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MATH5004-LEC2

FDM: Consistency, stability, convergence, and error estimates

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OUTLINE

- Global error
- Local truncation error
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Definition of the global error

Let $\mathbf{U} = (U_1, \dots, U_N)^T$ be the solution of finite difference scheme (assume no round-off errors),
 $\mathbf{u} = (u(x_1), \dots, u(x_N))^T$ be the exact solution at grid points.

The global error vector is defined as $\mathbf{E} = \mathbf{U} - \mathbf{u}$.

- The maximum norm (or the infinity norm) is

$$\|\mathbf{E}\|_{\infty} = \max_i |e_i|.$$

- The 1-norm is $\|\mathbf{E}\|_1 = \sum_i h_i |e_i|$
 similar to the continuous space $\int |e(x)| dx$.

- The 2-norm is $\|\mathbf{E}\|_2 = (\sum_i h_i |e_i|^2)^{1/2}$
 similar to the continuous space $(\int |e(x)|^2 dx)^{1/2}$.

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If $\|\mathbf{E}\| \leq Ch^p$, $p > 0$, C is a constant independent of h
 the finite difference (FD) scheme is ***p-th order accurate***

Definition A FD scheme is called convergent if $\lim_{h \rightarrow 0} \|\mathbf{E}\| = 0$

Local truncation error

Consider the DE $u_{xx} = f$ or $Lu = f$ (1)

L is the differential operator $L = \frac{d^2}{dx^2}$

By applying FDM

$$\text{DE(1) becomes } \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} = f$$

$$\text{or } L_h u = f$$

The local truncation error is $T(x) = Lu - L_h u$

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For the DE $u_{xx} = f(x)$

and the three-point central difference scheme,
the local truncation error is

$$\begin{aligned} T(x) &= Lu - L_h u \\ &= u_{xx} - \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} \\ &= f(x) - \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} \end{aligned}$$

which measures how well the FD discretisation
approximates the DE

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Convergent Method

Definition A finite difference scheme is called consistent if

$$\lim_{h \rightarrow 0} T(x) = \lim_{h \rightarrow 0} (Lu - L_h u) = 0$$

To check whether a FD scheme is consistent or not,
we use Taylor expansion.

For the DE $u_{xx} = f(x)$, we have

$$\begin{aligned} T(x) &= u_{xx} - \frac{u(x+h) - 2u(x) + u(x-h)}{h^2} \\ &\approx -\frac{h^2}{12} u^{(4)}(x) = Ch^2 \end{aligned}$$

$$\lim_{h \rightarrow 0} T(x) = \lim_{h \rightarrow 0} Ch^2 = 0$$

So the FD scheme
is consistent.

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As the consistence cannot guarantee a finite difference work, the stability of a FD scheme is required.

For the model problem, we have

$$A\mathbf{u} = \mathbf{F} + \mathbf{T}, \quad A\mathbf{U} = \mathbf{F}$$

$$A(\mathbf{u} - \mathbf{U}) = \mathbf{T}$$

$$A\mathbf{E} = \mathbf{T}$$

A is the coefficient matrix of the FD equations,

F is the modified source term by the BC,

T is the vector of the local truncation error at grid points

$$A\mathbf{E} = \mathbf{T}$$

If A is non-singular, then

$$\|\mathbf{E}\| = \|A^{-1}\mathbf{T}\| \leq \|A^{-1}\| \|\mathbf{T}\|.$$

If A is singular, then

$$\|\mathbf{E}\| \text{ may be arbitrary large.}$$

For the central FD scheme, we have

$$\|\mathbf{E}\| \leq \|A^{-1}\| h^2.$$

Thus, the global error depends on both the local truncation error and $\|A^{-1}\|$.

Definition

A FD method for the elliptic DE is stable if A is invertible and

$$\|A^{-1}\| \leq C, \quad \text{for all } h < h_0,$$

where C and h_0 are constants

Theorem

A consistent and stable finite difference scheme is convergent.

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Grid refinement analysis

Assume that a method is p -th order accurate, i.e.,

$$\|E_h\| \sim Ch^p$$

$$\log \|E_h\| = \log C + p \log h,$$

We can divide h by half to get $\|E_{h/2}\|$.

We then have

$$\text{ratio} = \frac{\|E_h\|}{\|E_{h/2}\|} = \frac{Ch^p}{C(h/2)^p} = 2^p,$$

$$p = \frac{\log (\|E_h\|/\|E_{h/2}\|)}{\log 2}.$$

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Improvement of Accuracy of Solution

Deferred Approach to the Limit

By reducing the value of k and h , i.e., through mesh refinement.

Denote u = true solution,

u_h = finite difference solution,

then $u = u_h + \text{error}$.

Let u_h be the solution of the Laplace equation by using the 5 point scheme, then

$$u = u_h + Ch^2.$$

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- Based on the above formulae, to accelerate the convergence of numerical solutions, we could use the so-called **deferred approach** to the limit suggested by Richardson.

$$u = u_1 + Ch^p. \quad (1.1)$$

If mesh size h is reduced from h to $h/2$, then

$$u = u_2 + C(h/2)^p. \quad (1.2)$$

where u_2 is the approximation obtained with $h/2$.

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From (1.1) and (1.2), by eliminating h^p , we obtain

$$u = \frac{2^p u_2 - u_1}{2^p - 1}. \quad (1.3)$$

For example, for $p = 2$,

$$u = \frac{4u_2 - u_1}{3}$$

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- If p is unknown, it can be estimated from three approximate solutions at the same point obtained by using different mesh sizes.
- Let u_1 , u_2 and u_3 are approximations at the same point obtained respectively using step size h_1 , h_2 and h_3 where

$$h_3 = \frac{1}{2}h_2 = \frac{1}{4}h_1$$

Then

$$u = u_1 + Ch_1^p,$$

$$u = u_2 + C\left(\frac{1}{2}\right)^p h_1^p,$$

$$u = u_3 + C\left(\frac{1}{4}\right)^p h_1^p,$$

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from which, we have

$$u_2 - u_1 + Ah_1^p \left[\left(\frac{1}{2} \right)^p - 1 \right] = 0$$

$$u_3 - u_2 + Ah_1^p \left(\frac{1}{2} \right)^p \left[\left(\frac{1}{2} \right)^p - 1 \right] = 0$$

Hence,

$$2^p = \frac{u_2 - u_1}{u_3 - u_2}.$$

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Elliptic equations

In two space dimensions, a constant-coefficient elliptic equation has the form

$$au_{xx} + bu_{xy} + cu_{yy} + h(x, y, u, u_x, u_y) = f(x, y)$$

where the coefficients a, b, c satisfy

$$b^2 - 4ac < 0.$$

Consider the problem

$$u_{xx} + u_{yy} = f(x, y), \quad 0 \leq x, y \leq 1$$

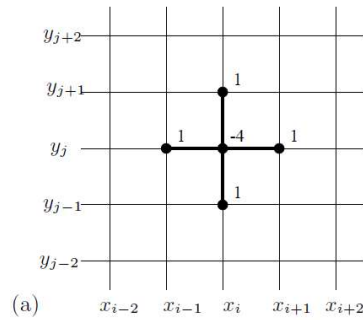
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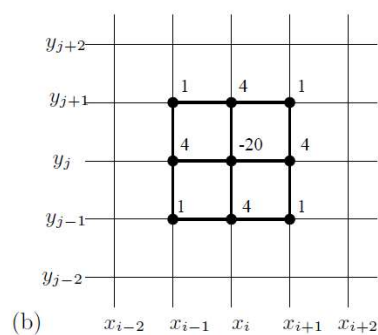
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Stencils for the 2D Laplacian



(a)

The five-point stencil



(b)

The nine-point stencil

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Accuracy and Stability: the five-point stencil

Let $\Delta x = \Delta y = h$

$$\begin{aligned} T(x) &= Lu - L_h u \\ &= (u_{xx} + u_{yy}) - \frac{u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} - 4u_{i,j}}{h^2} \end{aligned}$$

$$T_{ij} = f_{ij} - \frac{1}{h^2} (u_{i-1,j} + u_{i+1,j} + u_{i,j-1} + u_{i,j+1} - 4u_{i,j})$$

$$T_{ij} = \frac{1}{12} h^2 (u_{xxxx} + u_{yyyy}) + O(h^4)$$

The global error $E_{ij} = u(x_i, y_j) - u_{ij}$



$$A^h E^h = T^h$$

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Accuracy and Stability: the nine-point stencil

$$\nabla^2 u(x_i, y_j) = \frac{1}{6h^2} [4u_{i-1,j} + 4u_{i+1,j} + 4u_{i,j-1} + 4u_{i,j+1} \\ + u_{i-1,j-1} + u_{i-1,j+1} + u_{i+1,j-1} + u_{i+1,j+1} - 20u_{ij}]$$

$$\nabla^2 u(x_i, y_j) \\ = \nabla^2 u + \frac{1}{12} h^2 (u_{xxxx} + 2u_{xxyy} + u_{yyyy}) + O(h^4).$$

It is noted that the error is still $O(h^2)$.

Since

$$u_{xxxx} + 2u_{xxyy} + u_{yyyy} = \nabla^2(\nabla^2 u) \equiv \nabla^4 u.$$

From DE $\nabla^2 u = f$, we have

$$u_{xxxx} + 2u_{xxyy} + u_{yyyy} = \nabla^2 f.$$

We can obtain a fourth-order accurate method of the form

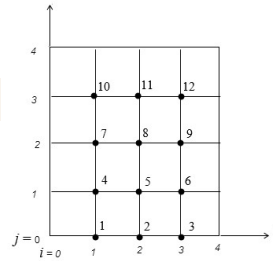
$$\nabla^2 u_{ij} = f(x_i, y_j) + \frac{h^2}{12} \nabla^2 f(x_i, y_j),$$

Example

Given

$$u_{xx} + u_{yy} = x^2 y^2, \quad 0 \leq x, y \leq \pi$$

$$\begin{aligned} u(0, y) &= 0, & u(\pi, y) &= 1 \\ u(x, \pi) &= 0, & \frac{\partial u(x, 0)}{\partial y} &= 1. \end{aligned}$$



For 5 grid points in x-direction and 5-grid points in y-direction,

- Derive the five-point FD equations of the PDE
- Derive the nine-point FD equations of the PDE