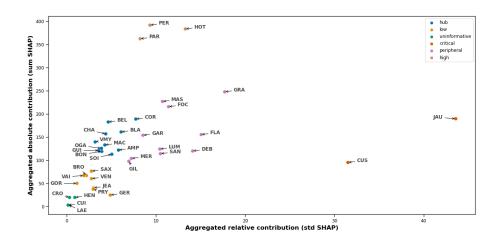
D1. Binary classification setting





D2. Results





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Thanks!

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