

# Tutorial 4

Q1

(a) Recall: An equilibrium point (solution) of a given ODE is a solution which is constant.

If  $x_E$  is an equilibrium pt of  $\ddot{x} = f(x)$ ,

$$\text{then } \ddot{x}_E = f(x_E)$$
$$\quad \quad \quad \parallel$$
$$\quad \quad \quad 0$$

$$\therefore f(x_E) = 0$$

So finding equilibrium point is  
finding roots of  $f(x) = 0$

(b) Stability of equilibrium pt

To discuss stability of equilibrium pt, we just need to look at those  $x$  near the equilibrium pt

Hence we want to find the approximate value of  $f(x)$ , where  $x$  near the equilibrium pt

We can use the tangent line at equilibrium pt to approximate  $f(x)$

$$f'(x_E) = \lim_{x \rightarrow x_E} \frac{f(x) - f(x_E)}{x - x_E}$$
$$\approx \frac{f(x) - f(x_E)}{x - x_E}$$

$$f(x) \approx f(x_E) + f'(x_E) (x - x_E)$$

$$\stackrel{0}{=} f'(x_E) x - f'(x_E) x_E$$

So near the equilibrium pt,  
the given ODE can be  
approximated by

$$\ddot{x} = f(x) \approx f'(x_E) x - f'(x_E) x_E$$

$\therefore$  We just need to discuss  
the stability of

$$\ddot{x} = f'(x_E) x - f'(x_E) x_E$$

$$\ddot{x} - f'(x_E) x = -f'(x_E) x_E$$

2nd order nonhomogeneous ODE

Case 1  $f'(x_E) < 0$ . Let  $\omega^2 = -f'(x_E)$

$$x = x_h + x_p$$

$$= \underbrace{A \cos \omega t + B \sin \omega t}_{\text{SHM}} + \underbrace{x_E}_{\text{constant}}$$

If the initial value is close to the equilibrium pt  $x_E$ , then  $x$  oscillates near  $x_E$ .

Hence the equilibrium pt  $x_E$  is stable.

Case 2  $f'(x_E) > 0$ . Let  $\omega^2 = f'(x_E)$

$$x = x_h + x_p$$

$$= A e^{\omega t} + B e^{-\omega t} + x_E$$

$x$  will move away from equilibrium pt.  $x_E$ . Hence  $x_E$  is not stable

Case 3  $f'(x_E) = 0$

$$\therefore \ddot{x} = f'(x_E)x + x_E = x_E$$

$$\therefore \dot{x} = x_E t + A$$

$$x = \frac{1}{2} x_E t^2 + A t + B$$

$\therefore x$  will move away from  $x_E$

$\therefore x_E$  not stable

$$(i) \ddot{x} = \cosh x = \frac{e^x + e^{-x}}{2}$$

$$f(x) = \frac{e^x + e^{-x}}{2} \neq 0 \text{ for all } x$$

$\therefore \ddot{x} = \cosh x$  has no equilibrium pt

$$(ii) \ddot{x} = \cos x$$

$$f(x) = \cos x$$

$$f(x_E) = 0 \Leftrightarrow x_E = \frac{\pi}{2}, \frac{3\pi}{2}, \dots$$

$$f'(x) = -\sin x$$

$$f'(x_E) = -\sin x_E = \begin{cases} + & \text{if } x_E = \frac{3\pi}{2} \\ - & \text{if } x_E = \frac{\pi}{2} \end{cases}$$

$$\therefore \text{At } x_E = \frac{\pi}{2} \quad \text{stable}$$

$$x_E = \frac{3\pi}{2} \quad \text{unstable}$$

$$\text{when } x_E = \frac{\pi}{2}$$

$$\omega^2 = -f'(x_E) = -(-\sin x_E)$$

$$= \sin x_E$$

$$= \sin \frac{\pi}{2} = 1$$

$$\omega = 1$$

$$(ii) \quad \ddot{x} = \tan(\sin x)$$

$$\therefore f(x) = \tan(\sin x)$$

$$f(x_E) = 0 \Leftrightarrow x_E = 0, \pi, \dots$$

$$f'(x) = [\sec^2(\sin x)] \cos x$$

$$f'(0) = 1 \quad \text{unstable}$$

$$f'(\pi) = -1 \quad \text{stable}$$

$$\omega^2 = -f'(\pi) = 1$$

$$\omega = 1$$

Q3

Q3 Amplitude  $A(\alpha)$  is given by

$$A(\alpha) = \frac{F_0/m}{\sqrt{(\omega^2 - \alpha^2)^2 + \frac{b^2}{m^2} \alpha^2}}$$

$$\text{Let } f(\alpha) = (\omega^2 - \alpha^2)^2 + \frac{b^2}{m^2} \alpha^2$$

Hence  $A(\alpha)$  local maxi (local mini)

$\Leftrightarrow f(\alpha)$  local mini (local maxi)

Find  $f'(\alpha)$

$$\begin{aligned} f'(\alpha) &= 2(\omega^2 - \alpha^2)(-2\alpha) + \frac{b^2}{m^2} 2\alpha \\ &= 4\alpha \left[ \alpha^2 - \left( \omega^2 - \frac{b^2}{2m^2} \right) \right] \end{aligned}$$

$$f''(\alpha) = 12\alpha^2 - \left( \omega^2 - \frac{b^2}{2m^2} \right) 4$$

Two cases:

Case 1  $\omega^2 - \frac{b^2}{2m^2} \geq 0$

$$\left( \omega^2 \geq \frac{b^2}{2m^2} \right)$$

$$f'(\alpha) = 0 \Leftrightarrow \alpha = 0 \quad \text{or} \quad \alpha^2 = \omega^2 - \frac{b^2}{2m^2}$$

Case 2  $\omega^2 - \frac{b^2}{2m^2} < 0$

$$\left( \omega^2 < \frac{b^2}{2m^2} \right)$$

$$f'(\alpha) = 0 \Leftrightarrow \alpha = 0$$

(Note that when  $\omega^2 - \frac{b^2}{2m^2} < 0$

then  $\alpha^2 - (\omega^2 - \frac{b^2}{2m^2}) \neq 0$  )



Case 1  $\omega^2 \geq \frac{b^2}{2m^2}$

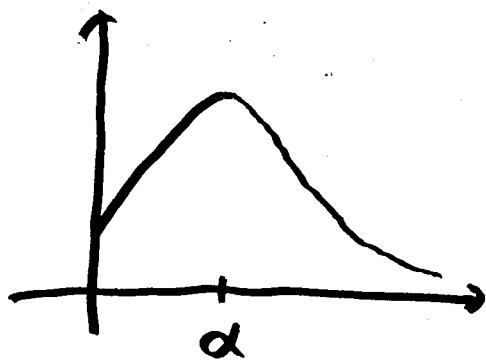
By 2nd derivative test,

At  $d=0$ ,  $f(d)$  is maxi (local)

$$d^2 = \omega^2 - \frac{b^2}{2m^2}, \quad f(d) \text{ is mini (local)}$$

$\therefore$  At  $d=0$ ,  $A(d)$  is mini (local)

$$d^2 = \omega^2 - \frac{b^2}{2m^2}, \quad A(d) \text{ is maxi (local)}$$



$$\text{where } d^2 = \omega^2 - \frac{b^2}{2m^2}$$

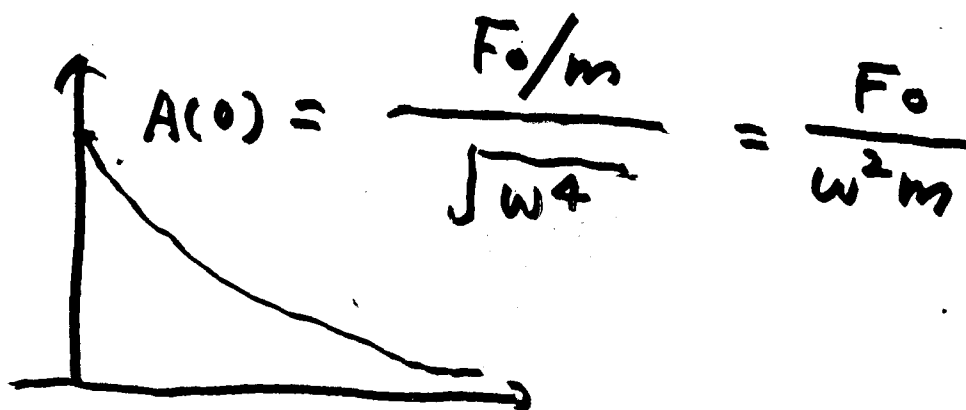
Case 2

$$\omega^2 < \frac{b^2}{2m^2}$$

By 2nd derivative test,

At  $d=0$ ,  $f(d)$  is mini (local)

$\therefore$  At  $d=0$ ,  $A(d)$  is maxi (local)



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when  $b$  is small

so  $\omega^2 \gg \frac{b^2}{2m^2}$  case 1

$$A(d) = \frac{F_0/m}{\sqrt{(\omega^2 - d^2)^2 + \frac{b^2}{m^2} d^2}}$$

$$d^2 = \omega^2 - \frac{b^2}{2m^2}$$

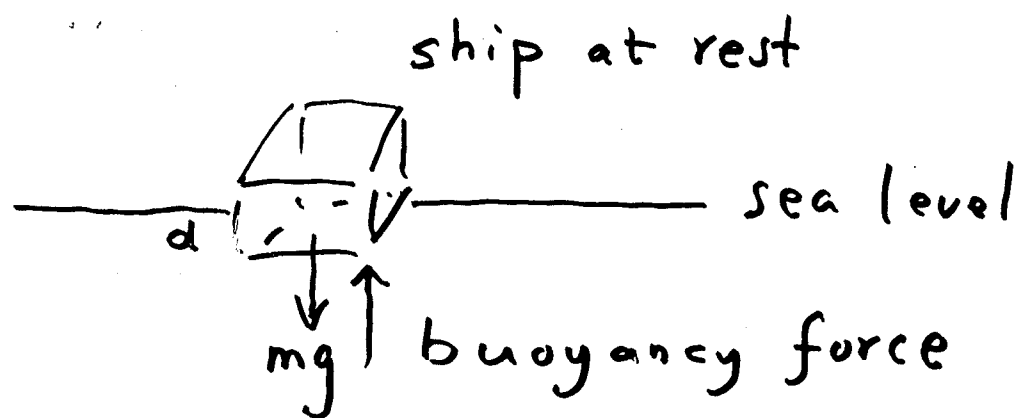
$$= \frac{F_0/m}{\sqrt{\left(\frac{b^2}{2m^2}\right)^2 + \frac{b^2}{m^2} \left(\omega^2 - \frac{b^2}{2m^2}\right)}}$$

$$A(\omega) = \frac{F_0/m}{\sqrt{\frac{b^2 \omega^2}{m^2} - \frac{1}{4} \frac{b^4}{m^4}}}$$

$$= \frac{F_0/m}{\frac{b\omega}{m} \sqrt{1 - \frac{1}{4} \frac{b^2}{m^2 \omega^2}}}$$

$$\approx \frac{F_0/m}{\frac{b\omega}{m}} = \frac{F_0}{b\omega}$$

Q4



$$mg = \text{buoyancy force}$$

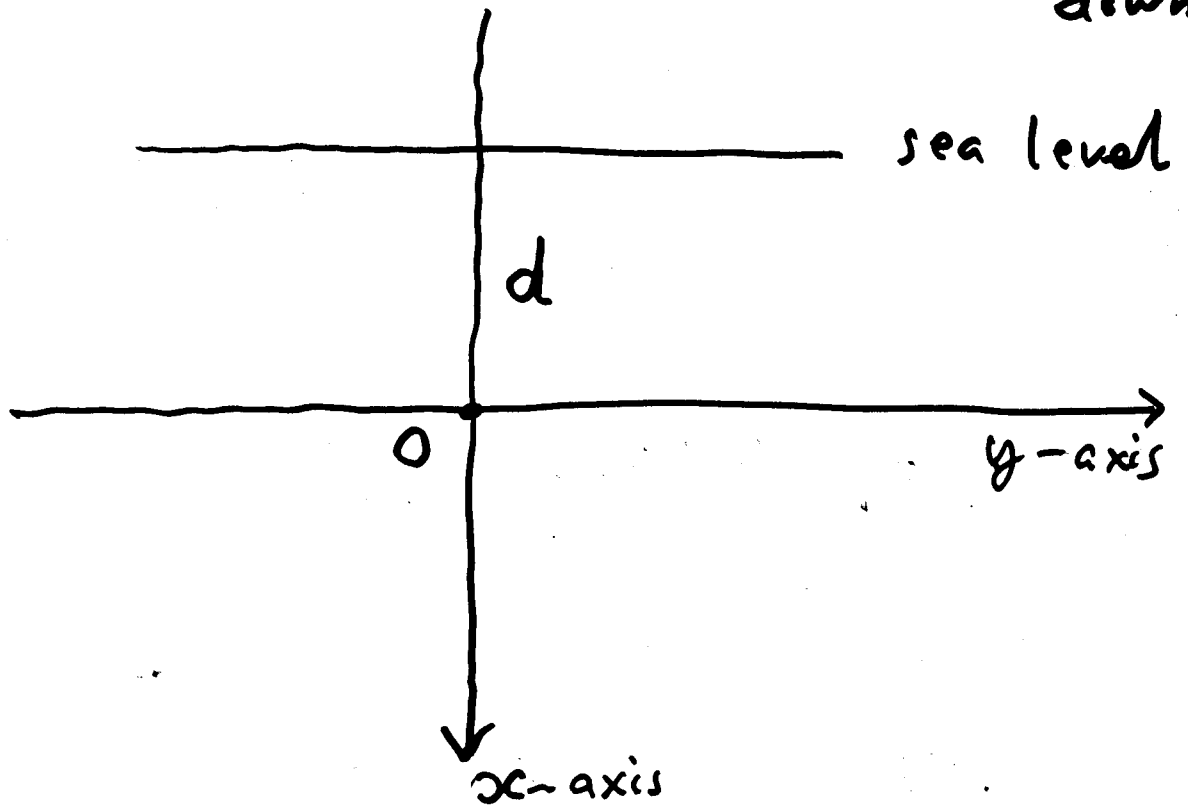
$$= \text{weight of displaced water}$$

$$mg = \rho (\text{volume of displaced water}) g$$

$$= \rho A d g = (\rho A g) d$$

↑  
spring (restoring)  
constant

ship moving up and down



SHM

$$m \ddot{x} = -\rho A x g = -(\rho A g) x$$

spring (restoring constant)

why?

weight of displaced water

$$\begin{aligned} m \ddot{x} &= mg - \rho A (x + d) g \\ &= mg - \rho A d g - \rho A x g \\ &= -\rho A x g \end{aligned}$$

$$\therefore m \ddot{x} = -kx \quad \text{where } k = \rho A g$$

This formula holds for any  
right prism with cross-section  
area  $A$ . e.g. cylinder



$$\ddot{x} = -\frac{k}{m} x$$

where

$$\frac{k}{m} = \frac{\rho A g}{m}$$

$$\text{or } = \frac{g}{d}$$

$$\text{since } mg = (\rho A g) d$$

$$\omega^2 = \frac{\rho A g}{m}$$

$$\text{or } \frac{g}{d} \quad \left( \omega^2 = \frac{k}{m} \right)$$

$$\omega = \sqrt{\frac{\rho A g}{m}}$$

$$\text{or } \sqrt{\frac{g}{d}}$$

$$m \ddot{x} + b \dot{x} + kx = F_0 \cos(\alpha t)$$

$\uparrow$   
friction

external force  
due to wave

$$k = \rho A g$$

Ref: 2.5 Forced Damped Oscillators

general soln  $x(t)$

= particular soln + general soln of

$$m \ddot{x} + b \dot{x} + kx = 0$$

tends to 0

rapidly (transient soln)

$\approx$  particular soln (called steady-state soln)

$$= \frac{\frac{1}{m} F_0 \cos(\alpha t - \gamma)}{\sqrt{(\omega^2 - \alpha^2)^2 + \frac{b^2}{m^2} \alpha^2}}$$

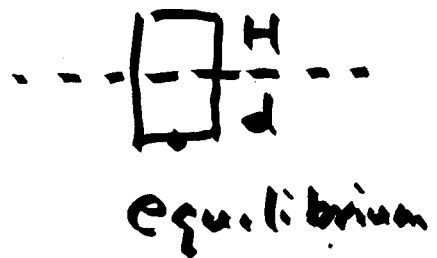
$$\omega = \sqrt{\frac{k}{m}}$$

Amplitude

$$A(\alpha) = \frac{F_0/m}{\sqrt{(\omega^2 - \alpha^2)^2 + \frac{b^2}{m^2} \alpha^2}}$$

We want

$$A(\alpha) < H + d$$



For convenience, we want

$$A(\alpha) < H \quad \text{for all } \alpha$$

$$A(\alpha)_{\max} \Leftrightarrow \alpha^2 = \omega^2 - \frac{b^2}{2m^2}$$

most dangerous  $\alpha$

$$A_{\max} = \frac{F_0/m}{\sqrt{\frac{b^2 \omega^2}{m^2} - \frac{1}{4} \frac{b^4}{m^4}}} \quad \omega = \sqrt{\frac{PAg}{m}}$$



$$A_{\max i} = \frac{2mF_0}{b\sqrt{4\rho mA g - b^2}} < H$$

Choose  $m$  and  $A$  such that  
above holds