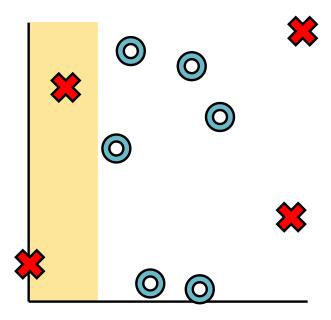
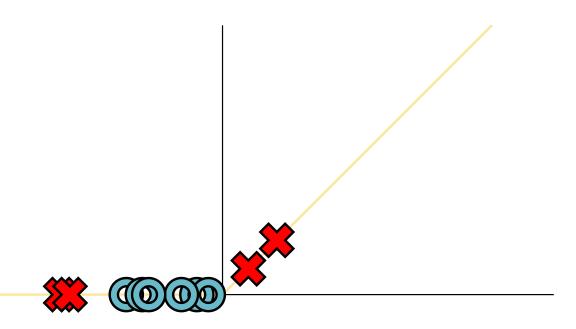
Module 2.1 - Tensors

Intuition: Split 1

```
yellow = Linear(-1, 0, 0.25)
```



Reshape: ReLU

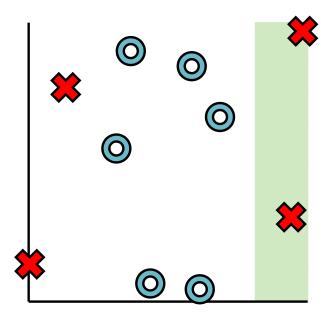


Math View

$$h_1 = \mathrm{ReLU}(\mathrm{lin}(x; w^0, b^0))$$

Intuition: Split 2

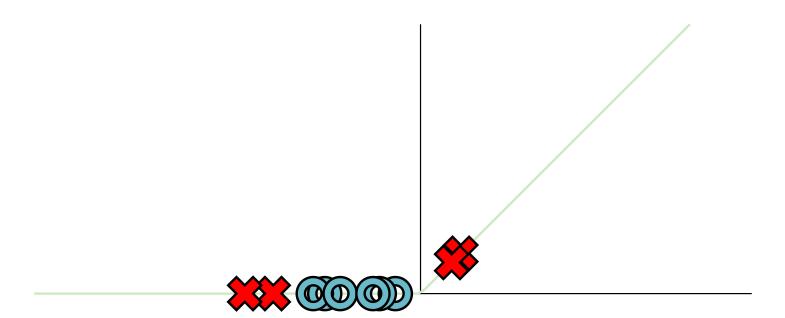
```
green = Linear(1, 0, -0.8)
```



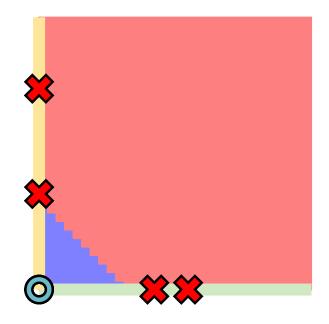
Math View

$$h_2 = \mathrm{ReLU}(\mathrm{lin}(x; w^1, b^1))$$

Reshape: ReLU



Reshape: ReLU



Math View (Alt)

$$egin{aligned} ext{lin}(x;w,b) &= x_1 imes w_1 + x_2 imes w_2 + b \ h_1 &= ext{ReLU}(ext{lin}(x;w^0,b^0)) \ h_2 &= ext{ReLU}(ext{lin}(x;w^1,b^1)) \ m(x_1,x_2) &= ext{lin}(h;w,b) \end{aligned}$$

Parameters: $w_1, w_2, w_1^0, w_2^0, w_1^1, w_2^1, b, b^0, b^1$

Quiz

Outline

- Tensors
- Operations
- Strides

Tensors

Motivation

$$egin{aligned} ext{lin}(x;w,b) &= x_1 imes w_1 + x_2 imes w_2 + b \ h_1 &= ext{ReLU}(ext{lin}(x;w^0,b^0)) \ h_2 &= ext{ReLU}(ext{lin}(x;w^1,b^1)) \ m(x_1,x_2) &= ext{lin}(h;w,b) \end{aligned}$$

Parameters: $w_1, w_2, w_1^0, w_2^0, w_1^1, w_2^1, b, b^0, b^1$

This is really messy!

Matrix Form

$$\mathbf{h} = \mathrm{ReLU}(\mathbf{W}^0\mathbf{x} + \mathbf{b}^0) \ m(\mathbf{x}) = \mathbf{W}h + \mathbf{b}$$

Parameters: $\mathbf{W}, \mathbf{b}, \mathbf{W}^{(0)}, \mathbf{b}^{(0)}$

Need to be careful thought

Tensors

What is it?

- Fancy multi-dimensional arrays
- Basis for an mathmatical programming

Tensors!

Key Building Block

- Matlab
- Numpy
- Tensorflow, etc.

Terminology

- 0-Dimensional Scalar
- Scalar from module-0

Terminology

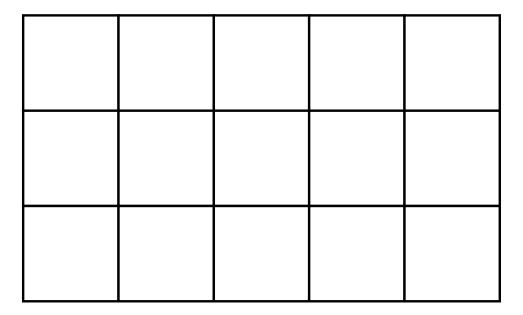
• 1-Dimensional

• Math: Vector

Terminology

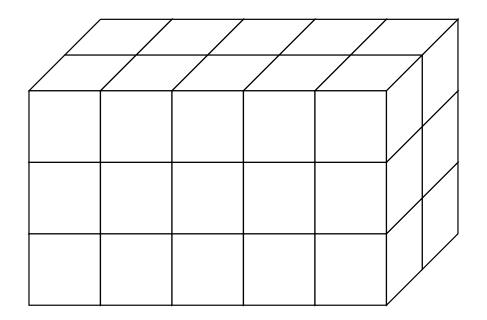
• 2-Dimensional

• Math: Matrix



Terminology

• Arbitrary dimensions - Tensor (Array in numpy)



Terminology

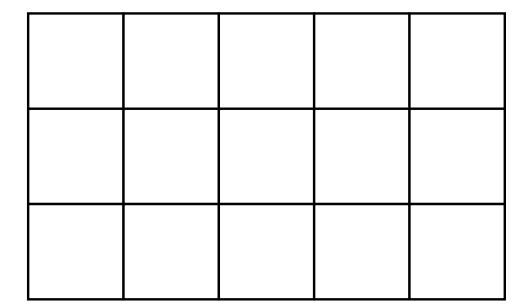
- Dims # dimensions (x.dims)
- Shape # cells per dimension (x.shape)
- Size # cells (x.size)

Example

• dims: 2

• shape: (3, 5)

• size : 15

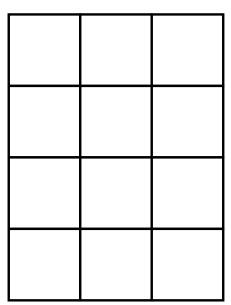


Example

• dims: ?

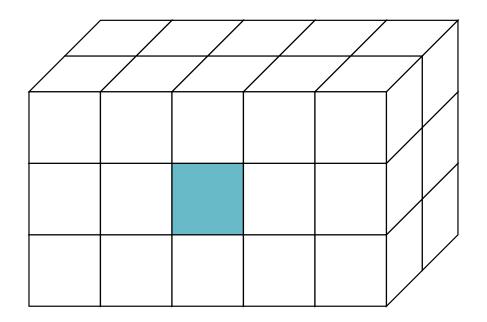
• shape: ?

• size : ?



Indexing

• Indexing syntax: tensor[0, 1, 2]



Convention

- depth
- row
- columns

Operations

Goal

- Support user api
- Keep track of tensor properties
- Setup fast / simple Functions

Tensor Usage

Unary

```
new_tensor = x.log()
```

Binary (for now, only same shape)

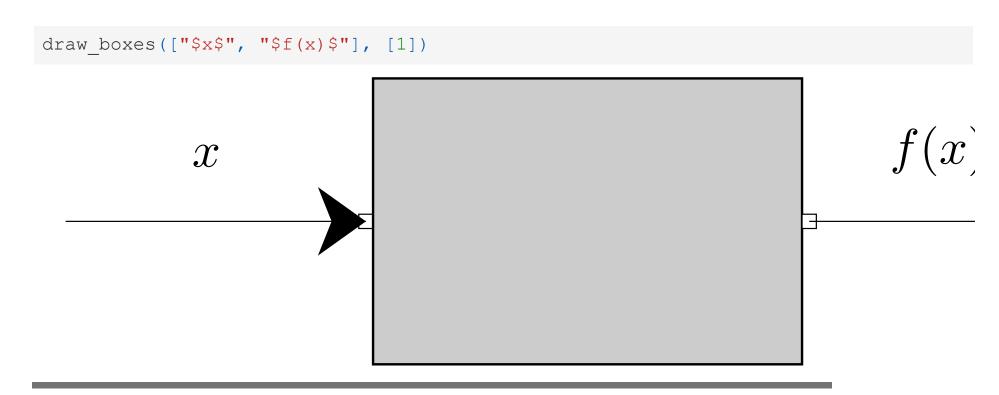
```
new_tensor = x + x
```

Reductions

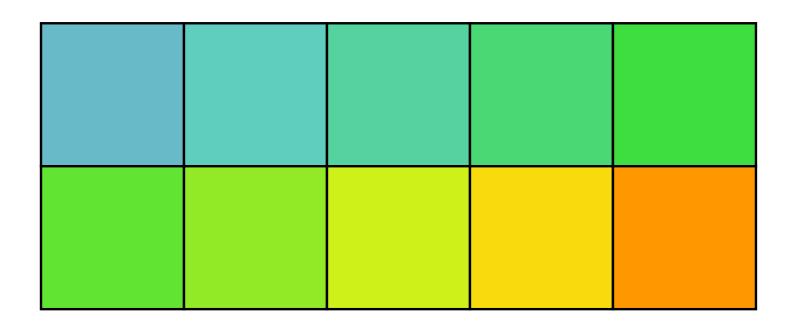
```
new_tensor = x.sum()
```

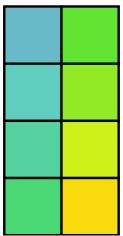
Idea 1: Immutable Operations

- Minitorch doesn't let you update tensors
- All operations return a new tensor (just like scalar)

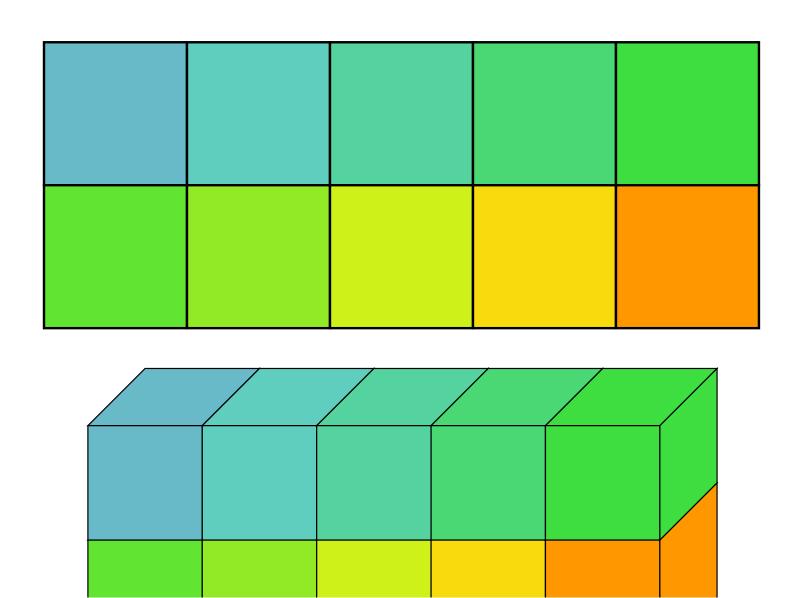


Shape Manipulation: Permutation





Shape Manipulation: View



Why not just use lists?

- Functions to manipulate shape
- Mathematical notation
- Can act as Variables / Parameters
- Efficient control of memory (Module-3)

Why not lists?

Matrix (5, 2)

```
ls = [[1, 2], [3, 4], [5, 7], [2, 3], [2, 4]]
```

View (1, 5, 2)

```
new_ls = [[[ls[j][i] for i in range(2)] for j in range(5)]]
```

Transpose (2, 5)

```
matrix_trans = [[ls[i][j] for i in range(5)] for j in range(2)]
```

Issues

Operators requires copying

```
matrix_trans = [[ls[i][j] for i in range(5)] for j in range(2)]
```

Storage shaped based on usage

```
new_tensor = [[[ls[j][i] for i in range(2)] for j in range(5)]]
```

Idea 2: Views

- Seperate storing information from user view
- Keep a mapping from users version to storage

What's bad about tensors?

- Hard to grow or shrink
- Only numerical values
- Lose comprehensions / python built-ins
- Shapes are easy to mess up

Next Couple Lectures

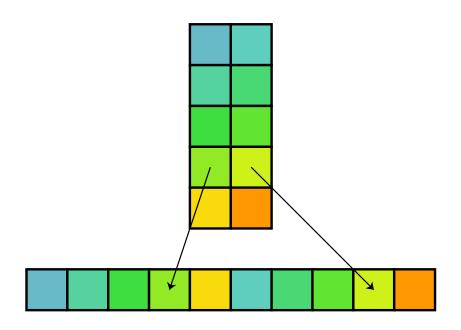
- No autodifferentiation for now
- Only consider forward tensor operations
- Add autodiff afterwards

Tensor Internals

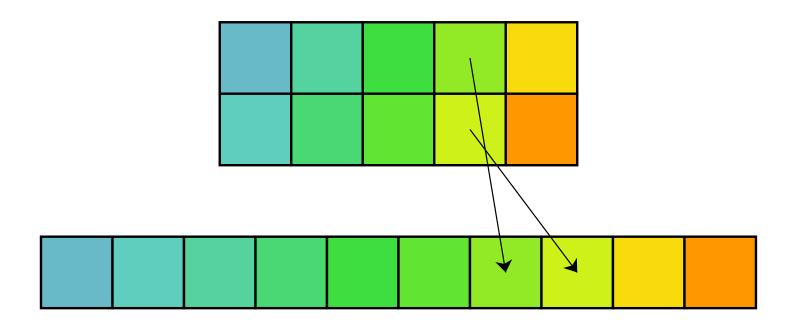
How does this work

- Storage: 1-D array of numbers of length size
- Strides: tuple that provides the mapping from user indexing to the position in the 1-D storage.

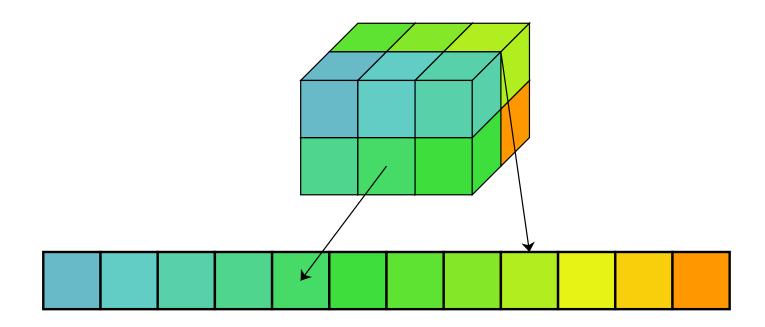
Strides



Strides



Strides



Which is best?

- Can be useful when it is contiguous
- Our Convention: Bigger strides left
- $ullet (s_1, s_2, s_3)$

Operation 1: Indexing

• v[i, j, k]

How to find data point?

Operation 2: Movement

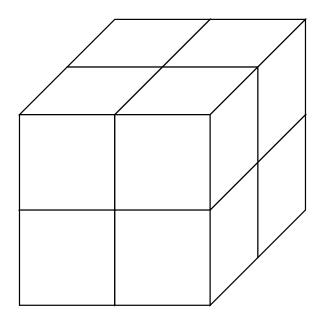
How do I move to the next in the row? Column?

Operation 3: Reverse Indexing

How do I find the index for data?

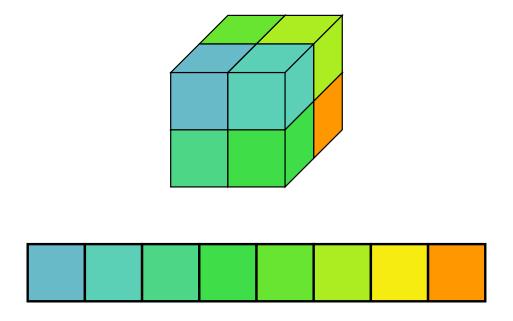
Stride Intuition

- Numerical bases,
- Index for position 0? Position 1? Position 2?



Stride Intuition

- Index for position 0? Position 1? Position 2?
- [0,0,0],[0,0,1],[0,1,0]



Conversion Formula

- Divide and mod
- k=p
- $j=(p//s_2)$
- ...

Key Operations

- Map from index to position
- Map from position to index

Implementation

• TensorData : Manager of strides and storage

Module-2

Overview

- tensor.py Tensor Variable
- tensor functions.py Tensor Functions
- tensor_data.py Storage and Indexing
- tensor_ops.py Low-level tensor operations

Q&A