

# Plaidypvs Cheat Sheet

## Propositional dL rules

<b>notR</b>	$\frac{\Gamma, P \vdash \Delta}{\Gamma \vdash \neg P, \Delta}$	<b>impliesR</b>	$\frac{\Gamma, P \vdash Q, \Delta}{\Gamma \vdash P \rightarrow Q, \Delta}$
<b>notL</b>	$\frac{\Gamma \vdash P, \Delta}{\Gamma, \neg P \vdash \Delta}$	<b>impliesL</b>	$\frac{\Gamma \vdash P, \Delta \quad \Gamma, Q \vdash \Delta}{\Gamma, P \rightarrow Q \vdash \Delta}$
<b>andR</b>	$\frac{\Gamma \vdash P, \Delta \quad \Gamma \vdash Q, \Delta}{\Gamma \vdash P \wedge Q, \Delta}$	<b>iffR</b>	$\frac{\Gamma, P \vdash Q, \Delta \quad \Gamma, Q \vdash P, \Delta}{\Gamma \vdash P \leftrightarrow Q, \Delta}$
<b>andL</b>	$\frac{\Gamma, P, Q \vdash \Delta}{\Gamma, P \wedge Q \vdash \Delta}$	<b>iffL</b>	$\frac{\Gamma, P \wedge Q \vdash \Delta \quad \Gamma, \neg P \wedge \neg Q \vdash \Delta}{\Gamma, P \leftrightarrow Q \vdash \Delta}$
<b>orR</b>	$\frac{\Gamma \vdash P \vee Q, \Delta}{\Gamma \vdash P, Q, \Delta}$	<b>falseL</b>	$\frac{}{\Gamma, \perp \vdash \Delta}$
<b>orL</b>	$\frac{\Gamma, P \vdash \Delta \quad \Gamma, Q \vdash \Delta}{\Gamma, P \vee Q \vdash \Delta}$	<b>trueR</b>	$\frac{}{\Gamma \vdash \top, \Delta}$
<b>cut</b>	$\frac{\Gamma \vdash C, \Delta \quad \Gamma, C \vdash \Delta}{\Gamma \vdash \Delta}$	<b>axiom</b>	$\frac{}{\Gamma, P \vdash P, \Delta}$
<b>weakR</b>	$\frac{\Gamma \vdash P, \Delta \quad P \vdash Q}{\Gamma \vdash Q, \Delta}$	<b>weakL</b>	$\frac{P, \Gamma \vdash \Delta \quad Q \vdash P}{\Gamma, Q \vdash \Delta}$

- flatten** Disjunctively simplifies the dL sequent by applying **trueR**, **falseR**, **orR**, **impliesR**, **notR**, **axiom**, **falseL**.
- ground** Disjunctively and conjunctively simplifies the dL sequent by applying **flatten** and additional splitting lemmas **andR**, **orL**, and **impliesL**.
- inst** Instantiates a universal quantifier in the dL-antecedent by applying **forallL** or an existential quantifier in the dL-consequent by applying **existsL**.
- skolem** Skolemizes an existential quantifier in dL-antecedent by applying **existsR** or an universal quantifier in the dL-consequent by applying **forallR**.
- grind** Repeatedly uses **ground** and **skolem**, and a number of rewrites related to real expressions. This strategy has the option to use the MetiTarski automatic theorem prover as an outside oracle to discharge the proof if possible.

### Quantifier rules

$$\begin{array}{l}
\text{existsR} \frac{\Gamma \vdash p(e), \Delta}{\Gamma \vdash \exists x : p(x), \Delta} \text{ (any } e\text{)} \\
\text{forallL} \frac{\Gamma, p(e) \vdash \Delta}{\Gamma, \forall x : p(x) \vdash \Delta} \text{ (any } e\text{)} \\
\text{forallR} \frac{\Gamma \vdash p(y), \Delta}{\Gamma \vdash \forall x : p(x), \Delta} \text{ (} y \text{ Skolem symbol)} \\
\text{existsL} \frac{\Gamma, p(y) \vdash \Delta}{\Gamma, \exists x : p(x) \vdash \Delta} \text{ (} y \text{ Skolem symbol)}
\end{array}$$

### Structural rules

$$\begin{array}{ll}
\text{moveR} \frac{\Gamma \vdash Q, P, \Delta}{\Gamma \vdash P, Q, \Delta} & \text{hideR} \frac{\Gamma \vdash \Delta}{\Gamma \vdash P, \Delta} \\
\text{moveL} \frac{\Gamma, Q, P \vdash \Delta}{\Gamma, P, Q \vdash \Delta} & \text{hideL} \frac{\Gamma \vdash \Delta}{\Gamma, P \vdash \Delta}
\end{array}$$

### Hybrid program rewrites

$$\begin{array}{l}
\text{boxd} \langle \alpha \rangle P \leftrightarrow \neg [\alpha] \neg P \\
\text{assignb} [x := \ell] P = \text{SUB}(\ell)(P) \\
\text{assignd} \langle x := \ell_2 \rangle P = \text{SUB}(\ell)(P) \\
\text{testb} [?Q] P = Q \rightarrow P \\
\text{testd} \langle ?Q \rangle P = Q \wedge P \\
\text{choiceb} [\alpha_1 \cup \alpha_2] P \leftrightarrow [\alpha_1] P \wedge [\alpha_2] P \\
\text{choiced} \langle \alpha_1 \cup \alpha_2 \rangle P \leftrightarrow \langle \alpha_1 \rangle P \wedge \langle \alpha_2 \rangle P \\
\text{composeb} [\alpha_1; \alpha_2] P \leftrightarrow [\alpha_1] [\alpha_2] P \\
\text{composed} \langle \alpha_1; \alpha_2 \rangle P \leftrightarrow \langle \alpha_1 \rangle \langle \alpha_2 \rangle P \\
\text{iterateb} [\alpha^*] P = P \wedge [\alpha] [\alpha^*] P \\
\text{iterated} \langle \alpha^* \rangle P = P \vee \langle \alpha \rangle \langle \alpha^* \rangle P \\
\text{anyb} [x := * \& Q(x)] P(x) = \forall x : Q(x) \rightarrow P(x) \\
\text{anyd} \langle x := * \& Q(x) \rangle P(x) = \exists x : Q(x) \rightarrow P(x)
\end{array}$$

**Hybrid program rules**

<b>Mb</b>	$\frac{\vdash P \rightarrow Q}{\Gamma \vdash [\alpha] P \rightarrow [\alpha] Q, \Delta}$	<b>Gb</b>	$\frac{\vdash P}{\Gamma \vdash [\alpha] P, \Delta}$
<b>Md</b>	$\frac{\vdash P \rightarrow Q}{\Gamma \vdash \langle \alpha \rangle P \rightarrow \langle \alpha \rangle Q, \Delta}$	<b>Gd</b>	$\frac{\vdash P}{\Gamma \vdash \langle \alpha \rangle P, \Delta}$
<b>K</b>	$\frac{\Gamma \vdash [\alpha] (P \rightarrow Q), \Delta}{\Gamma \vdash [\alpha] P \rightarrow [\alpha] Q, \Delta}$	<b>VRb</b>	$\frac{\Gamma \vdash P, \Delta}{\Gamma \vdash [\alpha] P, \Delta} \text{ fresh?}(P)(\text{bv}(\alpha))$
<b>loop</b>	$\frac{\Gamma \vdash [\alpha^*] P, \Delta}{\Gamma \vdash [\alpha] P, \Delta}$	<b>VRd</b>	$\frac{\Gamma \vdash P, \Delta}{\Gamma \vdash \langle \alpha \rangle P, \Delta} \text{ fresh?}(P)(\text{bv}(\alpha))$
<b>mbR</b>	$\frac{\Gamma \vdash [\alpha] Q, \Delta \quad Q \vdash P}{\Gamma \vdash [\alpha] P, \Delta}$	<b>mdR</b>	$\frac{\Gamma \vdash \langle \alpha \rangle Q, \Delta \quad Q \vdash P}{\Gamma \vdash \langle \alpha \rangle P, \Delta}$
<b>mbL</b>	$\frac{\Gamma, [\alpha] Q \vdash \Delta \quad P \vdash Q}{\Gamma, [\alpha] P \vdash \Delta}$	<b>mdL</b>	$\frac{\Gamma, \langle \alpha \rangle Q \vdash \Delta \quad P \vdash Q}{\Gamma, \langle \alpha \rangle P \vdash \Delta}$
<b>ghost</b>	$\frac{\Gamma \vdash [y := e] P, \Delta}{\Gamma \vdash P, \Delta} \text{ fresh?}(y)$		

**Differential equation rules**

<b>dinit</b>	$\frac{\Gamma, Q \vdash [x' = f(x) \& Q] P, \Delta}{\Gamma \vdash [x' = f(x) \& Q] P, \Delta}$
<b>dW</b>	$\frac{Q \vdash P}{\Gamma \vdash [x' = f(x) \& Q] P, \Delta}$
<b>dI</b>	$\frac{Q \vdash [x' := f(x)] (P)'}{P \vdash [x' = f(x) \& Q] P, \Delta}$
<b>dC</b>	$\frac{\Gamma \vdash [x' = f(x) \& Q] C, \Delta \quad \Gamma \vdash [x' = f(x) \& (Q \wedge C)] P, \Delta}{P \vdash [x' = f(x) \& Q] P, \Delta}$
<b>dG</b>	$\frac{\Gamma \vdash G, G \vdash P, \Gamma \vdash \exists y [x' = f(x), y' = a(x) \cdot y + b(x) \& Q] G, \Delta}{\Gamma \vdash [x' = f(x) \& Q] P, \Delta}$
<b>dS</b>	$\frac{\Gamma \vdash [x' = f(x) \& Q] P}{\Gamma \vdash \forall t \geq 0 (\forall 0 \leq s \leq t Q(y(s))) \rightarrow [x := y(t)] P}$