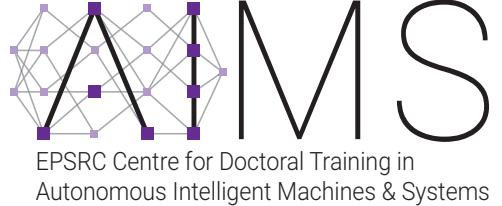




European Research Council
Established by the European Commission



Engineering and
Physical Sciences
Research Council



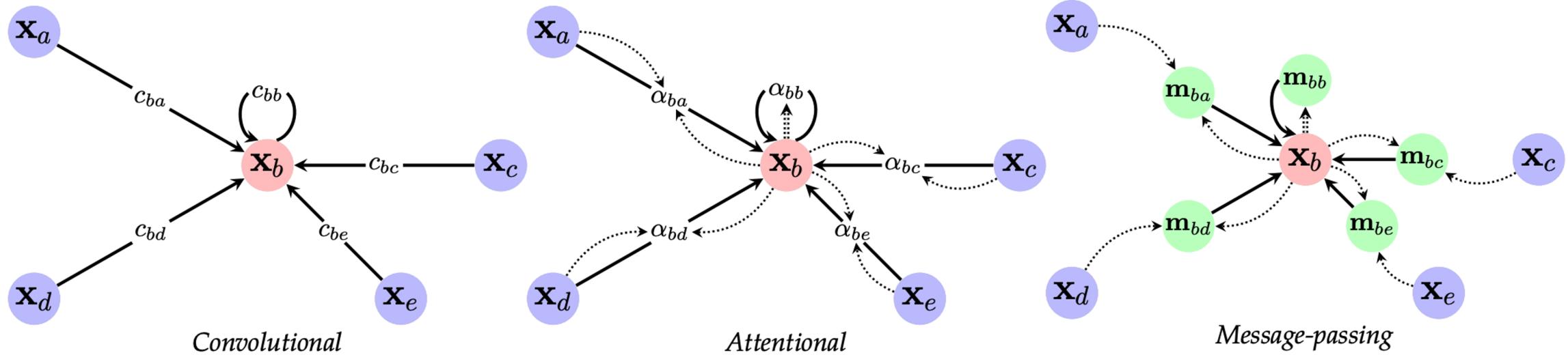
DRew: Dynamically Rewired Message Passing with Delay

Benjamin Gutteridge,
Xiaowen Dong, Michael Bronstein,
Francesco Di Giovanni

Overview

- Background: MPNNs and long-range interactions
- Contributions:
 - Dynamically Rewired Message Passing
 - DRew + **Delay**
- Why DRew works
- Experimental results

Message-Passing Neural Networks



- Message passing: aggregation and update steps
- Occurs over **1-hop neighbourhood**
- Several variations, but most graph neural networks are MPNNs

Challenges with MPNNs

- **Long-range dependency**
 - When the output of a MPNN depends on distant nodes interacting with each other

Necessitates more MPNNs layers, leading to:

- **Oversmoothing**
 - increasing network depth leading to homogeneous node representations and thus poor performance
- **Oversquashing**
 - “Lack of sensitivity of the output of an MPNN at node p to the input features at an k -hop-distant node s ”

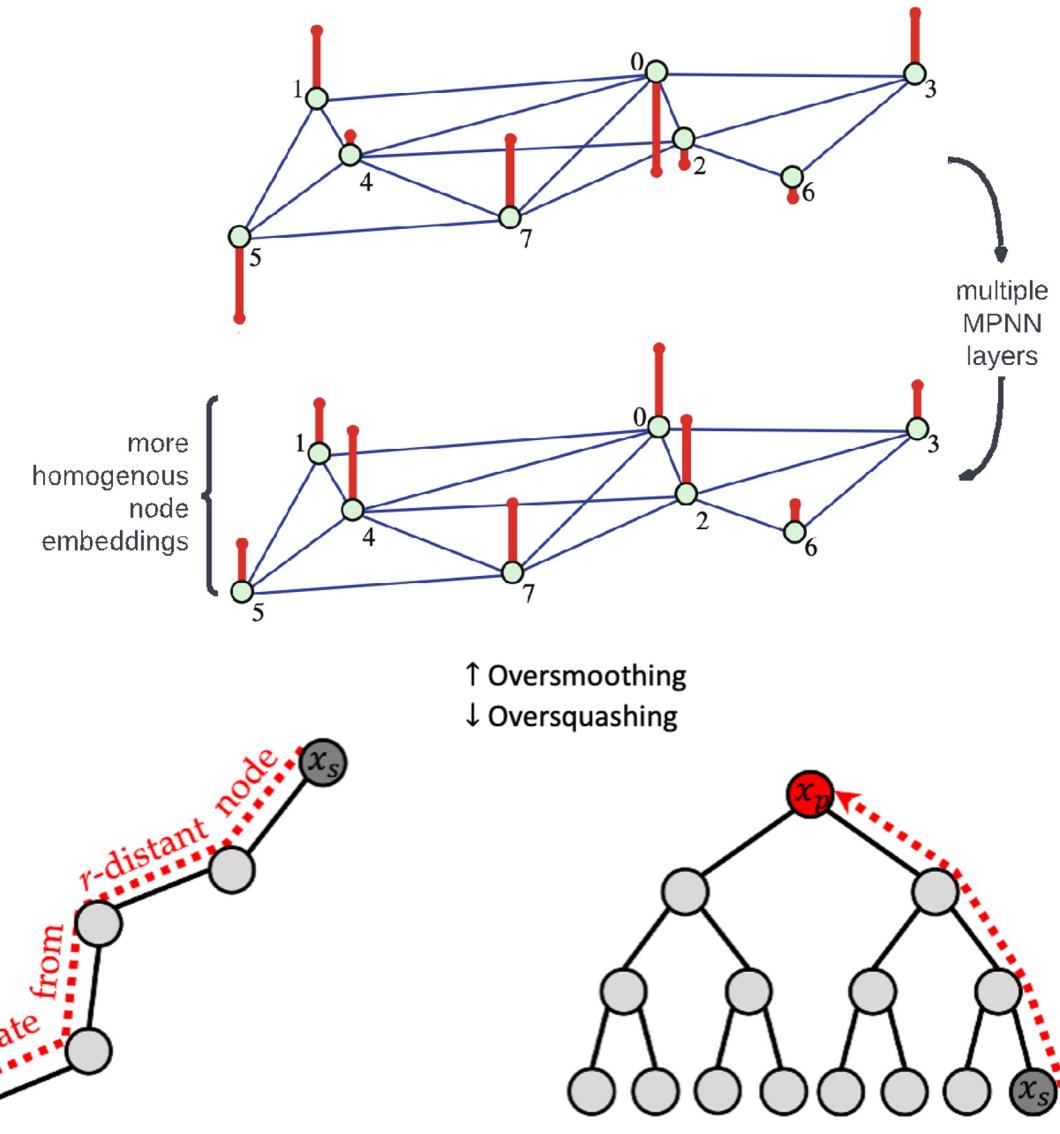


Figure credits: Topping et al 2022. Over-squashing, Bottlenecks, and Graph Ricci curvature (bottom). Stanković, Ljubiša, and Ervin Sejdić, eds. 2019. Vertex-frequency analysis of graph signals (top).

Long-range interactions

- Various domains use global graph information or rely on distant node interactions
- Many large graphs likely exhibit a degree of long-range dependence
- Several recent works looking at long-range interactions, as well as a set of benchmark datasets
 - Wu, Zhanghao, et al. "Representing long-range context for graph neural networks with global attention." (NIPS 2021)
 - Dwivedi, Vijay Prakash, et al. "Long range graph benchmark." (NIPS 2022)
 - Di Giovanni, Francesco, et al. "On over-squashing in message passing neural networks: The impact of width, depth, and topology." (ICML 2023)
 - Ma, Liheng, et al. "Graph Inductive Biases in Transformers without Message Passing." (ICML 2023).

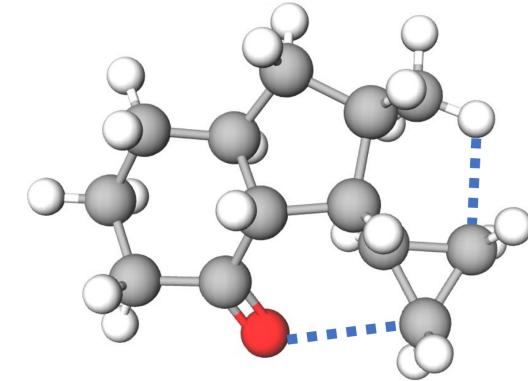


Figure 1: Molecule with LRIs (dotted lines showing 3D atomic contact) that are not trivially captured by the graph structure.

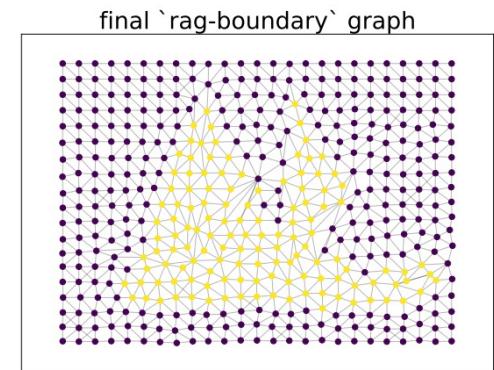
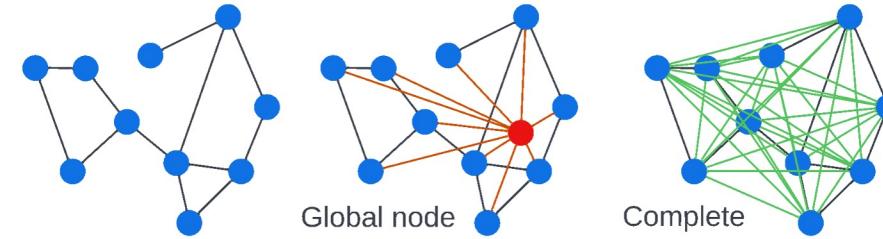


Figure credits: Dwivedi et al 2022, Long Range Graph Benchmark

Graph Rewiring

Static graph rewiring

- Graph topology itself is altered to make it ‘friendlier’
- E.g.
 - Dropping or adding nodes or edges (DropEdge, DropGNN)
 - Global nodes/fully adjacent layers
 - Rewiring according to a spectral/connectivity measure (SDRF, DIGL)
 - Positional encoding

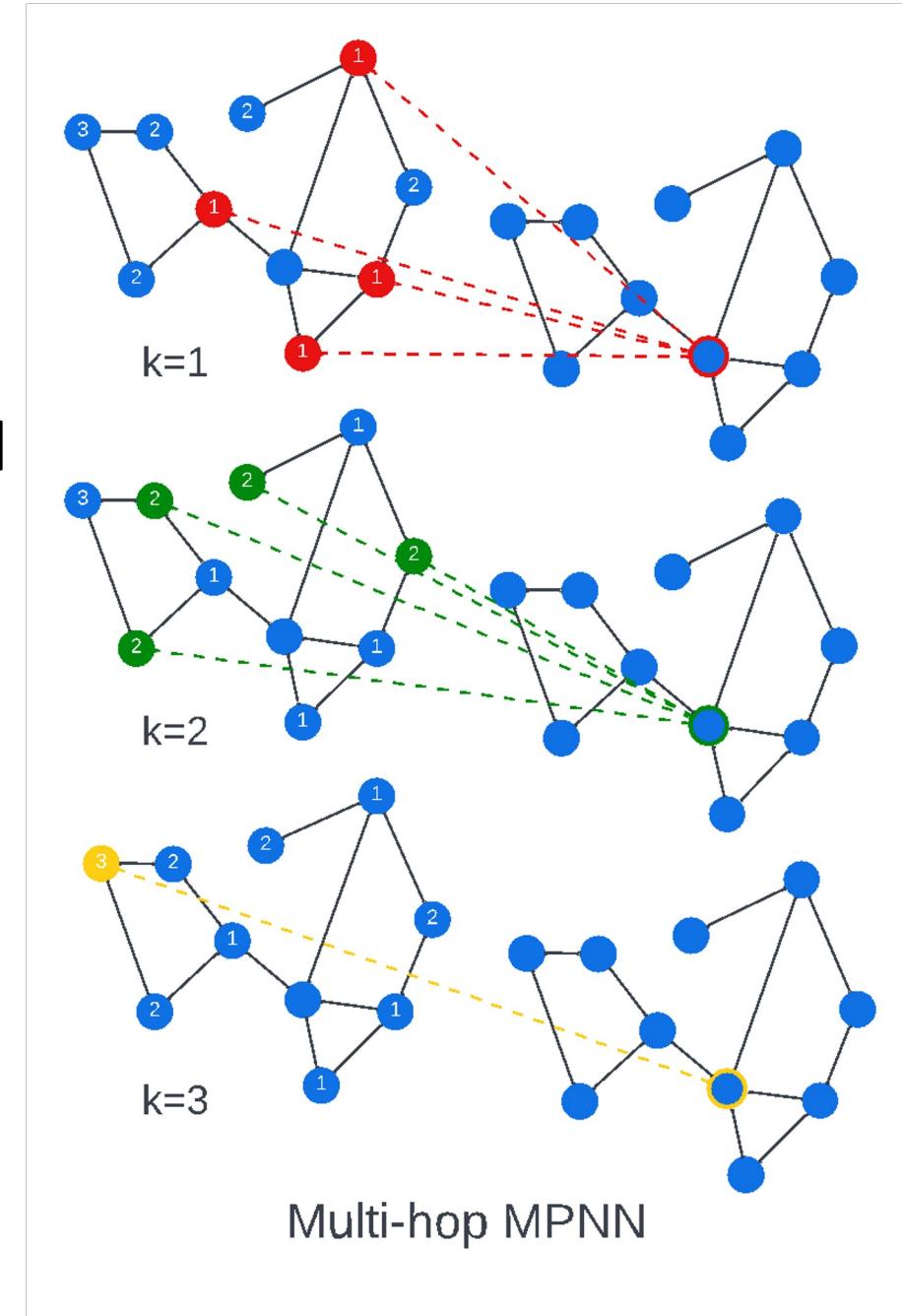


Computational graph rewiring

- Rather than changing input graph itself, you change the way you *allow information to propagate* during message passing
- E.g.
 - Multi-hop MPNNs (Shortest Path Network, N-GCN, MixHop, k-hop GNN)
 - Graph Transformers
- This is our focus

Proposal

- Transformers throw away the graph topology by making graphs fully-connected
- Multi-hop MPNNs are similar:
 - They make the computational graph denser
 - They lose the notion of information flow through the graph, i.e. that nodes that are closer should interact earlier
- How can we exploit these inductive biases?



Intuition: Dynamic Rewiring

“...aggregating information over distant nodes that goes beyond the limitations of classical MPNNs, but respects the inductive bias provided by the graph: **nodes that are closer should interact earlier in the architecture.**”

“We argue that it is important not simply *how* two node states interact with each other, but also ***when that happens.***”

Background: MPNNs

- MPNN:
 - 1-hop local aggregation
 - update
 - k -hop neighbourhood:
- $$a_i^{(\ell)} = \text{AGG}^{(\ell)} \left(\{h_j^{(\ell)} : j \in \mathcal{N}_1(i)\} \right),$$
- $$h_i^{(\ell+1)} = \text{UP}^{(\ell)} \left(h_i^{(\ell)}, a_i^{(\ell)} \right),$$
- $$\mathcal{N}_k(i) := \{j \in V : d_G(i, j) = k\}.$$
- Shortest path distance
- 1-hop neighbourhood

Dynamically Rewired MPNN

Vanilla
MPNN:

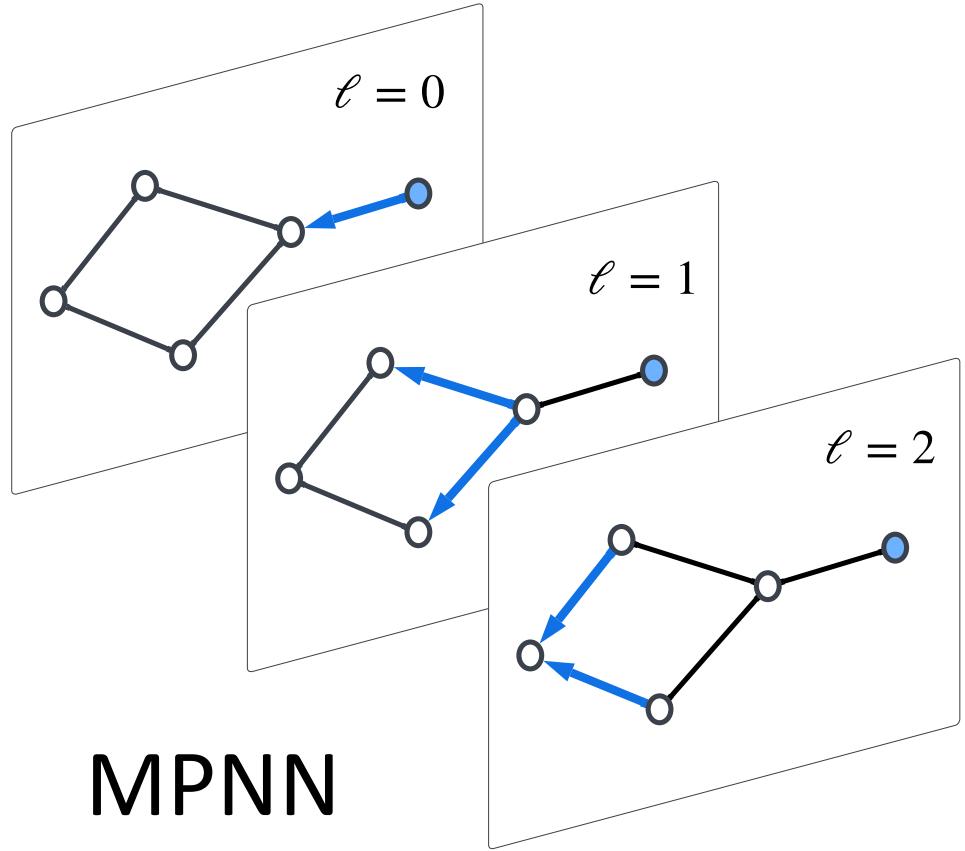
$$\begin{aligned} a_i^{(\ell)} &= \text{AGG}^{(\ell)} \left(\{h_j^{(\ell)} : j \in \mathcal{N}_1(i)\} \right), \\ h_i^{(\ell+1)} &= \text{UP}^{(\ell)} \left(h_i^{(\ell)}, a_i^{(\ell)} \right), \end{aligned}$$

Separate aggregation for
each k-hop neighbourhood

$$\begin{aligned} a_{i,k}^{(\ell)} &= \text{AGG}_k^{(\ell)} \left(\{h_j^{(\ell)} : j \in \mathcal{N}_k(i)\} \right), \quad 1 \leq k \leq \ell + 1 \\ h_i^{(\ell+1)} &= \text{UP}^{(\ell)} \left(h_i^{(\ell)}, a_{i,1}^{(\ell)}, \dots, a_{i,\ell+1}^{(\ell)} \right). \end{aligned} \tag{5}$$

Reduces to vanilla MPNN if
 $\text{AGG}_k = I$ for $k > 1$

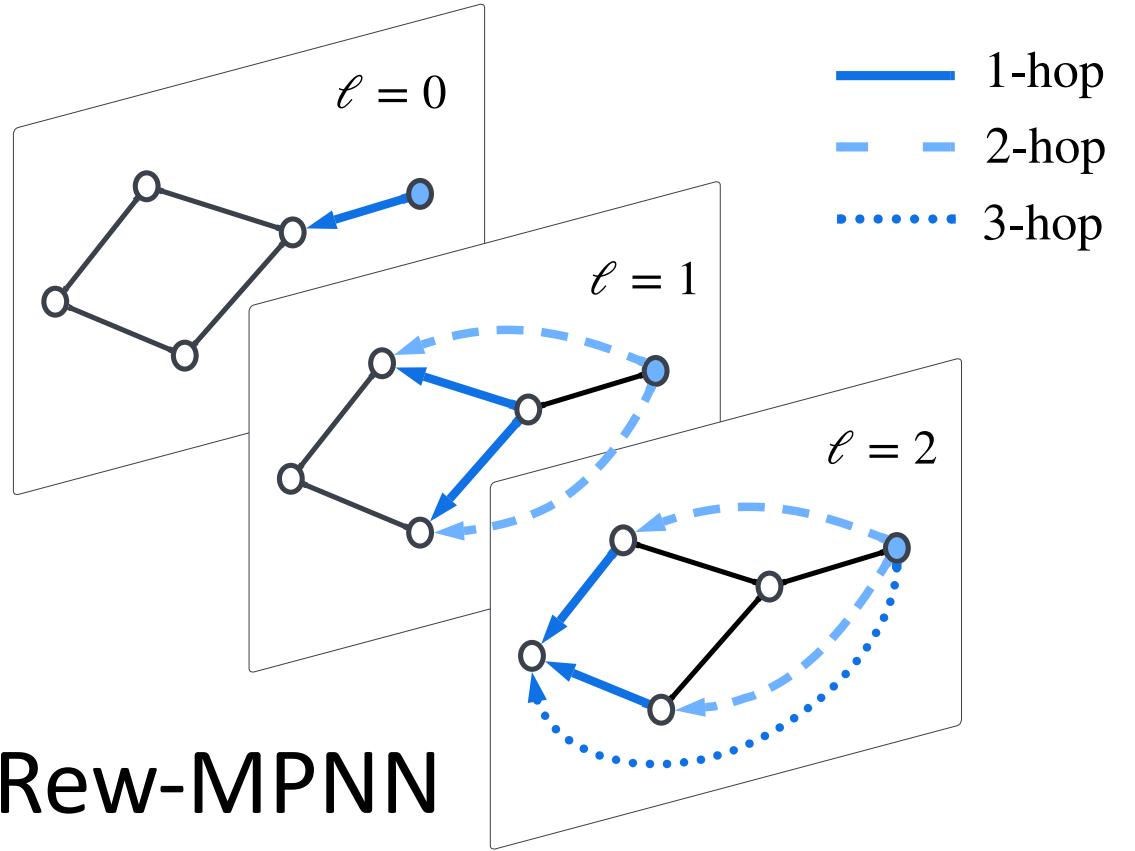
$(\ell + 1)$ th hop only
aggregated from layer ℓ



MPNN

$$a_i^{(\ell)} = \text{AGG}^{(\ell)} \left(\{h_j^{(\ell)} : j \in \mathcal{N}_1(i)\} \right),$$

$$h_i^{(\ell+1)} = \text{UP}^{(\ell)} \left(h_i^{(\ell)}, a_i^{(\ell)} \right),$$



DRew-MPNN

$$a_{i,k}^{(\ell)} = \text{AGG}_k^{(\ell)} \left(\{h_j^{(\ell)} : j \in \mathcal{N}_k(i)\} \right), 1 \leq k \leq \ell + 1$$

$$h_i^{(\ell+1)} = \text{UP}_k^{(\ell)} \left(h_i^{(\ell)}, a_{i,1}^{(\ell)}, \dots, a_{i,\ell+1}^{(\ell)} \right). \quad (5)$$

Introducing delay

Currently:

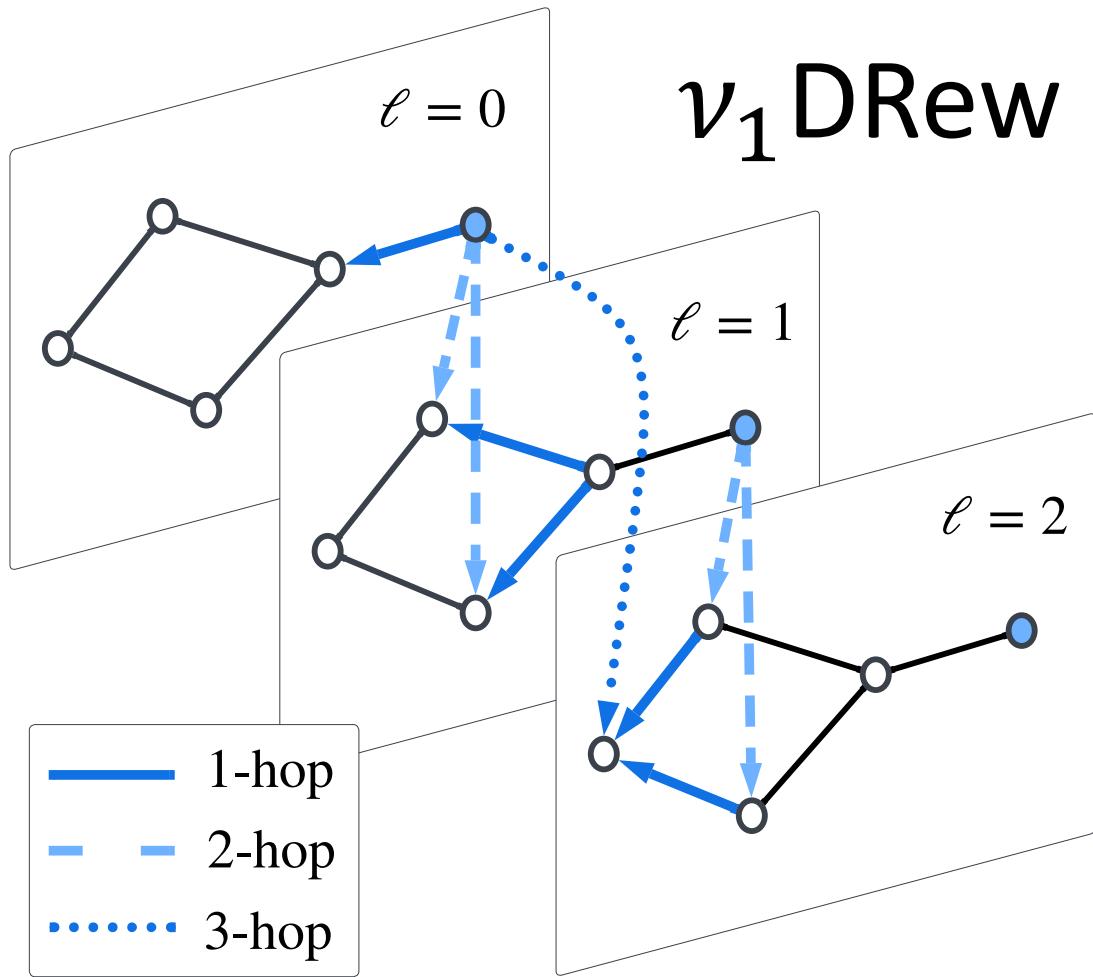
- MPNNs: nodes i, j interact with a constant delay given by their distance – leading to the same lag of information
- DRew: nodes interact only from a certain depth of the architecture, but without any delay

What if we consider the state of j as it was when the information ‘left’ to flow towards i ?

Introducing delay: ν DRew

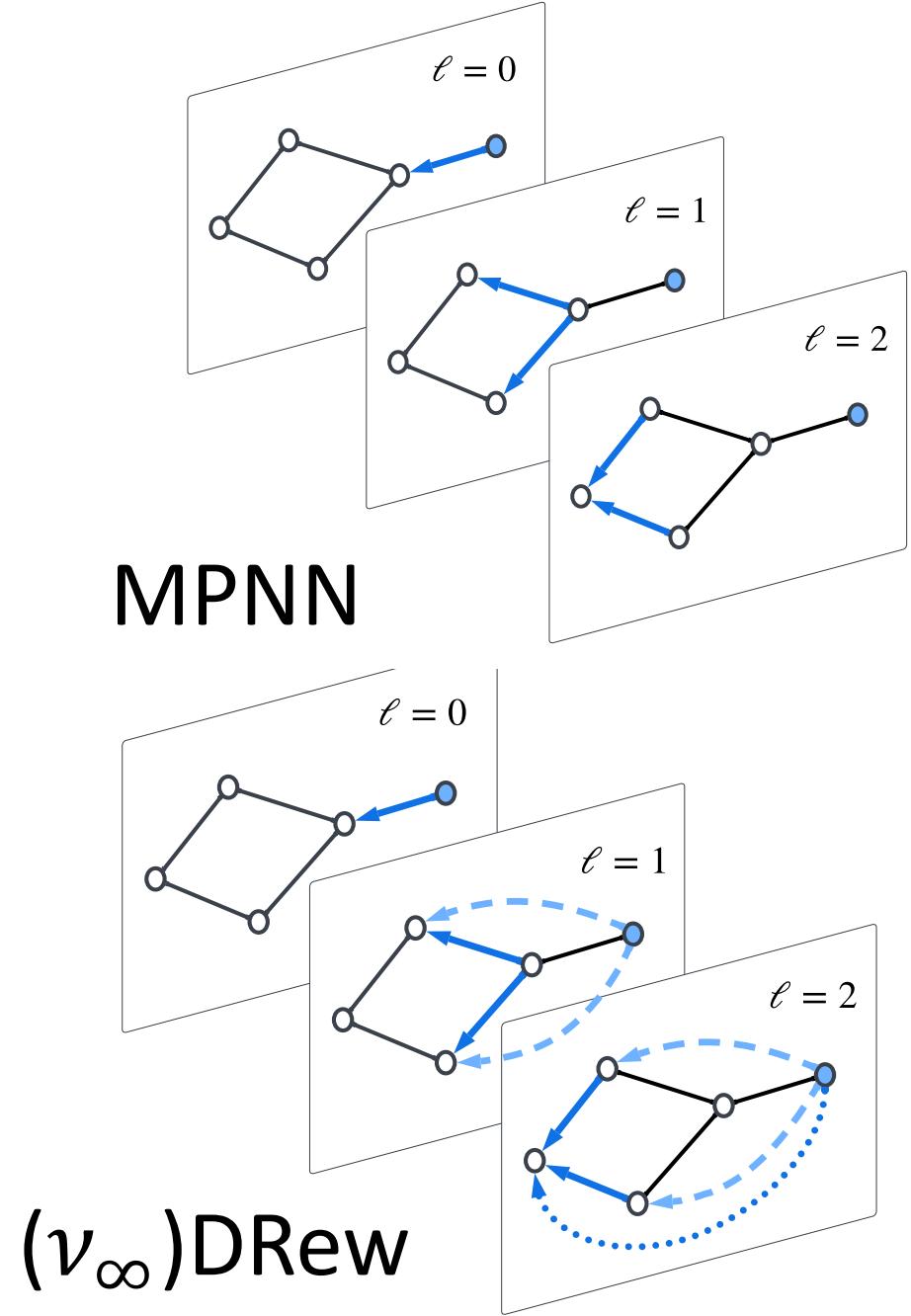
- What if we consider the state of j as it was when the information ‘left’ to flow towards i ?
 - Delay: $\tau_\nu(k) = \max(0, k - \nu)$
- k : current k -hop
 ν : ‘rate’ hyperparameter
➤ (i.e. the hop radius below which node communication is instantaneous)

$$a_{i,k}^{(\ell)} = \text{AGG}_k^{(\ell)} \left(\{ h_j^{(\ell - \tau_\nu(k))} : j \in \mathcal{N}_k(i) \} \right), 1 \leq k \leq \ell + 1$$
$$h_i^{(\ell+1)} = \text{UP}_k^{(\ell)} \left(h_i^{(\ell)}, a_{i,1}^{(\ell)}, \dots, a_{i,\ell+1}^{(\ell)} \right). \quad (6)$$

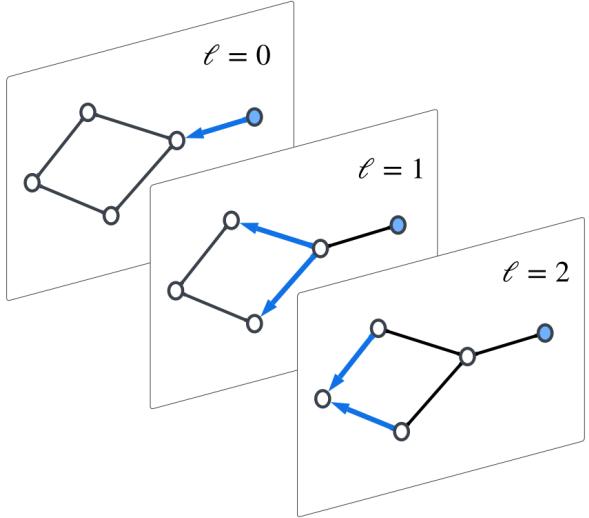


$$a_{i,k}^{(\ell)} = \text{AGG}_k^{(\ell)} \left(\{ h_j^{(\ell-\tau_\nu(k))} : j \in \mathcal{N}_k(i) \} \right), 1 \leq k \leq \ell + 1$$

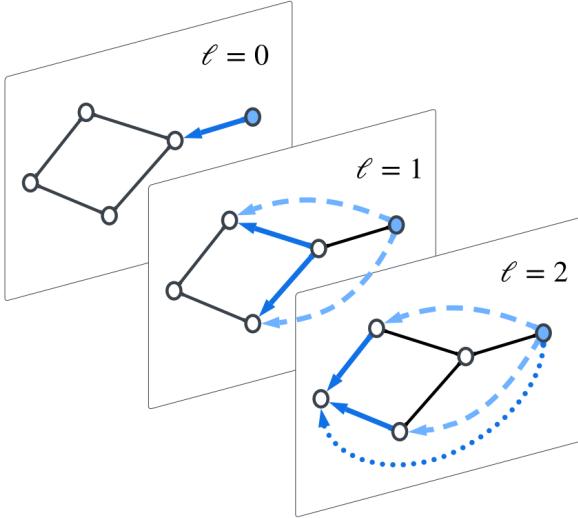
$$h_i^{(\ell+1)} = \text{UP}_k^{(\ell)} \left(h_i^{(\ell)}, a_{i,1}^{(\ell)}, \dots, a_{i,\ell+1}^{(\ell)} \right). \quad (6)$$



The graph-rewiring perspective: ν DRew as distance-aware skip connections

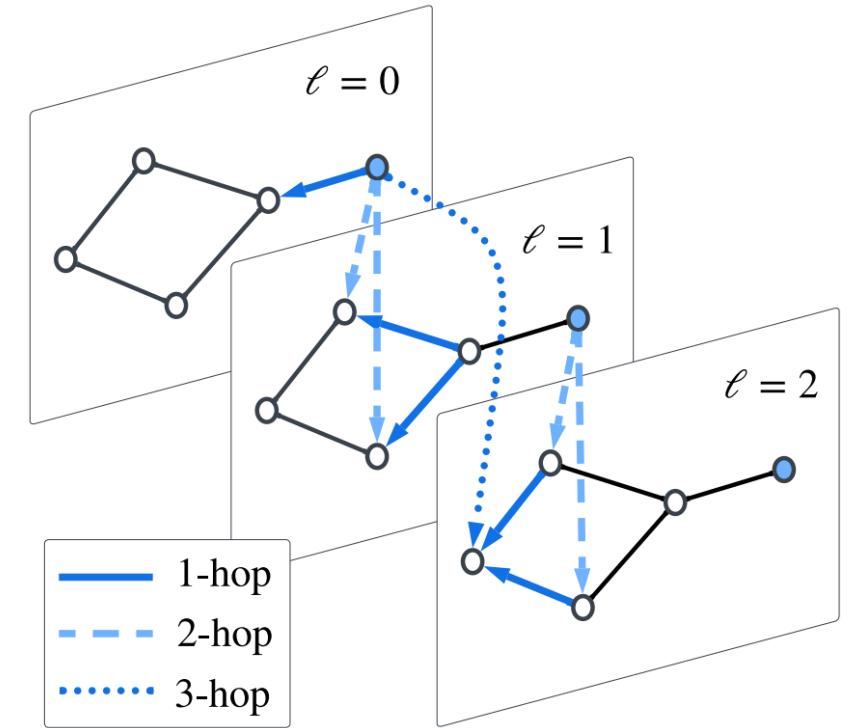


(a) Classical MPNN



(b) DRew

- 1-hop, horizontal only
- Multi-hop, horizontal only
- Computational graph gradually filled



(c) ν DRew

- Multi-hop, horizontal AND vertical skip connections, through distance and time (layer)
- Skip connections between *different* nodes, dependent on geometric distance

DRew instantiations of common MPNNs

- **GCN**
$$h_i^{(\ell+1)} = h_i^{(\ell)} + \sigma \left(\sum_{k=1}^{\ell+1} \sum_{j \in \mathcal{N}_k(i)} \mathbf{W}_k^{(\ell)} \gamma_{ij}^k h_j^{(\ell-\tau_\nu(k))} \right) \quad \gamma_{ij}^k = \begin{cases} \frac{1}{\sqrt{d_i d_j}}, & \text{if } d_G(i, j) = k \\ 0, & \text{otherwise.} \end{cases}$$

$$h_i^{(\ell+1)} = (1 + \epsilon) \text{MLP}_s^{(\ell)}(h_i^{(\ell)}) + \sum_{k=1}^{\ell+1} \sum_{j \in \mathcal{N}_k(i)} \text{MLP}_k^{(\ell)}(h_j^{(\ell-\tau_\nu(k))}),$$

- **GatedGCN**
$$h_i^{(\ell+1)} = \mathbf{W}_1^{(\ell)} h_i^{(\ell)} + \sum_{k=1}^{\ell+1} \sum_{j \in \mathcal{N}_k(i)} \eta_{i,j}^k \odot \mathbf{W}_2^{(\ell)} h_j^{(\ell-\tau_\nu(k))}$$
$$\eta_{i,j}^k = \frac{\hat{\eta}_{i,j}^k}{\sum_{j \in \mathcal{N}_k(i)} (\hat{\eta}_{i,j}^k) + \epsilon},$$
$$\hat{\eta}_{i,j}^k = \sigma \left(\mathbf{W}_3^{(\ell)} h_i^{(\ell)} + \mathbf{W}_4^{(\ell)} h_j^{(\ell-\tau_\nu(k))} \right)$$

Why does ν DRew help with over-squashing?

- Jacobian as a measure of sensitivity between nodes (Topping 2022)
- For vanilla MPNN, same adjacency A used in each layer (i.e. 1-hop aggregation) with which we can bound the Jacobian by power A^r for nodes i, j at hop distance r
- Due to skip connections, ν_1 DRew-GCN's sensitivity bound is different – see below
- Nodes at distance r can now interact via products of message-passing matrices containing fewer than r factors
- Oversquashing arises due to the entries i, j of normalised A^r decaying to zero exponentially with r
- Powers of Γ^k ($\gamma_{i,j} \in \Gamma$) are different unlike A , therefore oversquashing is mitigated

$$\left| \frac{\partial h_i^{(r)}}{\partial h_j^{(0)}} \right| \leq c (A^r)_{ij},$$

$$\left| \frac{\partial h_i^{(r)}}{\partial h_j^{(0)}} \right| \leq C \left(\sum_{k_1 + \dots + k_\ell = r} \left(\prod_{k_1, \dots, k_\ell} (\gamma^k)_{ij} \right) \right)$$

Why does ν DRew help with over-smoothing?

- Over-smoothing occurs because by the time information from node i reaches distant node j , it has been mixed many times with neighbours
- Skip connections with delay allow i to 'see' j before too much local smoothing has occurred
- Choice of delay parameter ν can be considered amount of local smoothing
 - High ν : more local smoothing
 - Low ν : less

Experiments

- Long-range graph benchmark
 - Chemistry and computer vision
 - Graph-, node- and edge-level tasks
- QM9 (see paper)
 - Chemistry, multi-task regression
- RingTransfer
 - Synthetic ‘true’ long-range task
- Peptides-func ablation
 - Demonstrate impact of delay parameter ν for task from LRGB

Performance on real-world datasets

Table 1. Classical MPNN benchmarks vs their DRew variants (without positional encoding) across four LRGB tasks: (from left to right) graph classification, graph regression, link prediction and node classification. All results are for the given metric on test data.

Model	Peptides-func	Peptides-struct	PCQM-Contact	PascalVOC-SP
	AP ↑	MAE ↓	MRR ↑	F1 ↑
GCN	0.5930±0.0023	0.3496±0.0013	0.3234±0.0006	0.1268±0.0060
+DRew	0.6996±0.0076	0.2781±0.0028	0.3444±0.0017	0.1848±0.0107
GINE	0.5498±0.0079	0.3547±0.0045	0.3180±0.0027	0.1265±0.0076
+DRew	0.6940±0.0074	0.2882±0.0025	0.3300±0.0007	0.2719±0.0043
GatedGCN	0.5864±0.0077	0.3420±0.0013	0.3218±0.0011	0.2873±0.0219
+DRew	0.6733±0.0094	0.2699±0.0018	0.3293±0.0005	0.3214±0.0021

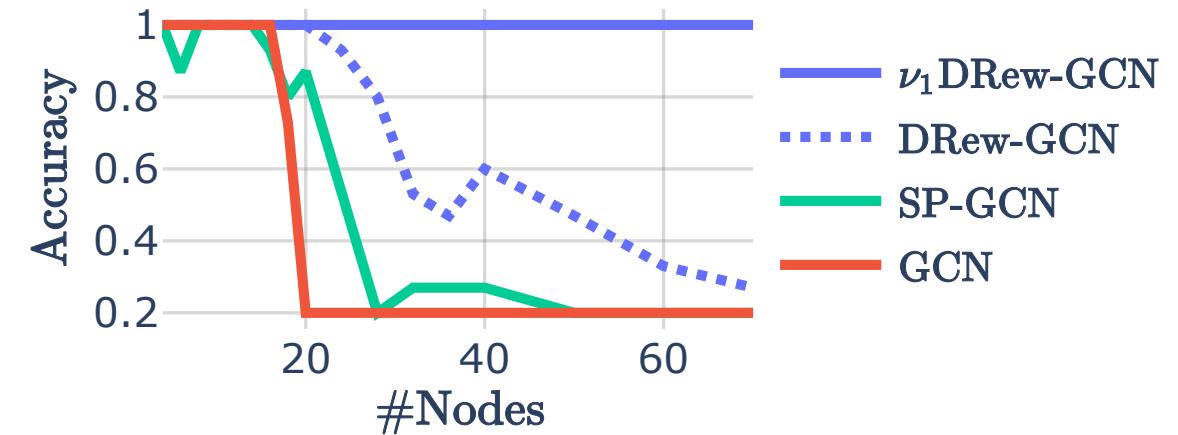
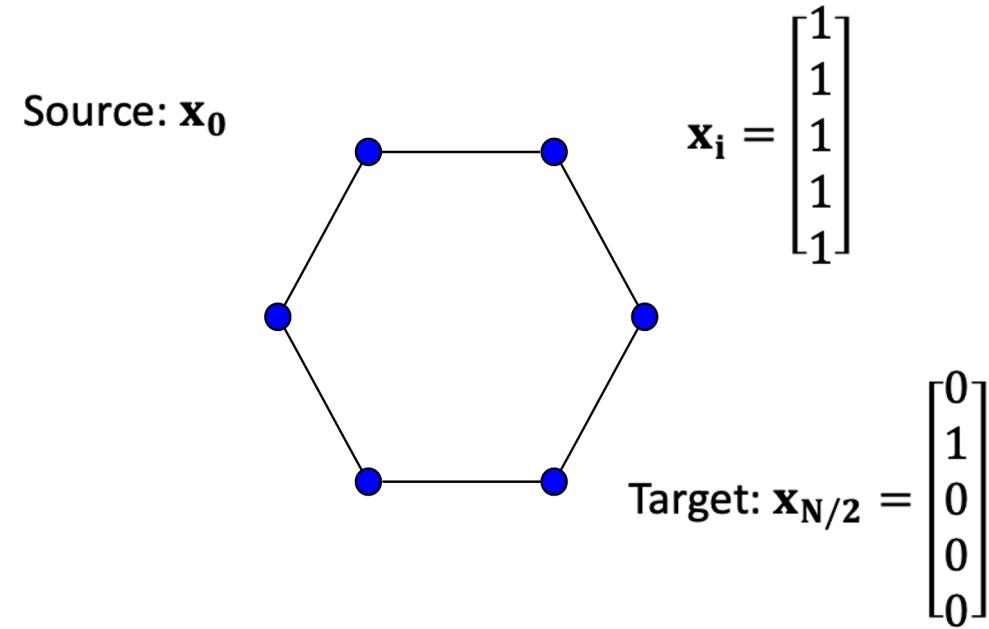
- Tasks from long-range graph benchmark; 4 different tasks
- DRew models **consistently beat their non-DRew counterparts**
- Fixed parameter budget of 500k
- Better performance even though *no edge features used in DRew*
 - for simplicity; we would expect use of edge features to further improve results

Table 2. Performance of various classical, multi-hop and static rewiring MPNN and graph Transformer benchmarks against DRew-MPNNs across four LRGB tasks. The **first**-, **second**- and **third**-best results for each task are colour-coded; models whose performance are within a standard deviation of one another are considered equal.

Model	Peptides-func	Peptides-struct	PCQM-Contact	PascalVOC-SP	
	AP ↑	MAE ↓	MRR ↑	F1 ↑	
Static rewiring benchmark	GCN	0.5930±0.0023	0.3496±0.0013	0.3234±0.0006	0.1268±0.0060
	GINE	0.5498±0.0079	0.3547±0.0045	0.3180±0.0027	0.1265±0.0076
	GatedGCN	0.5864±0.0077	0.3420±0.0013	0.3218±0.0011	0.2873±0.0219
	GatedGCN+PE	0.6069±0.0035	0.3357±0.0006	0.3242±0.0008	0.2860±0.0085
Multi-hop MPNN benchmark	DIGL+MPNN	0.6469±0.0019	0.3173±0.0007	0.1656±0.0029	0.2824±0.0039
	DIGL+MPNN+LapPE	0.6830±0.0026	0.2616±0.0018	0.1707±0.0021	0.2921±0.0038
	MixHop-GCN	0.6592±0.0036	0.2921±0.0023	0.3183±0.0009	0.2506±0.0133
	MixHop-GCN+LapPE	0.6843±0.0049	0.2614±0.0023	0.3250±0.0010	0.2218±0.0174
DRew mostly beating or on-par with Transformers	Transformer+LapPE	0.6326±0.0126	0.2529±0.0016	0.3174±0.0020	0.2694±0.0098
	SAN+LapPE	0.6384±0.0121	0.2683±0.0043	0.3350±0.0003	0.3230±0.0039
	GraphGPS+LapPE	0.6535±0.0041	0.2500±0.0005	0.3337±0.0006	0.3748±0.0109
	DRew-GCN	0.6996±0.0076	0.2781±0.0028	0.3444±0.0017	0.1848±0.0107
	DRew-GCN+LapPE	0.7150±0.0044	0.2536±0.0015	0.3442±0.0006	0.1851±0.0092
	DRew-GIN	0.6940±0.0074	0.2799±0.0016	0.3300±0.0007	0.2719±0.0043
	DRew-GIN+LapPE	0.7126±0.0045	0.2606±0.0014	0.3403±0.0035	0.2692±0.0059
	DRew-GatedGCN	0.6733±0.0094	0.2699±0.0018	0.3293±0.0005	0.3214±0.0021
	DRew-GatedGCN+LapPE	0.6977±0.0026	0.2539±0.0007	0.3324±0.0014	0.3314±0.0024

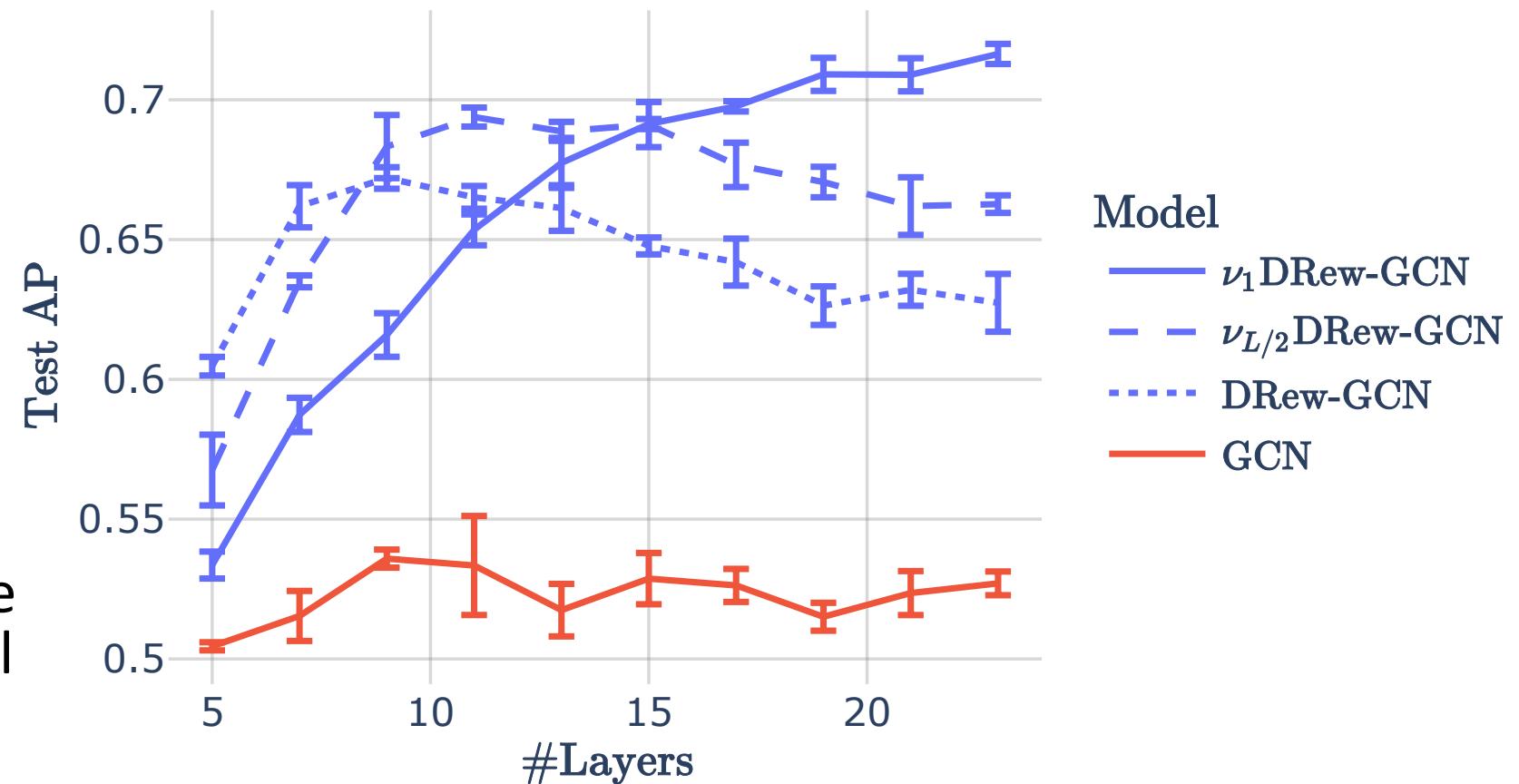
RingTransfer

- Synthetic task for testing LR dependence
- N rings, length n
- Target node must interact with source node $n/2$ hops away
- Fixed $n/2$ layers (needed for interaction)
- $C = 5$ classes
- MPNN/multi-hop MPNN < Drew < Drew + Delay
- MPNN << SP-GCN (multi-hop MPNN) << DRew << DRew + Delay



Fixed d ablation on peptides-func

- Looking at effect of delay hyperparam
- Param constraint lifted
- Delay reduces impact of oversmoothing
- With full delay, performance *improves* with more layers. Very unusual for MPNNs

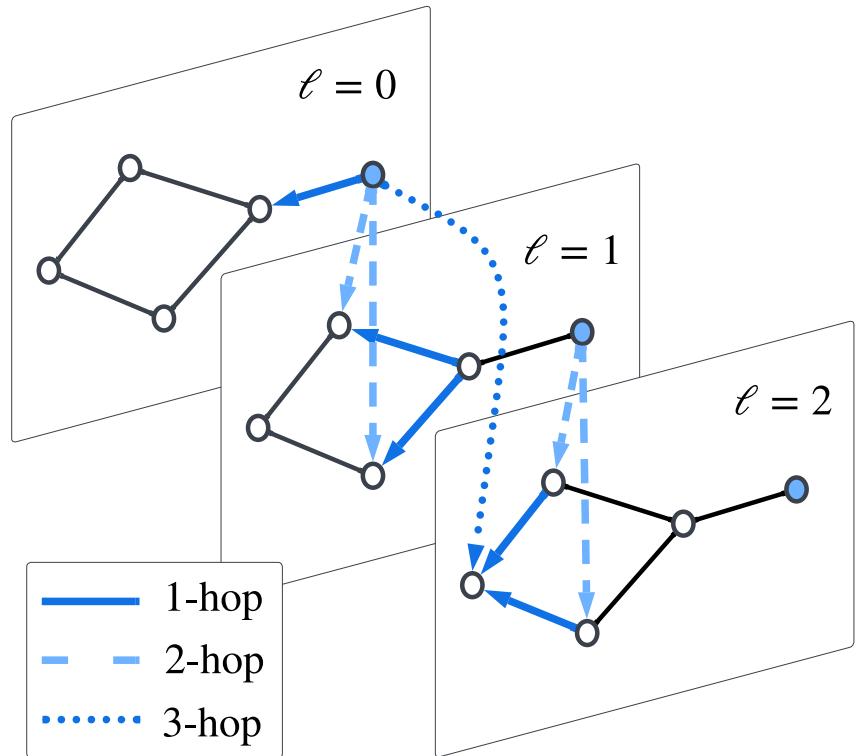


Conclusion

- Two contributions: **Dynamically Rewired** message passing and **Delay**
- Framework applicable to any MPNN
- Reduces over-smoothing and over-squashing
- Improves on vanilla/multi-hop MPNNs, static rewiring approaches and Transformers for synthetic and real-world long-range tasks

Future Work

- Investigating expressive power
- Reduce parameter scaling (good progress already on this front!)
- Alternate distance measures

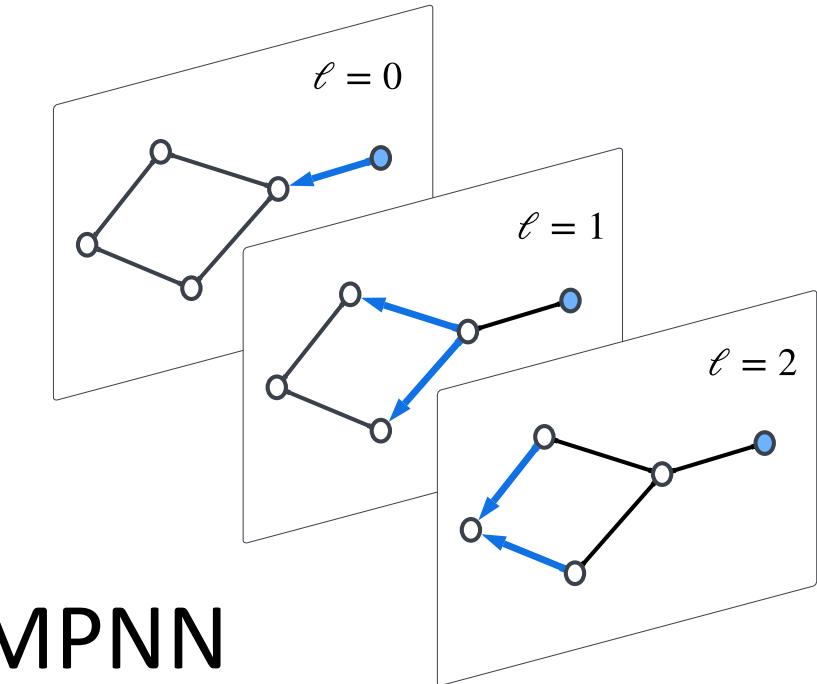


ν_1 DRew

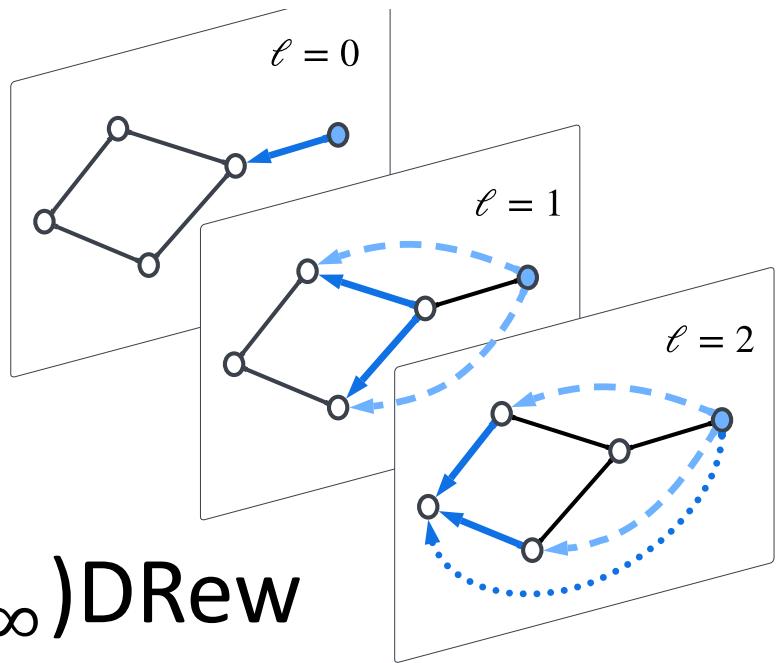
$$a_{i,k}^{(\ell)} = \text{AGG}_k^{(\ell)} \left(\{ h_j^{(\ell - \tau_\nu(k))} : j \in \mathcal{N}_k(i) \} \right), 1 \leq k \leq \ell + 1$$

$$h_i^{(\ell+1)} = \text{UP}_k^{(\ell)} \left(h_i^{(\ell)}, a_{i,1}^{(\ell)}, \dots, a_{i,\ell+1}^{(\ell)} \right). \quad (6)$$

Thanks for
watching!



MPNN



(ν_∞) DRew