## C. Duality

$$X(t) \rightleftharpoons x(-f)$$
 (2.6)

#### **Example 2-4(C):**

Consider the sinc function:  $x(t) = \alpha \operatorname{sinc}(2Bt)$  where  $\alpha$  and B are positive constant. Find  $\Im\{x(t)\}$ .

Start with the Fourier transform pair

$$\left[\tilde{x}(t) = A \operatorname{rect}\left(\frac{t}{T}\right)\right] \rightleftharpoons \left[\tilde{X}(f) = AT \operatorname{sinc}(Tf)\right]$$

and substitute T=2B and  $A=rac{lpha}{2B}$  to get

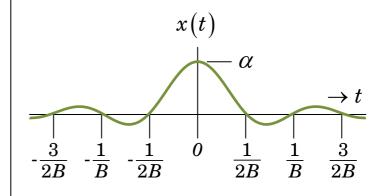
$$\left\lceil \tilde{x}(t) = \frac{\alpha}{2B} \operatorname{rect}\left(\frac{t}{2B}\right) \right\rceil \rightleftharpoons \left\lceil \tilde{X}(f) = \alpha \operatorname{sinc}(2Bf) \right\rceil.$$

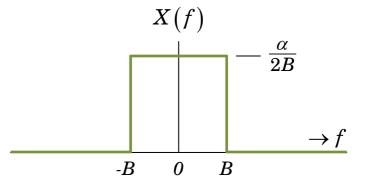
Applying the DUALITY property:

$$\left[\tilde{X}(t) = \alpha \operatorname{sinc}(2Bt)\right] \rightleftharpoons \left[\tilde{x}(-f) = \frac{\alpha}{2B} \operatorname{rect}\left(-\frac{f}{2B}\right)\right].$$

Hence,

$$\Im\{\alpha \operatorname{sinc}(2Bt)\} = \frac{\alpha}{2B} \operatorname{rect}\left(-\frac{f}{2B}\right) = \frac{\alpha}{2B} \operatorname{rect}\left(\frac{f}{2B}\right).$$





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# Illustration (Convolution): ( www.jhu.edu/~signals/index.html

Suppose x(t) = u(t) and  $h(t) = \exp(-t)u(t)$ . How do we evaluate y(t) = h(t) \*x(t)? because  $u(\tau)u(t-\tau) = \begin{cases} 1; & 0 \le \tau \le t \\ 0; & \text{otherwise} \end{cases}$  $\rightarrow \tau$  $h(\tau)$  \(\epsilon\)  $x(t_o-\tau)$  $\rightarrow \tau$  $y(t) = \int_{-\infty}^{\infty} h(\tau)x(t-\tau)d\tau \uparrow$  $y(t_o)$  $\rightarrow t$ 

• x(t) is REAL and EVEN:  $|x^*(t) = x(t)|$  and x(t) = x(-t)|

$$\left(\underbrace{x^*(t) = x(t)}_{x(t) \text{ is REAL, see (2.13)}} X^*(f) = X(-f)\right)$$

$$(x(t) \text{ is REAL, see (2.13)})$$

$$(x(-t) \rightleftharpoons X(-f) \cdots \text{ Scaling Property}$$

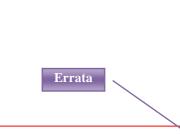
$$x(t) = x(-t) \longrightarrow X(f) = X(-f)$$

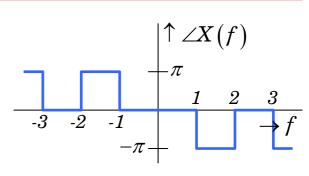
$$x(t) \text{ is EVEN}$$

$$(2.14)$$

$$X(f) \text{ is REAL and EVEN}$$

$$\angle X(f) = \begin{cases} 0; & X(f) \ge 0 \\ \pm \pi; & X(f) < 0 \end{cases}$$



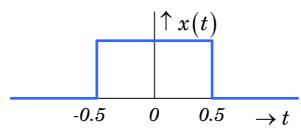


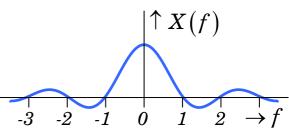
### Example 2-9:

$$\begin{bmatrix} x(t) = \text{rect}(t) \end{bmatrix}$$

$$\downarrow \uparrow$$

$$\begin{bmatrix} X(f) = \text{sinc}(f) \end{bmatrix}$$





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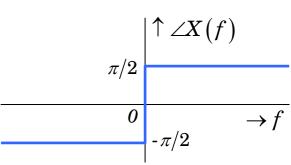
• 
$$x(t)$$
 is REAL and ODD:  $\left[x^*(t) = x(t) \text{ and } x(-t) = -x(t)\right]$ 

$$\underbrace{\left( \underbrace{x^*(t) = x(t)}_{x(t) \text{ is REAL, see (2.13)}}^{X^*(f) = X(-f)} \right)}$$

$$\left( \begin{array}{c} x\left(-t\right) \rightleftarrows X\left(-f\right) & \cdots & \text{Scaling Property} \\ \underline{x\left(t\right) = -x\left(-t\right)} & \Longrightarrow & X\left(f\right) = -X\left(-f\right) \\ \underline{x\left(t\right) \text{ is ODD}} & \end{array} \right)$$

$$\underbrace{ (x(-t) \rightleftharpoons X(-f) \cdots \text{ Scaling Property}}_{X(t) \text{ is ODD}} \underbrace{ X(f) = -X(-f) \cdots \text{ Scaling Property}}_{X(t) \text{ is ODD}} \underbrace{ X(f) = -X(f) \text{ and } X(f) = -X(-f) }_{X(f) \text{ is IMAGINARY and ODD}} \underbrace{ X(f) = -X(-f) }_{X(f) \text{ is ODD}}$$

$$\angle X(f) = \begin{cases} \pi/2; & \operatorname{Im}[X(f)] \ge 0 \\ -\pi/2; & \operatorname{Im}[X(f)] < 0 \end{cases} = \frac{\pi}{2} \operatorname{sgn}(\operatorname{Im}[X(f)])$$



### Example 2-10:

$$\begin{bmatrix} x(t) = -(2\pi)^{-0.5} t \exp(-t^2/2) \end{bmatrix}$$

$$\downarrow \uparrow$$

$$\begin{bmatrix} X(f) = j2\pi f \exp(-2\pi^2 f^2) \end{bmatrix}$$

$$see \ Example \ 2 - 4(F)$$

