

### MATH5004 Tutorial 7

#### Linear Interpolation Shape Functions

In the finite element method for one-dimensional problems, the region of interest is divided into elements connecting nodes. The elements and nodes are identified by a numbering system. The elements are numbered  $1, 2, \dots, N_e$ . The nodes of an element are identified by 1 and 2 in the **local node numbering system**. A connectivity table relates the local node numbers to the **global numbers**.

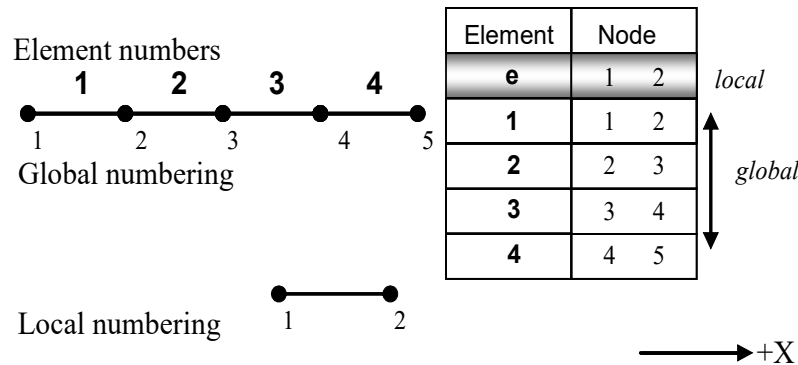


Fig. 1. Element and node numbering for a 4-element model.

Assume that the solution to a problem is the unknown function  $u(x)$ . The aim of the finite element method is to find an approximate solution  $u_h(x)$  by calculating its values at the nodes from an interpolation function  $u_h^e$  defined between two nodes.

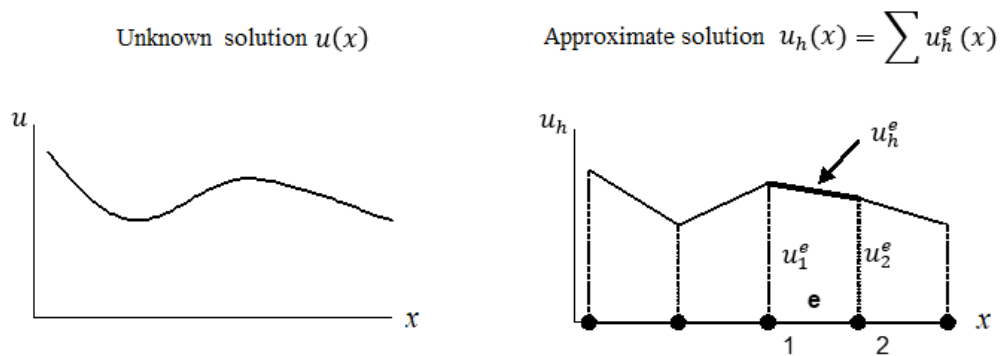


Fig. 2. Linear interpolation  $u_h^e$  used within each element to give the approximate solution  $u_h(x)$ .  $u_1^e$  and  $u_2^e$  are the nodal values of the approximation function in local coordinates.

To specify the location along the X-axis of a point, both global and local coordinate systems are used, as shown in Fig. 3.

- The global coordinates of the nodes are  $x_i$  ( $i = 1, 2, \dots, N_e+1$ ).
- The local coordinate system is often referred to as a **natural** or **intrinsic** coordinate system, denoted by  $\xi$  where

$$\xi = \frac{2(x - x_i)}{x_{i+1} - x_i} - 1 = \frac{2(x - x_i)}{h_i} - 1, \quad (1)$$

for the  $i^{\text{th}}$  element of length  $h_i = x_{i+1} - x_i$ .

At node 1 of an element,  $\xi = -1$  and at node 2,  $\xi = +1$ .

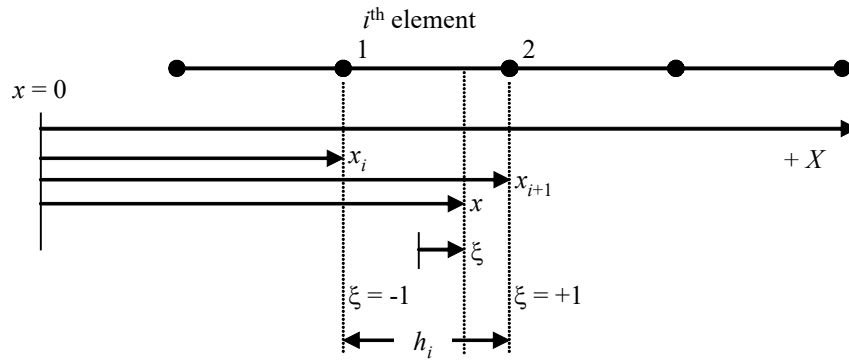


Fig. 3. Coordinate systems for a typical element.

From equation (1), we have the relationship

$$\frac{d\xi}{dx} = \frac{2}{h_i} \quad \text{and} \quad dx = \frac{h_i}{2} d\xi \quad (2)$$

The natural coordinate system is used to define the **linear interpolation shape functions**,  $N_1$  and  $N_2$  used for the interpolation within the  $e^{\text{th}}$  element

$$u_h^e(\xi) = N_1(\xi) u_1^e + N_2(\xi) u_2^e \quad (3)$$

where  $v_{e1}$  and  $v_{e2}$  are the local nodal values of the function  $v(x)$  and

$$N_1(\xi) = \frac{1-\xi}{2}, \quad N_2(\xi) = \frac{1+\xi}{2} \quad (4)$$

The interpolation functions are straight lines, with

$$N_1(-1) = 1, \quad N_1(+1) = 0, \quad N_2(-1) = 0, \quad N_2(+1) = 1$$

as shown in Fig. 4.

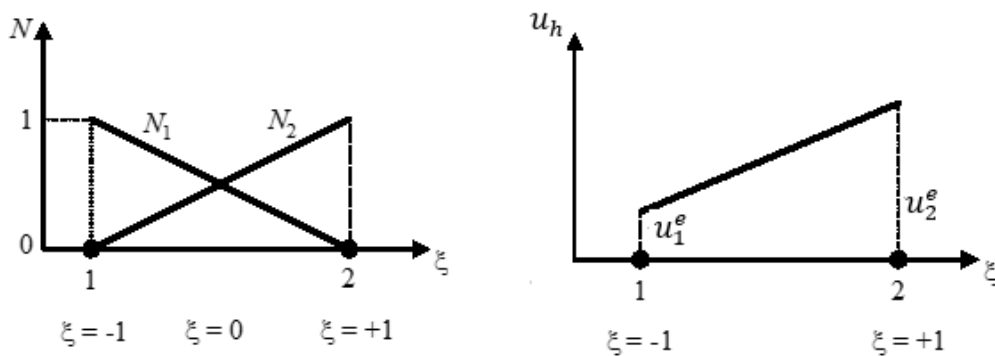


Fig. 4. Linear interpolation shape functions and linear interpolation using  $N_1$  and  $N_2$ .

The derivatives of the element interpolation function  $v_i$  and the shape functions  $N_1$  and  $N_2$  with respect to  $\xi$  and  $x$  are

$$\frac{dN_1}{d\xi} = -\frac{1}{2}, \quad \frac{dN_2}{d\xi} = \frac{1}{2} \quad (5a)$$

$$\frac{dN_1}{dx} = \frac{dN_1}{d\xi} \frac{d\xi}{dx} = \left(-\frac{1}{2}\right) \left(\frac{2}{h_i}\right) = -\frac{1}{h_i}, \quad \frac{dN_2}{dx} = \frac{1}{h_i} \quad (5b)$$

$$\frac{du_h^e}{d\xi} = -\frac{1}{2}u_1^e + \frac{1}{2}u_2^e \quad (6a)$$

$$\frac{du_h^e}{dx} = \frac{du_h^e}{d\xi} \frac{d\xi}{dx} = -\frac{1}{h_i}u_1^e + \frac{1}{h_i}u_2^e = \frac{1}{h_i}(-u_1^e + u_2^e) \quad (6b)$$

The interpolation function and its first derivative can be written in matrix form as

$$u_h^e = [N_1 \quad N_2] \begin{bmatrix} u_1^e \\ u_2^e \end{bmatrix} \quad (7)$$

$$\frac{du_h^e}{d\xi} = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} u_1^e \\ u_2^e \end{bmatrix}, \quad \frac{du_h^e}{dx} = \begin{bmatrix} -\frac{1}{h_i} & \frac{1}{h_i} \end{bmatrix} \begin{bmatrix} u_1^e \\ u_2^e \end{bmatrix}. \quad (8)$$

The coordinate transformation in equation (1) can also be written in matrix form using the shape functions

$$x = [N_1 \quad N_2] \begin{bmatrix} x_1^e \\ x_2^e \end{bmatrix} \quad (9)$$

where  $x_1^e$  and  $x_2^e$  are the local nodal X coordinates. When both the approximation function  $u_h(x)$  and coordinate  $x$  are interpolated using the same shape functions, the formulation is called **isoparametric**.

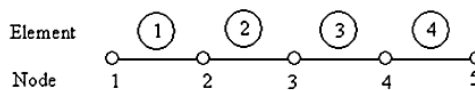
We can calculate the integrals of the shape function with respect to  $x$  over an element by calculating the area under the curves for  $N_1$  and  $N_2$ .

### Exercise

For four linear elements in computational domain, using a standardised (master) linear element to construct a global system  $\mathbf{Ku} = \mathbf{F} + \mathbf{F}_b$  of the BVP:

$$-u_{xx} = \delta(x - 2), \quad x \in (0, 4)$$

subject to  $u(0) = 2$ , and  $u_x(4) = -2(u(4) - 1)$ .



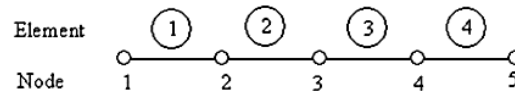
## Assignment II

### Question 1. (LUT-WK7)

For four linear elements in  $[0, 1]$ , using a standardised (master) linear element to construct a global system  $\mathbf{Ku} = \mathbf{F} + \mathbf{F}_b$  of the BVP:

$$-u_{xx} = \delta(x - 2), \quad x \in (0, 4)$$

subject to  $\frac{d}{dx}u(0) = 1 - u(0)$ , and  $u(4) = 1$ .



**Note:** Assignments II (25%): Assignment Questions will be given weekly.

In this week, Questions 1 (TUT-WK7) is a part of Assignment II, please submit a document file (typesetting using Microsoft word or LATEX) via Blackboard by the due date of Assignment I on Friday 23 October 2020