

Chapter 10

Surface Integrals

Overview

■ Parametric Surfaces

- Tangent Planes and Normal Vectors

■ Surface Integrals

- Surface Integrals of Scalar Functions
- Surface Integrals
- Surface Integrals of Vector Fields
- Orientation of Surfaces

Overview

■ Curl and Divergence

- Curl
- Divergence
- Del Operator
- Curl and Conservative Fields
- Stokes' Theorem

■ Divergence Theorem (Gauss' Theorem)

Parametric Surfaces

Parametric Representation of Curves :

Plane Curve : $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}, \quad a \leq t \leq b$

Space Curve : $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}, \quad a \leq t \leq b$

one parameter t

Representation of Surfaces

By a two variable function : $z = f(x, y)$

Parametric Representation of Surfaces ?

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

two parameters u and v

Parametric Surfaces

Parametric curves in space:

$$\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}, \quad a \leq t \leq b.$$

Parametric surfaces in space:

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k} \quad \text{-----} \quad (1)$$

where u and v are two independent parameters.

The equations

$$x = x(u, v), \quad y = y(u, v) \quad \text{and} \quad z = z(u, v)$$

are called the *parametric equations* of the surface.

Parametric Surfaces

$$\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$$

Single variable vector function

domain comes
from the real line

$t \longrightarrow \mathbf{r}(t) \longrightarrow \text{a vector}$

The collection of all output vectors form a space curve

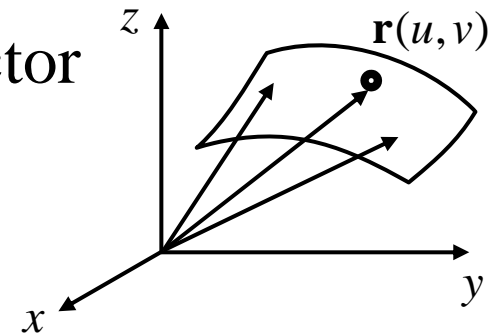
$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

Two variables vector function

domain comes
from 2D-plane

$(u, v) \longrightarrow \mathbf{r}(u, v) \longrightarrow \text{a vector}$

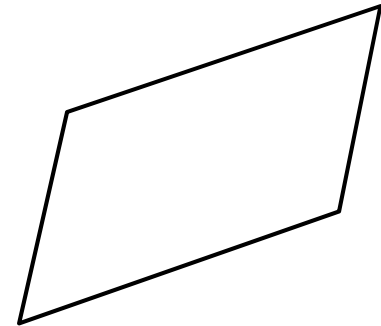
The collection of all output vectors form a surface



Example

$$\text{Plane } 3x + 2y - 4z = 6$$

$$z = \frac{1}{4}(3x + 2y - 6)$$



Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$x(u, v) = u, \quad y(u, v) = v, \quad z(u, v) = \frac{1}{4}(3u + 2v - 6)$$

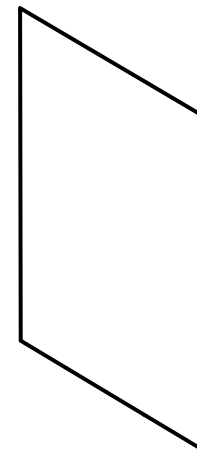
$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + \frac{1}{4}(3u + 2v - 6)\mathbf{k}$$

Example (One Variable is absent)

$$\text{Plane } 2y + x = 7$$

$$x = (7 - 2y)$$

z is missing



Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$z(u, v) = u, \quad y(u, v) = v, \quad x = (7 - 2v)$$

$$\mathbf{r}(u, v) = (7 - 2v)\mathbf{i} + v\mathbf{j} + u\mathbf{k}$$

Example (One Variable is absent)

$$\text{Plane } 2y + x = 7$$

$$y = \frac{1}{2}(7 - x)$$

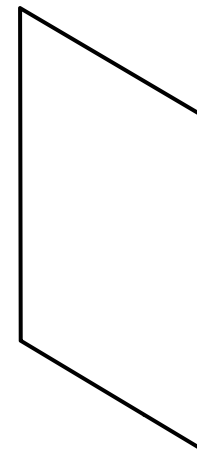
z is missing

Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$z(u, v) = u, \quad x = v, \quad y(u, v) = \frac{1}{2}(7 - v)$$

$$\mathbf{r}(u, v) = v\mathbf{i} + \frac{1}{2}(7 - v)\mathbf{j} + u\mathbf{k}$$



Example: Two Variables are absent

$$\text{Plane : } z = 7$$

x and y are missing

Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$\text{Let } x(u, v) = u \quad \text{and} \quad y(u, v) = v$$

$$z(u, v) = 7$$

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + 7\mathbf{k}$$

Example: Surfaces of the form $z = f(x, y)$

Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

Surface of the form $z = f(x, y)$

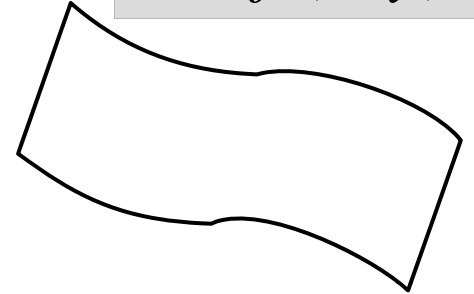
Take $x = u, y = v, z = f(u, v)$

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}$$

or

$$\mathbf{r}(x, y) = x\mathbf{i} + y\mathbf{j} + f(x, y)\mathbf{k}$$

$$z = f(x, y)$$



Example: Surfaces of the form $z = f(x, y)$

A natural parametric representation of S is

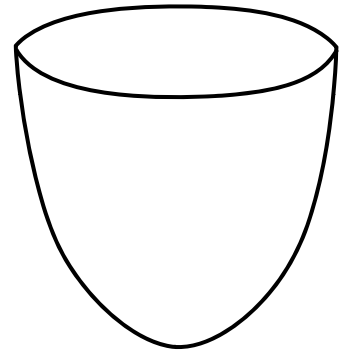
$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}.$$

The paraboloid $z = x^2 + y^2$.

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (u^2 + v^2)\mathbf{k}.$$

The upper cone $z = \sqrt{x^2 + y^2}$.

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + \sqrt{u^2 + v^2}\mathbf{k}.$$



Example: Surfaces of the form $z = f(x, y)$

Parametric Representation

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

Surface of the form $z = f(x, y)$

Take $x = u$, $y = v$, $z = f(u, v)$

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}$$

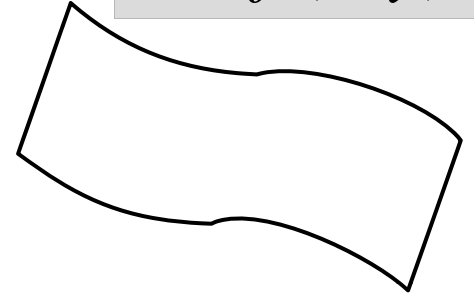
or

$$\mathbf{r}(x, y) = x\mathbf{i} + y\mathbf{j} + f(x, y)\mathbf{k}$$

Similarly for surfaces of the form

$$y = g(x, z) \quad \text{and} \quad x = h(y, z)$$

$$z = f(x, y)$$



Example: Spheres

$$x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

We have a *standard* parametric representation for a sphere $x^2 + y^2 + z^2 = a^2$ of radius a centered at the origin :

$$\mathbf{r}(u, v) = (a \sin u \cos v)\mathbf{i} + (a \sin u \sin v)\mathbf{j} + (a \cos u)\mathbf{k}$$

When

$$0 \leq u \leq \pi, \quad 0 \leq v \leq 2\pi,$$

the representation gives the full sphere.

When

$$0 \leq u \leq \frac{\pi}{2}, \quad 0 \leq v \leq 2\pi,$$

the representation gives the upper hemisphere.

Example: Spheres

$$x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

We have a *standard* parametric representation for a sphere $x^2 + y^2 + z^2 = a^2$ of radius a centered at the origin :

$$\mathbf{r}(u, v) = (a \sin u \cos v)\mathbf{i} + (a \sin u \sin v)\mathbf{j} + (a \cos u)\mathbf{k}$$

$$x = a \sin u \cos v$$

$$y = a \sin u \sin v$$

$$z = a \cos u$$

$$\begin{aligned} x^2 + y^2 &= (a \sin u \cos v)^2 + (a \sin u \sin v)^2 \\ &= a^2 \sin^2 u \cos^2 v + a^2 \sin^2 u \sin^2 v \\ &= a^2 \sin^2 u (\cos^2 v + \sin^2 v) \\ &= a^2 \sin^2 u \end{aligned}$$

$$\begin{aligned} x^2 + y^2 + z^2 &= a^2 \sin^2 u + (a \cos u)^2 \\ &= a^2 \sin^2 u + a^2 \cos^2 u \\ &= a^2 \end{aligned}$$

We have a *standard* parametric representation for a sphere $x^2 + y^2 + z^2 = a^2$ of radius a centered at the origin :

$$\mathbf{r}(u, v) = (a \sin u \cos v)\mathbf{i} + (a \sin u \sin v)\mathbf{j} + (a \cos u)\mathbf{k}$$

When

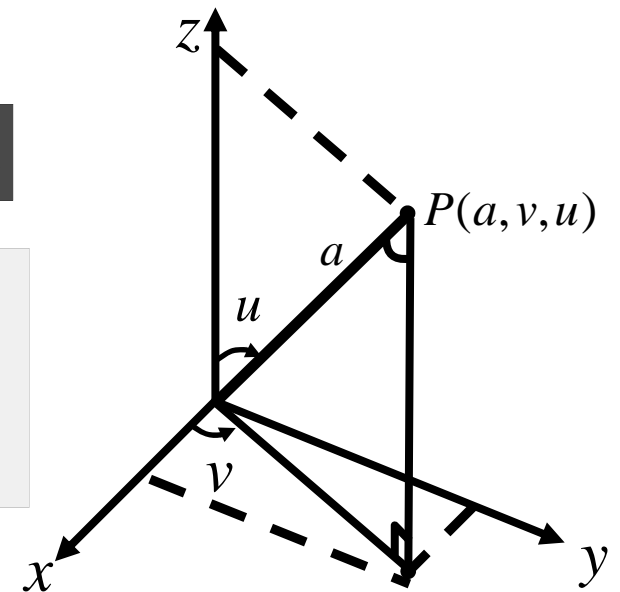
$$0 \leq u \leq \frac{\pi}{2}, \quad 0 \leq v \leq 2\pi,$$

the representation gives the upper hemisphere.

Note : As $z = a \cos u$, z depends on only u .

For $0 \leq u \leq \frac{\pi}{2}$, we have $\cos u \geq 0$, hence, $z \geq 0$.

Thus, we get the upper hemisphere.



We have a *standard* parametric representation for a sphere $x^2 + y^2 + z^2 = a^2$ of radius a centered at the origin :

$$\mathbf{r}(u, v) = (a \sin u \cos v)\mathbf{i} + (a \sin u \sin v)\mathbf{j} + (a \cos u)\mathbf{k}$$

When

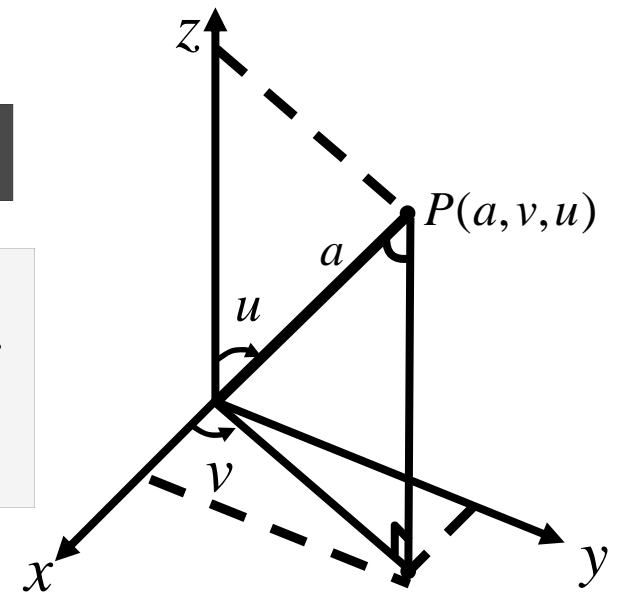
$$\frac{\pi}{2} \leq u \leq \pi, \quad 0 \leq v \leq 2\pi,$$

the representation gives the lower hemisphere

Note : As $z = a \cos u$, z depends on only u .

For $\frac{\pi}{2} \leq u \leq \pi$, we have $\cos u \leq 0$, hence, $z \leq 0$.

Thus, we get the lower hemisphere.



We have a *standard* parametric representation for a sphere $x^2 + y^2 + z^2 = a^2$ of radius a centered at the origin :

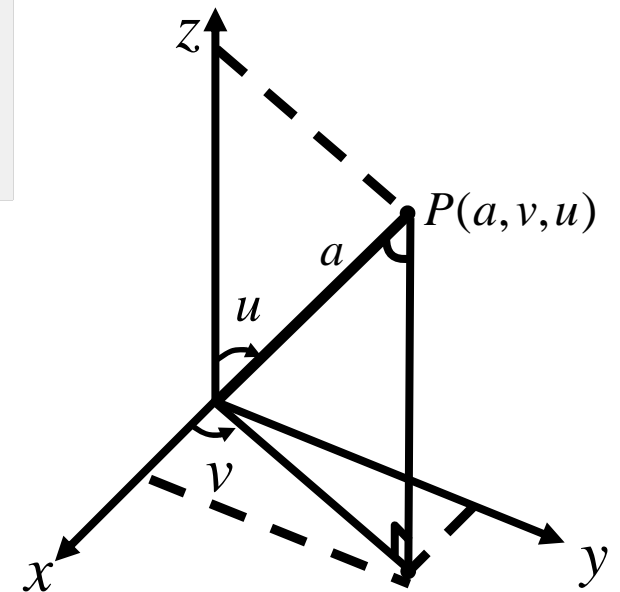
$$\mathbf{r}(u, v) = (a \sin u \cos v)\mathbf{i} + (a \sin u \sin v)\mathbf{j} + (a \cos u)\mathbf{k}$$

Note : As $z = a \cos u$, z depends on only u .

When

$$0 \leq u \leq \pi, \quad 0 \leq v \leq 2\pi,$$

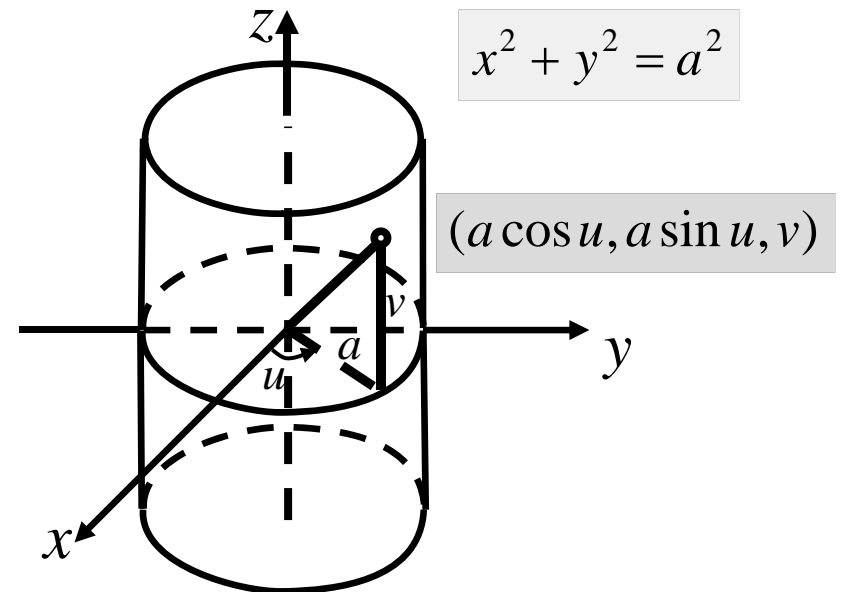
the representation gives the full sphere.



Example: Circular Cylinder

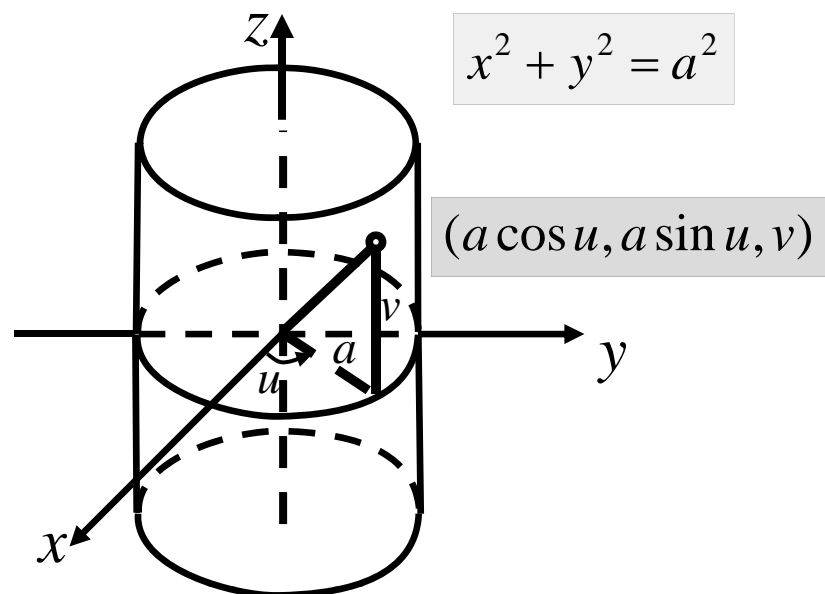
We have a *standard* parametric representation for circular cylinder $x^2 + y^2 = a^2$ about the z - axis :

$$\mathbf{r}(u, v) = (a \cos u)\mathbf{i} + (a \sin u)\mathbf{j} + v\mathbf{k}$$



Here u measures the angle from the positive x - axis (about the z - axis) while v measures the height from the xy - plane along the cylinder.

Example: Circular Cylinder



Circular cylinder $x^2 + y^2 = a^2$ about the z -axis:

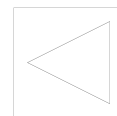
$$\mathbf{r}(u, v) = (a \cos u)\mathbf{i} + (a \sin u)\mathbf{j} + v\mathbf{k}$$

Similarly for $x^2 + z^2 = a^2$ and $y^2 + z^2 = a^2$ (cylinders about y - and x -axes respectively), we have respectively

$$\mathbf{r}(u, v) = (a \cos u)\mathbf{i} + v\mathbf{j} + (a \sin u)\mathbf{k}$$

and

$$\mathbf{r}(u, v) = v\mathbf{i} + (a \cos u)\mathbf{j} + (a \sin u)\mathbf{k}$$



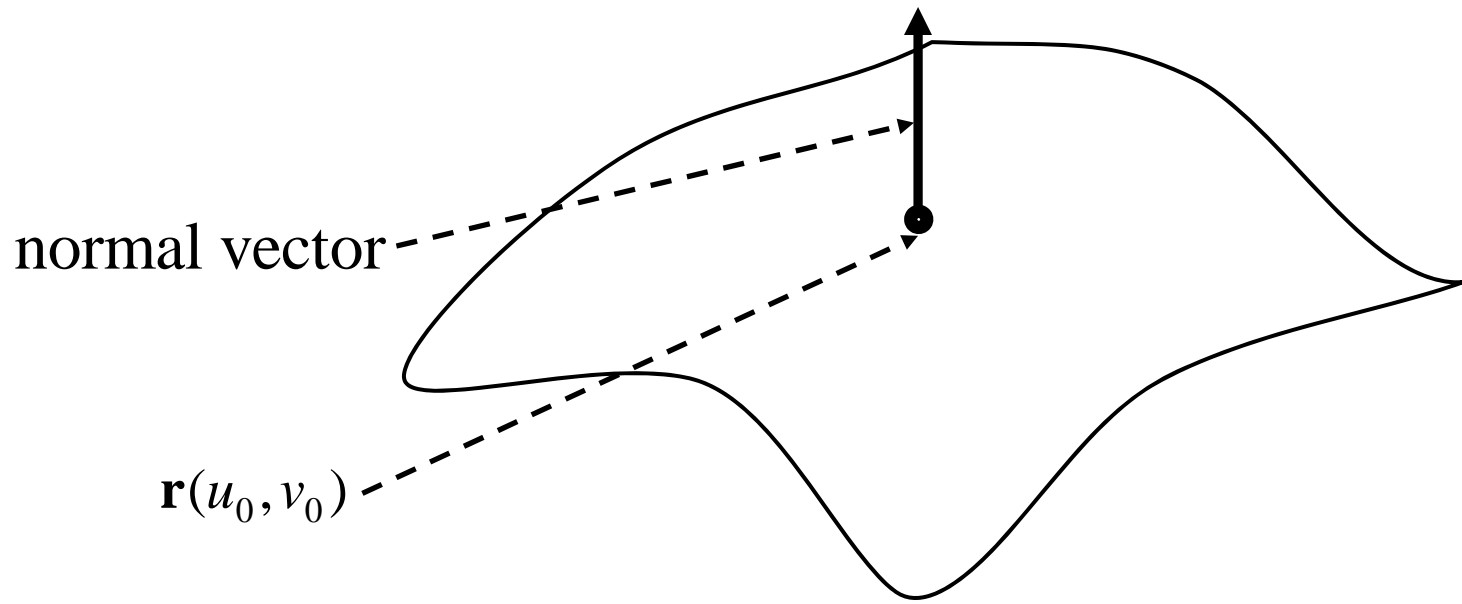
Tangent Planes and Normal Vectors

Given *surface* S whose parametric representation is

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}, \quad \text{-----} \quad (2)$$

at a point P_0 with position vector $\mathbf{r}_0 = \mathbf{r}(u_0, v_0)$.

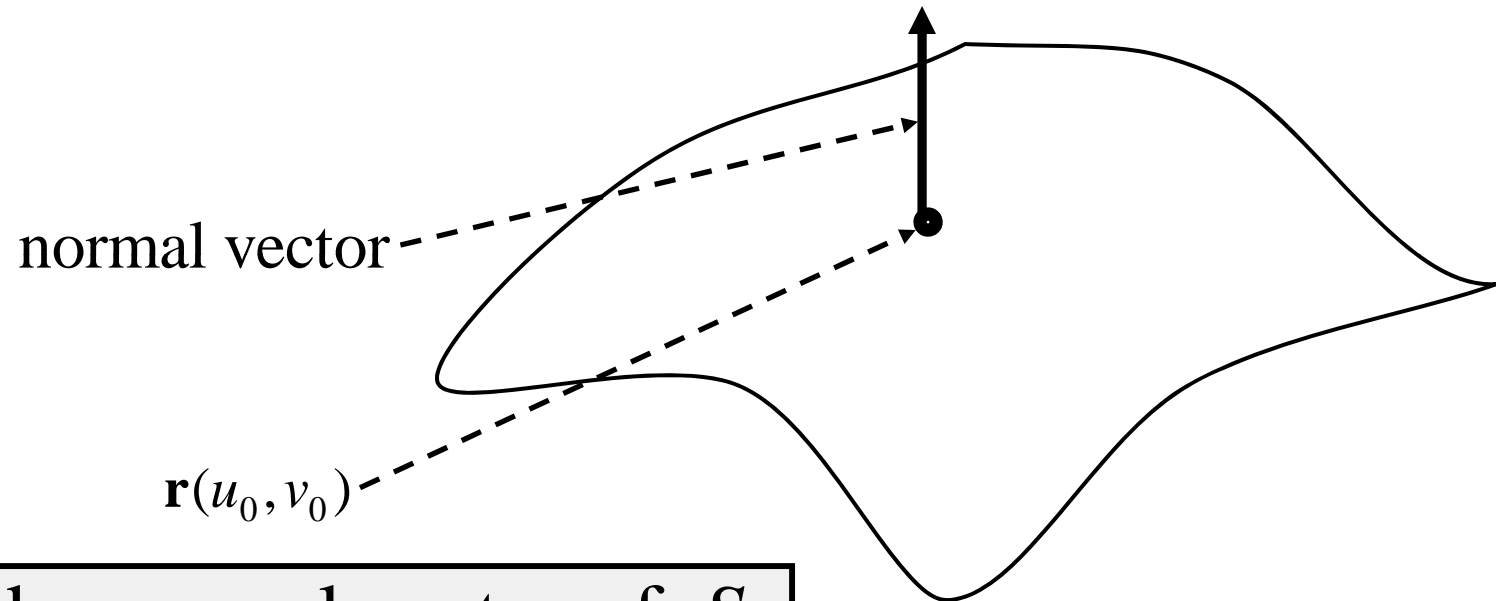
To find : the equation of the *tangent plane* to S at P_0 .



Tangent Plane and Normal Vectors

Surface S is given by

$$S : \mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$



How to find a normal vector of S
at a given point from $\mathbf{r}(u, v)$??

Answer :

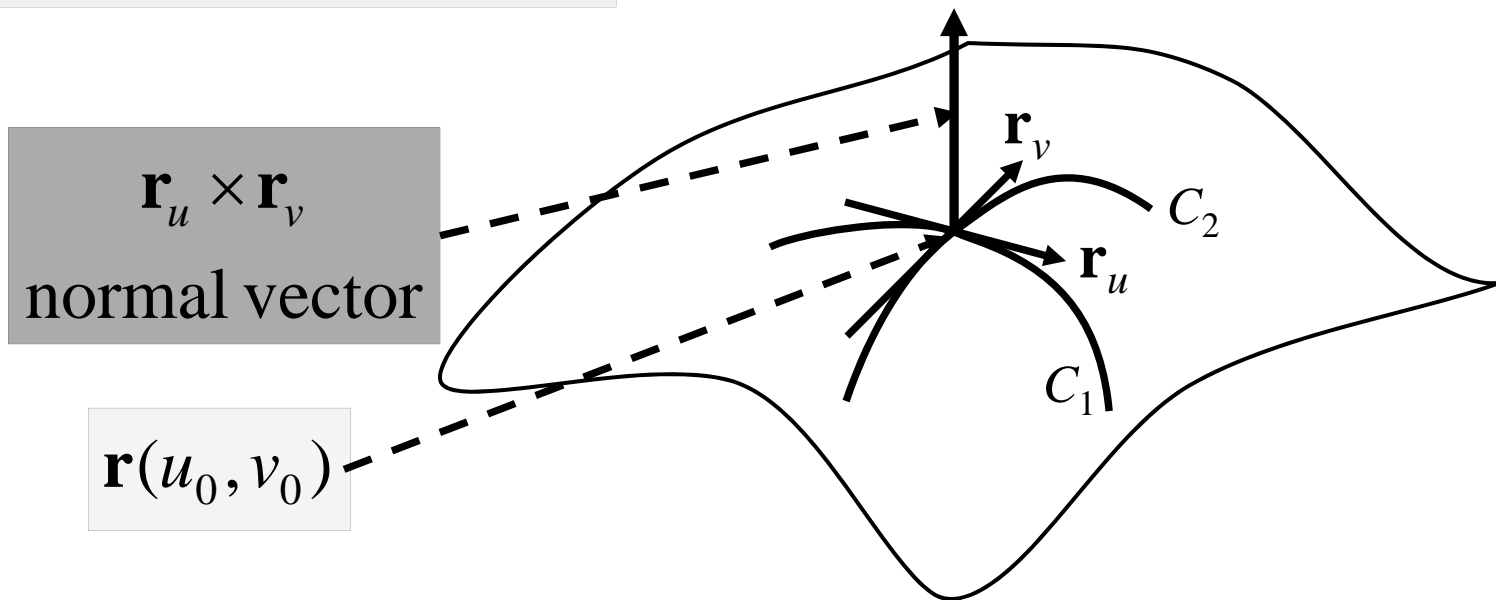
Normal Vectors

Surface S is given by

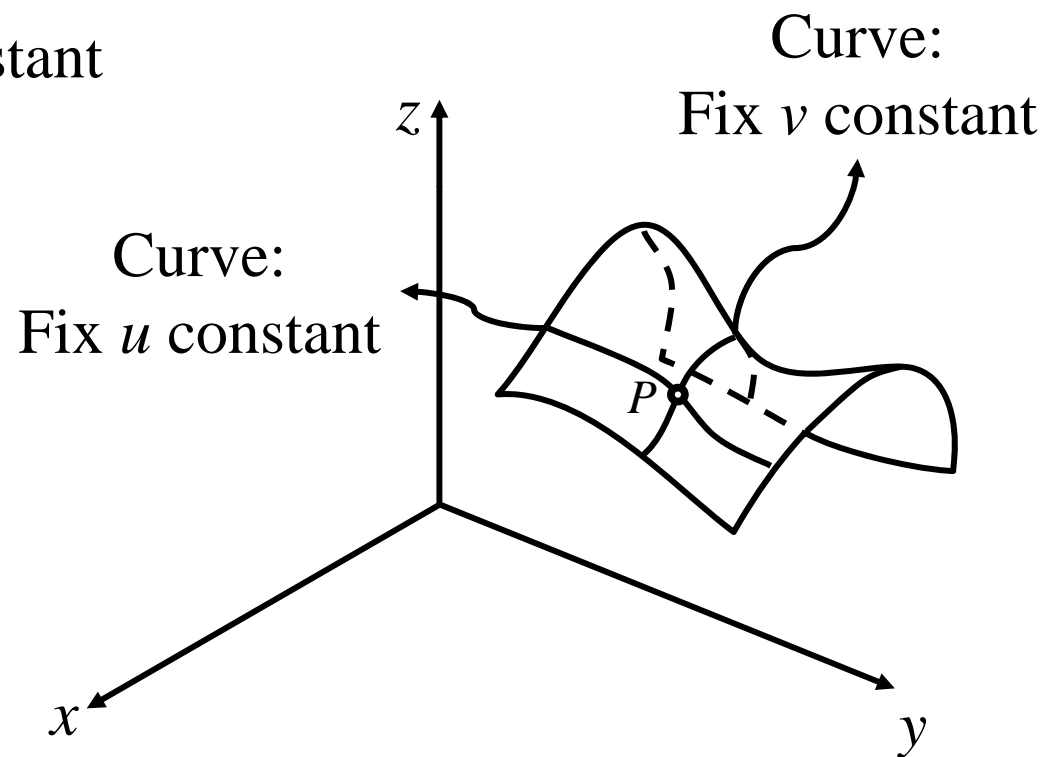
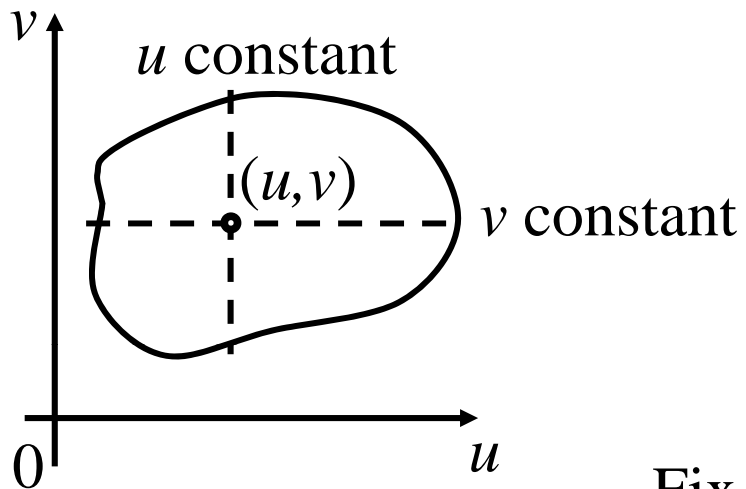
$$S : \mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

$$\mathbf{r}_u = x_u\mathbf{i} + y_u\mathbf{j} + z_u\mathbf{k}$$

$$\mathbf{r}_v = x_v\mathbf{i} + y_v\mathbf{j} + z_v\mathbf{k}$$

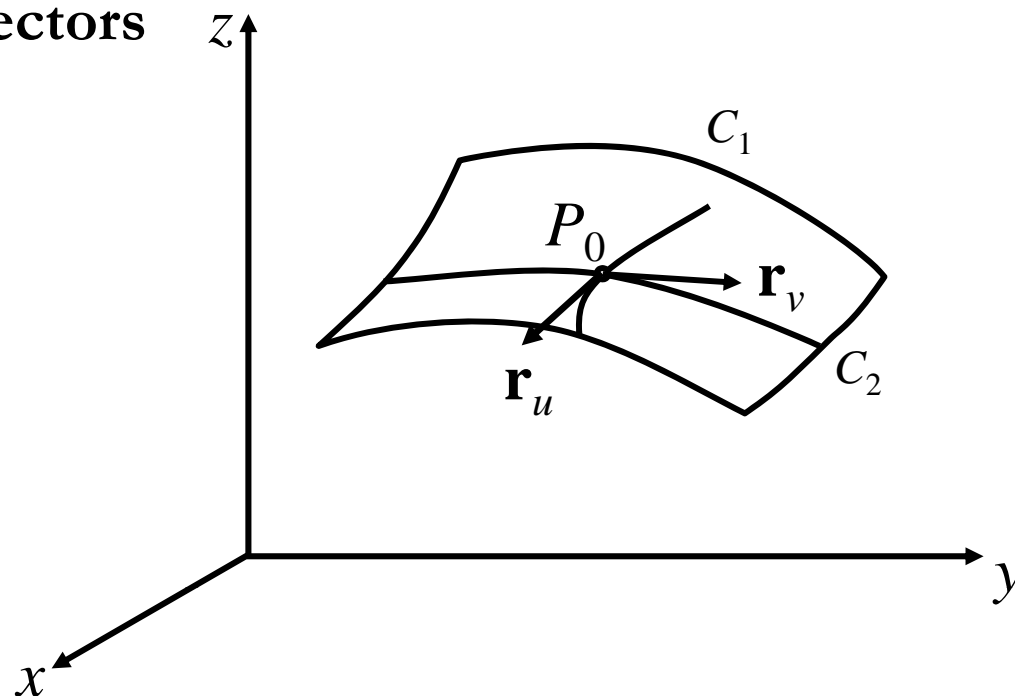


Parametric Surfaces



$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

Tangent Planes and Normal Vectors



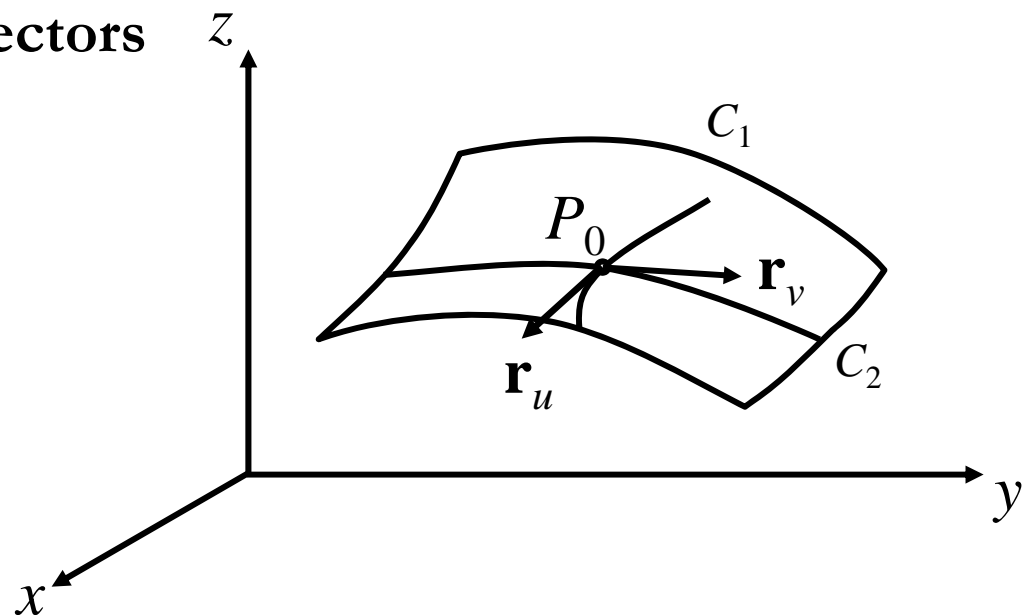
Fix $v = v_0$,

$$C_1 : \mathbf{r}(u, v_0) = x(u, v_0)\mathbf{i} + y(u, v_0)\mathbf{j} + z(u, v_0)\mathbf{k}.$$

Fix $u = u_0$,

$$C_2 : \mathbf{r}(u_0, v) = x(u_0, v)\mathbf{i} + y(u_0, v)\mathbf{j} + z(u_0, v)\mathbf{k}.$$

Tangent Planes and Normal Vectors



Fix $v = v_0$,

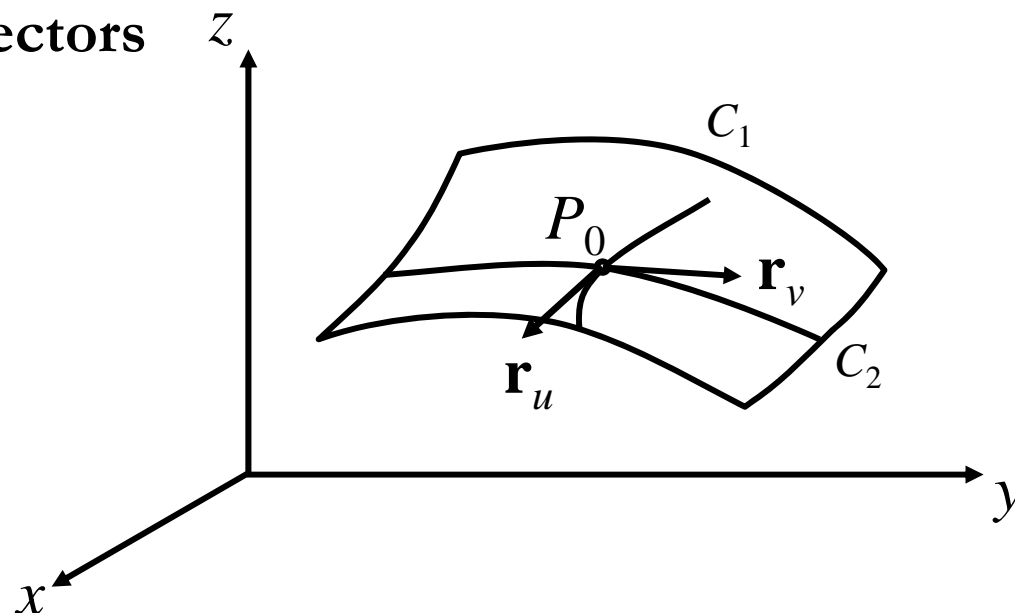
$$C_1 : \mathbf{r}(u, v_0) = x(u, v_0)\mathbf{i} + y(u, v_0)\mathbf{j} + z(u, v_0)\mathbf{k}.$$

The tangent vector to C_1 at P_0 is given by $\frac{d}{du} \mathbf{r}(u, v_0) \Big|_{u=u_0}$,

which is simply

$$\mathbf{r}_u \equiv \frac{\partial x}{\partial u}(u_0, v_0)\mathbf{i} + \frac{\partial y}{\partial u}(u_0, v_0)\mathbf{j} + \frac{\partial z}{\partial u}(u_0, v_0)\mathbf{k}.$$

Tangent Planes and Normal Vectors



Fix $u = u_0$,

$$C_2 : \mathbf{r}(u_0, v) = x(u_0, v)\mathbf{i} + y(u_0, v)\mathbf{j} + z(u_0, v)\mathbf{k}.$$

The tangent vector to C_2 at P_0 is given by

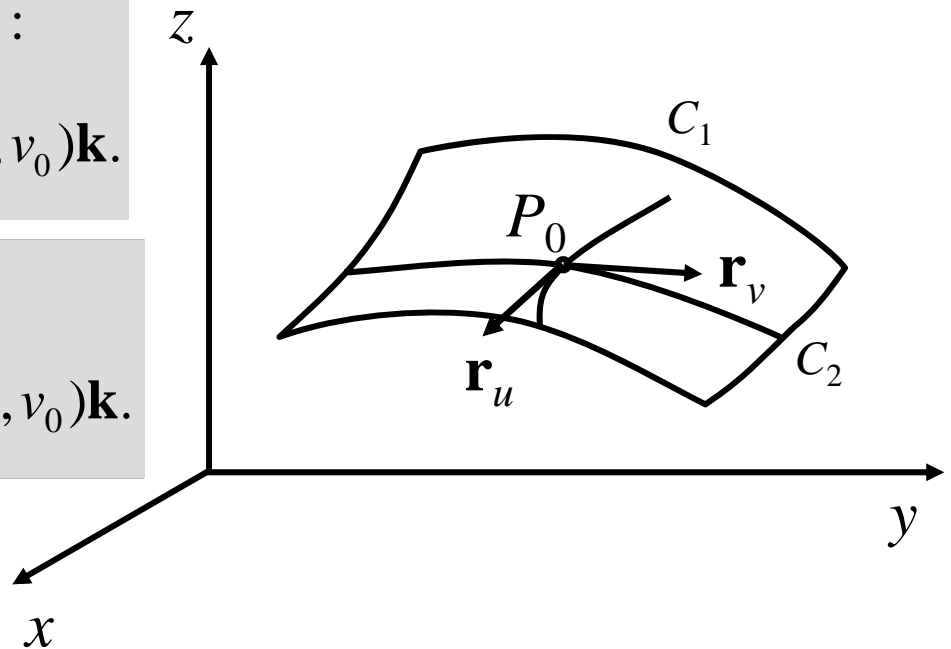
$$\mathbf{r}_v \equiv \frac{\partial x}{\partial v}(u_0, v_0)\mathbf{i} + \frac{\partial y}{\partial v}(u_0, v_0)\mathbf{j} + \frac{\partial z}{\partial v}(u_0, v_0)\mathbf{k}.$$

The tangent vector to C_1 at P_0 is given by :

$$\mathbf{r}_u \equiv \frac{\partial x}{\partial u}(u_0, v_0)\mathbf{i} + \frac{\partial y}{\partial u}(u_0, v_0)\mathbf{j} + \frac{\partial z}{\partial u}(u_0, v_0)\mathbf{k}.$$

The tangent vector to C_2 at P_0 is given by

$$\mathbf{r}_v \equiv \frac{\partial x}{\partial v}(u_0, v_0)\mathbf{i} + \frac{\partial y}{\partial v}(u_0, v_0)\mathbf{j} + \frac{\partial z}{\partial v}(u_0, v_0)\mathbf{k}.$$



Both vectors \mathbf{r}_u and \mathbf{r}_v lie in the tangent plane to S at P_0 .

Therefore the ***cross product*** $\mathbf{r}_u \times \mathbf{r}_v$, assuming it is nonzero, provides a ***normal*** vector to the tangent plane to S at P_0 .

Therefore,

$$(\mathbf{r} - \mathbf{r}_0) \cdot (\mathbf{r}_u \times \mathbf{r}_v) = 0$$

is the ***equation*** of the ***tangent plane*** at P_0 .

Example

Find the equation of the tangent plane to the surface with parametric representation

$$\mathbf{r}(u, v) = u\mathbf{i} + v^2\mathbf{j} + (u^2 - v)\mathbf{k}$$

at the point $(1, 4, -1)$.

$$\mathbf{r}_u = \mathbf{i} + 0\mathbf{j} + 2u\mathbf{k}$$

$$\mathbf{r}_v = 0\mathbf{i} + 2v\mathbf{j} - \mathbf{k}$$

$$\mathbf{r}_u \times \mathbf{r}_v = -4uv\mathbf{i} + \mathbf{j} + 2v\mathbf{k}$$

The point $(1, 4, -1)$ corresponds to $\mathbf{r}(u, v) = \mathbf{i} + 4\mathbf{j} - \mathbf{k}$. so we have

$$\begin{cases} u = 1 \\ v^2 = 4 \\ u^2 - v = -1 \end{cases}$$

which implies $(u, v) = (1, 2)$.

Example

Find the equation of the tangent plane to the surface with parametric representation

$$\mathbf{r}(u, v) = u\mathbf{i} + v^2\mathbf{j} + (u^2 - v)\mathbf{k}$$

at the point $(1, 4, -1)$.

$$\mathbf{r}_u \times \mathbf{r}_v = -4uv\mathbf{i} + \mathbf{j} + 2v\mathbf{k}$$

At the point $(1, 4, -1)$, we have $u = 1$ and $v = 2$.

Thus, at $(1, -4, 1)$,

$$\mathbf{r}_u \times \mathbf{r}_v = -4uv\mathbf{i} + \mathbf{j} + 2v\mathbf{k} = -8\mathbf{i} + \mathbf{j} + 4\mathbf{k}.$$

The equation of the tangent plane is:

$$(\mathbf{r} - \mathbf{r}_0) \cdot (\mathbf{r}_u \times \mathbf{r}_v) = 0$$

$$[(x-1)\mathbf{i} + (y-4)\mathbf{j} + (z+1)\mathbf{k}] \cdot (-8\mathbf{i} + \mathbf{j} + 4\mathbf{k}) = 0.$$

$$\text{Final Answer : } -8x + y + 4z + 8 = 0.$$

Example

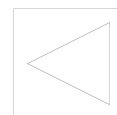
If S has Cartesian equation $z = f(x, y)$, then a parametric representation of S is

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}.$$

Thus, $\mathbf{r}_u = \mathbf{i} + 0\mathbf{j} + f_u\mathbf{k}$ and $\mathbf{r}_v = 0\mathbf{i} + \mathbf{j} + f_v\mathbf{k}$.

So the normal vector

$$\mathbf{r}_u \times \mathbf{r}_v = -f_u\mathbf{i} - f_v\mathbf{j} + \mathbf{k}.$$



Surface Integrals

Surface Integrals of Scalar Functions

$f(x, y, z)$: a (scalar) function defined on surface S .

$$\iint_S f(x, y, z) dS$$

Surface Integral

$$\iint_R f(x, y) dA$$

Double Integral

S is a bounded surface

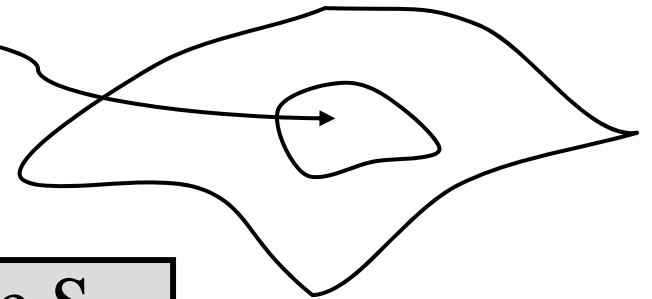
Physical Meaning

$f(x, y, z)$ = density function of a surface S

Surface integral gives the mass of the surface

$f(x, y, z)$ = constant function 1

Surface integral gives the area of the surface

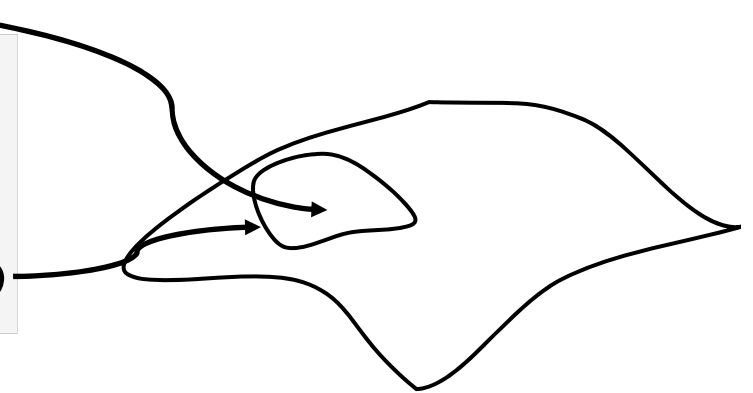


Surface Integrals of Scalar Functions

S is a bounded surface

$$S : \mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

(u, v) come from a bounded domain D



The surface integral of f over S is

$$\underbrace{\iint_S f(x, y, z) \, dS}_{\text{Surface Integral}} = \underbrace{\iint_D f(\mathbf{r}(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\| \, dA}_{\text{Double Integral}}$$

Surface Integral

Double Integral

$dudv$

Surface Integrals (Procedure)

Surface Integral of Scalar Functions $\iint_S f(x, y, z) dS$

1. Find the parametric equation of S :

$$S : \mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k} \quad (u, v) \in D$$

2. Find the domain D in terms of ranges of u and v

3. Substitution: $f(\mathbf{r}(u, v)) = f(x(u, v), y(u, v), z(u, v))$

4. Find normal vector of $\mathbf{r}_u \times \mathbf{r}_v$:
$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x_u & y_u & z_u \\ x_v & y_v & z_v \end{vmatrix}$$

5. Compute $\iint_D f(\mathbf{r}(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\| dA$ Double Integral

Surface Integrals of Scalar Functions

Let

Surface S : $\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$,

D : corresponding domain for (u, v) ,

$f(x, y, z)$: a function defined on S .

The surface integral of a scalar function f over S is

$$\iint_S f(x, y, z) dS = \iint_D f(\mathbf{r}(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\| dA.$$

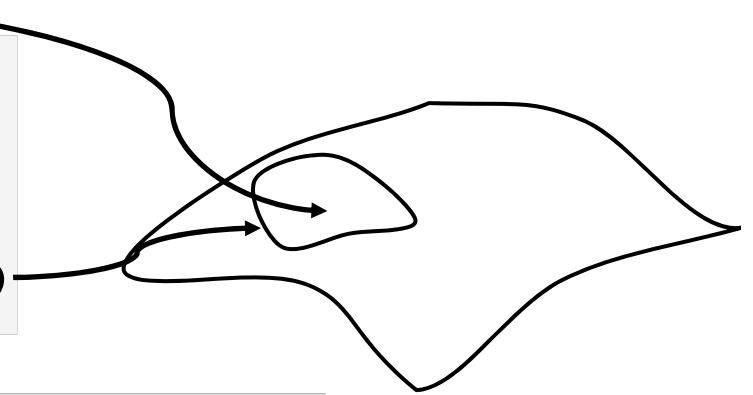
Note that $dS = \|\mathbf{r}_u \times \mathbf{r}_v\| dA = \|\mathbf{r}_u \times \mathbf{r}_v\| du dv$

Surface Integrals of Scalar Functions

S is a bounded surface

$$S : \mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

(u, v) come from a bounded domain D



The surface integral of f over S is

$$\underbrace{\iint_S f(x, y, z) dS}_{\text{Surface Integral}} = \underbrace{\iint_D f(\mathbf{r}(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\|}_{\text{Double Integral}} \underbrace{(dA)}_{\substack{dudv}}$$

Surface Integral

Double Integral

$$\iint_S 1(dS) = \text{surface area of } S$$

$$= \iint_D \sqrt{f_x^2 + f_y^2 + 1} dA = \iint_D \|\mathbf{r}_u \times \mathbf{r}_v\| dA$$

Example

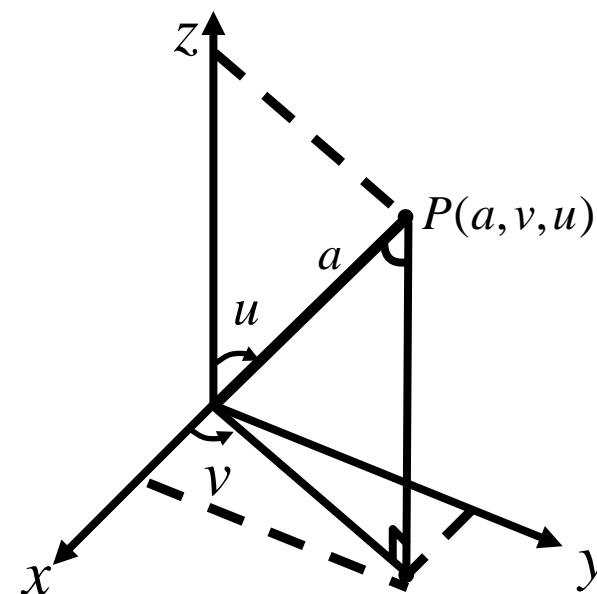
Evaluate $\iint_S (xz + yz) dS$ where S is part of the sphere $x^2 + y^2 + z^2 = 9$ in the first octant.

A parametric representation of the sphere is given by

$$\mathbf{r}(u, v) = 3 \sin u \cos v \mathbf{i} + 3 \sin u \sin v \mathbf{j} + 3 \cos u \mathbf{k}.$$

To represent the first octant, the domain D is given by

$$0 \leq u \leq \frac{\pi}{2} \quad \text{and} \quad 0 \leq v \leq \frac{\pi}{2}.$$



Example

$$\mathbf{r}(u, v) = 3 \sin u \cos v \mathbf{i} + 3 \sin u \sin v \mathbf{j} + 3 \cos u \mathbf{k}$$

$$\begin{aligned} \mathbf{r}_u \times \mathbf{r}_v &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 \cos u \cos v & 3 \cos u \sin v & -3 \sin u \\ -3 \sin u \sin v & 3 \sin u \cos v & 0 \end{vmatrix} \\ &= 9 \sin^2 u \cos v \mathbf{i} + 9 \sin^2 u \sin v \mathbf{j} + 9 \sin u \cos u \mathbf{k} \end{aligned}$$

$$\text{Thus, } \|\mathbf{r}_u \times \mathbf{r}_v\| = 9 \sin u.$$

Evaluate $\iint_S (xz + yz) dS$ where S is part of the sphere $x^2 + y^2 + z^2 = 9$ in the first octant.

$$\mathbf{r}(u, v) = 3 \sin u \cos v \mathbf{i} + 3 \sin u \sin v \mathbf{j} + 3 \cos u \mathbf{k}$$

$$\text{Domain } D : \quad 0 \leq u \leq \frac{\pi}{2} \quad \text{and} \quad 0 \leq v \leq \frac{\pi}{2}.$$

$$\text{Thus, } \|\mathbf{r}_u \times \mathbf{r}_v\| = 9 \sin u.$$

$$\begin{aligned} \iint_S (xz + yz) dS &= \iint_D (9 \sin u \cos u \cos v + 9 \sin u \cos u \sin v) \|\mathbf{r}_u \times \mathbf{r}_v\| dA \\ &= \int_0^{\pi/2} \int_0^{\pi/2} 81 \sin^2 u \cos u (\cos v + \sin v) du dv \\ &= 81 \int_0^{\pi/2} \sin^2 u \cos u du \int_0^{\pi/2} (\cos v + \sin v) dv \\ &= 81 \left[\frac{1}{3} \sin^3 u \right]_0^{\pi/2} = 54. \end{aligned}$$

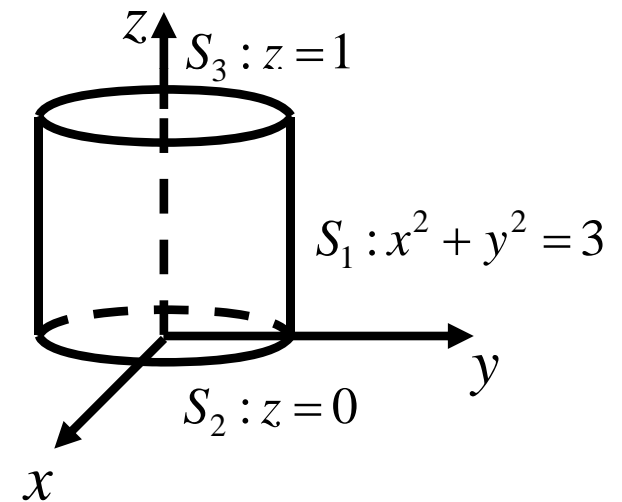
Evaluate $\iint_S z \, dS$, where S is the closed surface bounded laterally by S_1 : the cylinder $x^2 + y^2 = 3$; bounded below by S_2 : the xy - plane and bounded on top by S_3 : the horizontal plane $z = 1$.

Need to find the three surface integrals:

$$\iint_{S_1} z \, dS$$

$$\iint_{S_2} z \, dS$$

and $\iint_{S_3} z \, dS.$



The surface integral is the sum of three surface integrals :

$$\iint_S z \, dS = \iint_{S_1} z \, dS + \iint_{S_2} z \, dS + \iint_{S_3} z \, dS.$$

To find $\iint_{S_1} z \, dS$

S_1 : lateral surface of the cylinder $x^2 + y^2 = 3$

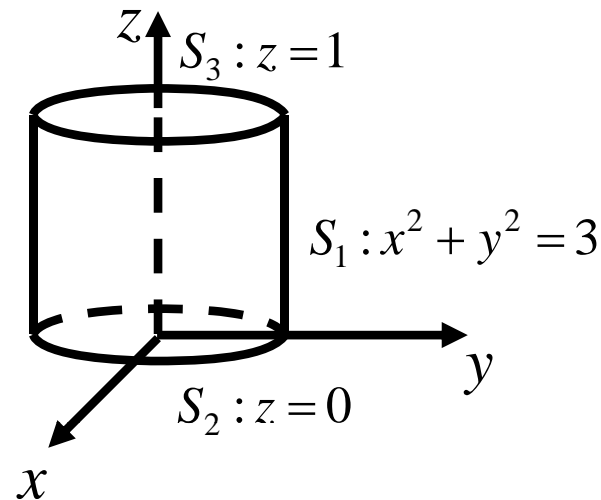
$$S_1 : \mathbf{r}(u, v) = \sqrt{3} \cos u \mathbf{i} + \sqrt{3} \sin u \mathbf{j} + v \mathbf{k}$$

$$D : 0 \leq u \leq 2\pi \text{ and } 0 \leq v \leq 1$$

$$\mathbf{r}_u \times \mathbf{r}_v = \sqrt{3} \cos u \mathbf{i} + \sqrt{3} \sin u \mathbf{j} + 0 \mathbf{k}$$

$$\|\mathbf{r}_u \times \mathbf{r}_v\| = \sqrt{3}$$

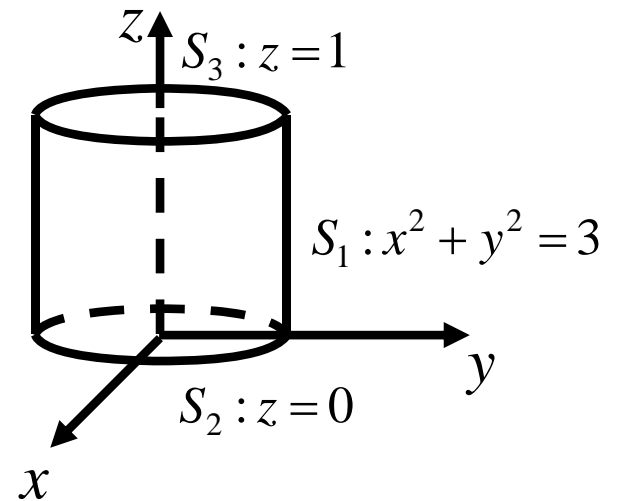
$$\begin{aligned} \iint_{S_1} z \, dS &= \iint_D v \|\mathbf{r}_u \times \mathbf{r}_v\| \, dA \\ &= \int_0^{2\pi} \int_0^1 \sqrt{3} v \, dv \, du \\ &= \int_0^{2\pi} \frac{\sqrt{3}}{2} du = \sqrt{3}\pi \end{aligned}$$



To find $\iint_{S_2} z \, dS$

S_2 : the xy -plane

S_2 is on the xy -plane.



Note that $z = 0$ on the xy -plane.

Thus, the integrand of $\iint_{S_2} z \, dS$ is zero.

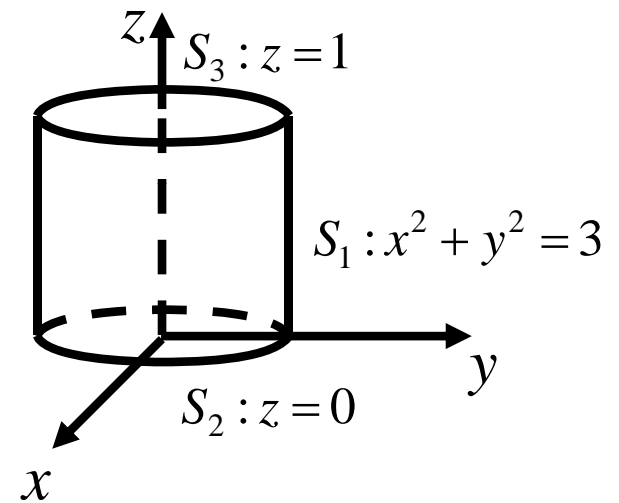
Hence, $\iint_{S_2} z \, dS = 0$.

To find $\iint_{S_3} z \, dS$

S_3 : the horizontal plane $z = 1$

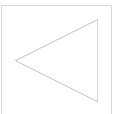
The surface S_3 is on the horizontal plane $z = 1$.

$$\begin{aligned}\iint_{S_3} z \, dS &= \iint_{S_3} dS \\ &= \text{area of } S_3 \\ &= \pi(\sqrt{3})^2 \\ &= 3\pi.\end{aligned}$$



$\iint_S 1 \, dS = \text{surface area of } S$

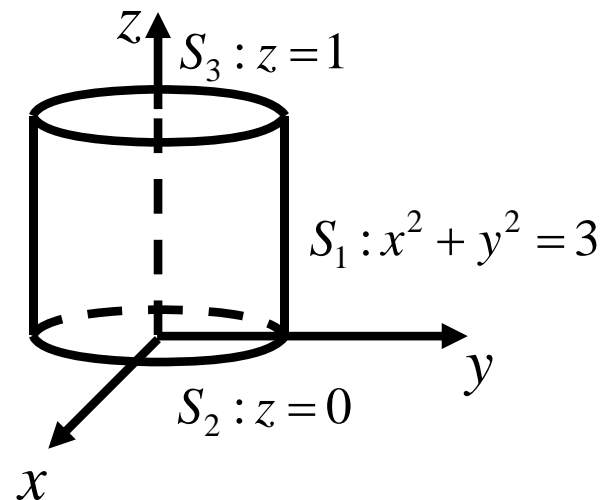
$$= \iint_D \sqrt{f_x^2 + f_y^2 + 1} \, dA = \iint_D \|\mathbf{r}_u \times \mathbf{r}_v\| \, dA$$



$$\iint_{S_1} z \, dS = \sqrt{3}\pi$$

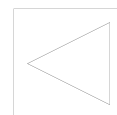
$$\iint_{S_2} z \, dS = 0$$

$$\iint_{S_3} z \, dS = 3\pi$$



Consequently,

$$\iint_S z \, dS = \iint_{S_1} z \, dS + \iint_{S_2} z \, dS + \iint_{S_3} z \, dS = (3 + \sqrt{3})\pi.$$

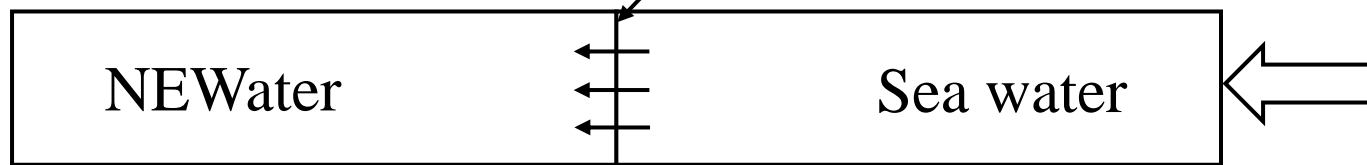


Volume Flow Rate

Reverse osmosis

Semi-permeable membrane

pressure



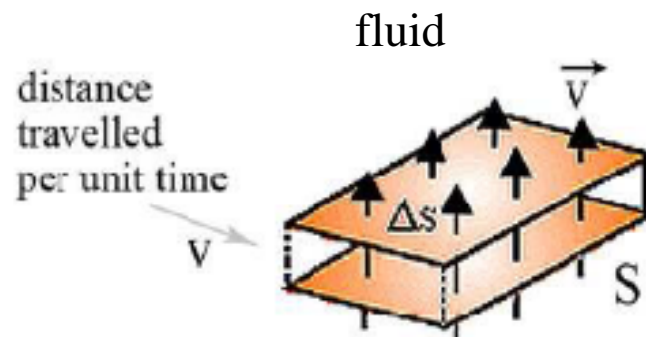
Volume flow rate through the membrane

$\text{Volume} / \text{sec} = \text{lateral distance} / \text{sec} \times \text{cross - sectional area}$

$\text{Volume rate} = \text{velocity of water flow} \times \text{cross - sectional area}$

Volume Flow Rate

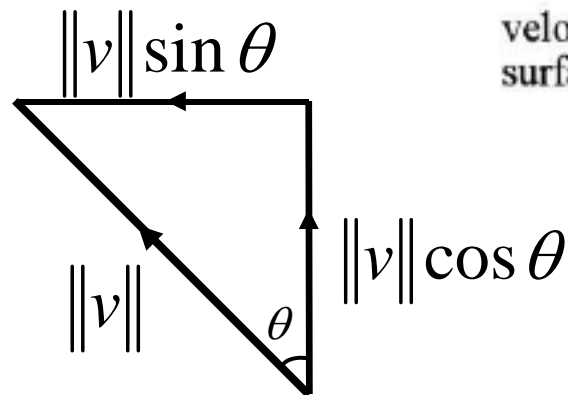
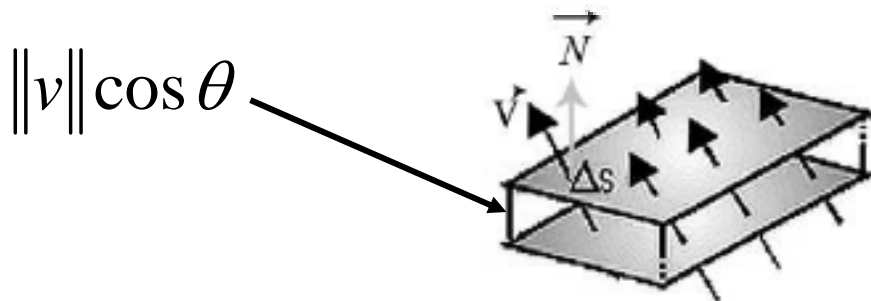
- (i) The fluid velocity is constant over flat surface S and its direction is perpendicular to S .



The volume flow rate $w = \| v \| \Delta s$

Volume Flow Rate

(ii) The fluid velocity is constant over flat surface S but its direction is not perpendicular to S .



velocity is constant
surface is flat

$$\begin{aligned}\vec{v} \cdot \vec{N} &= \|\vec{v}\| \|\vec{N}\| \cos \theta \\ &= \|\vec{v}\| \cos \theta\end{aligned}$$

\vec{N} : unit normal vector to the surface

$$\begin{aligned}\text{The volume rate } w &= (\|\vec{v}\| \cos \theta) \times \Delta s \\ &= (\vec{v} \cdot \vec{N}) \times \Delta s\end{aligned}$$

Volume Flow Rate

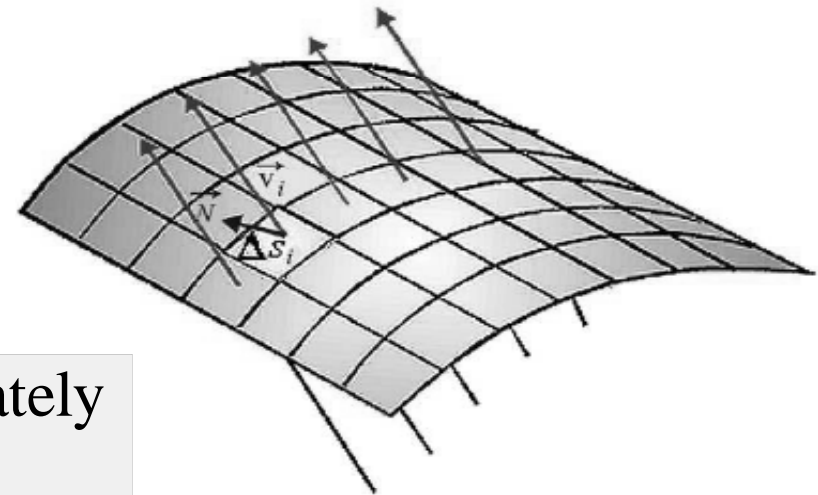
(iii) The fluid velocity is changing over curved surface S .

In a particular segment,
we have

$$w_i \approx \mathbf{v}(x_i, y_i, z_i) \cdot \mathbf{N}_i \Delta s_i.$$

Thus, the total flow rate is approximately

$$w \approx \sum_{i=1}^n \mathbf{v}(x_i, y_i, z_i) \cdot \mathbf{N}_i \Delta s_i \quad \text{-----} \quad (3)$$



General case (velocity is changing on a curved surface)

Let n goes to infinity, the RHS of (3) becomes an integral

$$\iint_S \mathbf{v}(x, y, z) \cdot \mathbf{N} ds$$

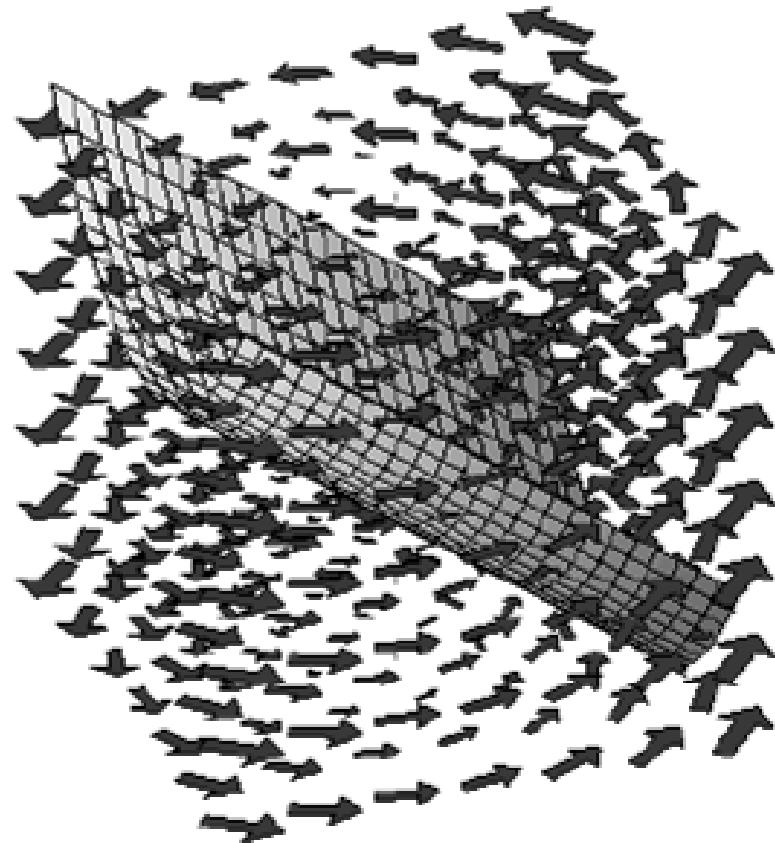
which represents the actual total volume flow rate.

This integral is called a *surface integral of the vector field \mathbf{v}* .

Flux

The Flux of a vector field F through the surface is a measure of the rate of change of the amount of the flow through the surface

Fluid flow
Heat flow
Electric flow
Magnetic flow etc



Surface Integrals of Vector Fields

Let S : surface with unit normal vector \mathbf{n} ,
and \mathbf{F} : continuous *vector field* defined on S .

The *surface integral* of \mathbf{F} over S is given by

$$\iint_S \mathbf{F} \cdot \mathbf{n} \, dS, \text{ where } \mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{\|\mathbf{r}_u \times \mathbf{r}_v\|}$$

or simply

$$\iint_S \mathbf{F} \cdot d\mathbf{S}.$$

This integral is also called the *flux* of \mathbf{F} over S as it is related to the volume flow rate of fluid.

Surface Integrals of Vector Fields

If S is given by the parametric representation $\mathbf{r}(u,v)$ with domain D , then

$$\begin{aligned}\iint_S \mathbf{F} \cdot d\mathbf{S} &= \iint_S \mathbf{F} \cdot \frac{\mathbf{r}_u \times \mathbf{r}_v}{\|\mathbf{r}_u \times \mathbf{r}_v\|} dS \\ &= \iint_D \left[\mathbf{F}(\mathbf{r}(u,v)) \cdot \frac{\mathbf{r}_u \times \mathbf{r}_v}{\|\mathbf{r}_u \times \mathbf{r}_v\|} \right] \|\mathbf{r}_u \times \mathbf{r}_v\| dA \\ &= \iint_D \mathbf{F}(\mathbf{r}(u,v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA\end{aligned}$$

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F}(\mathbf{r}(u,v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$$

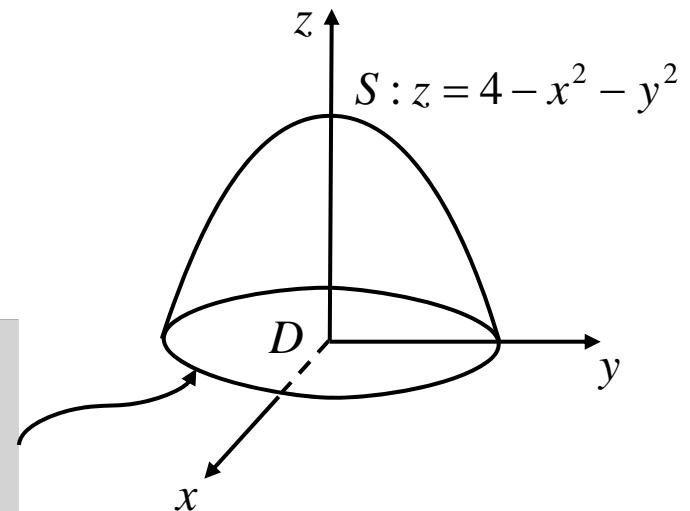
Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x, y, z) = x\mathbf{i} + y\mathbf{j} + xy\mathbf{k}$ and S is the part of the paraboloid $z = 4 - x^2 - y^2$ above the xy - plane.

Since S has Cartesian equation $z = 4 - x^2 - y^2$, the parametric representation is

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (4 - u^2 - v^2)\mathbf{k}.$$

$$z = f(x, y)$$

D is the projection onto xy - plane, which is the disk of radius 2.



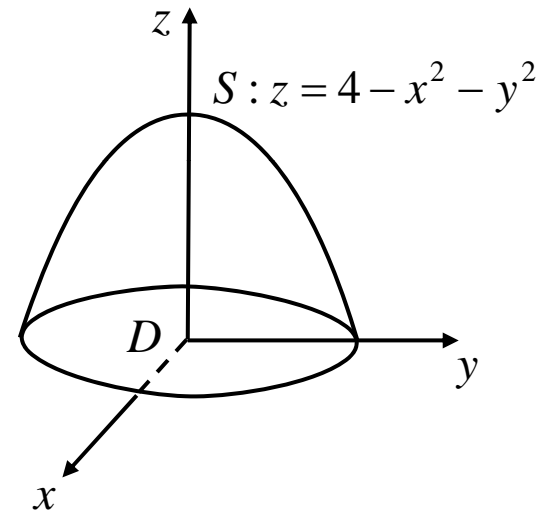
Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x, y, z) = x\mathbf{i} + y\mathbf{j} + xy\mathbf{k}$ and S is the part of the paraboloid $z = 4 - x^2 - y^2$ above the xy - plane.

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (4 - u^2 - v^2)\mathbf{k}$$

D : the disk of radius 2.

$$\mathbf{r}_u = \mathbf{i} + 0\mathbf{j} - 2u\mathbf{k} \quad \text{and} \quad \mathbf{r}_v = 0\mathbf{i} + \mathbf{j} - 2v\mathbf{k}$$

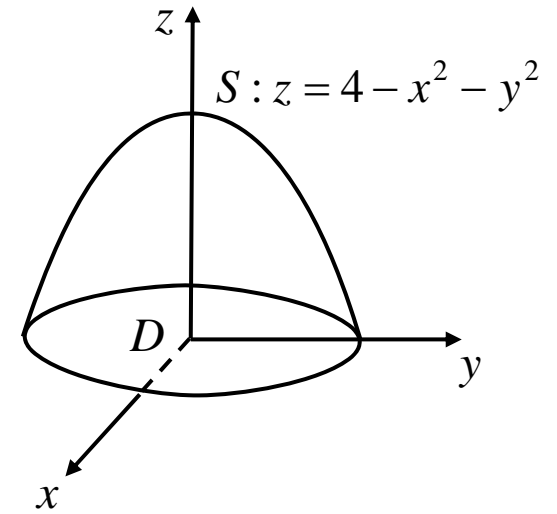
$$\mathbf{r}_u \times \mathbf{r}_v = 2u\mathbf{i} + 2v\mathbf{j} + \mathbf{k}$$



$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \iint_D \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) \, dA \\ &= \iint_D (u\mathbf{i} + v\mathbf{j} + uv\mathbf{k}) \cdot (2u\mathbf{i} + 2v\mathbf{j} + \mathbf{k}) \, dA \\ &= \iint_D (2u^2 + 2v^2 + uv) \, dA \end{aligned}$$

D : the disk of radius 2.

Note : the region D is a circular disk,
we compute the double integral
in polar coordinates.



$$\begin{aligned}\iint_S \mathbf{F} \cdot d\mathbf{S} &= \iint_D \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA \\ &= \iint_D (u\mathbf{i} + v\mathbf{j} + uv\mathbf{k}) \cdot (2u\mathbf{i} + 2v\mathbf{j} + \mathbf{k}) dA \\ &= \iint_D (2u^2 + 2v^2 + uv) dA\end{aligned}$$

$$\begin{aligned}&= \int_0^{2\pi} \int_0^2 (2r^2 + r^2 \cos \theta \sin \theta) r dr d\theta \\ &= 16\pi.\end{aligned}$$

Let $\mathbf{F}(x, y, z) = y\mathbf{i} + x\mathbf{j} + z\mathbf{k}$. Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where S is the sphere $x^2 + y^2 + z^2 = 1$.

A parametric representation of the unit sphere is given by

$$\mathbf{r}(u, v) = \sin u \cos v \mathbf{i} + \sin u \sin v \mathbf{j} + \cos u \mathbf{k},$$

with D given by $0 \leq u \leq \pi$ and $0 \leq v \leq 2\pi$.

$$\mathbf{r}_u \times \mathbf{r}_v = \sin^2 u \cos v \mathbf{i} + \sin^2 u \sin v \mathbf{j} + \sin u \cos u \mathbf{k}$$

$$\mathbf{F}(\mathbf{r}(u, v)) = \sin u \sin v \mathbf{i} + \sin u \cos v \mathbf{j} + \cos u \mathbf{k}$$

$$\mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) = 2 \sin^3 u \sin v \cos v + \sin u \cos^2 u$$

Let $\mathbf{F}(x, y, z) = y\mathbf{i} + x\mathbf{j} + z\mathbf{k}$. Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where S is the sphere $x^2 + y^2 + z^2 = 1$.

$$\mathbf{r}(u, v) = \sin u \cos v \mathbf{i} + \sin u \sin v \mathbf{j} + \cos u \mathbf{k},$$

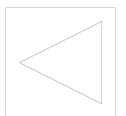
$$D : 0 \leq u \leq \pi \text{ and } 0 \leq v \leq 2\pi$$

$$\mathbf{r}_u \times \mathbf{r}_v = \sin^2 u \cos v \mathbf{i} + \sin^2 u \sin v \mathbf{j} + \sin u \cos u \mathbf{k}$$

$$\mathbf{F}(\mathbf{r}(u, v)) = \sin u \sin v \mathbf{i} + \sin u \cos v \mathbf{j} + \cos u \mathbf{k}$$

$$\mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) = 2 \sin^3 u \sin v \cos v + \sin u \cos^2 u$$

$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \int_0^{2\pi} \int_0^\pi (2 \sin^3 u \sin v \cos v + \sin u \cos^2 u) \, du \, dv \\ &= \int_0^\pi \sin^3 u \, du \int_0^{2\pi} \sin 2v \, dv + \int_0^\pi \sin u \cos^2 u \, du \int_0^{2\pi} dv \\ &= \frac{4\pi}{3}. \end{aligned}$$



Orientation of Surfaces

If S is a surface given in parametric form by $\mathbf{r} = \mathbf{r}(u, v)$, then the normal vector $\mathbf{r}_u \times \mathbf{r}_v$ automatically defines an orientation of S .

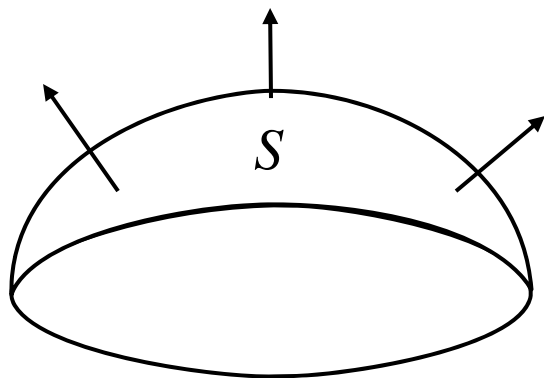
The opposite orientation is given by $\mathbf{r}_v \times \mathbf{r}_u = -\mathbf{r}_u \times \mathbf{r}_v$ and the corresponding oriented surface is denoted by $-S$.

$$\iint_{-S} \mathbf{F} \cdot d\mathbf{S} = -\iint_S \mathbf{F} \cdot d\mathbf{S}$$

Orientation of Surfaces

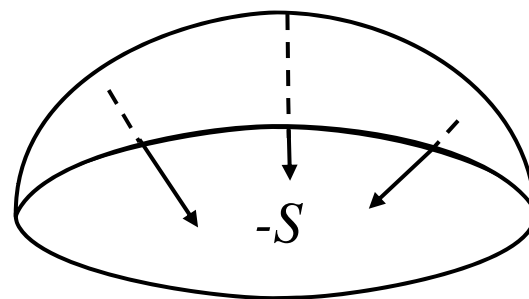
Two possible orientations of surface

----- depends on the choice of normal vectors



One Orientation

Upward Normal Vector
Outer Normal Vector



The Other Orientation

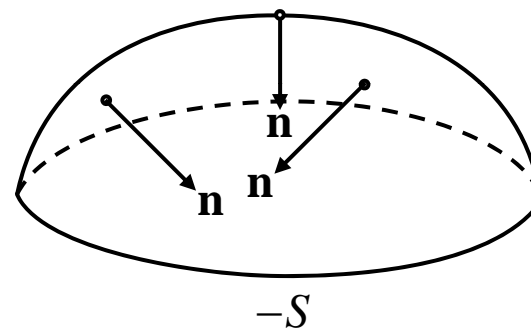
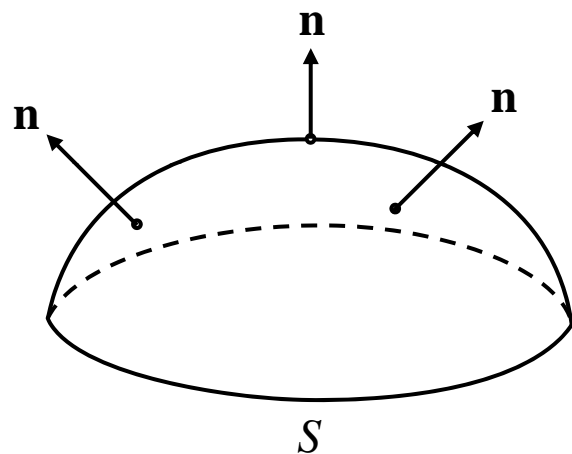
Downward Normal Vector
Inner Normal Vector

$S : \mathbf{r}(u, v)$ $\mathbf{r}_u \times \mathbf{r}_v$ supply S with an orientation

$\mathbf{r}_v \times \mathbf{r}_u = -\mathbf{r}_u \times \mathbf{r}_v$ the orientation of $-S$

$$\boxed{\iint_{-S} \mathbf{F} \cdot d\mathbf{S} = -\iint_S \mathbf{F} \cdot d\mathbf{S}}$$

Orientation of Surfaces



If S has Cartesian equation $z = f(x, y)$, then a parametric representation of S is

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + f(u, v)\mathbf{k}.$$

Thus, $\mathbf{r}_u = \mathbf{i} + 0\mathbf{j} + f_u\mathbf{k}$ and $\mathbf{r}_v = 0\mathbf{i} + \mathbf{j} + f_v\mathbf{k}$.

So the normal vector

$$\mathbf{r}_u \times \mathbf{r}_v = -f_u\mathbf{i} - f_v\mathbf{j} + \mathbf{k}.$$

$S : \mathbf{r}(u, v)$ $\mathbf{r}_u \times \mathbf{r}_v$ supply S with an orientation

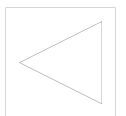
PAUSE and THINK !!

How to check $\mathbf{r}_u \times \mathbf{r}_v$ is

Upward Normal Vector

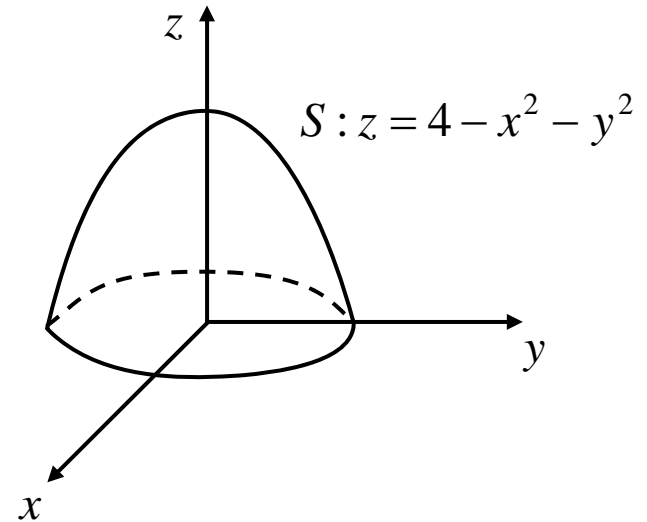
or

Downward Normal Vector ???



Example

Let S to be part of the paraboloid $z = 4 - x^2 - y^2$ above the xy - plane. We have seen the parametric representation $\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (4 - u^2 - v^2)\mathbf{k}$ and the normal vector $\mathbf{r}_u \times \mathbf{r}_v = 2u\mathbf{i} + 2v\mathbf{j} + \mathbf{k}$.



$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (4 - u^2 - v^2)\mathbf{k}$$

Normal Vector $\mathbf{r}_u \times \mathbf{r}_v = 2u\mathbf{i} + 2v\mathbf{j} + \mathbf{k}$ upward or downward?

Consider the point $(0, 0, 4)$ on the paraboloid.

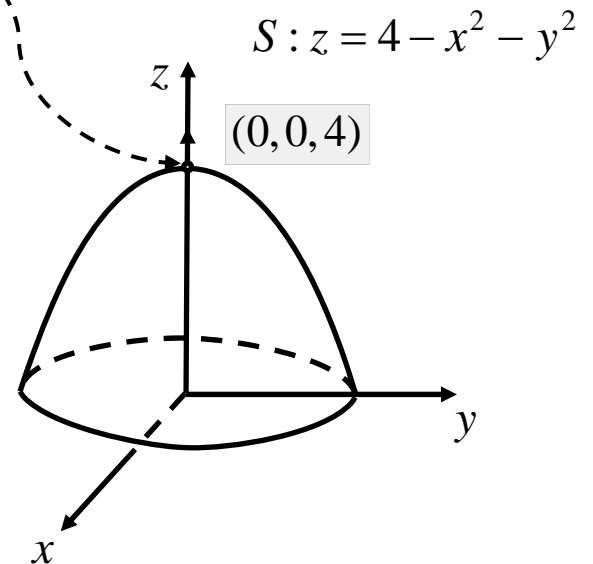
$u = 0, v = 0$

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (4 - u^2 - v^2)\mathbf{k}$$

Put $u = 0$ and $v = 0$: $\mathbf{r}_u \times \mathbf{r}_v = \mathbf{k}$

Thus, $\mathbf{r}_u \times \mathbf{r}_v$ is pointing "upwards".

Orientation of the paraboloid
is given by the
upward normal vector



Let S to be the unit sphere $x^2 + y^2 + z^2 = 1$. We have seen the parametric representation

$$\mathbf{r}(u, v) = \sin u \cos v \mathbf{i} + \sin u \sin v \mathbf{j} + \cos u \mathbf{k}$$

and the normal vector

$$\mathbf{r}_u \times \mathbf{r}_v = \sin^2 u \cos v \mathbf{i} + \sin^2 u \sin v \mathbf{j} + \sin u \cos u \mathbf{k}.$$

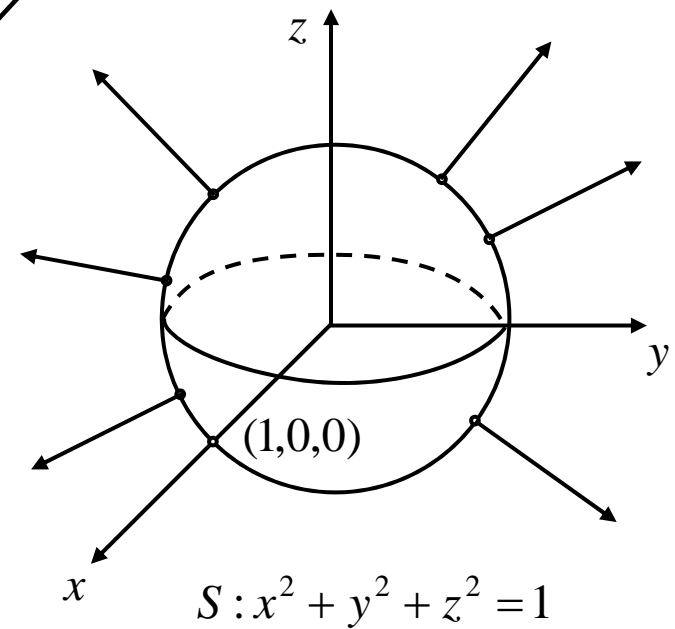
Consider the point $(1, 0, 0)$ on the sphere.

This point corresponds to $u = \frac{\pi}{2}$ and $v = 0$.

Substitute $u = \frac{\pi}{2}$ and $v = 0$ into $\mathbf{r}_u \times \mathbf{r}_v$

At $(1, 0, 0)$, $\mathbf{r}_u \times \mathbf{r}_v = \mathbf{i}$,
which is pointing "outwards".

Hence, the orientation of the sphere is given by the *outward normal vector*.



Curl and Divergence

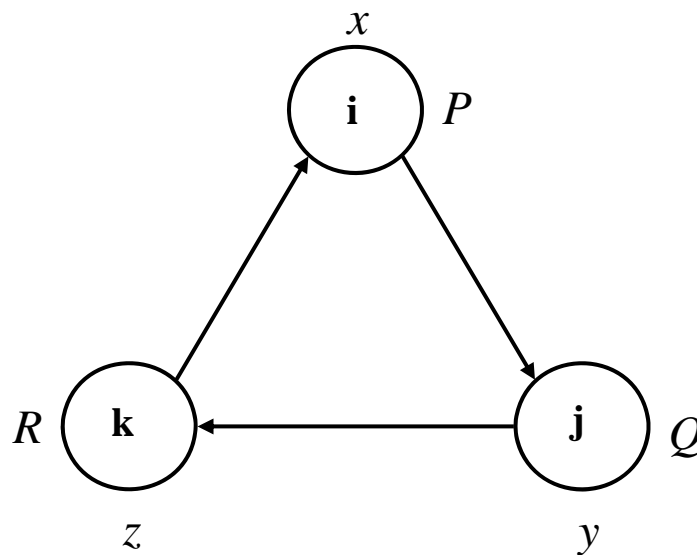
Curl

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ be a vector field in the xyz -space.

Then *curl* of \mathbf{F} is defined by

$$\text{curl } \mathbf{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

is a *vector* field.



Divergence

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ be a vector field in the xyz -space.

Then *divergence* of \mathbf{F} is defined by

$$\operatorname{div} \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

is a *scalar* field.



Curl and Divergence

Operations on vector fields

3 variable vector field $\mathbf{F} = P \mathbf{i} + Q \mathbf{j} + R \mathbf{k}$

$$\text{Curl : } \text{curl } \mathbf{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

vector field \longrightarrow curl \longrightarrow vector field

$$\text{Divergence : } \text{div } \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

vector field \longrightarrow div \longrightarrow scalar function

Del Operator

The curl and divergence operators can be expressed in terms of the del operator:

$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}.$$

Del Operator

(i) Taking the cross product of ∇ with a vector field $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$:

$$\begin{aligned}\nabla \times \mathbf{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}\end{aligned}$$

$$\boxed{\nabla \times \mathbf{F} = \text{curl } \mathbf{F}}$$

Del Operator

(ii) Taking the dot product of ∇ with a vector field $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$,

$$\begin{aligned}\nabla \cdot \mathbf{F} &= \left(\frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k} \right) \cdot (P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}) \\ &= \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}\end{aligned}$$

$$\boxed{\nabla \cdot \mathbf{F} = \operatorname{div} \mathbf{F}}$$

Example

$$\text{Let } \mathbf{F}(x, y, z) = x^2 yz\mathbf{i} + xy^2 z\mathbf{j} + xyz^2\mathbf{k}.$$

$$\nabla = \frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}.$$

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$$

$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 yz & xy^2 z & xyz^2 \end{vmatrix}$$

$$= (xz^2 - xy^2)\mathbf{i} + (x^2 y - yz^2)\mathbf{j} + (y^2 z - x^2 z)\mathbf{k}.$$

Example

$$\text{Let } \mathbf{F}(x, y, z) = x^2 yz\mathbf{i} + xy^2 z\mathbf{j} + xyz^2\mathbf{k}.$$

$$\nabla = \frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}.$$

$$\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F}$$

$$= \frac{\partial}{\partial x}(x^2 yz) + \frac{\partial}{\partial y}(xy^2 z) + \frac{\partial}{\partial z}(xyz^2)$$

$$= 6xyz.$$

Example

Show that $\text{curl } (\nabla f) = \mathbf{0}$,
i.e., $\nabla \times (\nabla f) = \mathbf{0}$.

Note that

$$f_{xy} = f_{yx}, \quad f_{xz} = f_{zx} \quad \text{and} \quad f_{yz} = f_{zy}.$$

Show that $\text{curl} (\nabla f) = \mathbf{0}$,
i.e., $\nabla \times (\nabla f) = \mathbf{0}$.

$$\text{curl} (\nabla f)$$

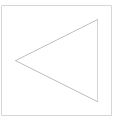
$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix}$$

$$= \left(\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) \mathbf{i} + \left(\frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z} \right) \mathbf{j} + \left(\frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) \mathbf{k}$$

$$= \mathbf{0}.$$

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$$

$$\nabla = \frac{\partial}{\partial x} \mathbf{i} + \frac{\partial}{\partial y} \mathbf{j} + \frac{\partial}{\partial z} \mathbf{k}$$



Curl and Conservation Fields

Let \mathbf{F} be a vector field in the xyz -space.

If $\text{curl } \mathbf{F} = \mathbf{0}$, then \mathbf{F} is a conservation field.

The converse is also true.

$$\mathbf{F} \text{ is conservative} \iff \nabla \times \mathbf{F} = \mathbf{0}$$

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$$

Curl and Conservative Fields

$$\text{curl } \mathbf{F} = 0 \iff \mathbf{F} \text{ is conservative (i.e., } \mathbf{F} = \nabla f)$$

$$\text{Let } \mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}.$$

$$\begin{aligned}\text{curl } \mathbf{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \\ &= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}\end{aligned}$$

$$\begin{aligned}\text{curl } \mathbf{F} = 0 &\Rightarrow \frac{\partial R}{\partial y} = \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} = \frac{\partial R}{\partial x}, \frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y} \\ &\Rightarrow \mathbf{F} \text{ is conservative}\end{aligned}$$

Example

Let $\mathbf{F}(x, y, z) = x^2 yz\mathbf{i} + xy^2 z\mathbf{j} + xyz^2\mathbf{k}$.

$$\begin{aligned}\text{curl } \mathbf{F} &= (xz^2 - xy^2)\mathbf{i} + (x^2 y - yz^2)\mathbf{j} + (y^2 z - x^2 z)\mathbf{k} \\ &\neq \mathbf{0}\end{aligned}$$

Thus, \mathbf{F} is not conservative.

Example

Find the *curl* of the velocity vector fields defined by

(a) $\mathbf{F}_1 = x\mathbf{i} + y\mathbf{j}$, (b) $\mathbf{F}_2 = -y\mathbf{i} + x\mathbf{j}$, (c) $\mathbf{F}_3 = \cos y \mathbf{i} + \sin x \mathbf{j}$.

Solution:

(a) $\text{curl } \mathbf{F}_1 = \mathbf{0}$

(b) $\text{curl } \mathbf{F}_2 = 2\mathbf{k}$

(c) $\text{curl } \mathbf{F}_3 = (\cos x + \sin y)\mathbf{k}$

Example

Find the *divergence* of the velocity vector fields defined by

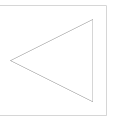
(a) $\mathbf{F}_1 = x\mathbf{i} + y\mathbf{j}$, (b) $\mathbf{F}_2 = -y\mathbf{i} + x\mathbf{j}$, (c) $\mathbf{F}_3 = -x^2\mathbf{i} + y^2\mathbf{j}$.

Solution:

(a) $\operatorname{div} \mathbf{F}_1 = 2$

(b) $\operatorname{div} \mathbf{F}_2 = 0$

(c) $\operatorname{div} \mathbf{F}_3 = 2(y - x)$



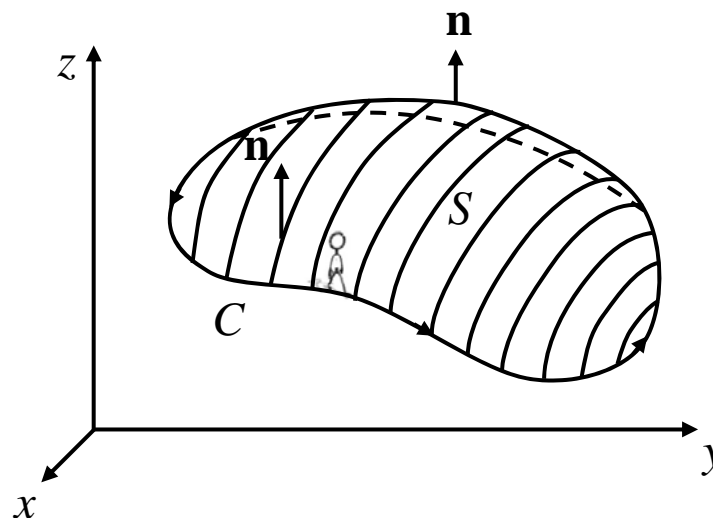
Stokes' Theorem

Let S be an oriented piecewise-smooth surface that is bounded by a closed, piecewise-smooth boundary curve C . Let \mathbf{F} be a vector field whose components have continuous partial derivatives on S . Then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}.$$

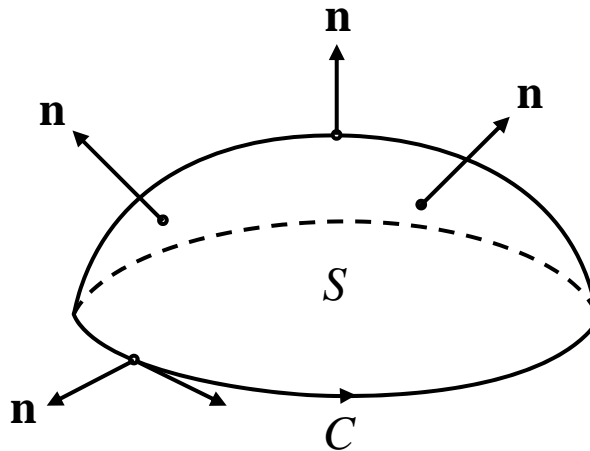


George Gabriel Stokes
1819 - 1903



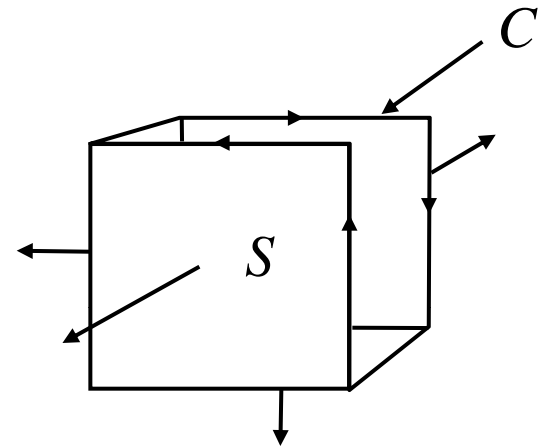
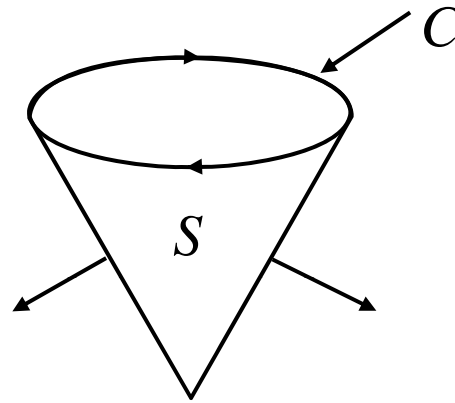
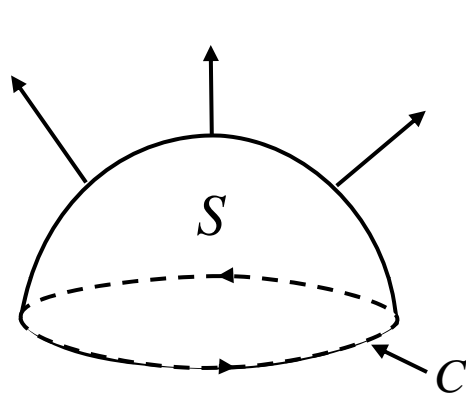
Stokes' Theorem - Note

The orientation of C must be consistent with that of S :
when you walk in the direction (orientation) around C with your head pointing in the direction of the normal vector of S , the surface S should be on your left.



Orientation - Boundary Curve of Surface

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\text{curl } \mathbf{F}) \cdot d\mathbf{S}$$



Orientation of C must be consistent with orientation of S :
Traverse in the direction (orientation) of C , with head in the direction (orientation) of the normal vector of S . The corresponding "face" of S must be on the left hand side.

Stokes' Theorem

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$.

$$\text{curl } \mathbf{F} = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \oint_C P \, dx + Q \, dy + R \, dz$$

Stokes' Theorem

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$.

\mathbf{F} : vector field whose components have continuous partial derivatives on surface S .

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \oint_C P \, dx + Q \, dy + R \, dz$$

$$\left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

line integral
of vector field

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\text{curl } \mathbf{F}) \cdot d\mathbf{S}$$

surface integral
of vector field

Make sure the orientations of C and S are correct.

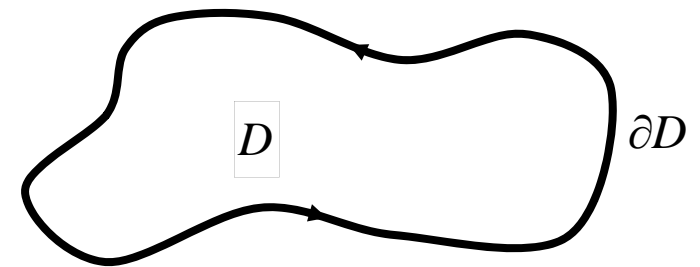
S : oriented piecewise-smooth surface with a "boundary curve" C .

Green's Theorem

$$\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$$

We may write the line integral as

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C P \, dx + Q \, dy.$$



positive orientation of ∂D

By Green's Theorem,

$$\oint_{\partial D} P \, dx + Q \, dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

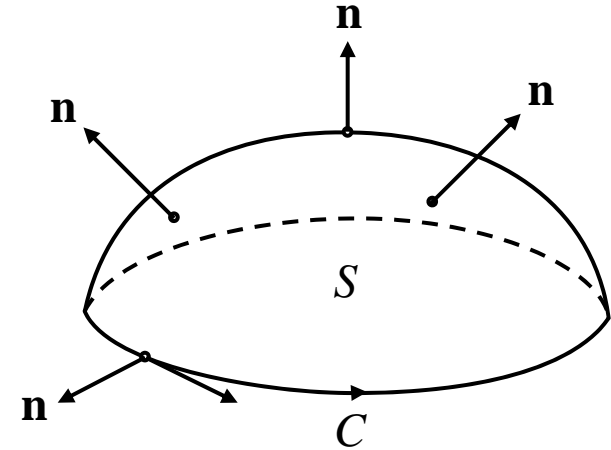
Note : Green's Theorem is for two variables

Stokes' Theorem

Let $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$.

We may write the line integral as

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C P dx + Q dy + R dz.$$



By Stokes' Theorem,

$$\int_C P dx + Q dy + R dz =$$

$$\iint_S \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k} \cdot d\mathbf{S}$$

Note : Stoke's Theorem is for three variables

Stokes' Theorem

Recall that

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F}(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$$

By Stokes' Theorem,

$$\begin{aligned} \int_C \mathbf{F} \cdot d\mathbf{r} &= \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} \\ &= \iint_D (\text{curl } \mathbf{F})(\mathbf{r}(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA \end{aligned}$$

Example

Use Stokes' Theorem to evaluate $\int_C \mathbf{F} \cdot d\mathbf{r}$, where $\mathbf{F} = yz\mathbf{i} - xz\mathbf{j} + xy\mathbf{k}$ and C is the curve of intersection of the plane $y + z = 3$ and the cylinder $x^2 + y^2 = 4$. (C is oriented in the **counterclockwise** sense when viewed from above.)

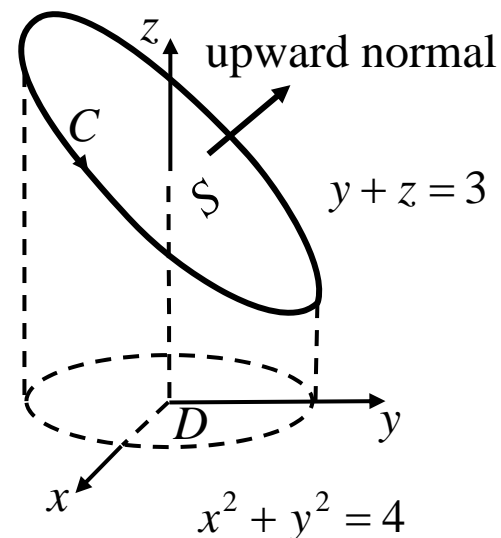
Let S be the (bounded) surface enclosed by C on the plane $y + z = 3$.

$$z = y - 3$$

S has parametric representation

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (3 - v)\mathbf{k}$$

and the region D is the disk of radius 2.



D : disk of radius 2

$$\mathbf{r}(u, v) = u\mathbf{i} + v\mathbf{j} + (3 - v)\mathbf{k}$$

$$\mathbf{r}_u = \mathbf{i}$$

$$\mathbf{r}_v = \mathbf{j} - \mathbf{k}$$

Note that : $\mathbf{r}_u \times \mathbf{r}_v = \mathbf{j} + \mathbf{k}$ upward normal vector of S .

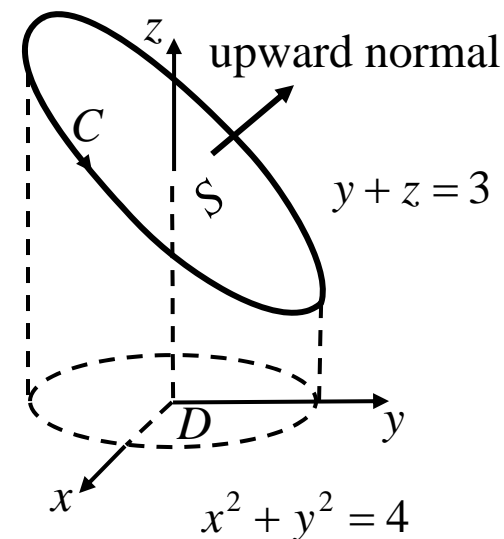
This gives the orientation of S which agrees with that of C .

$$\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$$

$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & -xz & xy \end{vmatrix} = 2x\mathbf{i} - 2z\mathbf{k}.$$

By Stokes' Theorem,

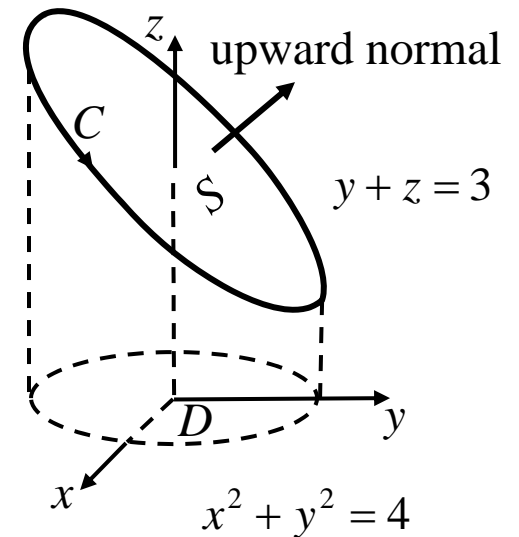
$$\begin{aligned} \int_C \mathbf{F} \cdot d\mathbf{r} &= \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} \\ &= \iint_D (2u\mathbf{i} - 2(3 - v)\mathbf{k}) \cdot (\mathbf{j} + \mathbf{k}) dA \\ &= \iint_D (-6 + 2v) dA \end{aligned}$$



D : disk of radius 2

By Stokes' Theorem,

$$\begin{aligned}\int_C \mathbf{F} \cdot d\mathbf{r} &= \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} \\ &= \iint_D (2u\mathbf{i} - 2(3-v)\mathbf{k}) \cdot (\mathbf{j} + \mathbf{k}) \, dA \\ &= \iint_D (-6 + 2v) \, dA\end{aligned}$$



D : disk of radius 2

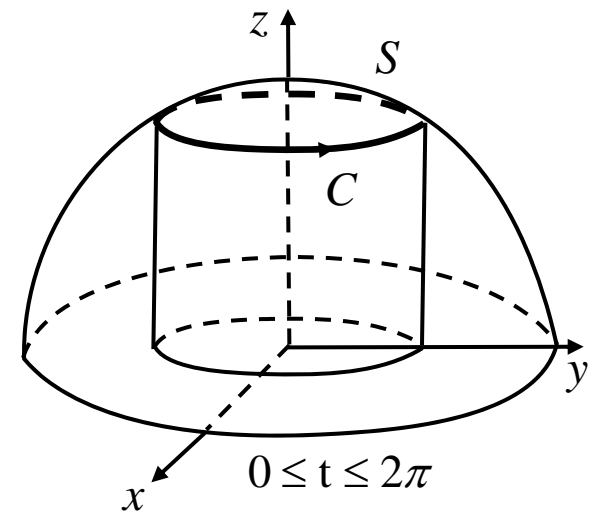
Since D is the disk of radius 2, we may use polar coordinates:

$$\begin{aligned}\int_C \mathbf{F} \cdot d\mathbf{r} &= \int_0^{2\pi} \int_0^2 (-6 + 2r \sin \theta) r \, dr \, d\theta \\ &= \int_0^{2\pi} \left(-12 + \frac{16}{3} \sin \theta \right) d\theta \\ &= -24\pi.\end{aligned}$$

Example

Use Stokes' Theorem to evaluate $\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x, y, z) = y^2 z \mathbf{i} + x \mathbf{j} + (x + y) \mathbf{k}$ and S is the part of the upper hemisphere $z = \sqrt{9 - x^2 - y^2}$ that lies within the cylinder $x^2 + y^2 = 5$ and the orientation of S is given by the upward normal vector.

The boundary of S is C which is the intersection of hemisphere and cylinder (circle in horizontal plane)



S : part of the upper hemisphere $z = \sqrt{9 - x^2 - y^2}$
that lies within the cylinder $x^2 + y^2 = 5$.

Not easy to have a parametric representation for S .

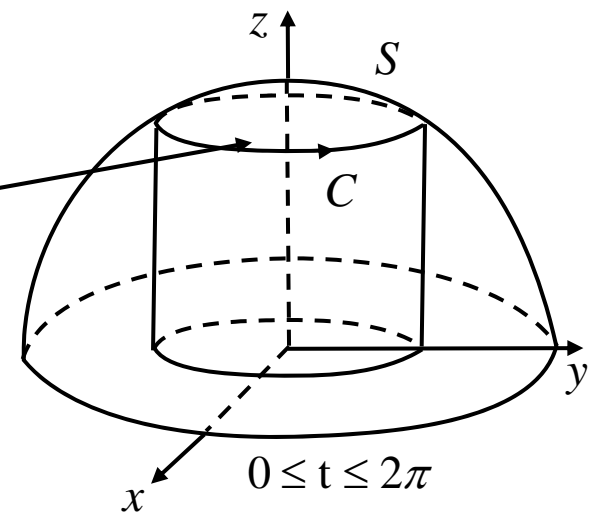
C : a circle in the horizontal plane

Easy to give a parametric representation for C .

Parametric equation of C :

$$\mathbf{r}(t) = \sqrt{5} \cos t \mathbf{i} + \sqrt{5} \sin t \mathbf{j} + a \mathbf{k}$$

Solving $x^2 + y^2 = 5$ and $z = \sqrt{9 - x^2 - y^2}$,
we get $z = 2$



$$\iint_S (\text{curl } \mathbf{F}) \cdot d\mathbf{S} = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

Use Stoke's Theorem
find line integral instead.

S is the part of the upper hemisphere $z = \sqrt{9 - x^2 - y^2}$ that lies within the cylinder $x^2 + y^2 = 5$ and the orientation of S is given by the upward normal vector.

Parametric equation of C :

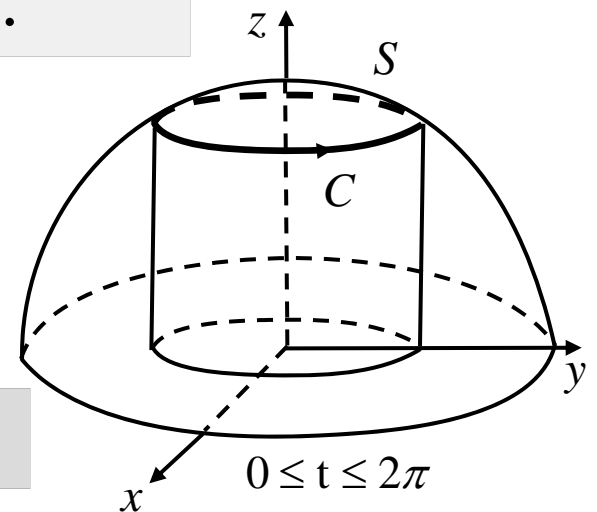
$$\mathbf{r}(t) = \sqrt{5} \cos t \mathbf{i} + \sqrt{5} \sin t \mathbf{j} + 2 \mathbf{k}$$

With this vector equation, the curve traverses in anticlockwise direction when viewed from top. This agrees with the given orientation of S .

$$\mathbf{r}'(t) = -\sqrt{5} \sin t \mathbf{i} + \sqrt{5} \cos t \mathbf{j} + 0 \mathbf{k}$$

$$\mathbf{F}(x, y, z) = y^2 z \mathbf{i} + x \mathbf{j} + (x + y) \mathbf{k}$$

$$\mathbf{F}(\mathbf{r}(t)) = 10 \sin^2 t \mathbf{i} + \sqrt{5} \cos t \mathbf{j} + \sqrt{5}(\cos t + \sin t) \mathbf{k}$$



Parametric equation of C :

$$\mathbf{r}(t) = \sqrt{5} \cos t \mathbf{i} + \sqrt{5} \sin t \mathbf{j} + 2 \mathbf{k}$$

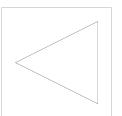
$$0 \leq t \leq 2\pi$$

$$\mathbf{r}'(t) = -\sqrt{5} \sin t \mathbf{i} + \sqrt{5} \cos t \mathbf{j} + 0\mathbf{k}$$

$$\mathbf{F}(\mathbf{r}(t)) = 10 \sin^2 t \mathbf{i} + \sqrt{5} \cos t \mathbf{j} + \sqrt{5}(\cos t + \sin t)\mathbf{k}$$

By Stokes' Theorem,

$$\begin{aligned} \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} &= \int_C \mathbf{F} \cdot d\mathbf{r} \\ &= \int_C \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt \\ &= \int_0^{2\pi} (-10\sqrt{5} \sin^3 t + 5 \cos^2 t) dt \\ &= 5\pi. \end{aligned}$$



PAUSE and THINK !!

What is the difference between the two examples ???

Use Stokes' Theorem to evaluate $\int_C \mathbf{F} \cdot d\mathbf{r}$, where

$\mathbf{F} = yz\mathbf{i} - xz\mathbf{j} + xy\mathbf{k}$ and C is the curve of intersection of the plane $y + z = 3$ and the cylinder $x^2 + y^2 = 4$. (C is oriented in the clockwise sense when viewed from above.)

By Stokes' Theorem, $\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} = \iint_D (2u\mathbf{i} - 2(3-v)\mathbf{k}) \cdot (\mathbf{j} + \mathbf{k}) dA$

Use Stokes' Theorem to evaluate $\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F}(x, y, z) = y^2 z\mathbf{i} + x\mathbf{j} + (x + y)\mathbf{k}$ and S is the part of the upper hemisphere $z = \sqrt{9 - x^2 - y^2}$ that lies within the cylinder $x^2 + y^2 = 5$ and the orientation of S is given by the upward normal vector.

By Stokes' Theorem,

$$\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} = \int_C \mathbf{F} \cdot d\mathbf{r} = \int_C \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_0^{2\pi} (-10\sqrt{5} \sin^3 t + 5 \cos^2 t) dt = 5\pi$$

Divergence Theorem (Gauss' Theorem)

Divergence Theorem

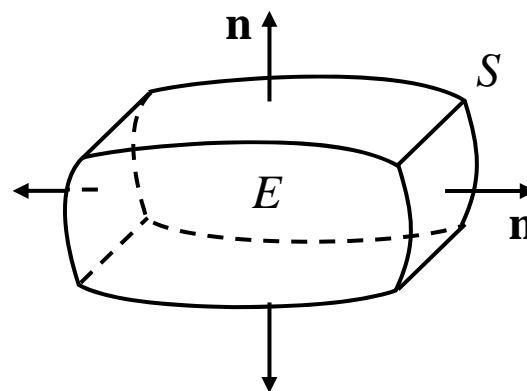


Divergence Theorem

Let E be a solid region and let S be the boundary of E , given with the *outward orientation*^{*}. Let \mathbf{F} be a vector field whose component functions have continuous partial derivatives in E . Then

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \operatorname{div} \mathbf{F} \, dV$$

^{*}The outward orientation of the boundary surface of a solid region E is the one for which the normal vector point outward from E .



Divergence Theorem

surface integral
of vector field

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iiint_E \operatorname{div} \mathbf{F} dV$$

triple integral
of scalar function

take the outer normal orientation

\mathbf{F} : a vector field whose component functions have continuous partial derivatives in E .

E : a bounded solid region

S : the boundary surface of E

i.e., S must be a closed surface

Evaluate $\iint_S \mathbf{F} \cdot d\mathbf{S}$, where $\mathbf{F} = x^2\mathbf{i} + (xy + x \cos z)\mathbf{j} + e^{xy}\mathbf{k}$ and S is the surface of the cubic region E bounded by the three coordinate planes $x = 0, y = 0, z = 0$ and the three planes $x = 1, y = 1, z = 1$. The orientation of S is given by the outward normal vector.

The cubic region E can be described as

$$E : 0 \leq x \leq 1, \quad 0 \leq y \leq 1, \quad 0 \leq z \leq 1.$$

By the Divergence Theorem, we have

$$\begin{aligned} \iint_S \mathbf{F} \cdot d\mathbf{S} &= \iiint_E \operatorname{div} \mathbf{F} \, dV \\ &= \iiint_E 3x \, dV \\ &= 3 \int_0^1 \int_0^1 \int_0^1 x \, dx \, dy \, dz = \frac{3}{2}. \end{aligned}$$

Find $\iint_S \mathbf{F} \cdot d\mathbf{S}$ where $\mathbf{F}(x, y, z) = (x + y)\mathbf{i} + (y + z)\mathbf{j} + (z + x)\mathbf{k}$ and S is the unit sphere $x^2 + y^2 + z^2 = 1$.

Note that : S is a closed surface

By the Divergence Theorem,

$$\begin{aligned}\iint_S \mathbf{F} \cdot d\mathbf{S} &= \iiint_E \operatorname{div} \mathbf{F} \, dV \quad \text{where } E = \text{unit ball} \\ &= \iiint_E 3 \, dV \\ &= 3 \times \text{volume of the unit ball} \\ &= 4\pi\end{aligned}$$

$$\text{volume of the unit ball} = \frac{4}{3} \pi r^3 = \frac{4}{3} \pi$$

End