

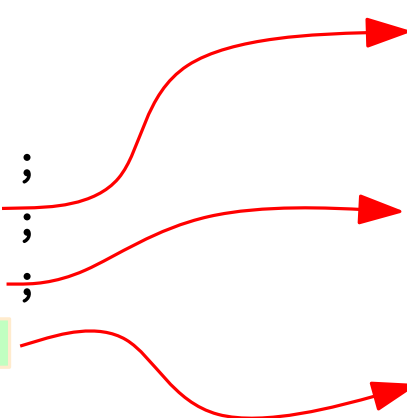
# Sources of Inefficiency in Syntax-Based Translations. Optimizations.

– lecture 6 pre-recording –

# Sources of Inefficiency in Generated Code

- Inefficient code:
  - Redundant instructions (which can be removed without changing the functionality of the code)
  - Groups of instructions that can be replaced by smaller, faster, but functionally equivalent instructions.
- Appear at the boundary between code fragments generated for different components.
  - Translation scheme has to assume worst-case scenario
  - Cannot safely assume availability of data in registers; always loads/saves to memory
  - These loads/saves are often redundant
- Important to understand what kind of code will be inefficient
  - Gives us a chance to correctly detect opportunities for optimizations.

# Inefficient Instruction Groups / Redundant Loads

<pre>global a ; a = 1 ; { local b,c ;   b = a + 1 ;   c = a + b ;   a = b + c }</pre>		<pre>movl \$1,a movl a,%eax addl \$1,%eax movl %eax,-4(%ebp) movl a,%eax addl -4(%ebp),%eax movl %eax,-8(%ebp) movl -4(%ebp),%eax addl -8(%ebp),%eax movl %eax,a</pre>	<pre># could be replaced with #   addl a,%eax  # redundant</pre>
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# GCC's Optimization

Obtained with `gcc -O2`

```
int a ;  
void f(int x) {  
    a = x ;  
    {  
        int b,c ;  
        b = a + 1 ;  
        c = a + b ;  
        a = b + c ;  
    }  
}
```

`leal 2(%eax,%eax,2), %eax`



Equivalent to  $a = 3*a+2$  (local variables optimized away)

Compiler performs algebraic reconstruction, applies algebraic laws, and recompiles resulting formula

# Jump Into Jump / Consec Uncond Jumps

```

global i,j ;
i = 10 ; j = 100 ;
if ( i < j ) then {
    j = j - 1
} ;
while i > 0 do {
    if i == 5
    then { i = i - 2 }
    else { j = j + 1 ;
           continue } ;
    i = i - 1
}
    
```

```

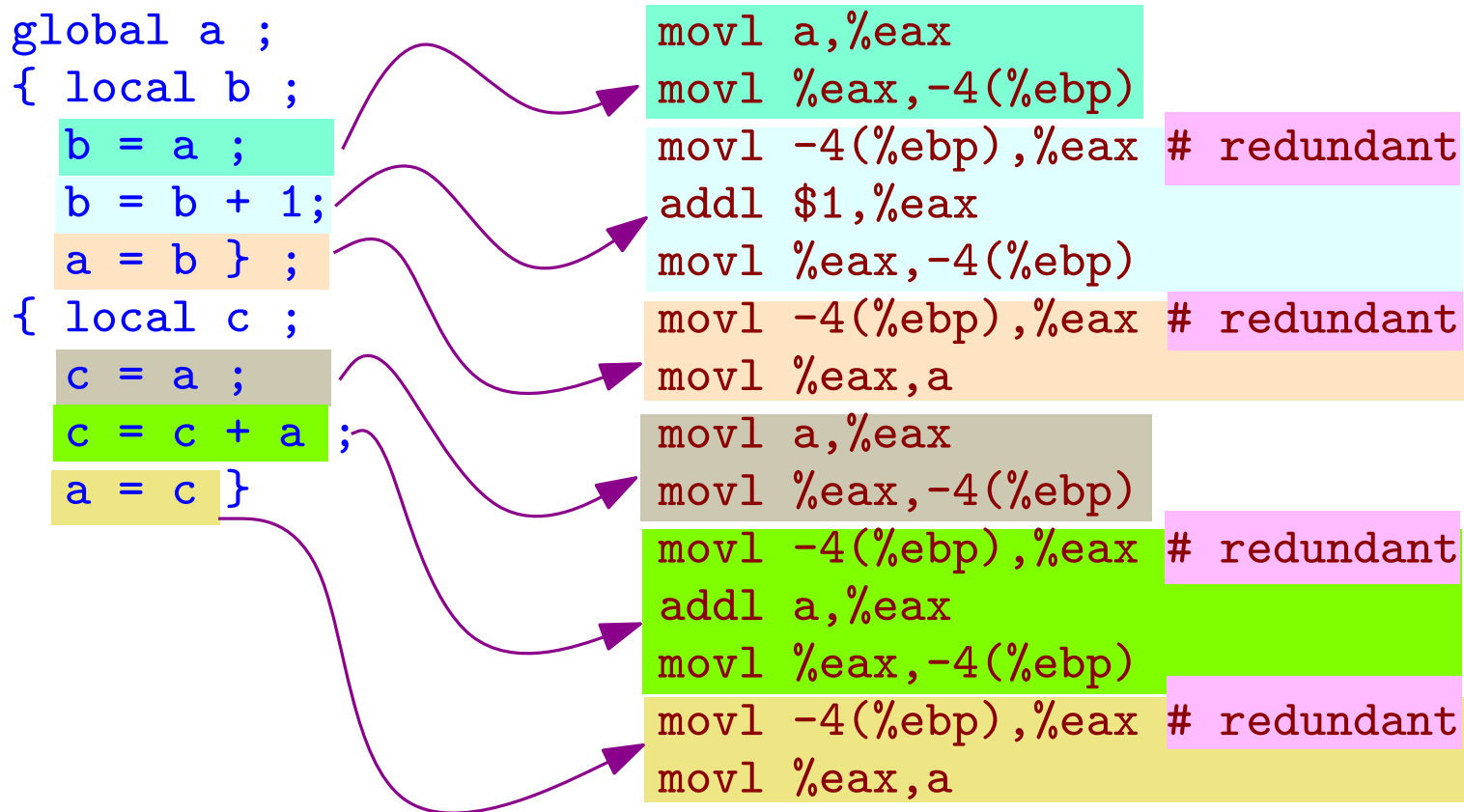
movl $10,i
movl $100,j
movl i,%eax
cmpl j,%eax
jge L0      # could be replaced by jge L5
movl j,%eax
subl $1,%eax
movl %eax,j
L0:
    jmp L5
L4:
    movl i,%eax
    cmpl $5,%eax
    je L2
    movl j,%eax
    addl $1,%eax
    movl %eax,j
    jmp L1
    jmp L3      # redundant, never executed
L2:
    movl i,%eax
    subl $2,%eax
    movl %eax,i
L3:
    movl i,%eax
    subl $1,%eax
    movl %eax,i
L5:
L1:
    movl i,%eax
    cmpl $0,%eax
    jg L4
    
```

# GCC's Optimization

```
int i,j ;
void f(c10,c100) {
    i = c10 ; j = c100 ;
    if ( i < j ) {
        j = j - 1 ;
    }
    while (i > 0) {
        if (i == 5) {
            i = i - 2 ;
        } else {
            j = j + 1 ;
            continue ;
        }
        i = i - 1 ;
    }
}
```

```
    movl 8(%ebp), %eax
    movl 12(%ebp), %edx
    movl %eax, _i
    cmpl %edx, %eax
    jge L2
    subl $1, %edx
L2:
    testl %eax, %eax
    movl _i, %ecx
    jle L8
L5:
    cmpl $5, %eax
    je L6
    addl $1, %edx
    movl %ecx, %eax
L9:
    testl %eax, %eax
    jg L5
L8:
    movl %ecx, _i
    movl %edx, _j
    popl %ebp
    ret
L6:
    movl $2, %ecx
    movl %ecx, %eax
    jmp L9
```

# Redundant Loads



# GCC's Optimization

```
int a ;  
void f() {  
  { int b ;  
    b = a ;  
    b = b + 1 ;  
    a = b ; }  
  { int c ;  
    c = a ;  
    c = c + a ;  
    a = c ; }  
}
```

leal 2(%eax,%eax), %eax  
movl %eax, \_a

a = 3\*a



# Conclusion

- Syntax-based translation leads to inherent inefficiency
- In designing translation schemes for components, worst case scenarios have to be assumed.
- Optimizations:
  - Peephole: directly on generated code, looking at short groups of instructions
  - Algebraic: reconstructing general expressions from generated code, applying algebraic laws, and re-translating