C-SPY ICE2000 quick reference

This document gives information about the C-SPY options that apply to the ICE2000 emulator. Refer to the C-SPY documentation and to Microchip Technology Inc.'s MPLAB®-ICE User's Guide for detailed reference information.

Installation

When installing the IAR Embedded Workbench on Microsoft Windows NT or Windows 2000, Microchip MPLAB must also be installed since MPLAB uses its own parallel port device driver. The latest version of MPLAB may be found on **www.microchip.com**. On Windows NT4, service pack 4 or later must be installed for the parallel port to function properly.

Specifying the ICE2000 emulator in the IAR Embedded Workbench

To use the ICE2000 emulator, select **Project>Options** in the IAR Embedded Workbench. On the **C-SPY Settings** page in the **C-SPY** category, select the **ICE2000 Emulator** in the **Driver** list. Then select the **ICE settings** page:

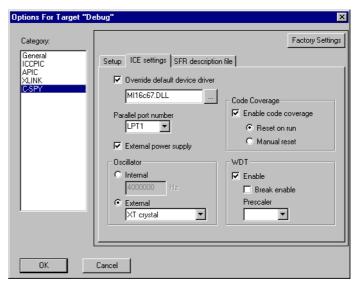


Figure 1: ICE settings in the C-SPY category in the IAR Embedded Workbench

OVERRIDE DEFAULT DEVICE DRIVER

If C-SPY fails to find a driver DLL, use this option to select a driver manually. A browse button is available for your convenience.

EXTERNAL POWER SUPPLY

By default, ICE2000 will run using an internal power supply. Select this option to use target board power instead. Refer to Microchip's MPLAB®-ICE User's Guide for the current ratings.

OSCILLATOR

Select **Internal** or **External** oscillator source using the radio buttons. Note that ICE2000 must have external power to run with an external oscillator.

- When using the internal oscillator (default), enter the clock frequency in Hertz.
- When using the external oscillator, select the oscillator driver type from the drop-down list.

WDT - WATCHDOG TIMER

Enable the watchdog timer reset by checking the **Enable** box. To enable a break on watchdog timer overflow, check the **Break enable** box. If the target is high-end, select the prescale value from the **Prescaler** drop-down list.

The IAR C-SPY Emulator menu

The C-SPY **Emulator** menu is used for controlling the ICE2000 emulator. The menu commands are mainly concerned with complex triggers. For information about complex triggers and the available options, please see Microchip's *MPLAB*®-*ICE User's Guide*, available at **www.microchip.com**.

CODE COVERAGE SETTINGS

To use complex triggers and the Trace window with ICE2000, code coverage must be disabled. When you no longer need complex triggers, you can enable code coverage once more.

Note: Disabling code coverage speeds up emulation considerably, and may be attractive even when you are not using complex triggers.

TRIGGER IN/OUT SETTINGS

Use this command to adjust the logic probe trigger settings. See Microchip's *MPLAB®-ICE User's Guide* for information.



Figure 2: Trigger In/Out Settings dialog box

COMPLEX TRIGGER SETTINGS

Select this command to set up the four complex triggers of the ICE2000 emulator. Each event may be set to instruction fetch, data read/write, logic probe, and with or without pass counter.

These four events may be combined in four ways: All, Any, Sequential or Time Between Events. You can also choose to filter the trace on for example fetch intervals. That means that you can remove any cycles in a specific function from the trace buffer.

In the figure below, a trigger has been set to halt execution when data on address 0x21 is read:

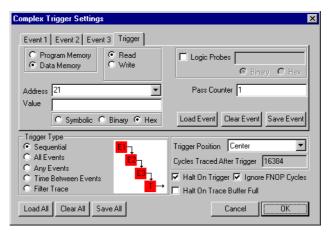


Figure 3: Example of setting complex triggers

Note: You do not have to set all four events to make the trigger work; just leave the ones you do not need empty.

For detailed information and tutorials, please see Microchip's $MPLAB^{@}$ - $ICE\ User's\ Guide.$

OPEN TRACE WINDOW

The Trace Memory window shows the contents of the trace memory buffer:

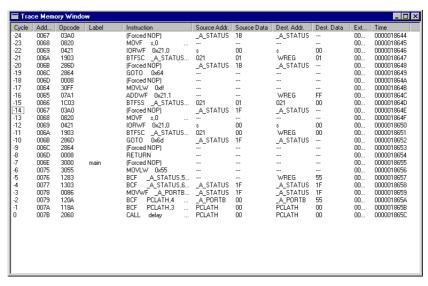


Figure 4: Trace Memory window

Typically it shows the most recently executed instructions, but you may also filter some instructions when you set up the trigger. If you right click in the window, a pop-up menu with trace window settings and an option for reloading the trace window contents becomes available. For details about the contents of this window, please see Microchip's MPLAB®-ICE User's Guide.

Specifying the ICE2000 emulator from the command line

This is a summary of C-SPY options that apply to the ICE2000 emulator. Refer to the C-SPY documentation for detailed reference information.

Option	Description
-d	Selects the C-SPY driver.
-ecn	Controls code coverage.
-ed	Overrides the default MPLAB driver.
-ef	Sets the internal clock frequency.
-eon	Specifies the external clock oscillator mode.
-ep	Specifies external power.
-ewb	Enables break on watchdog overflow.
-ewe	Enables the watchdog timer.
-ewp <i>n</i>	Specifies watchdog timer prescaler.

Table 1: Summary of C-SPY ICE2000 command line options

-d Select the C-SPY driver. The available drivers are:

Driver	Description
IPIC16	ICE2000 emulator for PIC16
IPIC17	ICE2000 emulator for PIC17
SPIC16	C-SPY simulator for PIC16
SPIC17	C-SPY simulator for PIC17

Table 2: C-SPY drivers

Example

To specify the ICE2000 emulator for the PIC17 family:

-d IPIC17

-ecn Controls code coverage. The possible values for n are:

Value	Code coverage
0	Off
1	Enabled with reset on run

Table 3: Code coverage options

Value	Code coverage
2	Enabled with manual reset (processor reset)

Table 3: Code coverage options (Continued)

The code coverage setting may also be changed from the C-SPY graphic user interface.

Note: Code coverage and complex triggers may not be used simultaneously because of hardware limitations. However, running with code coverage disabled also substantially increases emulation speed.

-ed Specifies the device driver by overriding the default MPLAB driver.

Example

-ed MI17C42A.DLL

-ef n Specifies the internal clock frequency where n is the frequency in Hz. This option cannot be combined with the -eo option.

Example

To set a 16MHz clock:

-ef 16000000

-eon Specifies the oscillator mode of the external clock, where n is the decimal value of the binary representation of the oscillator mode in the chip configuration word. See the MPLAB®-ICE User's Guide.

This option must be combined with the -ep option; it cannot be combined with -ef.

Example

To set the HS oscillator:

-eo2

- -ep Specifies that the emulator uses external power from the target board.
- -ewb Enables a break on watchdog overflow.

-ewe Enables a watchdog timer.

-ewpn Specifies a watchdog timer prescaler, where the value n is 0-8:

V alue	Prescaler	
0	Off	
1	I	
2	2	
3	4	
4	8	
5	16	
6	32	
7	64	
8	128	

Table 4: Watchdog timer prescaler values

Example

To set the prescaler to 16:

-ewp5

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