CS2020 Data Structures and Algorithms (Recitation)

Welcome!

Today

2-3-4 Trees:

New type of balanced search tree

Cache Aware Algorithms

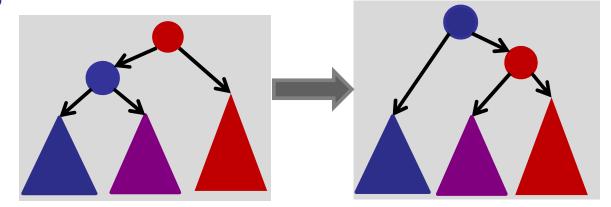
- Modeling cache performance
- B-trees

Balanced Search Trees

Many types:

- AVL trees
- Red-Black trees
- Splay trees
- **–** ...

All use rotations

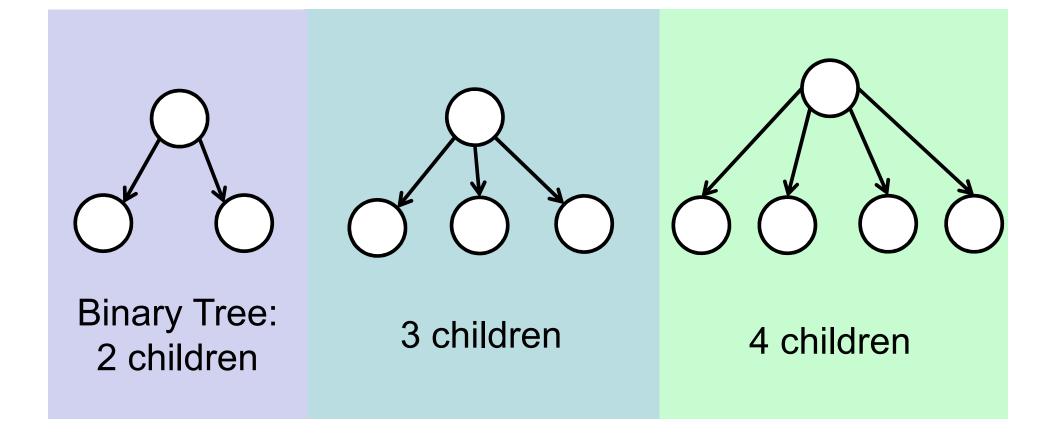


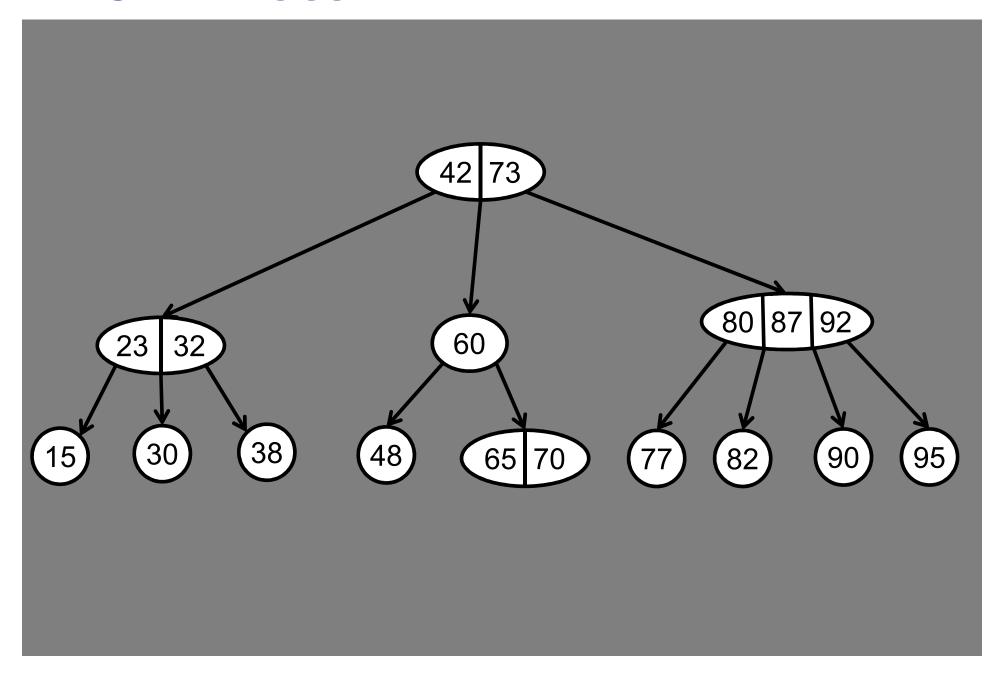
- Complicated and unintuitive
- Concurrency is hard
- Messy: lots of case analysis

Rule # 1:

– Every non-leaf node has either:

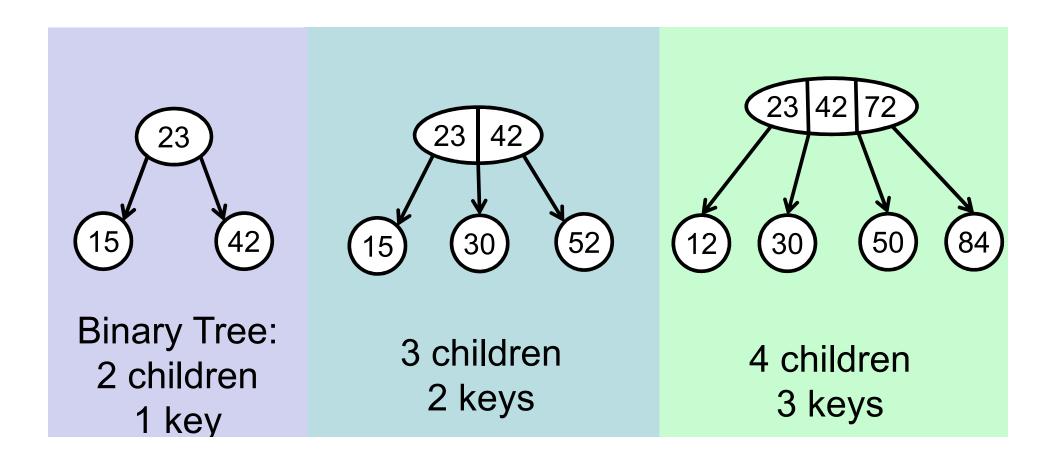
2 or 3 or 4 children





Rule # 2:

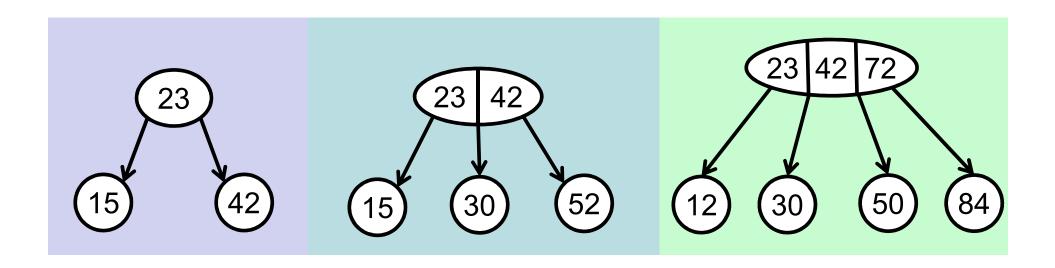
Satisfies binary search property

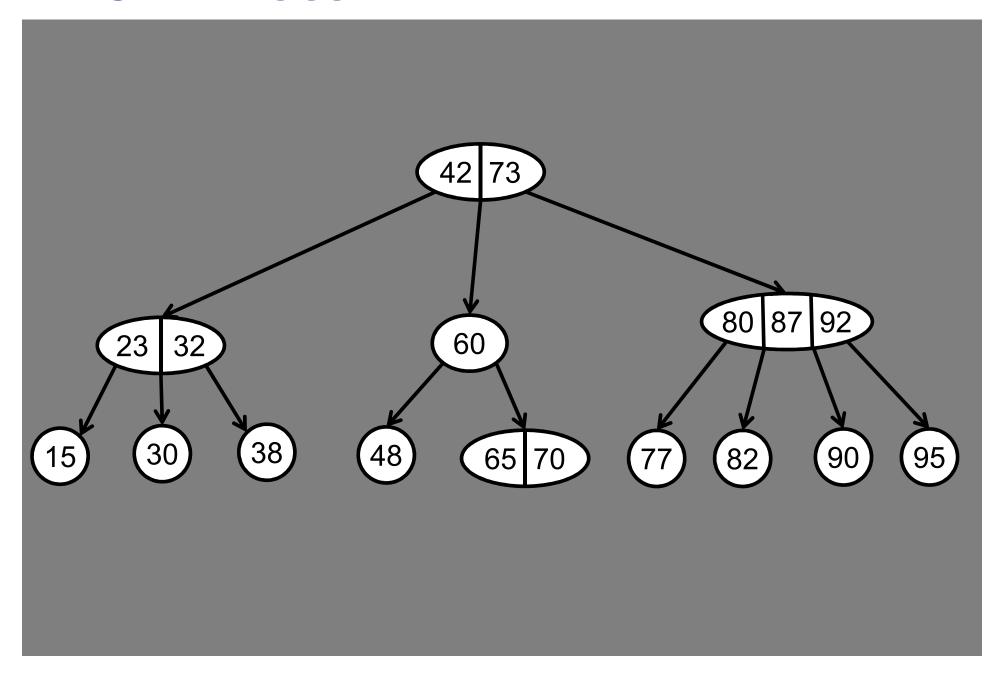


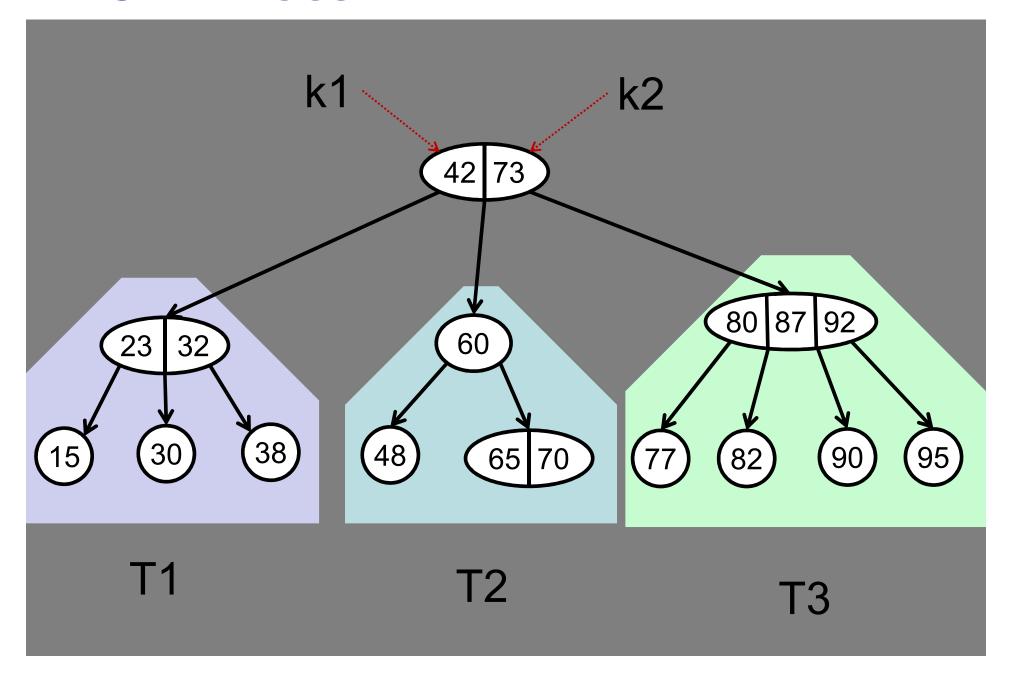
Rule # 2:

Satisfies binary search property

Node contains keys $\{k_1, ..., k_r\}$, $r \in \{1,2,3\}$ Node contains subtrees $\{T_1, ..., T_{r+1}\}$, $r \in \{1,2,3\}$





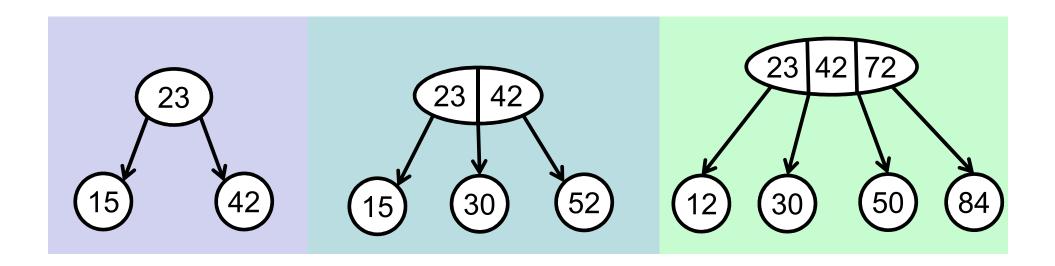


Rule # 2:

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Node contains keys $\{k_1, ..., k_r\}$, $r \in \{1,2,3\}$ Node contains subtrees $\{T_1, ..., T_{r+1}\}$, $r \in \{1,2,3\}$

$$keys(T_1) < k_1 < keys(T_2) < k_1 < keys(T_3) < k_3 < keys(T_4)$$

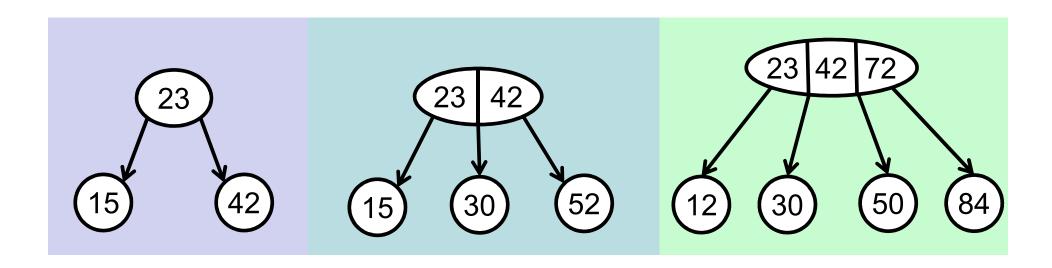


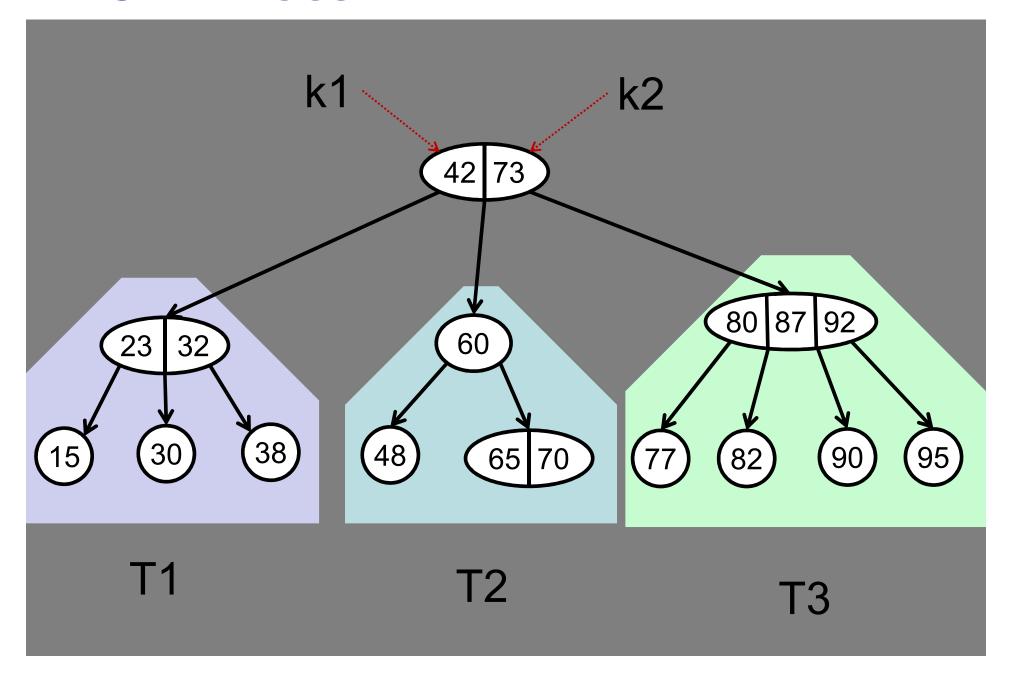
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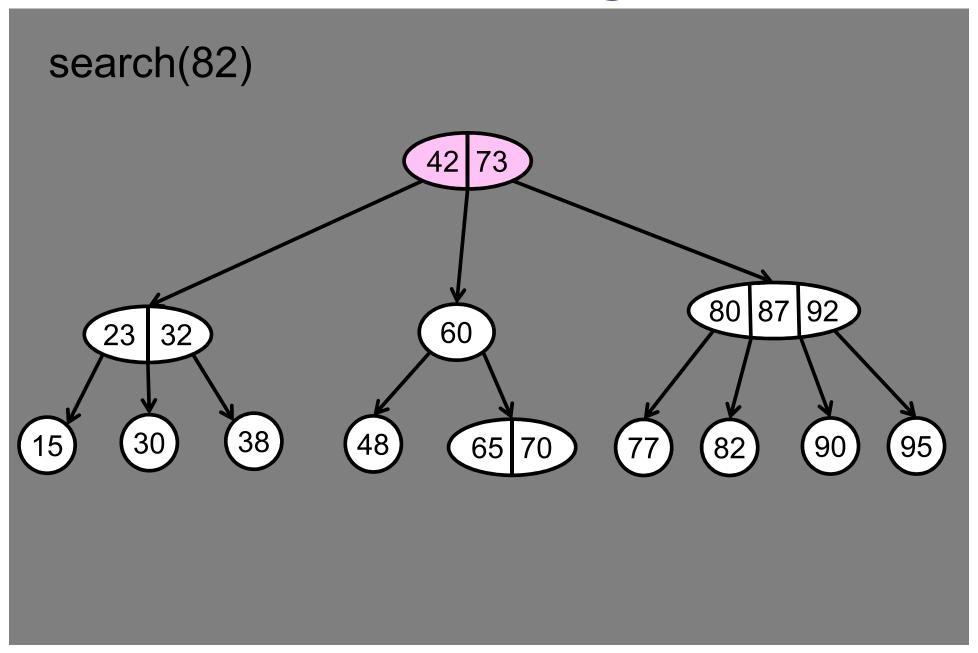
Node contains keys $\{k_1, ..., k_r\}$, $r \in \{1,2,3\}$ Node contains subtrees $\{T_1, ..., T_{r+1}\}$, $r \in \{1,2,3\}$

$$\forall r \in \{1,2,3\}: keys(T_r) < k_r < keys(T_{r+1})$$

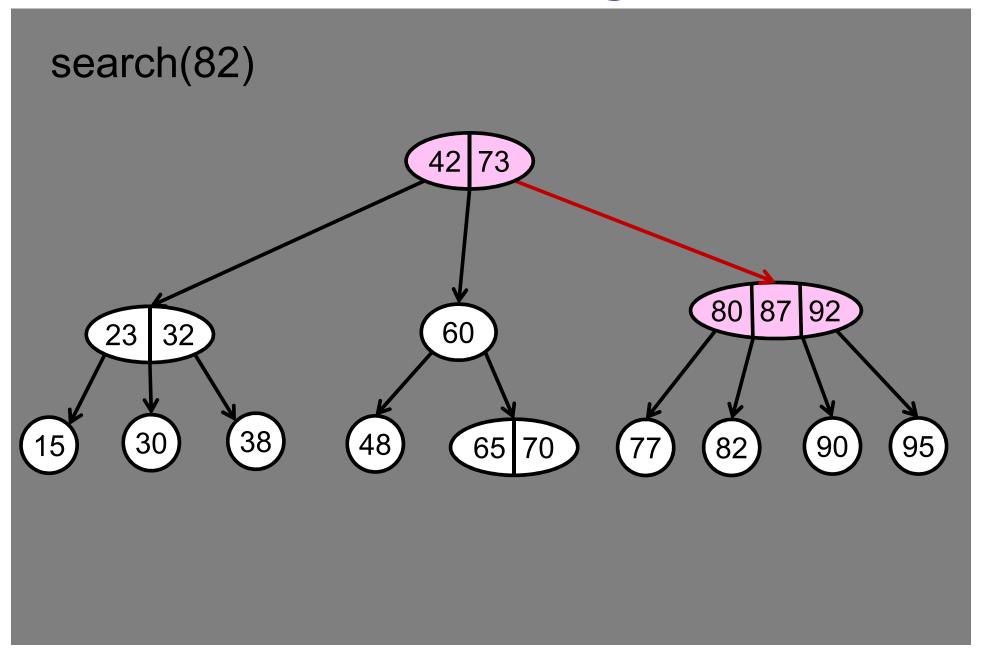




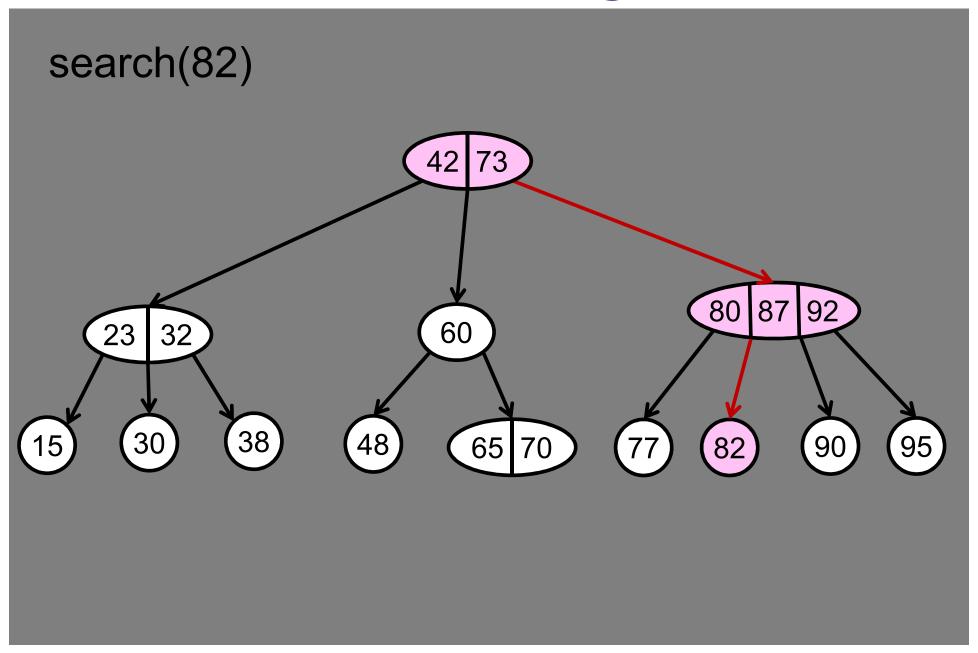
2-3-4 Trees: Searching



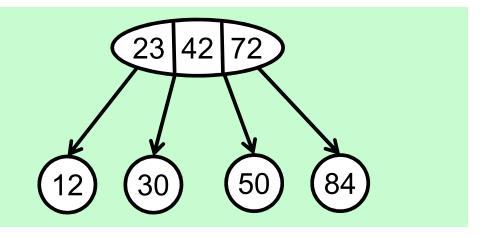
2-3-4 Trees: Searching

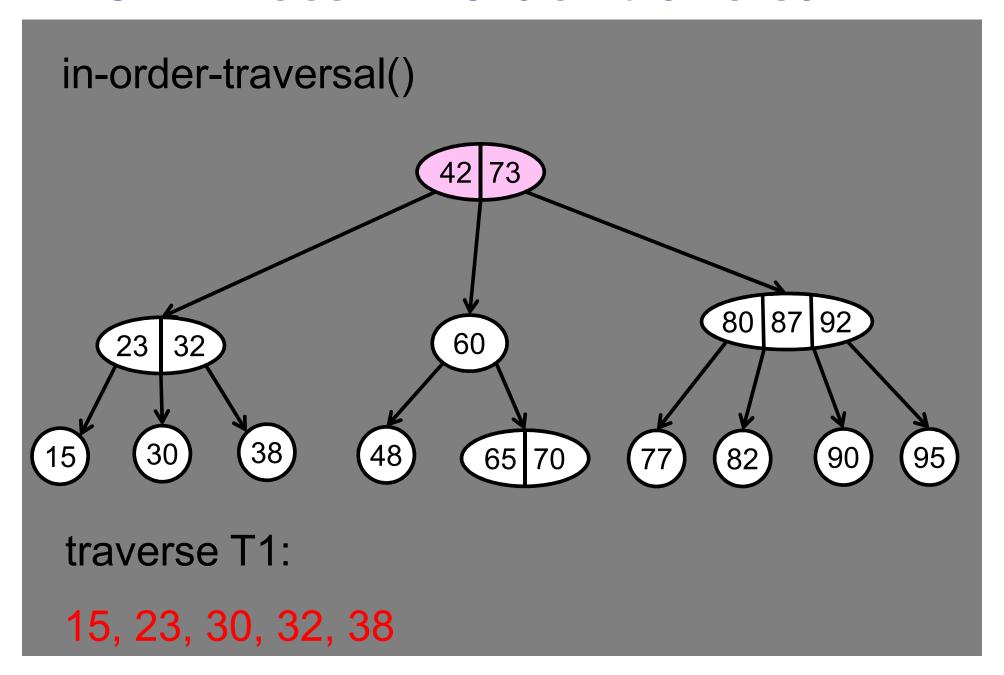


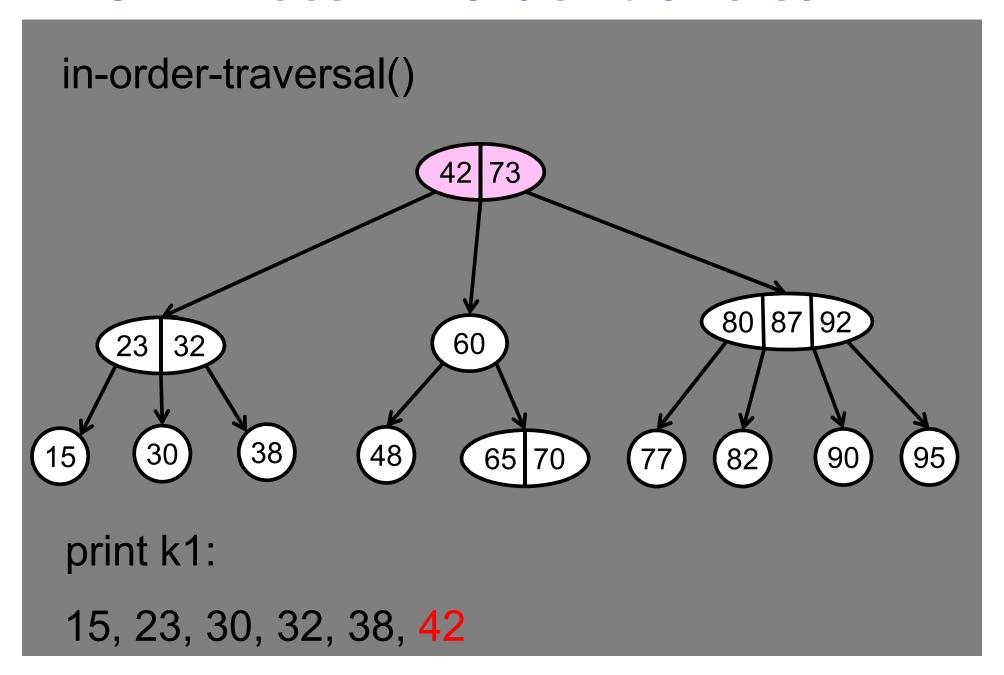
2-3-4 Trees: Searching

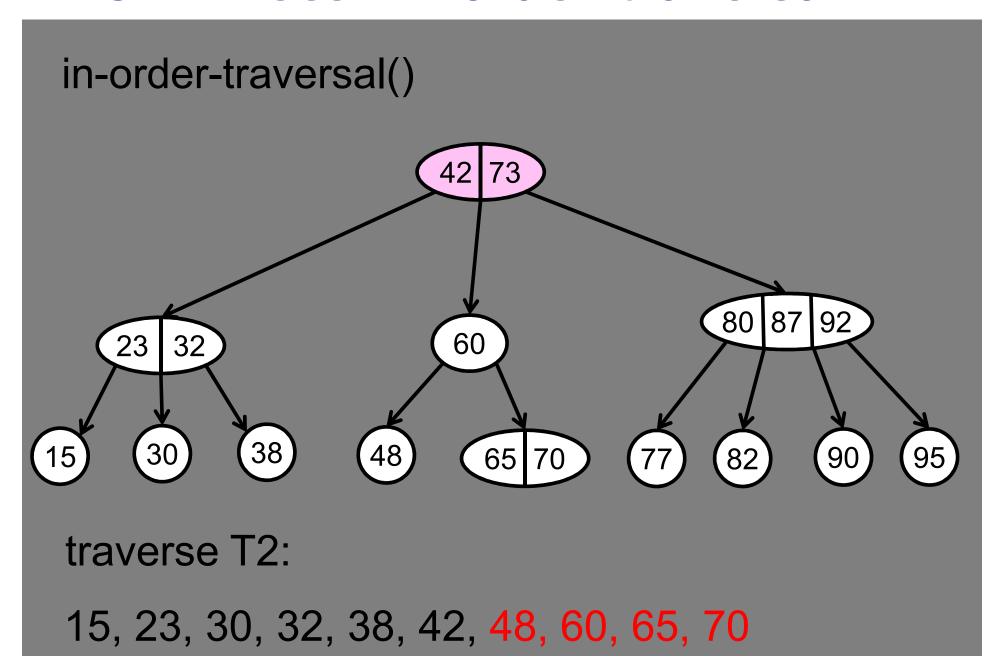


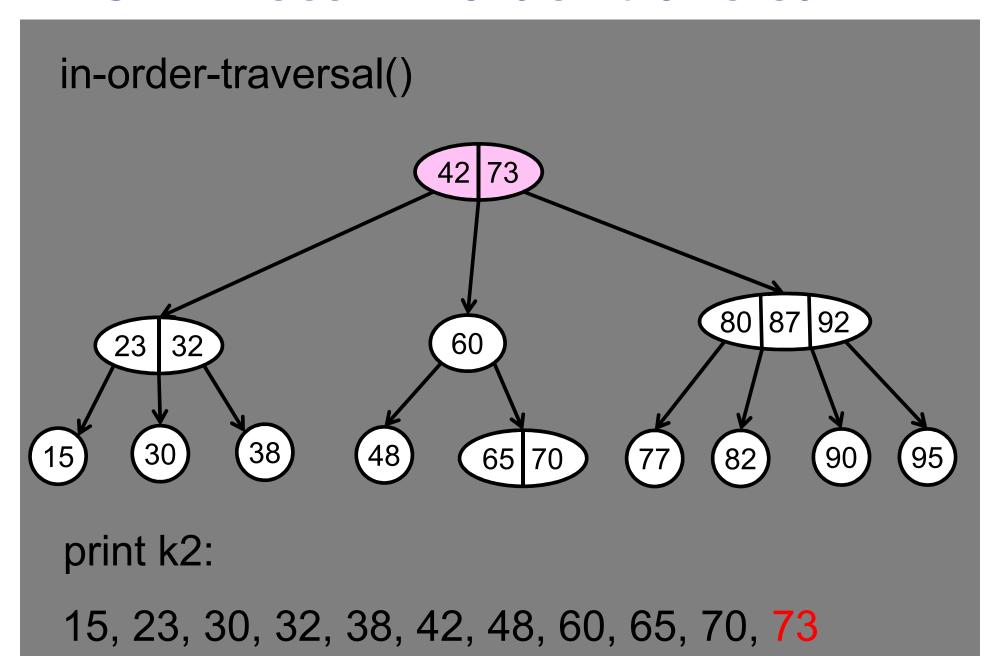
```
search(k): j = 1; while (j \le num\_keys) and (k > k_j) do j++; if (j \le num\_keys) and (k == k_j) then return true; else if (T_j != null) then return T_j.search(k); else return false;
```

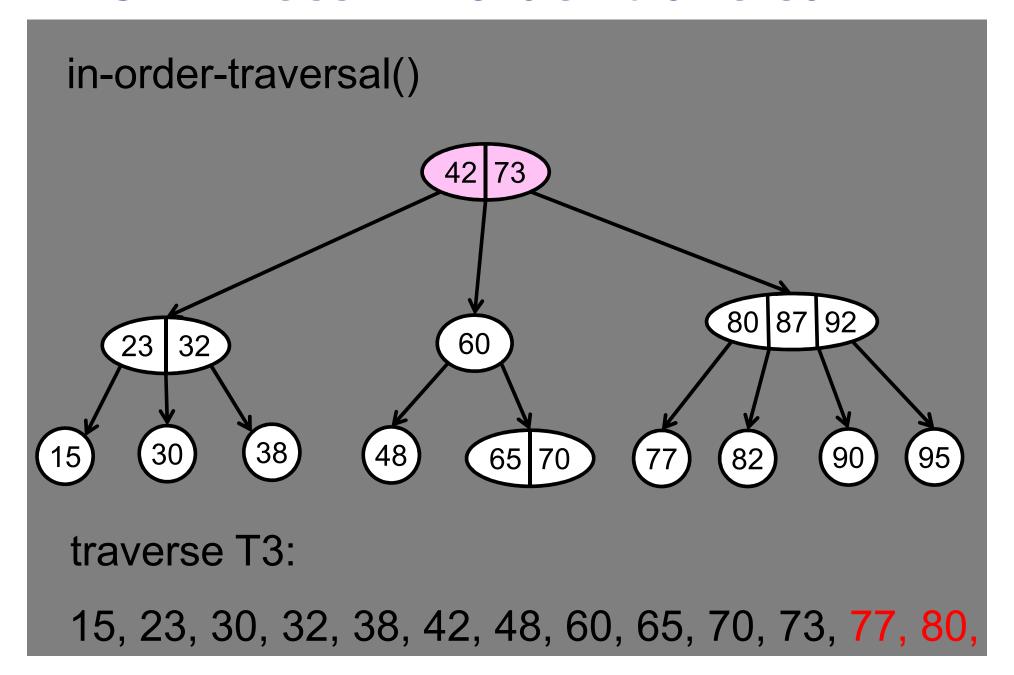






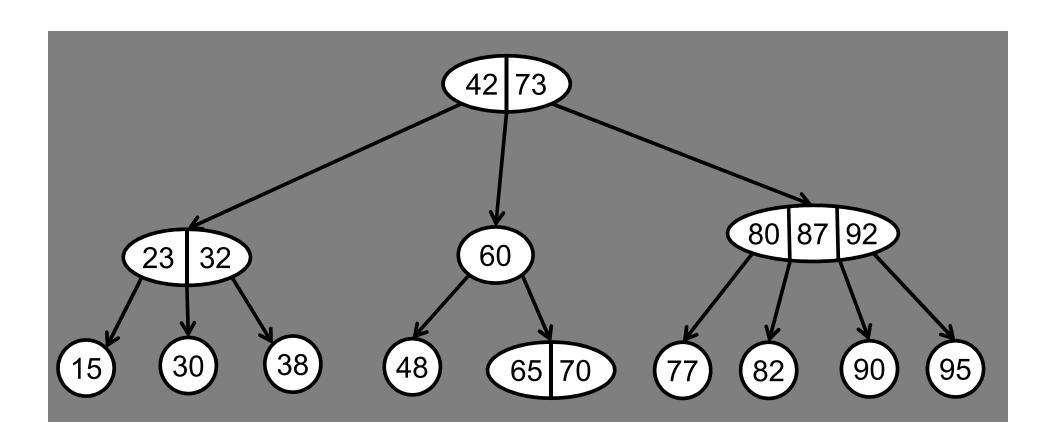






Rule #3: Every leaf has the same depth.

Every path from root->leaf is the same length.



Claim: a B-tree with n keys has height O(log n)

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Intuition:

- Every node has at least two children.
- When the height increases by 1, the number of keys doubles.
- After log(n) levels, there are at least n keys.

Claim: h < c log n

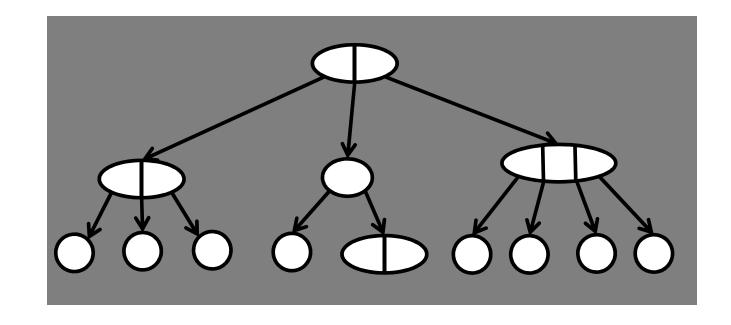
Proof:

depth = 0: 1

depth = 1: 2

depth = 2: 4

depth = 3: 8



. . .

$$depth = h: 2^h$$

$$n \ge 1 + 2 + 4 + 8 + \dots + 2^h = \sum_{j=0}^{n} 2^j$$

Math Intermission

Prove:
$$\sum_{j=1}^{h} 2^{j} = 2^{h+1} - 1$$

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Induction:

- Base case: h=0

$$\sum_{j=0}^{0} 2^{j} = 2^{0} = 1 = 2^{1} - 1 = 2^{h+1} - 1$$

Math Intermission

Prove:
$$\sum_{j=0}^{h} 2^{j} = 2^{h+1} - 1$$

Inductive step:
$$\sum_{j=0}^{h} 2^{j} = 2^{h} + \sum_{j=0}^{h-1} 2^{j}$$

$$= 2^h + \left(2^h - 1\right)$$

$$= 2^{h+1} - 1$$

Claim: $h = O(\log n)$

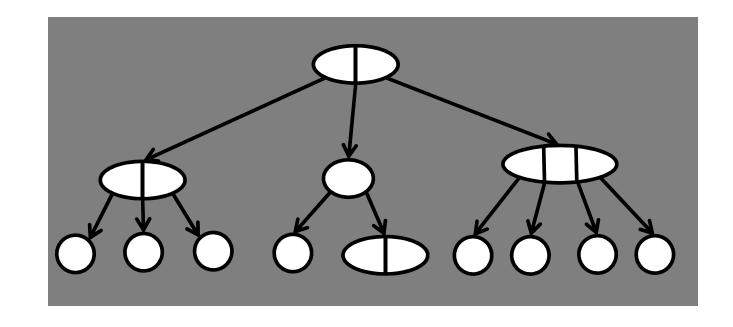
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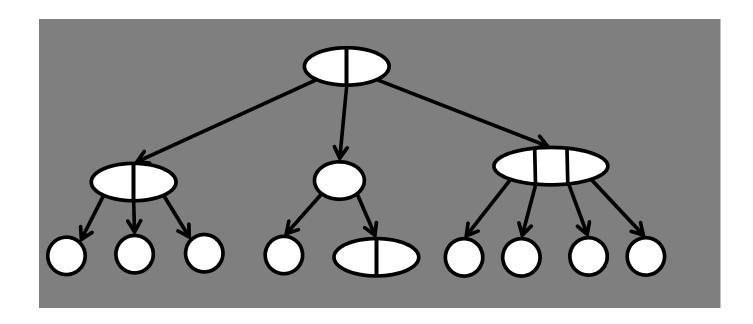


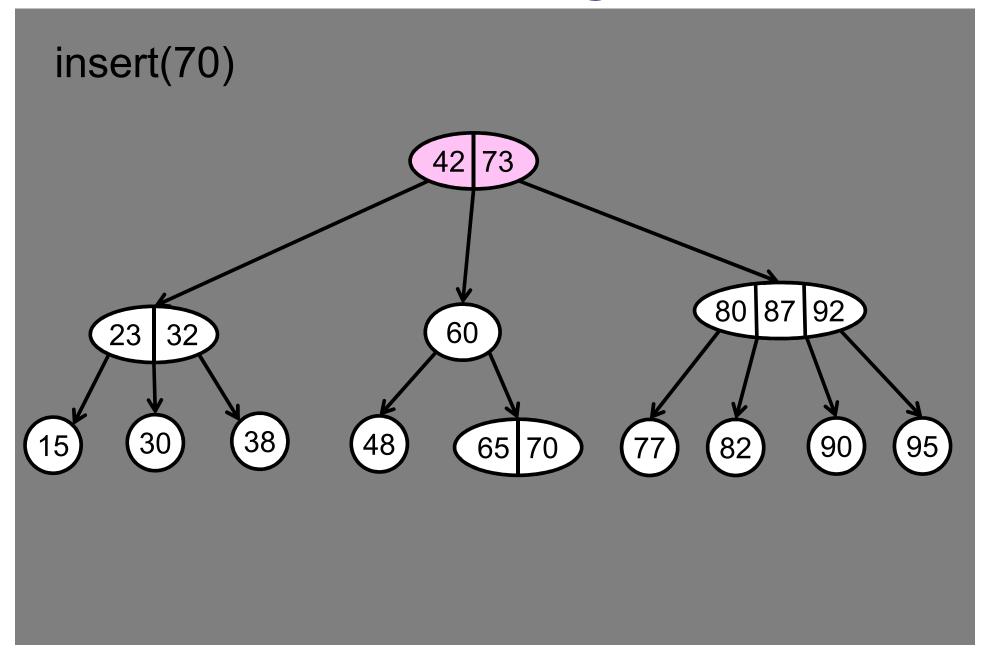
...

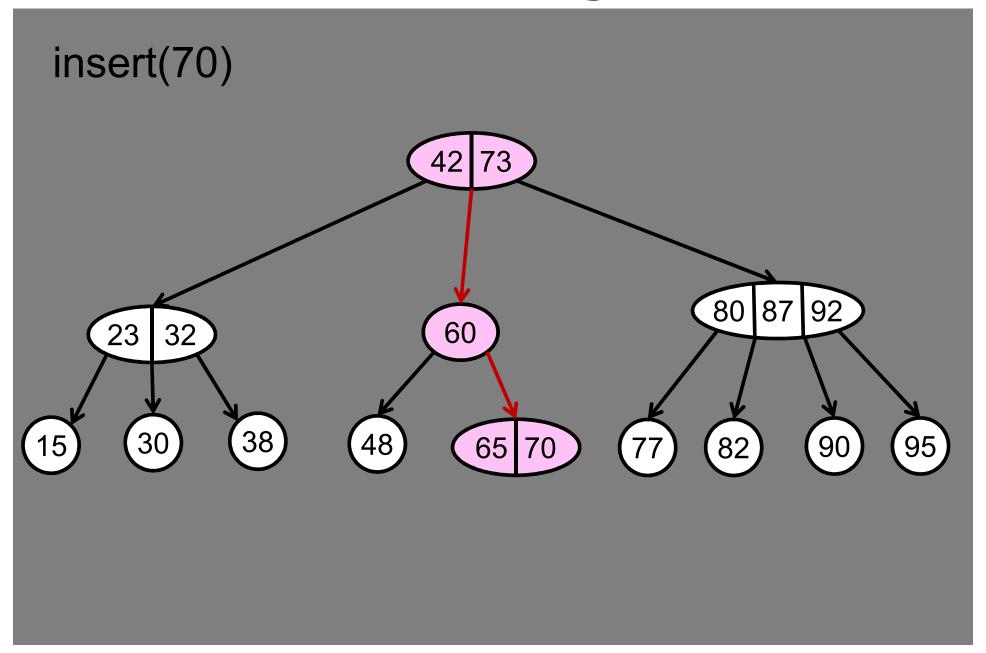
 $depth = h: 2^h$

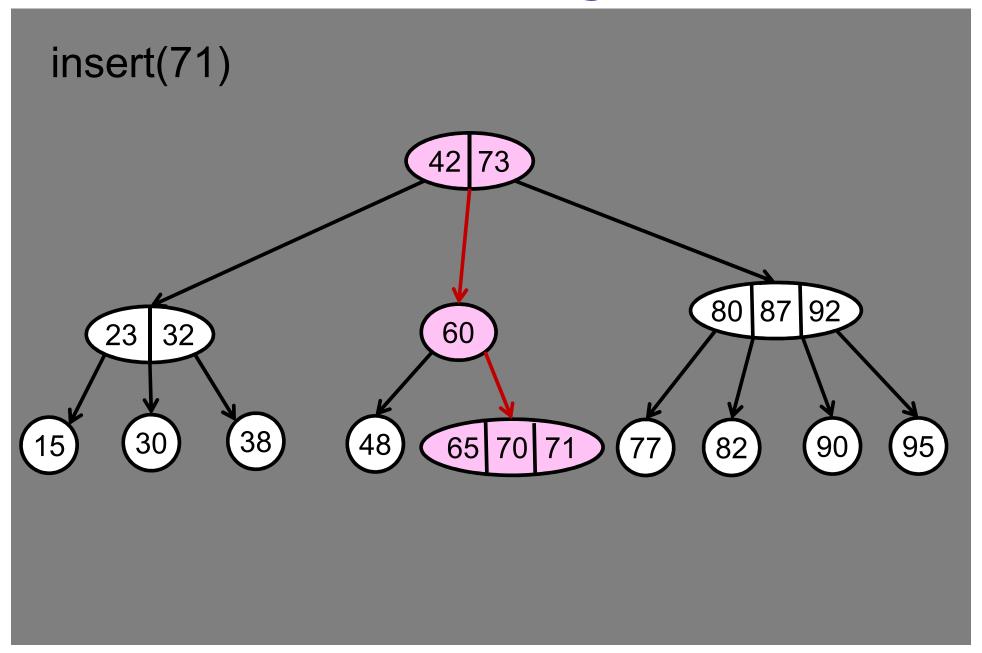
$$n \ge 1 + 2 + 4 + 8 + \ldots + 2^h = \sum_{j=0}^h 2^j = 2^{h+1} - 1$$

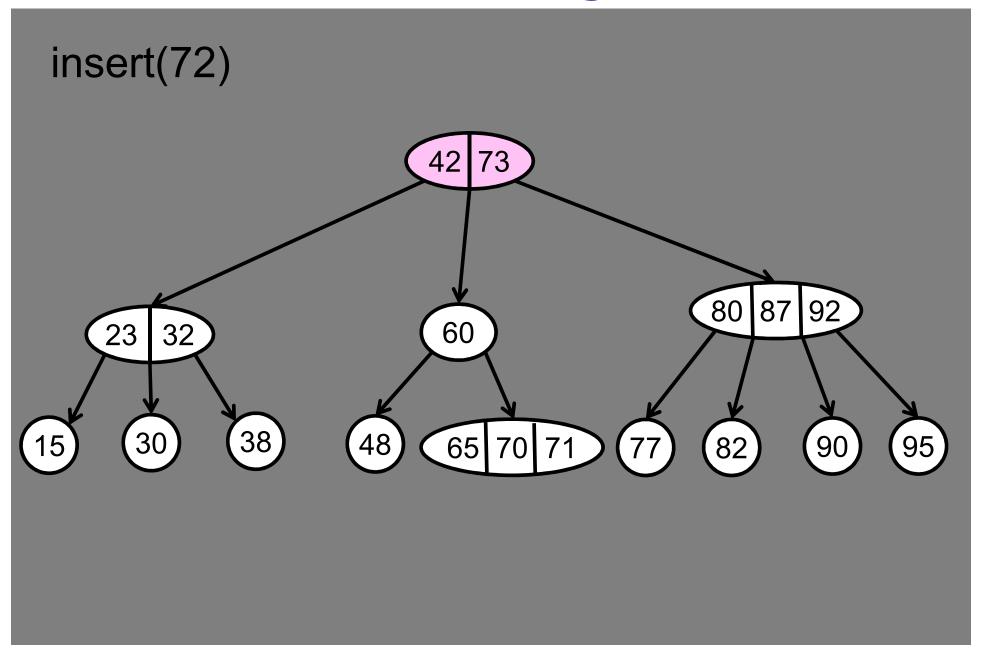
search: O(log n)

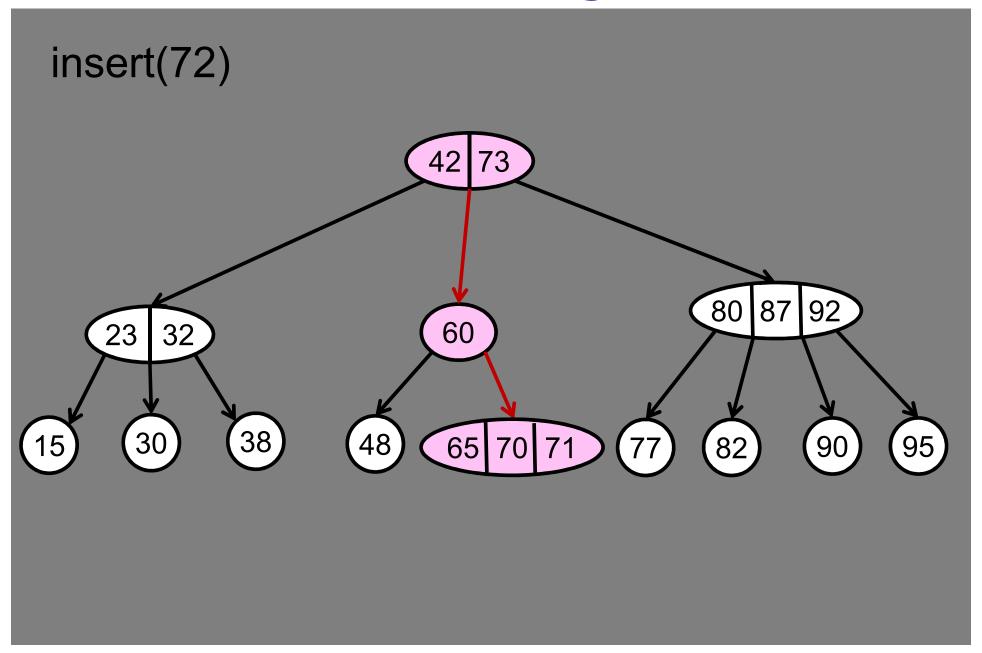


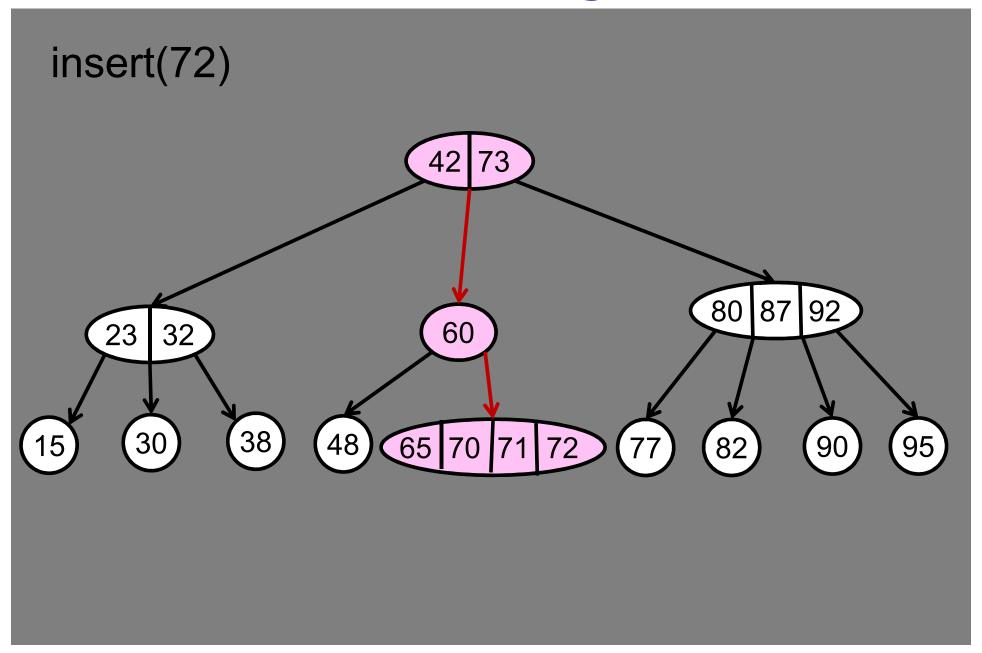


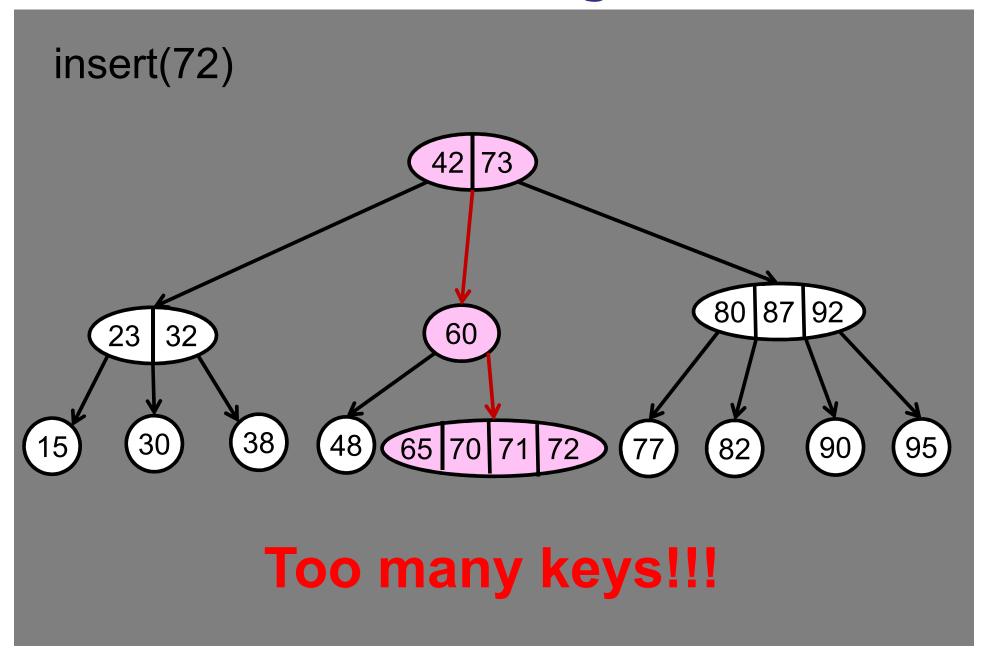


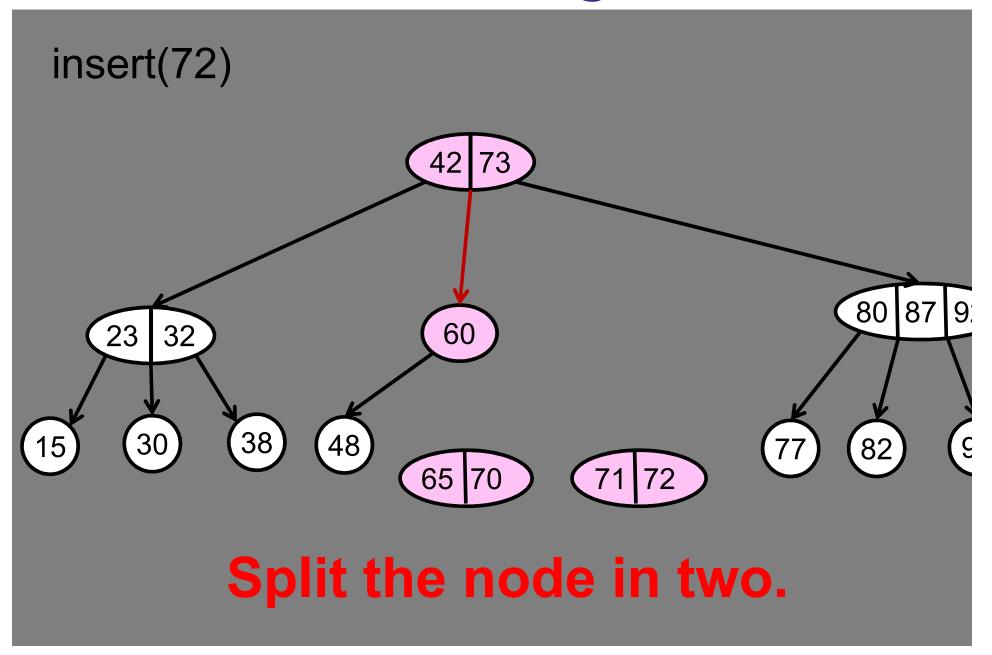


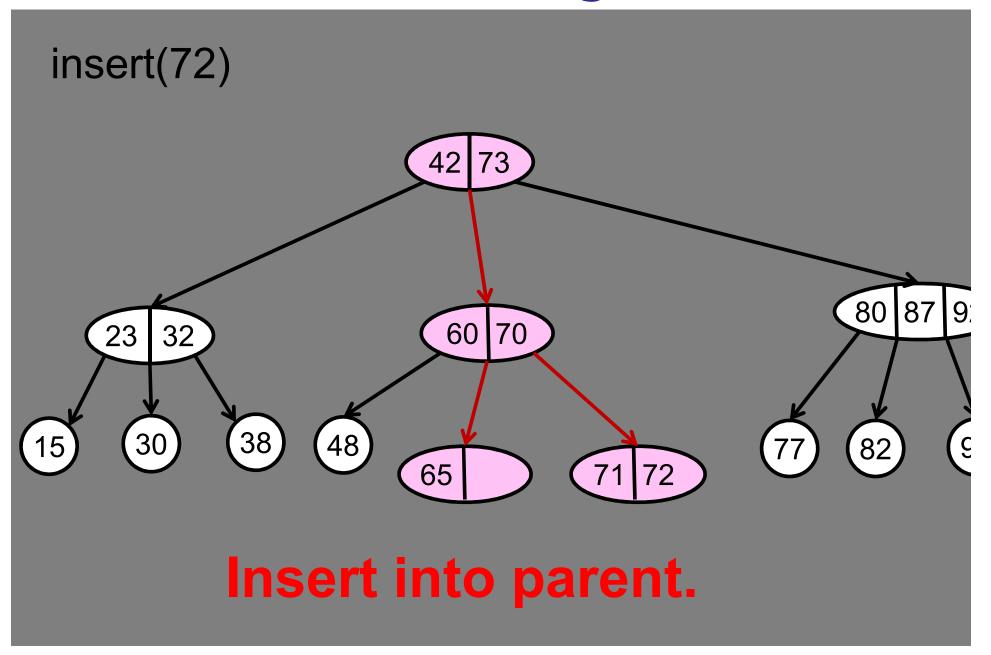


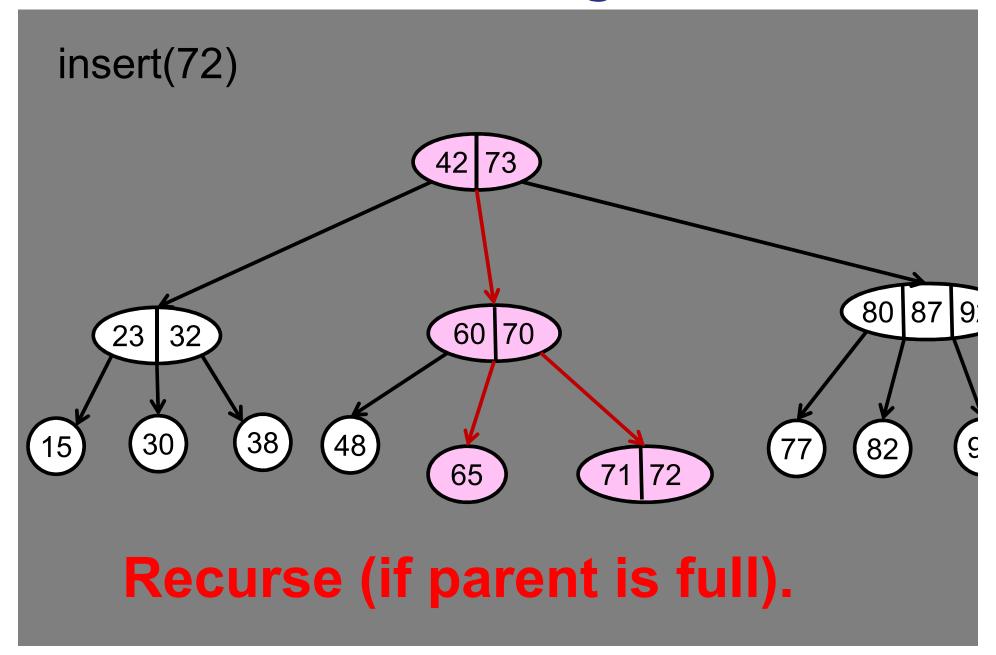


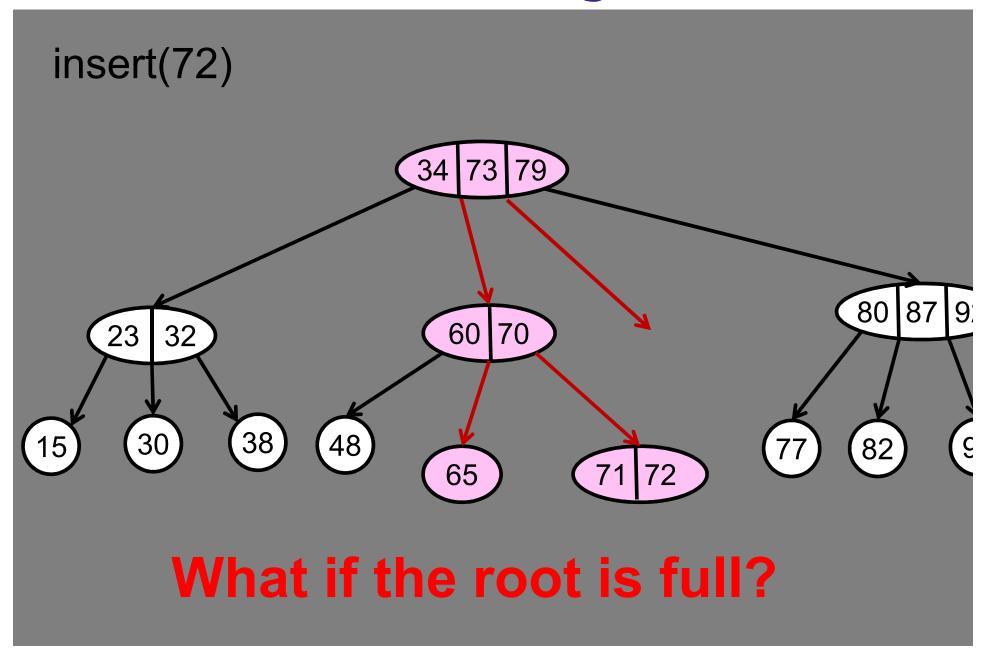


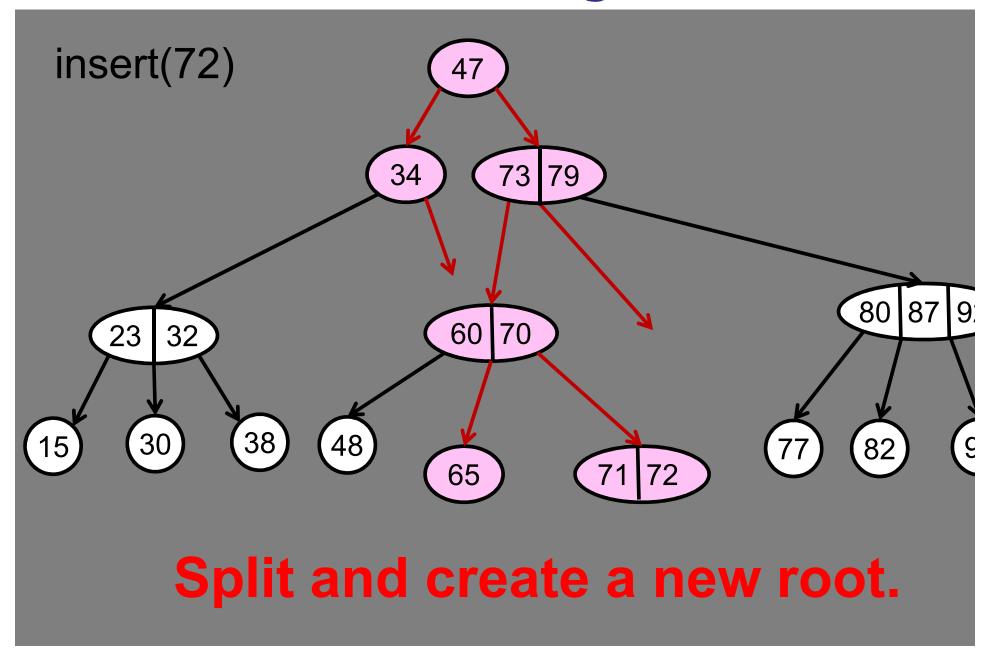






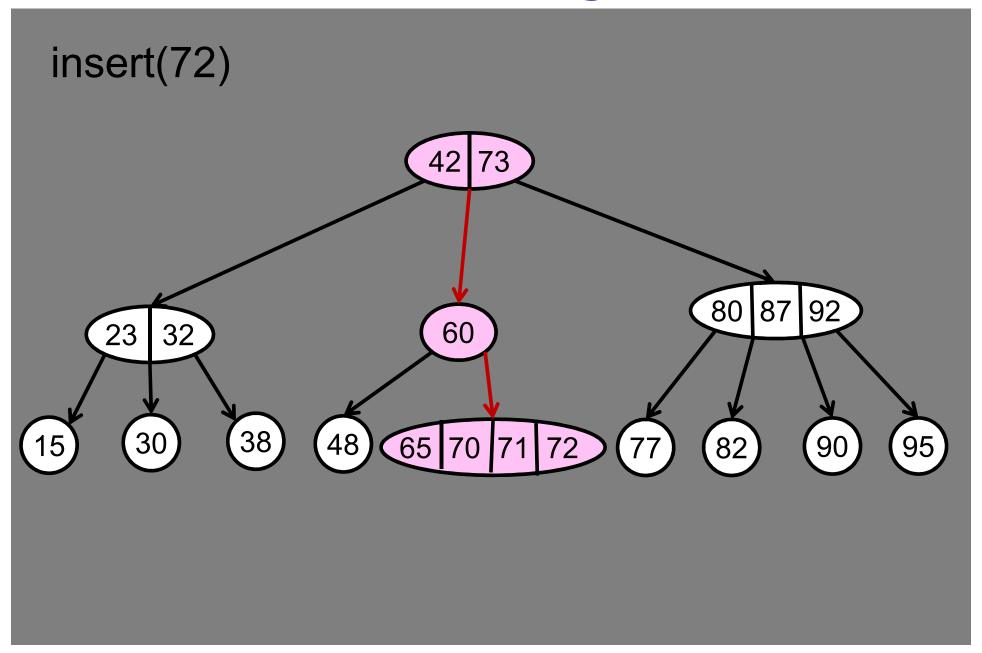


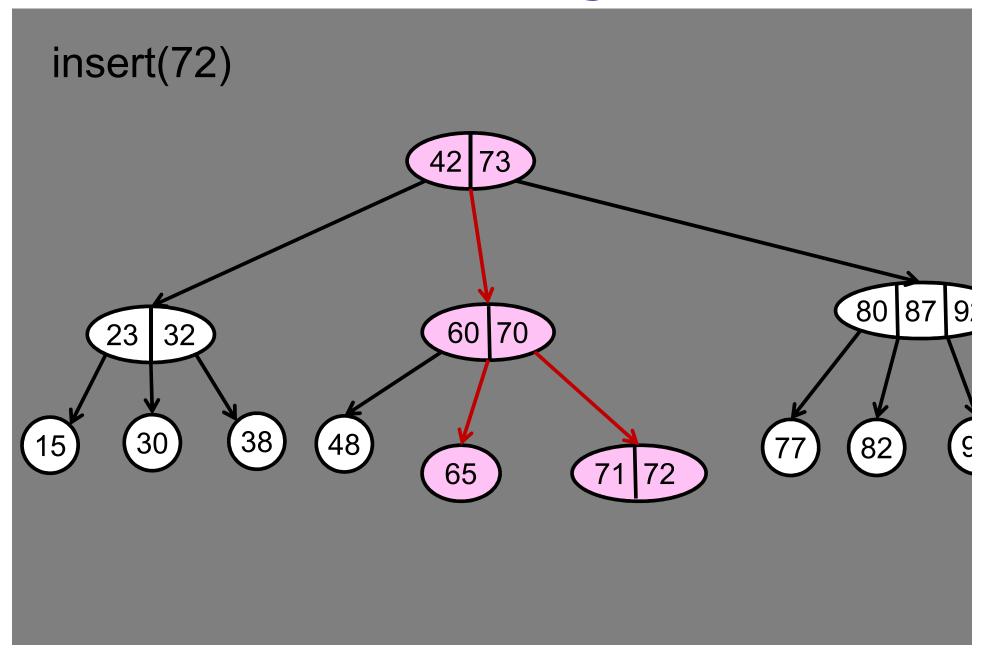




insert(key)

- 1. Search for leaf x to start insert.
- 2. Repeat until done:
- 3. Insert **key** into **x**.
- 4. If **x** overfull:
- **5.** key = median(x);
- 6. remove **key** from **x** and split(**x**);
- 7. If (x == root) then create new root.
- 8. Else $\mathbf{x} = parent(\mathbf{x})$
- 9. Else done;





Preserves 3 Properties:

- 1. Every node has 2 or 3 or 4 children.
- 2. Search tree property.
- 3. All leaves have the same depth.

Lazy option: do splitting when needed.

Proactive option: split in advance.

One pass insertion:

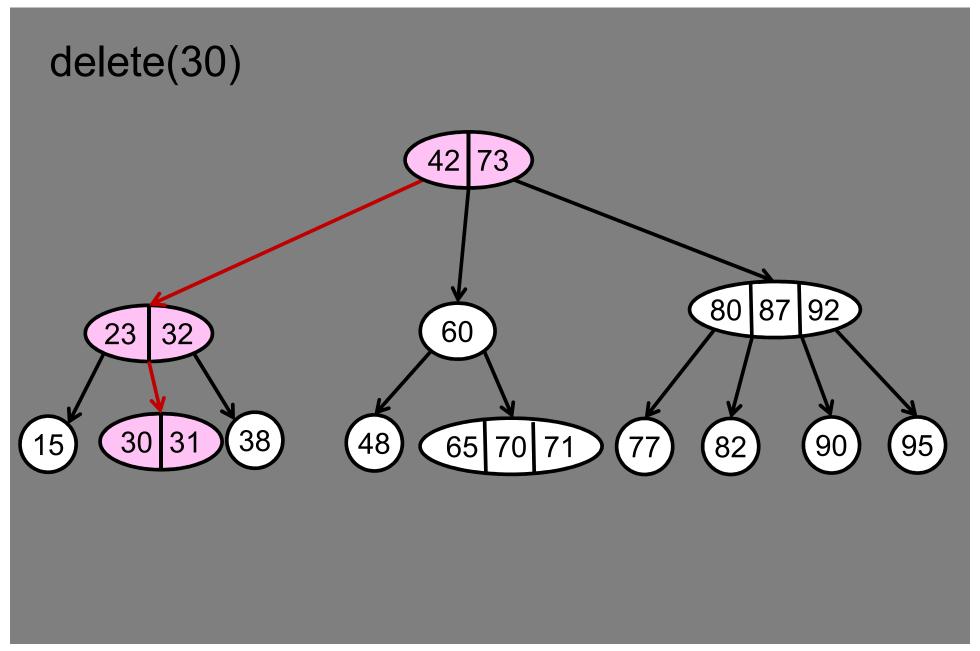
- If root contains 3 keys, split root and create new root (containing one key).
- While searching for the leaf, split any node that is full (i.e., contains 3 keys).
- On arrival at leaf, there is enough space in the leaf to add the key!

```
x.insert(key): (assume x not full)
    if leaf() then add key to array of keys.
    else
2.
        let j be the insertion point in x;
3.
4.
        if Tj has 3 keys, then
            split(x, j, Tj)
5.
            if (key > kj) then j++;
6.
        Tj.insert(key)
7.
```

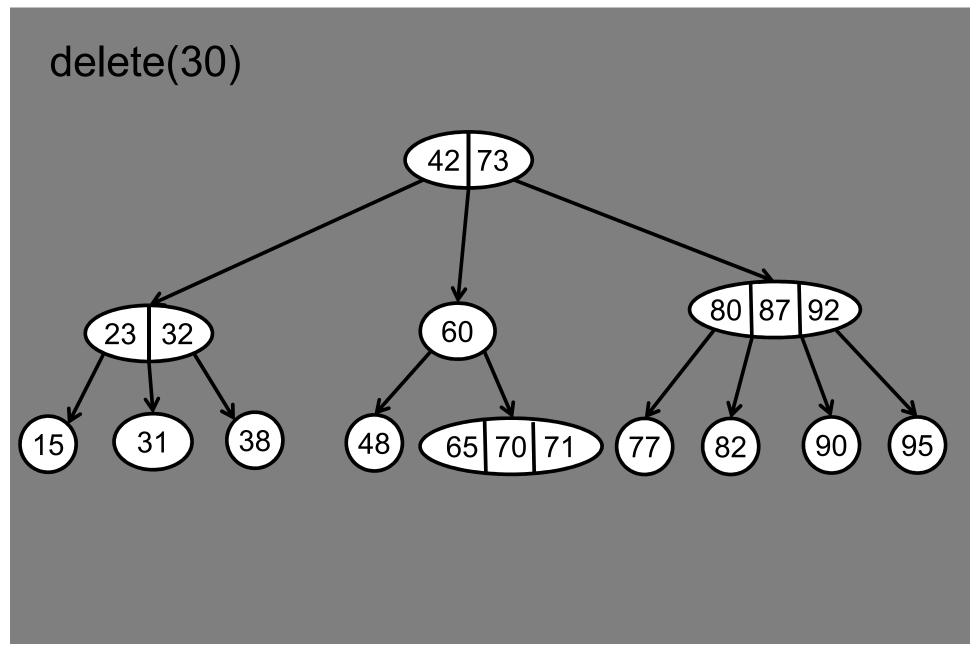
```
x.delete(key): (assume x has at least 2 keys)
```

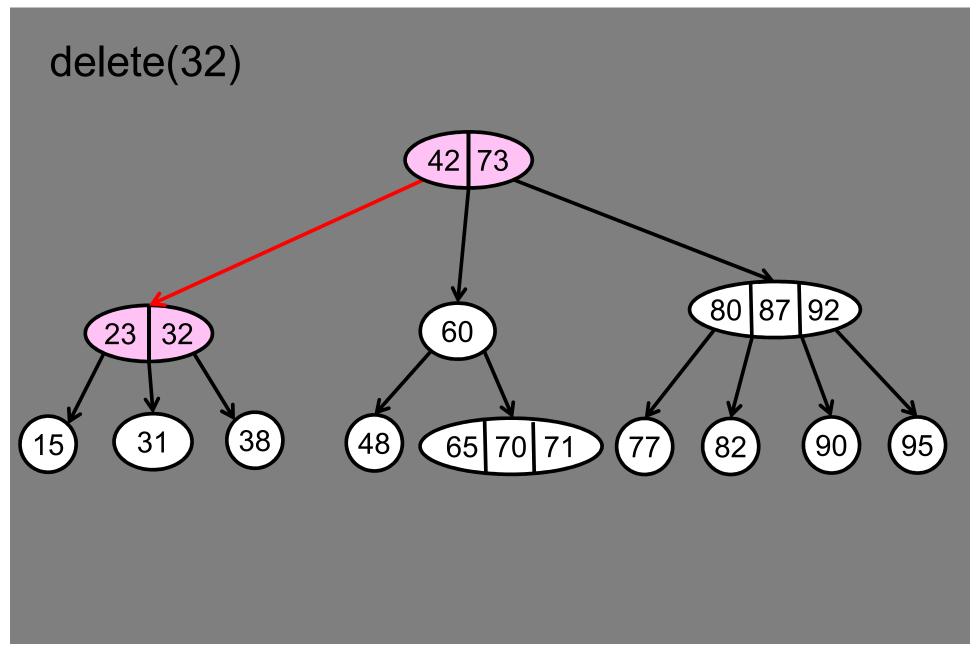
- 1. if leaf() then remove key
- 2. else if (key found at x in key kj)
- 3. if T(j) and T(j+1) have 1 key each:
- 4. merge T(j) and T(j+1) and delete kj
- else replace kj with successor in T(j+1) or predecessor in T(j)
- 6. else if (key in Tj and Tj has at least 2 keys)
- 7. Tj.delete(key)
- 8. else ...

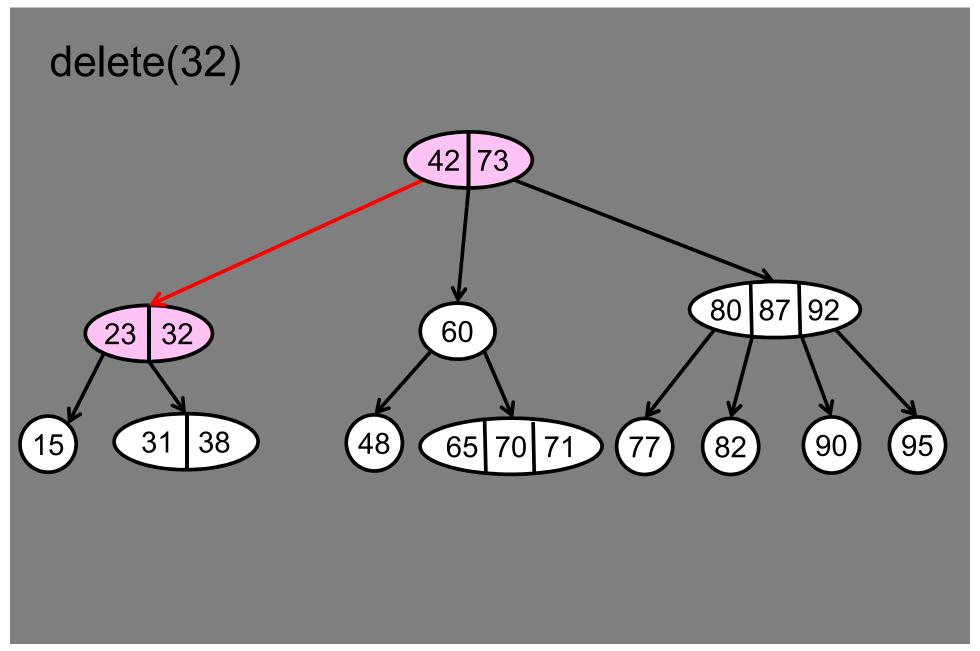
2-3-4 Trees: Deleting (leaf)

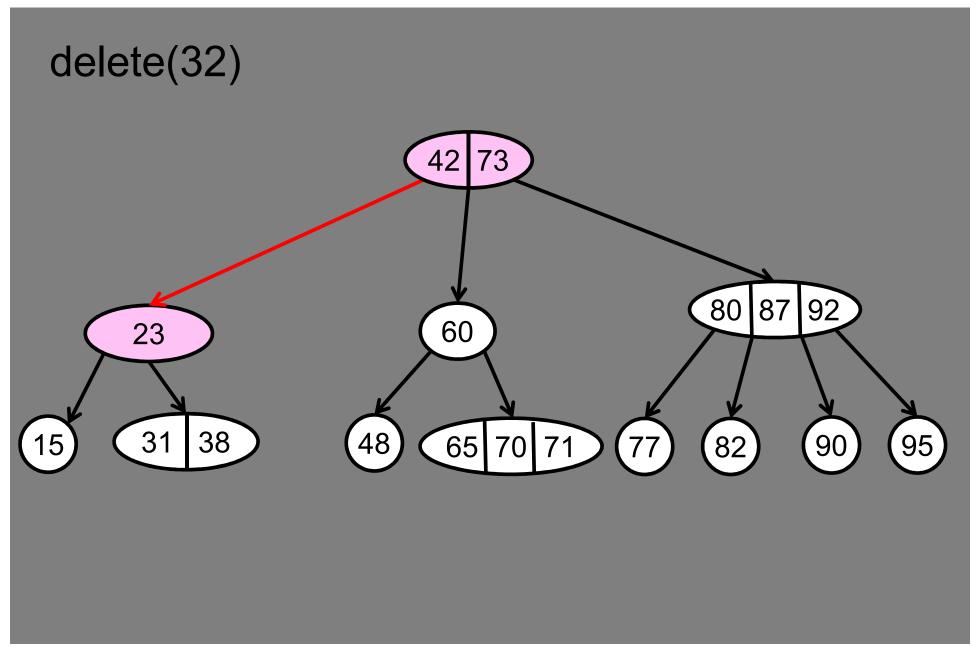


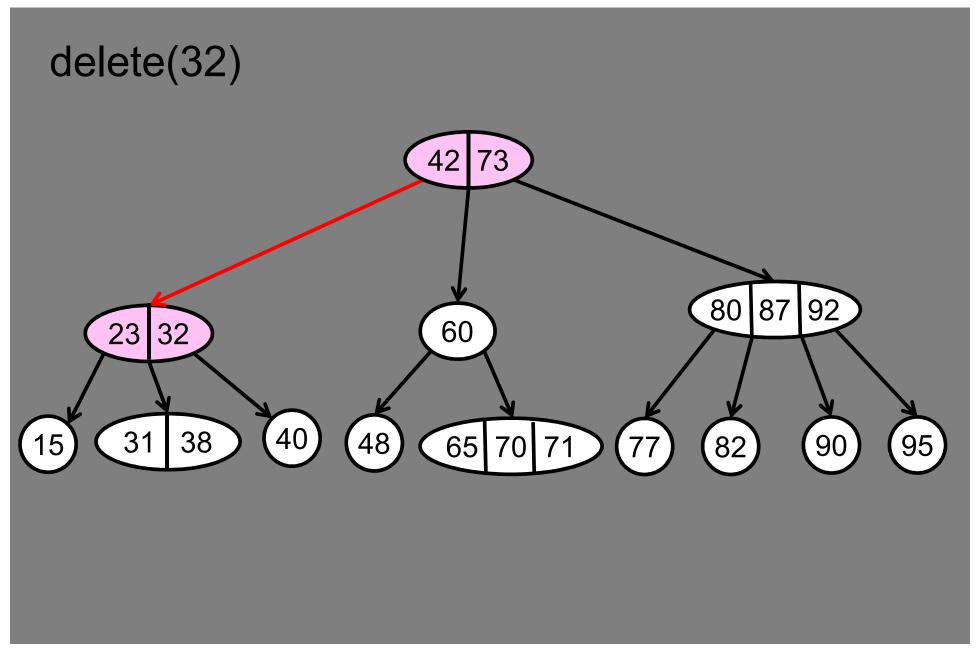
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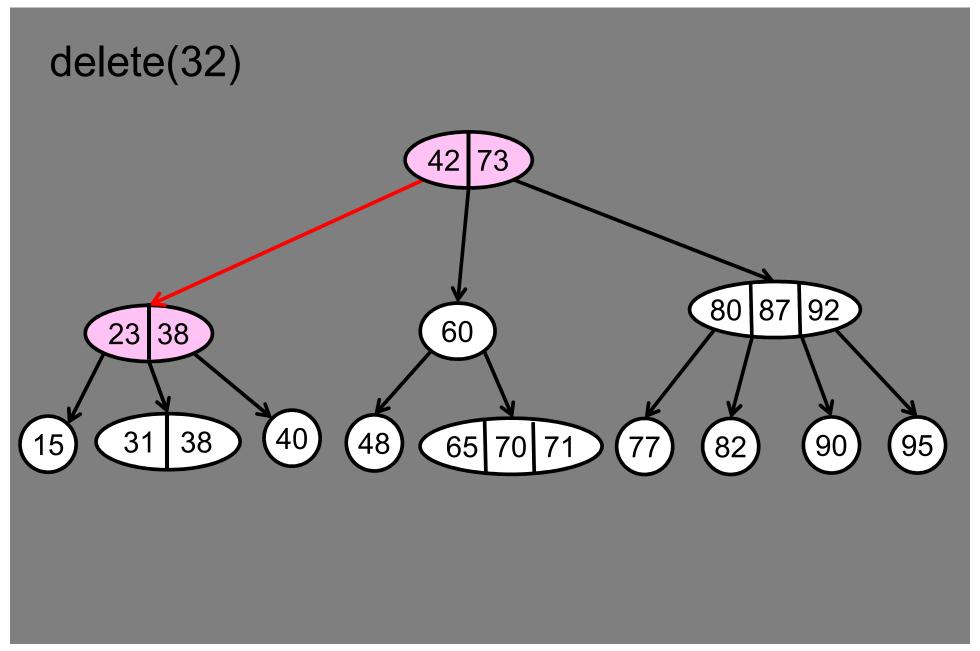


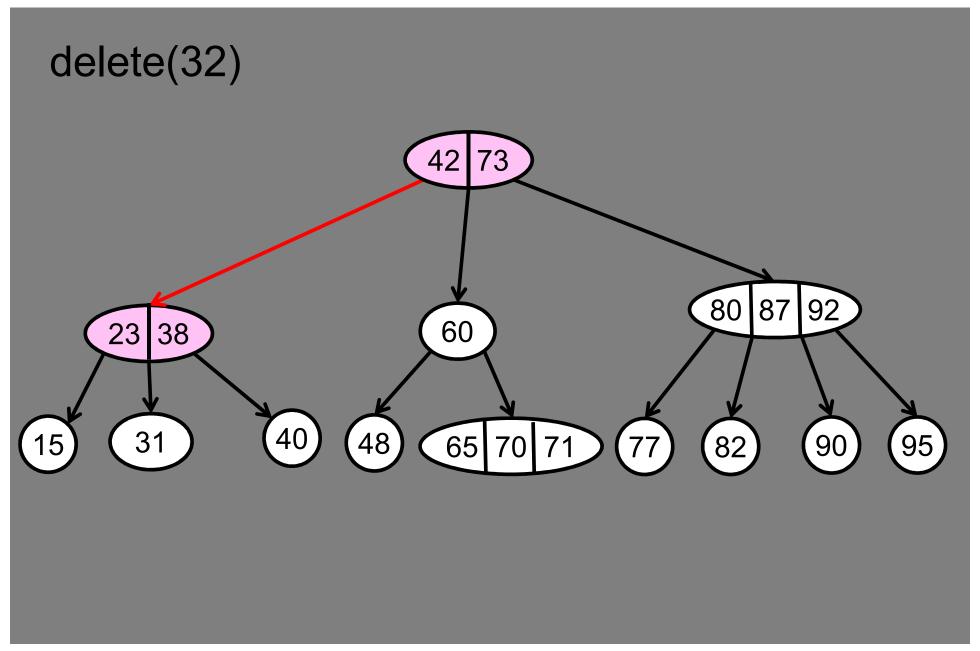


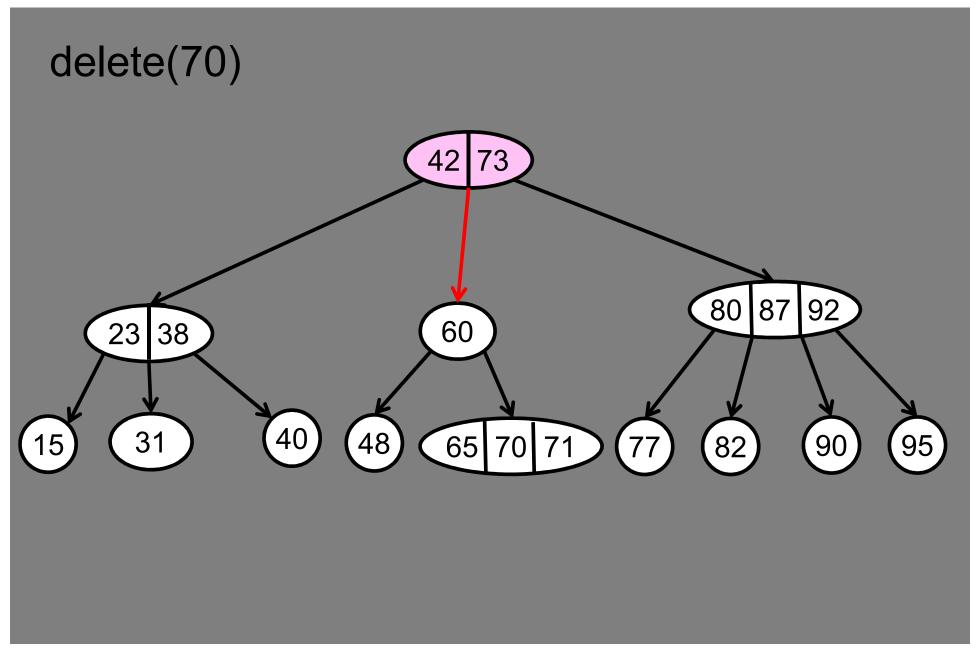


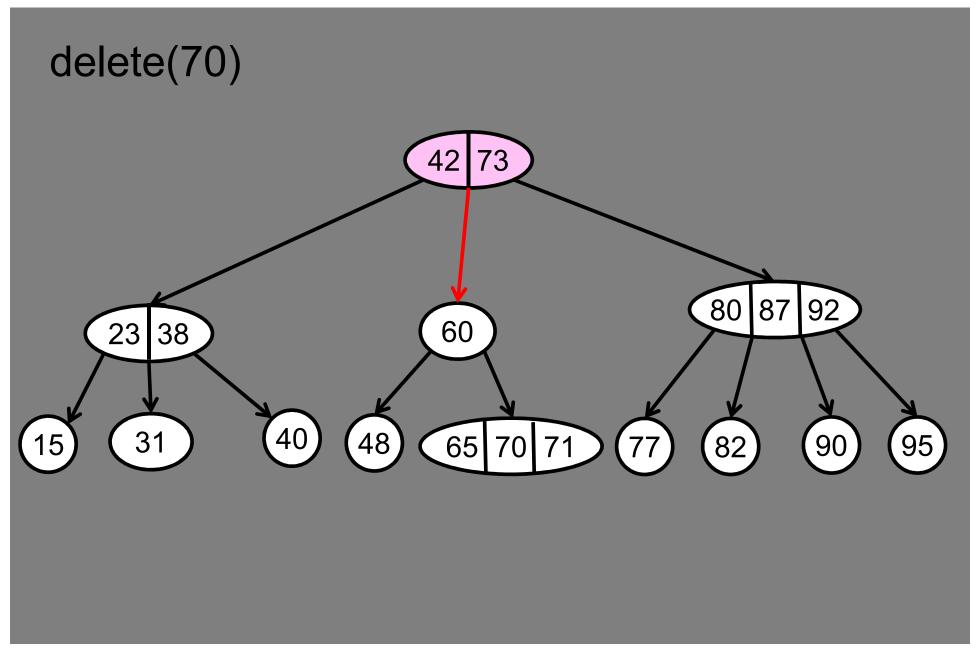


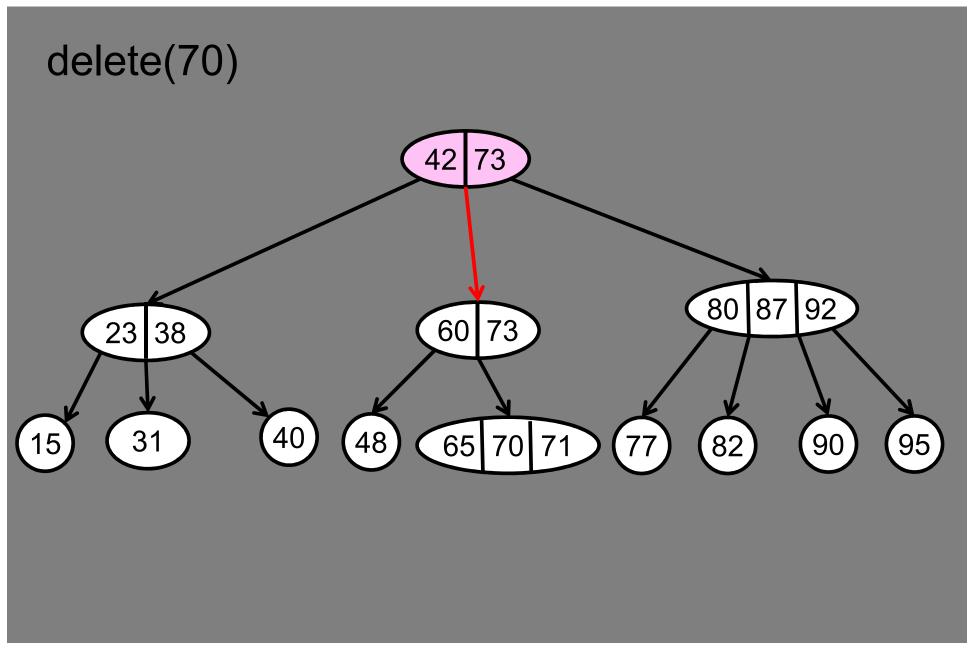


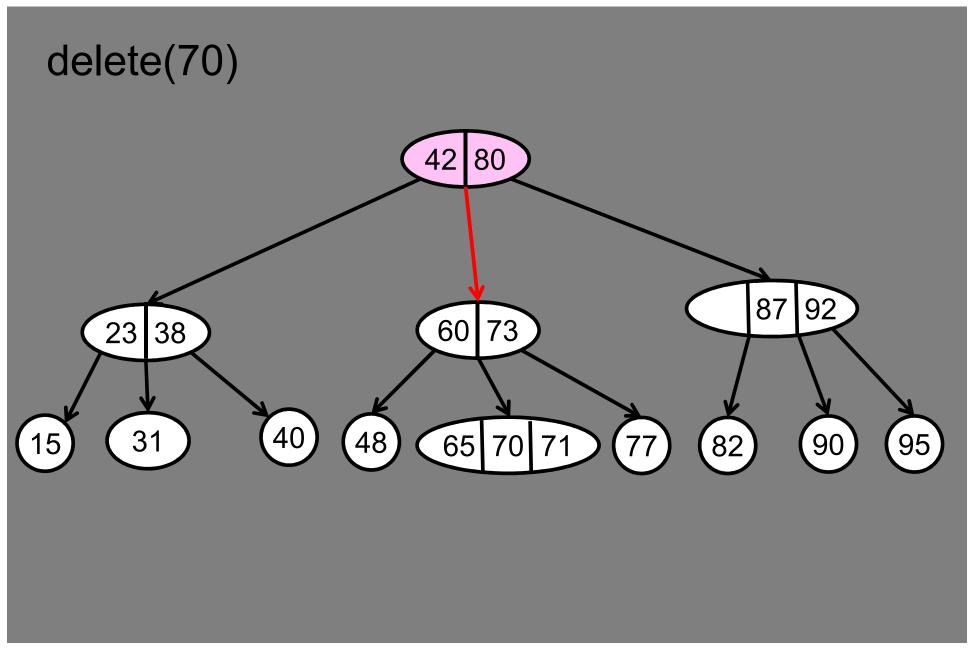


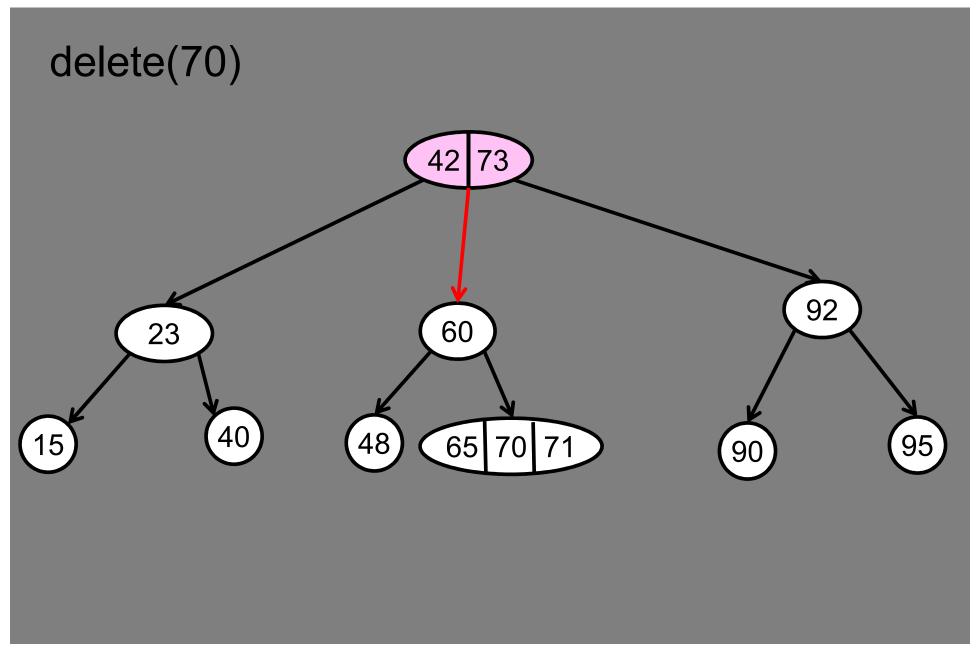


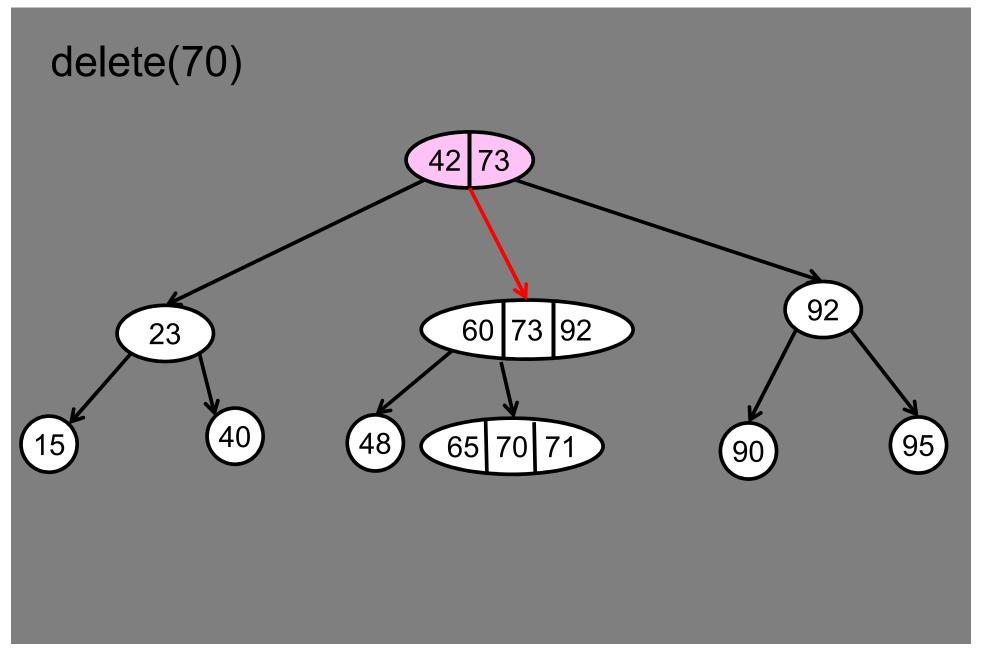


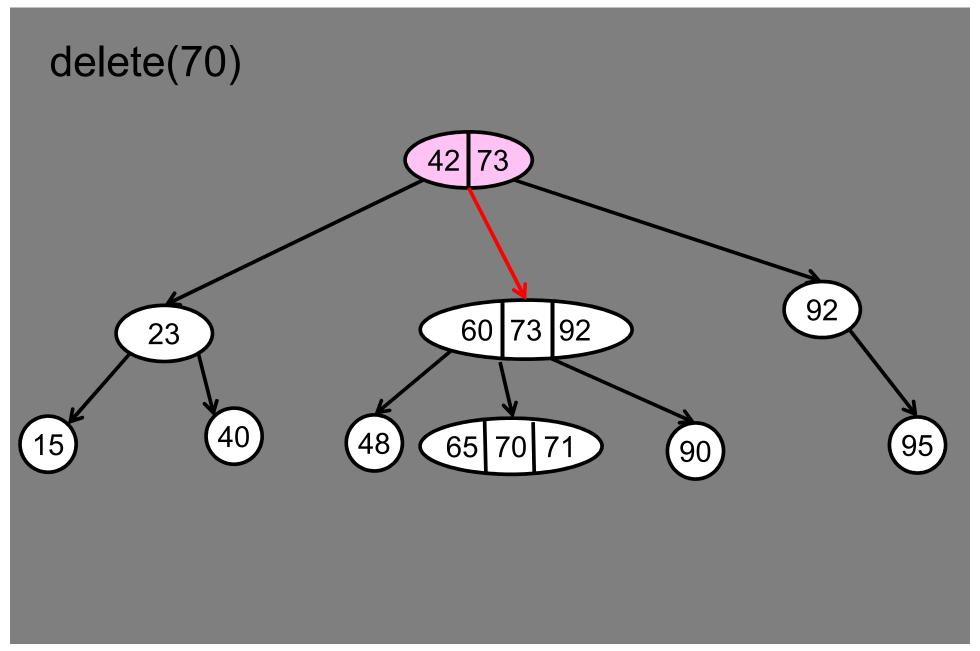


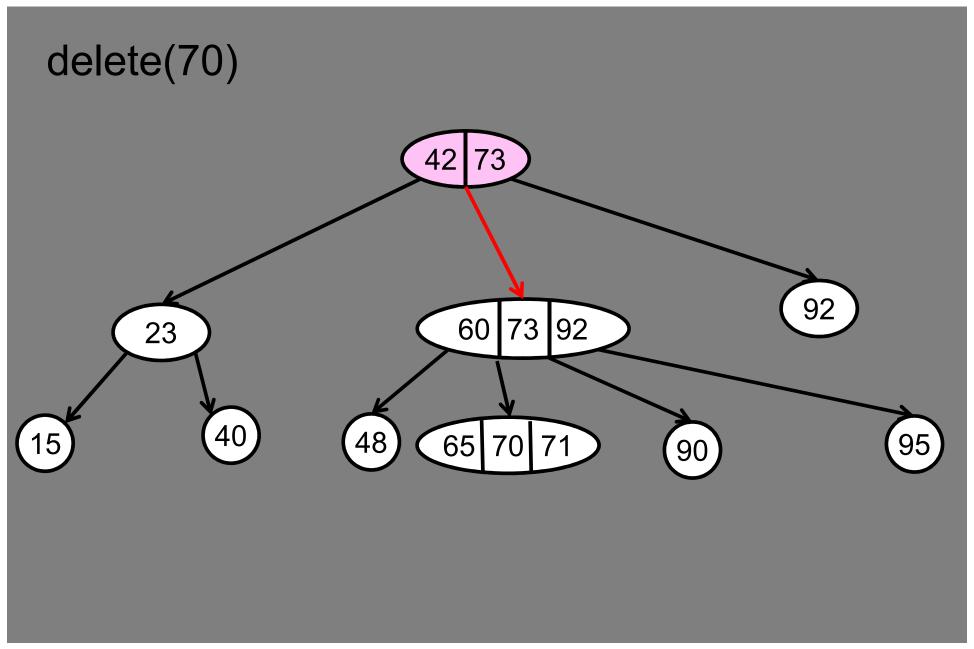


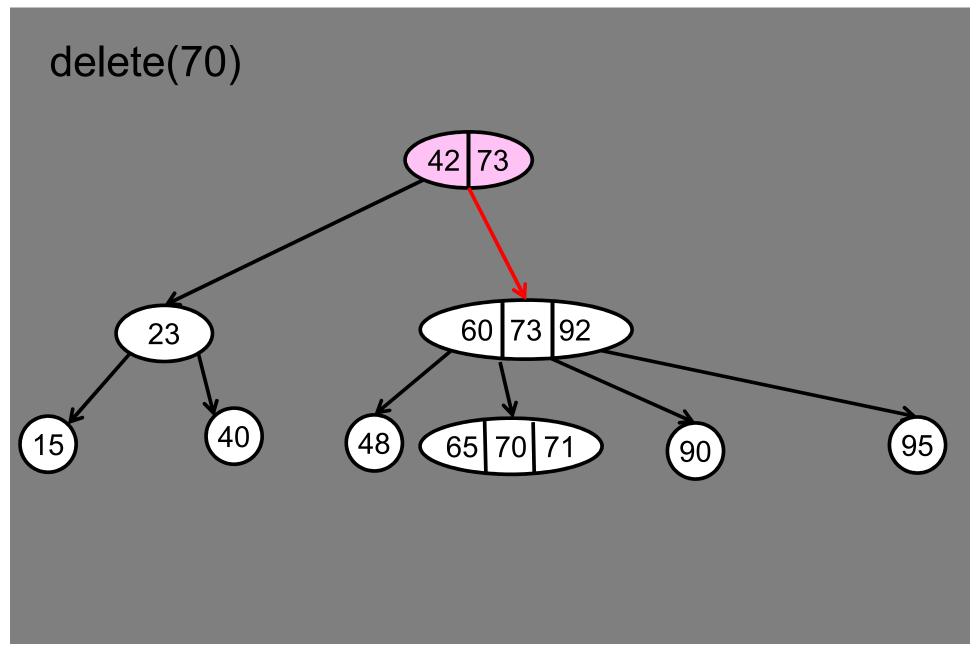


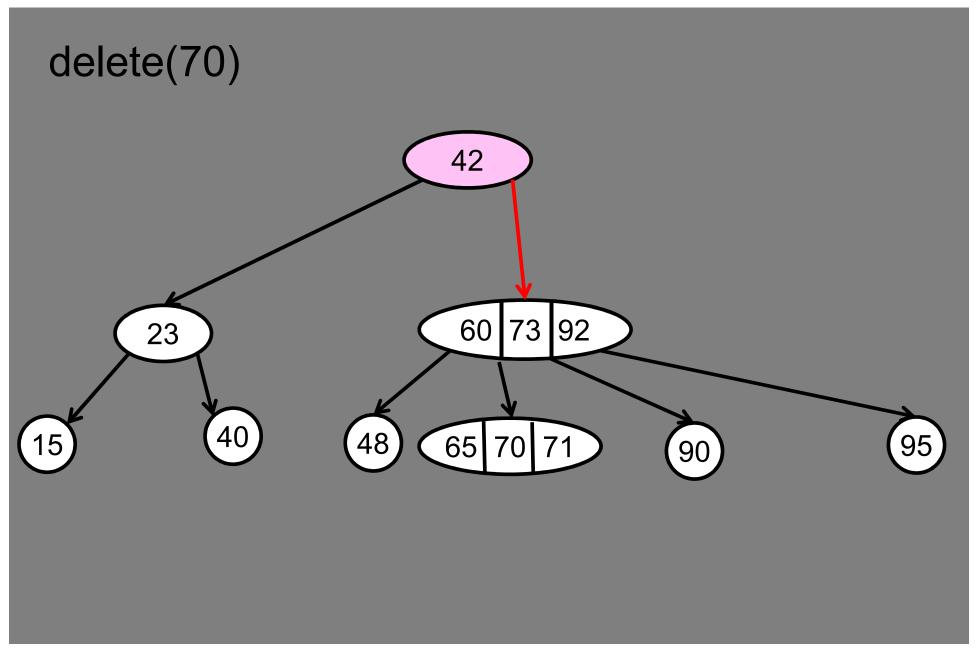












Summary:

- Three rules:
 - 1. Two, three, or four children
 - 2. Search Property
 - 3. All leafs have same depth
- Search: typical tree search
- Insert: split nodes to make room
- Delete: merge and juggle (see CLRS for details)

The search tree used by all large databases...

Where is most data stored? Hard disk!

- Magnetic
- Mechanical
- Slow (6000rpm = 10ms)

Two step access:

- 1. seek (find right track)
- 2. read track

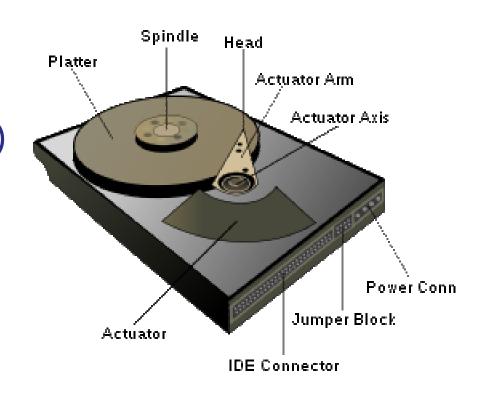
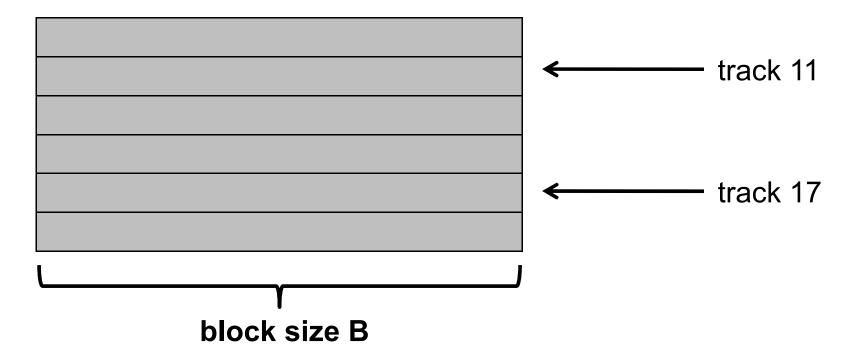


Image source: Wikipedia

Two step access:

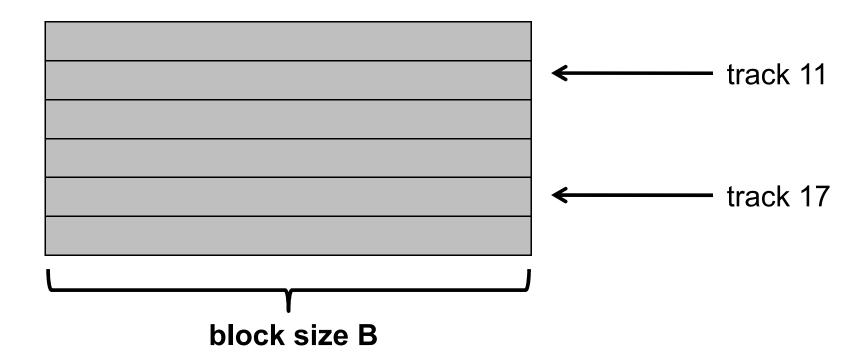
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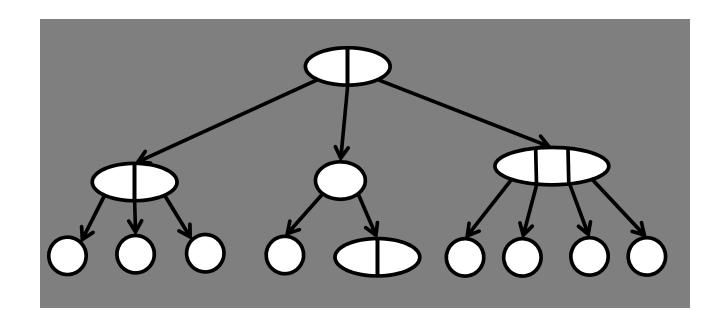
Solution: Cache entire track



Solution: Cache entire track

- Read in new track: costs 1 unit of work
- Read cached data: free



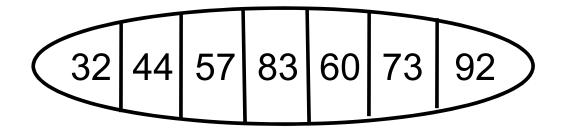


Search:

- Each step of the search reads a new track.
- Reading a track takes 10ms
- Each search takes 10ms*O(log n) time!

Bigger nodes:

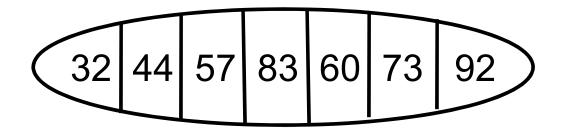
- Each node stores at least B keys
- No node stores more than 2B-1 keys
- All leaves have same depth.



Time to search node: ???

Bigger nodes:

- Each node stores at least B keys
- No node stores more than 2B-1 keys
- All leaves have same depth.



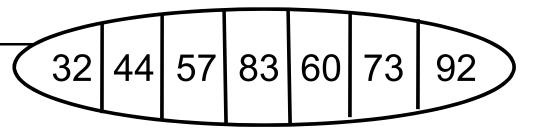
Time to search node: O(B) reads

O(1) disk seeks!

Tree depth:

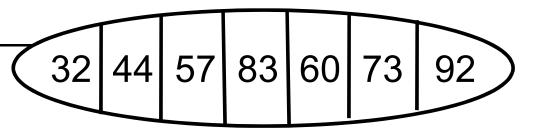
- Level 1: B
- Level 2: B²
- Level 3: **B**³
- Level 4: B⁴
- •
- Level h: Bh

$$n > B^h => h < log_B n = log(n)/log(B)$$



Bigger nodes:

- Search, insert, delete as before.
- How to find index in big node?
 - Linear search: O(B)
 - Binary search: O(log B)



Bigger nodes:

- Search, insert, delete as before.
- How to find index in big node?
 - Linear search: O(B)
 - Binary search: O(log B)
- But there are level 2 caches and level 3 caches...
 - Use small B-tree for smaller value of B to search for key within node!

Summary:

- Caching performance matters.
- B-trees are fast
- B-trees are concurrent
- B-trees are (generally) simpler

Research: (cache-oblivious algorithms)

- What if you don't know the size of your cache?
- Can you devise an algorithm that performs well for all values of B?