

Development of a machine learning model to determine the forces on the piston in the pump-tube of a two-stage gas gun deforming due to a taper

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Abstract

Abstract here.

1 TODO

1. Get output parameters
2. Model automation
3. Mesh optimization

2 Introduction

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- We will use: ton, mm, s, N, MPa, N-mm

2.1 Gas gun design

2.1.1 title

3 Finite element simulation

3.1 Material models

3.1.1 ABS

1. Yield stress: 48.26 MPa from <https://peer.asee.org/tensile-comparison-of-polymer-specimens-produced-with-different-processes.pdf>

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MASS	LENGTH	TIME	FORCE	STRESS	ENERGY	Steel Density	Steel Modulus	G - Gravity Constant
kg	m	s	N	Pa	Joule	7.83E+03	2.07E+11	9.81
kg	mm	ms	kN	Gpa	kN-mm	7.83E-06	2.07E+02	9.81E-03
g	cm	s	dyne	dyne/cm^2	erg	7.83E+00	2.07E+12	9.81E+02
g	cm	us	1e7N	Mbar	1e7 N-cm	7.83E+00	2.07E+00	9.81E-10
g	mm	s	1e-6N	Pa	1e-9 J	7.83E-03	2.07E+11	9.81E+03
g	mm	ms	N	Mpa	N-mm	7.83E-03	2.07E+05	9.81E-03
ton	mm	s	N	Mpa	N-mm	7.83E-09	2.07E+05	9.81E+03
lbf-s^2/in	in	s	lbf	psi	lbf-in	7.33E-04	3.00E+07	3.86E+02
slug	ft	s	lbf	psi	lbf-ft	1.52E+01	4.32E+09	32.2

Figure 1: Consistent units for ABAQUS. From <https://www.researchgate.net/post/What-are-the-Abaqus-Units-in-Visualization>

2. (Modelled as perfect plasticity)

3. Poisson's ration: 0.35 from <http://www.goodfellow.com/A/Polyacrylonitrile-butadiene-styrene.html>

4. Young's modulus: 2.1-2.4 GPa from <http://www.goodfellow.com/A/Polyacrylonitrile-butadiene-styrene.html>

5. Density 1.05×10^{-9} ton/mm³ from <http://www.goodfellow.com/A/Polyacrylonitrile-butadiene-styrene.html>

3.1.2 Steel

1. Poisson's ration: 0.3 from <http://www.matweb.com/search/datasheet.aspx?bassnum=MS0001&ckck=1>

2. Young's modulus: 200 GPa from <http://www.matweb.com/search/datasheet.aspx?bassnum=MS0001&ckck=1>

3. Density 8×10^{-9} ton/mm³ from <http://www.matweb.com/search/datasheet.aspx?bassnum=MS0001&ckck=1>

3.2 Single test simulation

3.3 Mesh optimization

Parameters

1. ratio of element expansion for piston
2. ratio of element expansion for tube
3. n elements

Objective function

1. Min elements

Constraint

1. Force
2. Dissipation

4 Machine learning surrogate model

4.1 Feature engineering

Predictive features:

1. Coefficient of friction: μ
2. Taper angle: α
3. Velocity: v
4. Distance between piston front and taper start: x_{taper}
5. Pressure difference between piston front and back: Δp
6. Piston length: l_p
7. Piston density: ρ_p
8. Accumulative plastic strain in the piston: γ

Dependent variables:

1. Axial force on piston due to taper: F_z
2. Increment in accumulated plastic dissipation: $\Delta\gamma$

4.1.1 Dimensional analysis

Table 1: Fundamental dimensional units

Mass $[M]$	Length $[L]$	Time $[T]$
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$$\Pi = F_c^{k_1} \langle \dot{\Phi}_c \rangle^{k_2} \Delta P^{k_4} v^{k_5} \langle \Phi_c \rangle^{k_3} x_t^{k_6} \quad (1)$$

$$r = 3 \quad (2)$$

$$n = 24 \quad (3)$$

$$n_{\text{n-dim}} = n - r = 21 \quad (4)$$

$$\begin{matrix} M \\ L \\ T \end{matrix} \begin{matrix} F_c & \langle \dot{\Phi}_c \rangle & \Delta P & v & \langle \Phi_c \rangle & x_t \\ \begin{bmatrix} 1 & 1 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 1 & -1 & 1 \\ -2 & -3 & -2 & -1 & -2 & 0 \end{bmatrix} \end{matrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \\ k_4 \\ k_5 \\ k_6 \end{bmatrix} = \mathbf{0}. \quad (5)$$

1. Enter units as symbols in sympy
2. Construct dimensional matrix

Table 2: Variables on which the problem depends **Check that units are correct**

Component	Description	Symbol	Units
Cap	Axial contact force	F_c	$[MLT^{-2}]$
	Rate of volume average plastic dissipation	$\langle \dot{\Phi}_c \rangle$	$[ML^{-1}T^{-3}]$
	Volume average plastic dissipation	$\langle \Phi_c \rangle$	$[ML^{-1}T^{-2}]$
	Pressure difference	ΔP	$[ML^{-1}T^{-2}]$
	Velocity	v	$[LT^{-1}]$
	Distance of cap past taper	x_t	$[L]$
	Length past piston	l_c	$[L]$
	Diameter	d_c	$[L]$
	Density	ρ_c	$[ML^{-3}]$
	Young's modulus	E_c	$[ML^{-1}T^{-2}]$
	Poisson's ratio	ν_c	$[\bullet]$
	Yield stress	σ_{yc}	$[ML^{-1}T^{-2}]$
Piston	Length	l_p	$[L]$
	Diameter	d_p	$[L]$
	Density	ρ_p	$[ML^{-3}]$
	Young's modulus	E_p	$[ML^{-1}T^{-2}]$
	Poisson's ratio	ν_p	$[\bullet]$
Transition piece	Length	l_t	$[L]$
	Diameter change	Δd_t	$[L]$
	Density	ρ_t	$[ML^{-3}]$
	Young's modulus	E_t	$[ML^{-1}T^{-2}]$
	Poisson's ratio	ν_t	$[\bullet]$
Friction	Cap-on-steel CoF	μ_{cs}	$[\bullet]$
	Steel-on-steel CoF	μ_{ss}	$[\bullet]$
	Aluminium-on-steel CoF	μ_{as}	$[\bullet]$

3. Find solutions k_i^j to dimensional matrix by $n - r$ values in k to 0 (except for 1 which on sets to 1).

4. Automatically print out resulting dimensionless products table.

Based on [1]:

Notes:

1.

Direct quote from [1]

“Dimensional analysis is a method with the aid of which one may for instance test a formula for dimensional correctness. It leads to a first understanding of the solution of a physical problem and yields a precise information about the number of variables that are necessary to describe it, a fact that is

Table 3: Non-dimensional parameters

F_c	$\langle \dot{\Phi}_c \rangle$	$\langle \Phi_c \rangle$	ΔP	v	x_t
k_1	k_2	k_3	k_4	k_5	k_6

particularly important when experiments are being performed. Very often dimensional analysis reduces the number of variables upon which a physical problem was initially surmised to depend. If for instance the quantity y depends upon x_1, x_2, \dots, x_n , where all quantities have a certain physical dimension, then dimensional analysis shows that y can only depend upon certain products of powers of x_1, x_2, \dots, x_n , a fact that corresponds regularly to a considerable reduction of the number of variables. Naturally then, experiments may more simply or more economically be performed than without knowledge of this fact.”

“The first step in a dimensional analysis consists in the listing of the parameters, which influence a physical problem. This step is very decisive. If too many variables are listed that may describe a physical problem, then the final equations will contain superfluous variables, if too few variables are introduced, incomplete equations may emerge, which results in incomplete equations or ”more often” false inferences or the result can not be expressed in terms of dimensionally homogeneous functions.”

4.2 Experimental input parameters

In order of importance:

1. Initial velocity: v_0
2. Pressure path: p_{path}
3. Piston length: l_p
4. Coefficient of friction: μ

4.3 Experimental results

4.4 Model

5 Packaging of model for use in 1D code

5.1 PIP

5.2 Usage example

References

- [1] K. Hutter and K. Jöhnk. *Continuum Methods of Physical Modeling: Continuum Mechanics, Dimensional Analysis, Turbulence*. Springer Science & Business Media, 2013.