

**CG2271 Real Time Operating Systems**  
**Tutorial 8**

Question 1

Describe what a race condition is.

Suppose two identical tasks update a shared variable *tmp* using this instruction:

```
tmp++ ;
```

Can a race condition occur? Why or why not?

Question 2

Using Google, the textbook or any other resource, describe what "atomicity" means. The kernel often disables interrupts to guarantee atomicity. Explain how this works. Explain further why it's a bad idea to allow user processes to achieve atomicity in the same way.

Question 3

For each of the following mechanisms:

- i) Is the mechanism effective in enforcing mutual exclusions, and why or why not.
- ii) If the mechanism is able to enforce mutual exclusion, list and explain the advantages and disadvantages of the mechanism.

- 1) Disabling Interrupts.
- 2) Lock variables.
- 3) Strict alternation.
- 4) Peterson's Solution.
- 5) Sleep/wakeup.

Question 4

The condition variables in monitors work in a very similar way to "sleep" and "wake".

- a. Explain how condition variables are the same and how they are different from "sleep" and "wake".
- b. The "sleep" and "wake" operations are known to cause deadlock, resulting in the producer/consumer problem. If a buffer is implemented using monitors and condition variables, can the producer/consumer problem still occur? Why or why not?