

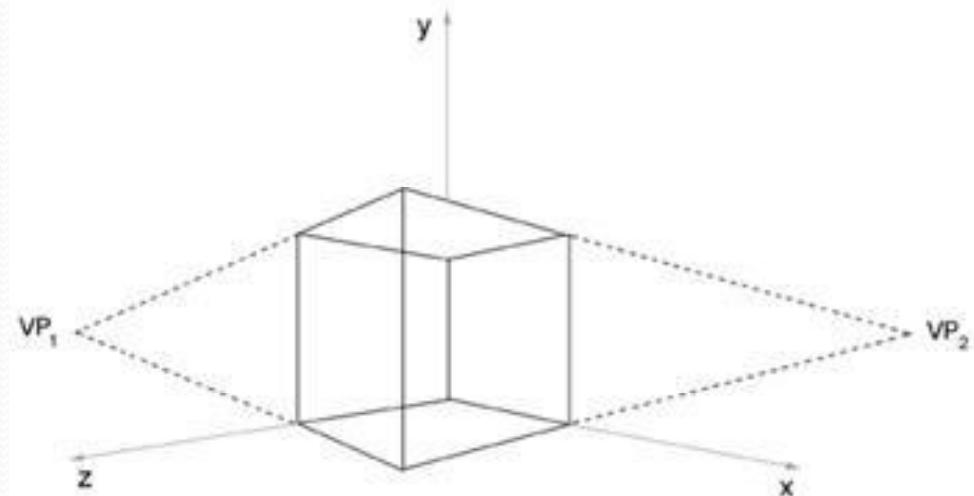
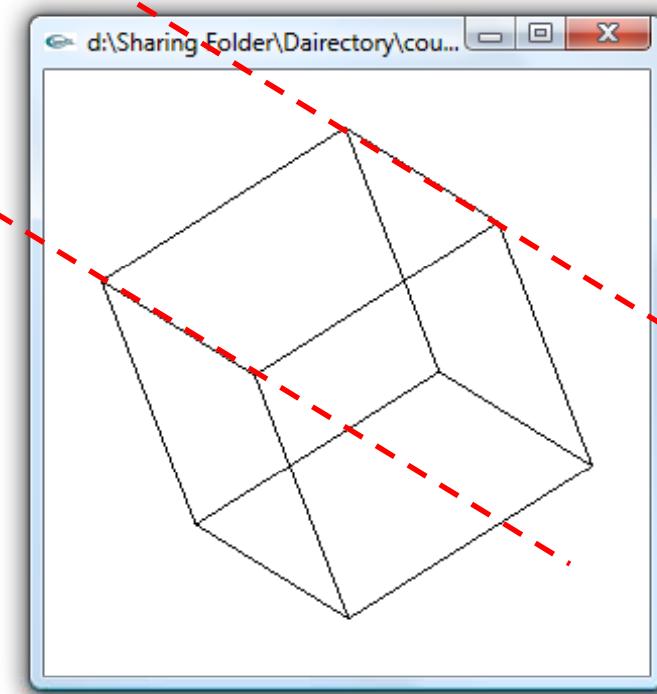


# Viewing

“Let’s put things  
into prospective”

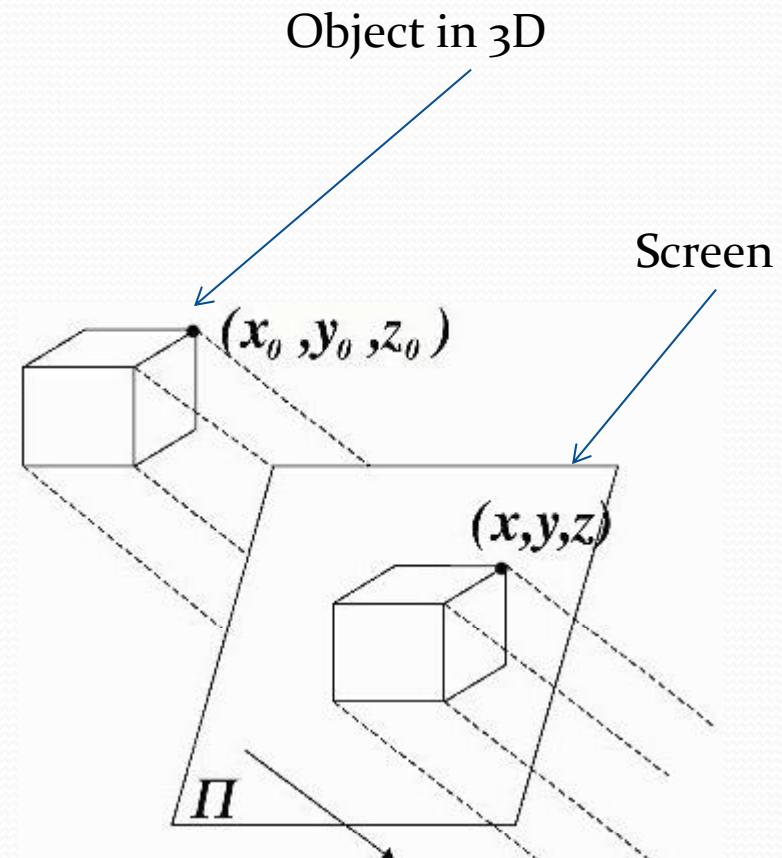
# Something is not very right?!

- Parallel Projection
- Perspective Projection

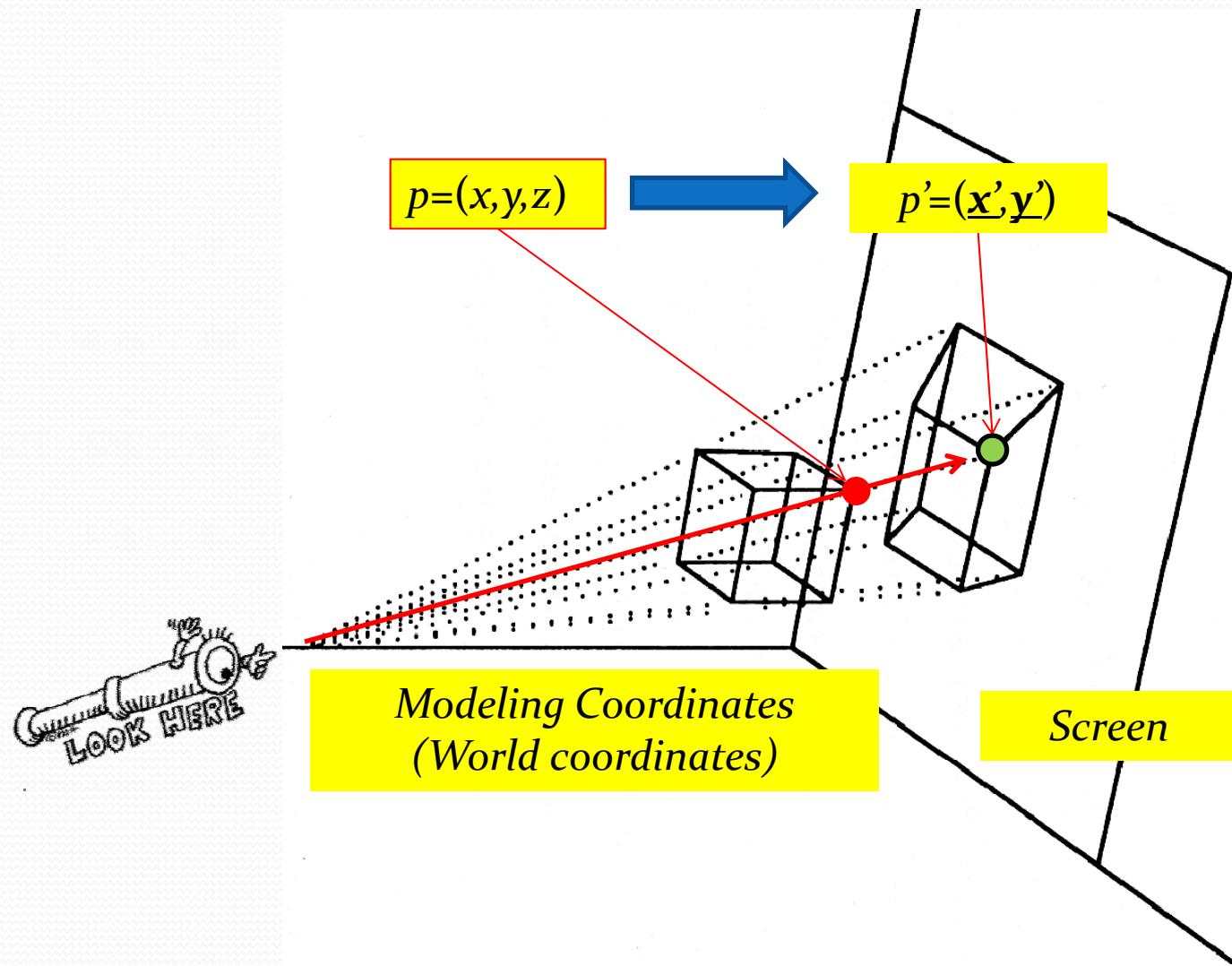


# Current Stage

- Objects are transformed in 3D
  - As in 2D, after the reference frame is changed
- Although objects are in 3D, OpenGL just take the first ( $x,y$ ) coordinates to draw on the screen
  - E.g. in the diagram, the position drawn on the screen is :  $(x,y) = (x_0, y_0)$

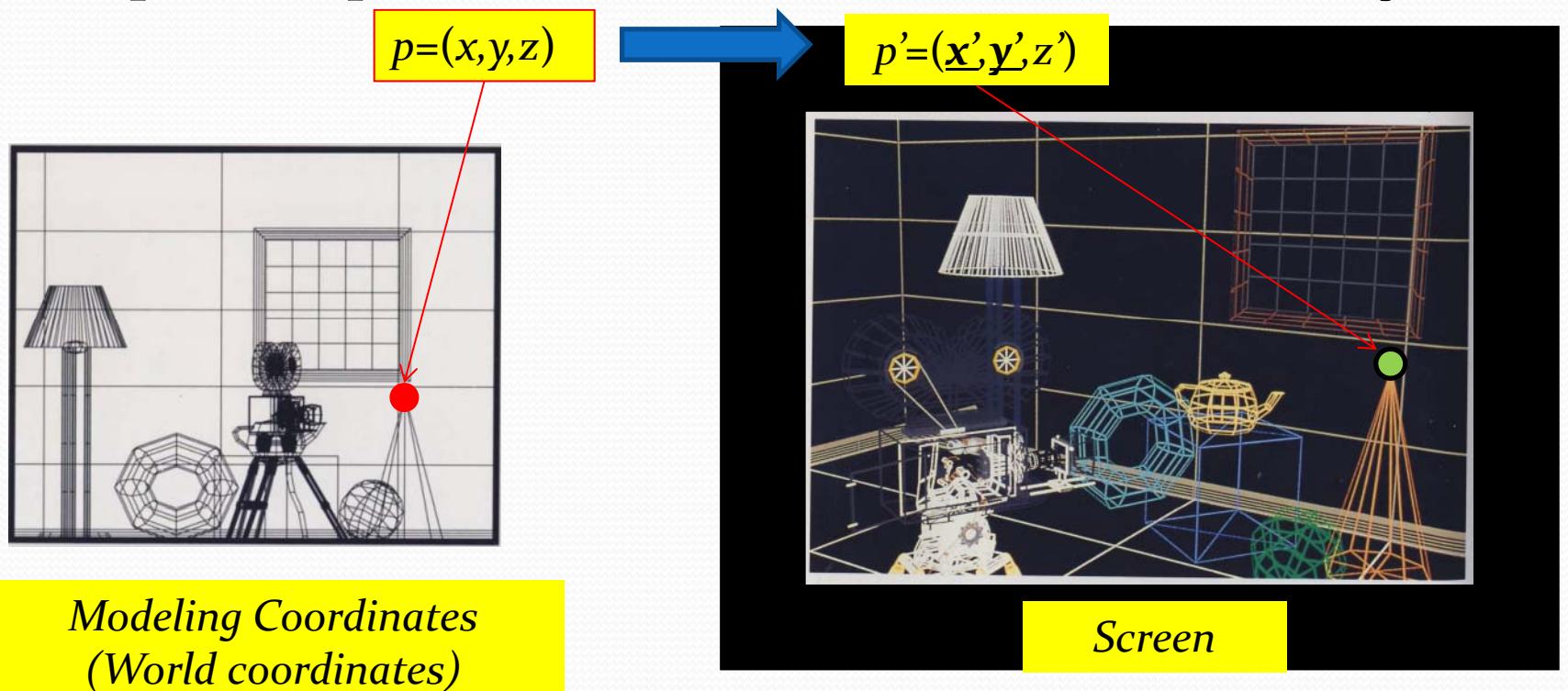


# How to draw a cube?

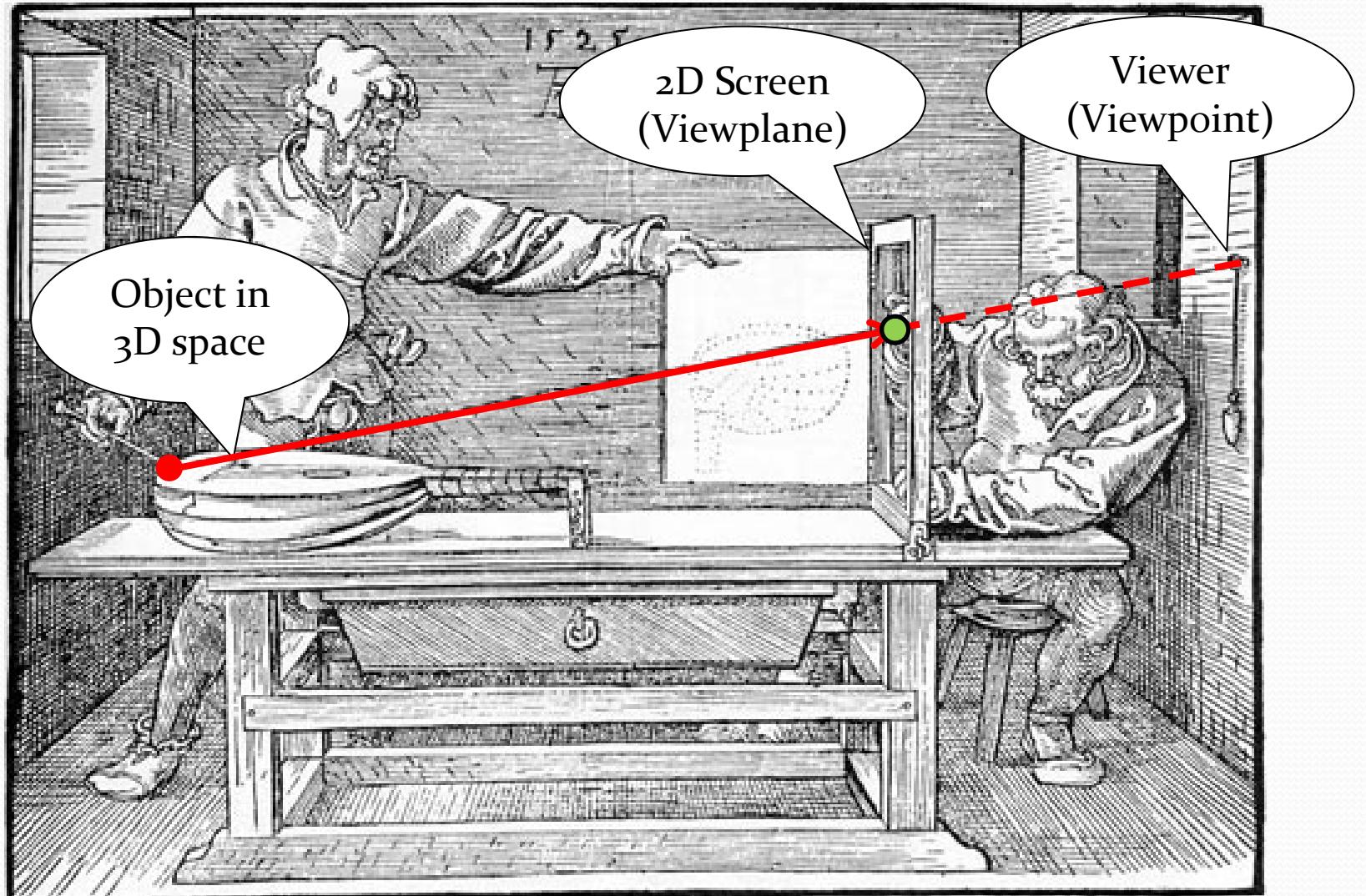


# Transformation/Viewing

- After we specified the vertices positions  $(x,y,z)$  of the objects in the world coordinates
- Compute its position on the screen coordinates  $(x',y')$

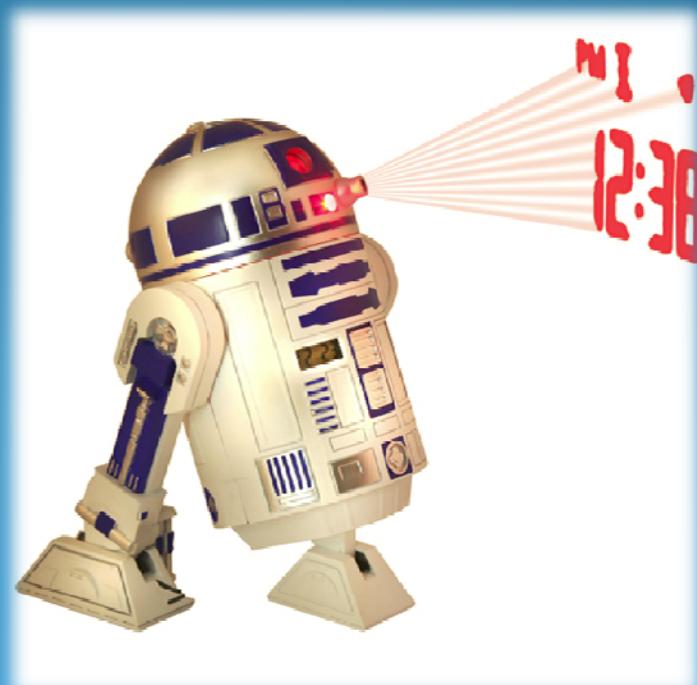


# Perspective Projection



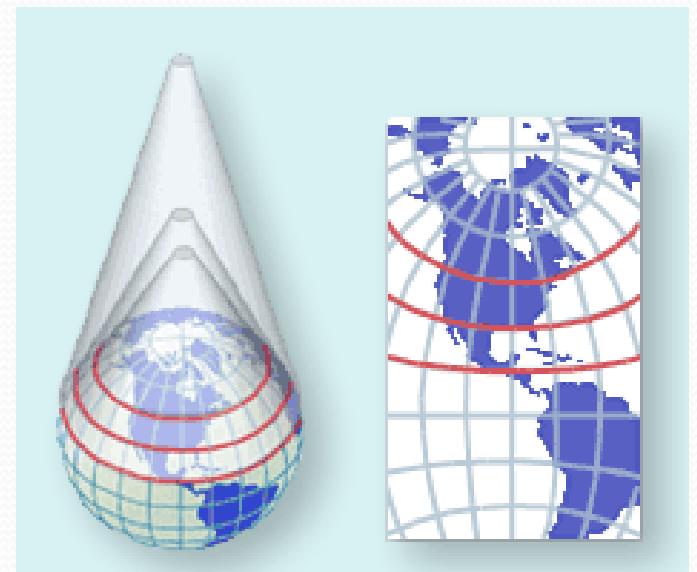
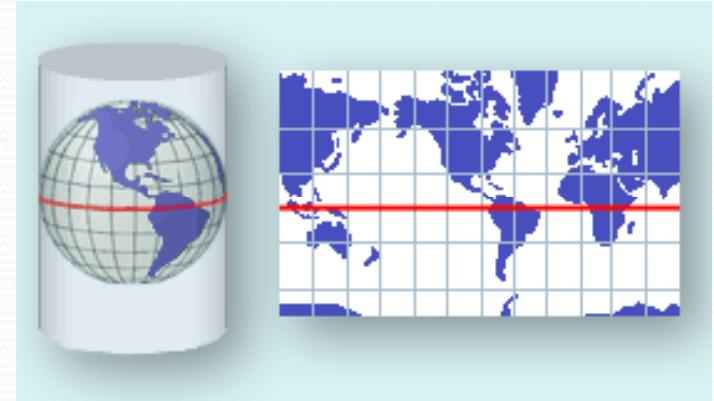
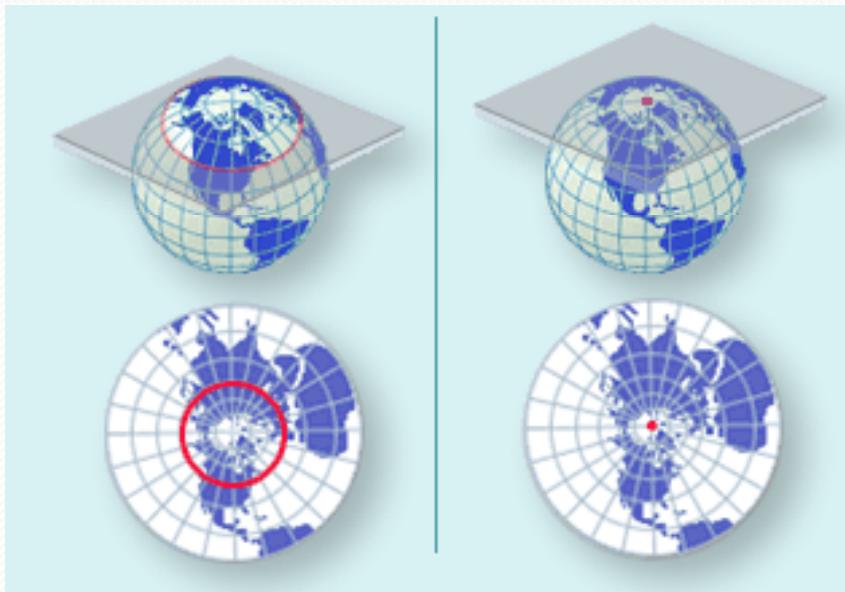
# Two Types of Projections

Orthographic vs Perspective



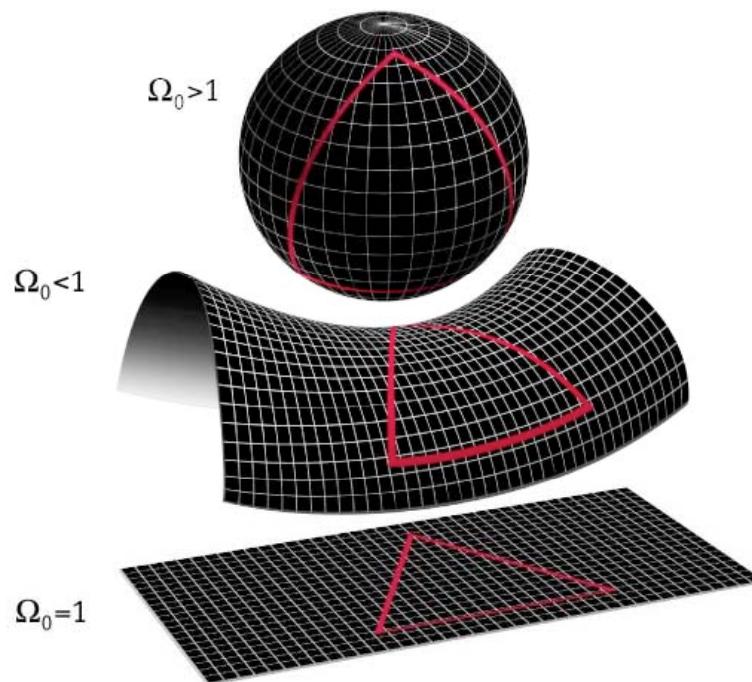
# Map Projections

- Mainly 3 basic types
  - Cylindrical
  - Conic
  - Azimuthal



# Definition of Projection

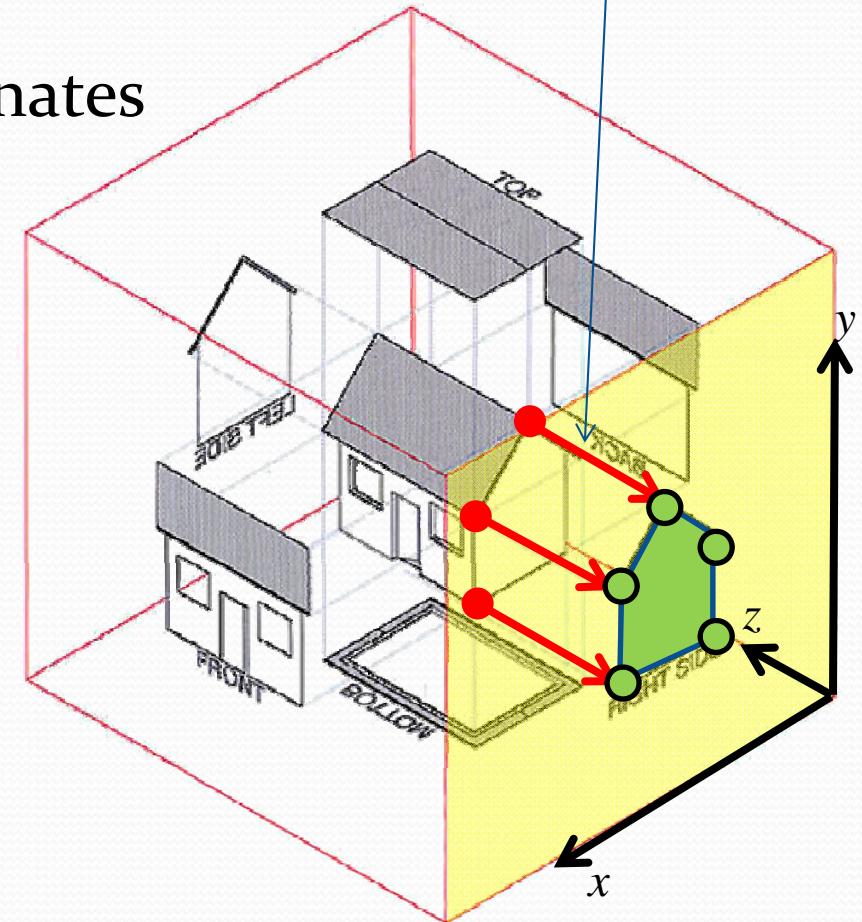
- The transformation of an “image” (points, lines, etc) from one space to another
  - The “spaces” could be anything other than “planes”
- However, we focus on projecting the 3D space onto a 2D plane



# Orthographic Projection

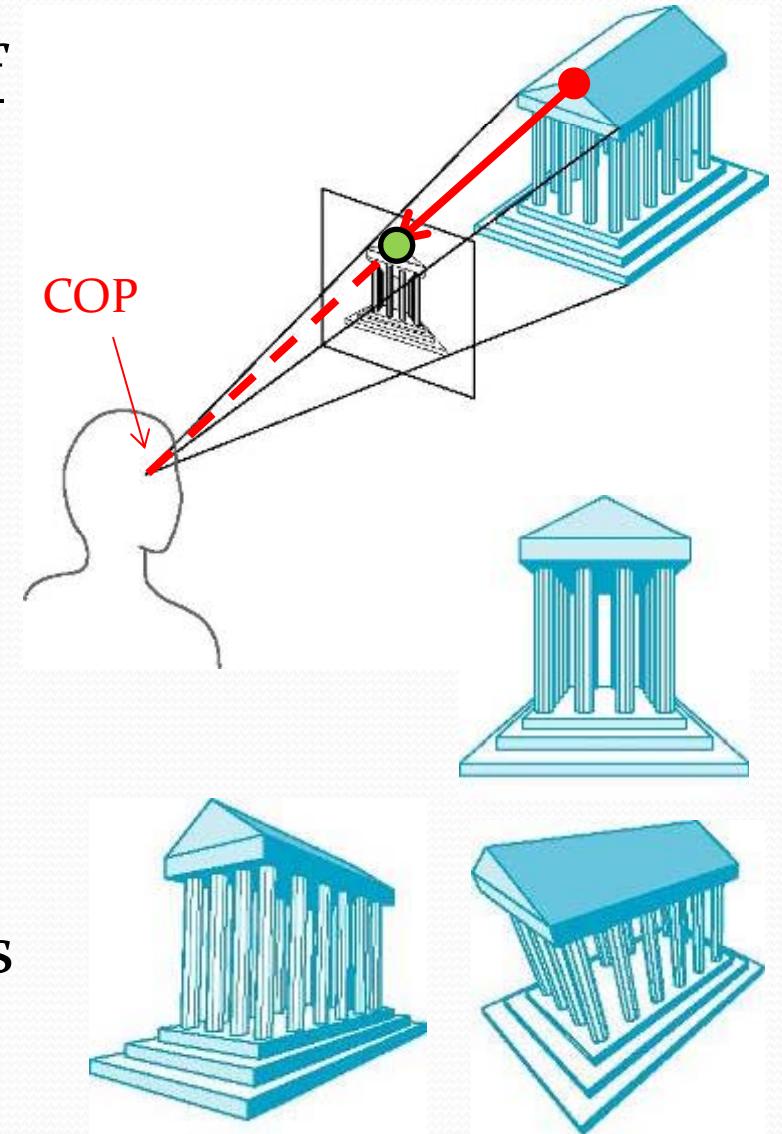
- A *parallel* projection
- Just ignore one of the coordinates
  - E.g. taking  $x$  and  $y$  only
- Good for
  - Graphic designs
  - Construction drawings
- However, not “realistic”
  - Not what human eyes see

These arrows that bring the points from 3D to 2D are called “*projectors*”.

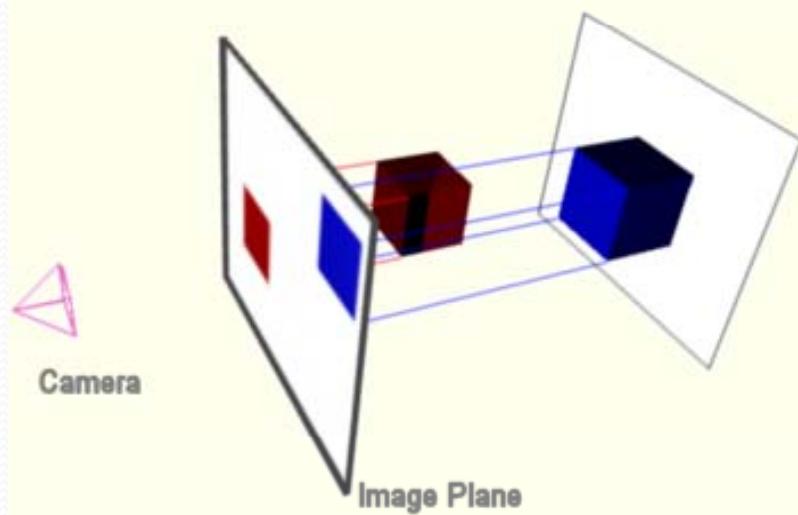


# Perspective Projection

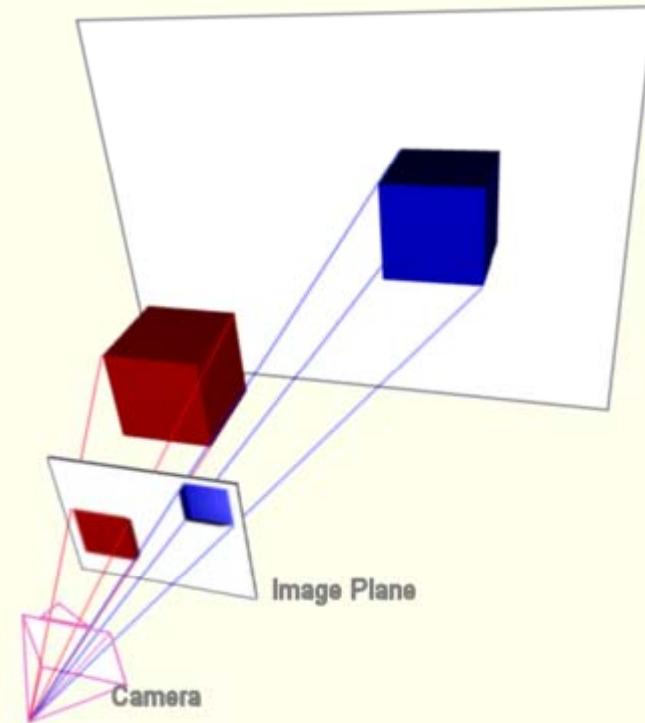
- Projectors converge at center of projection
- Further objects are smaller, nearer objects are bigger
  - This looks more realistic, our eyes (and most cameras) work in a similar fashion.
- Equal distances along a line are not projected into equal distances (foreshortening)
- Angles preserved only in planes parallel to the projection plane



# Two Types of Projection

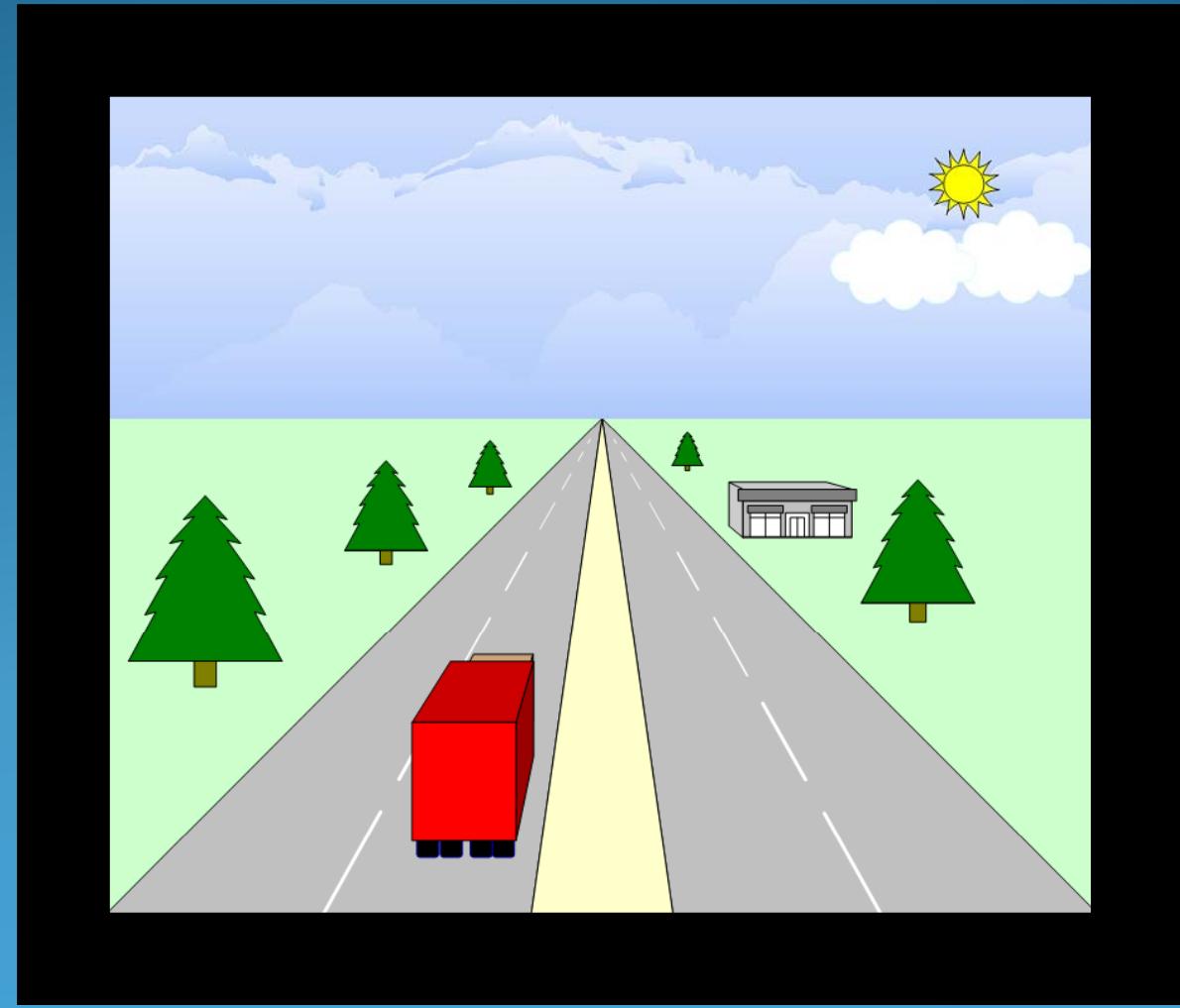


Parallel Projection

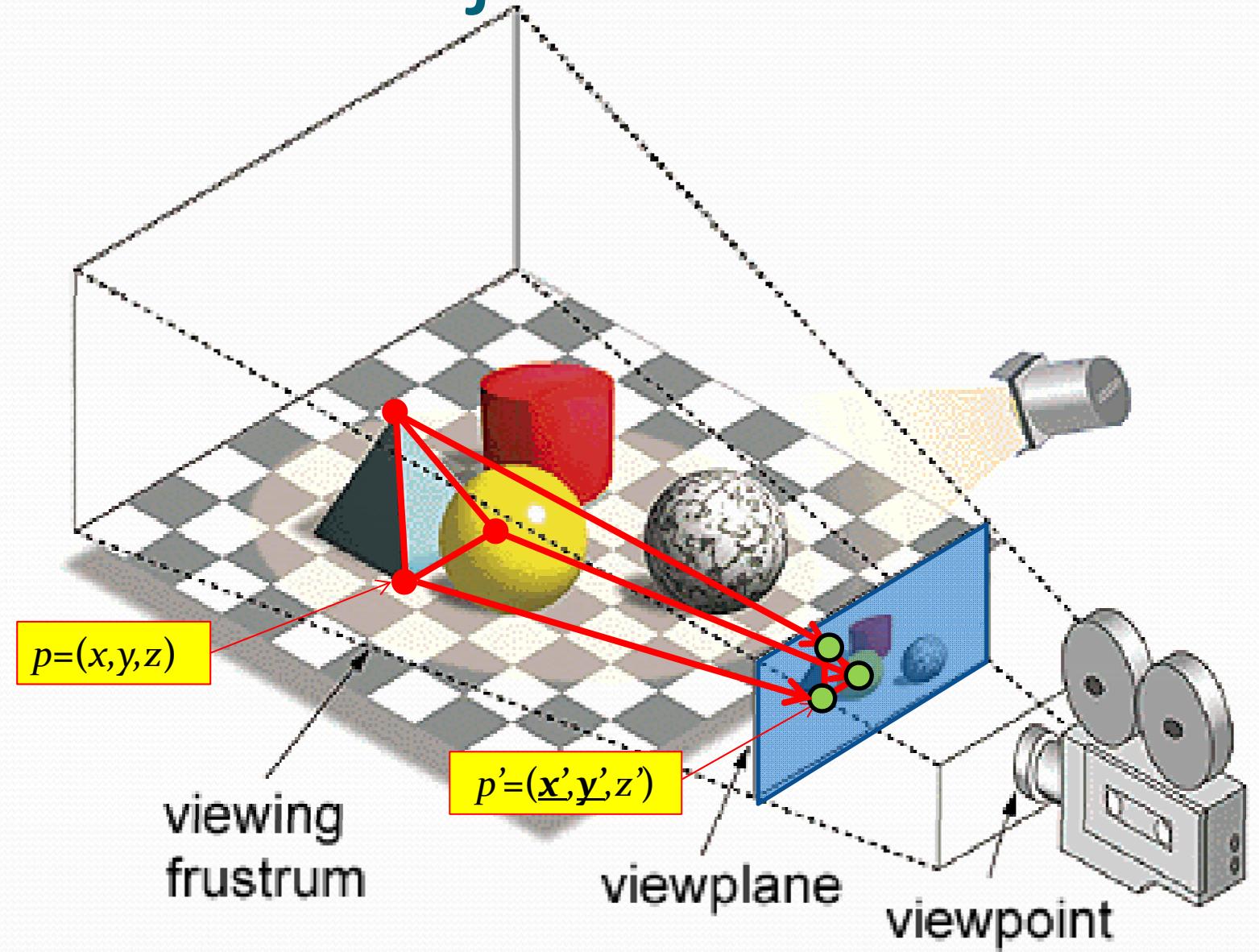


Perspective Projection

# Perspective Projection

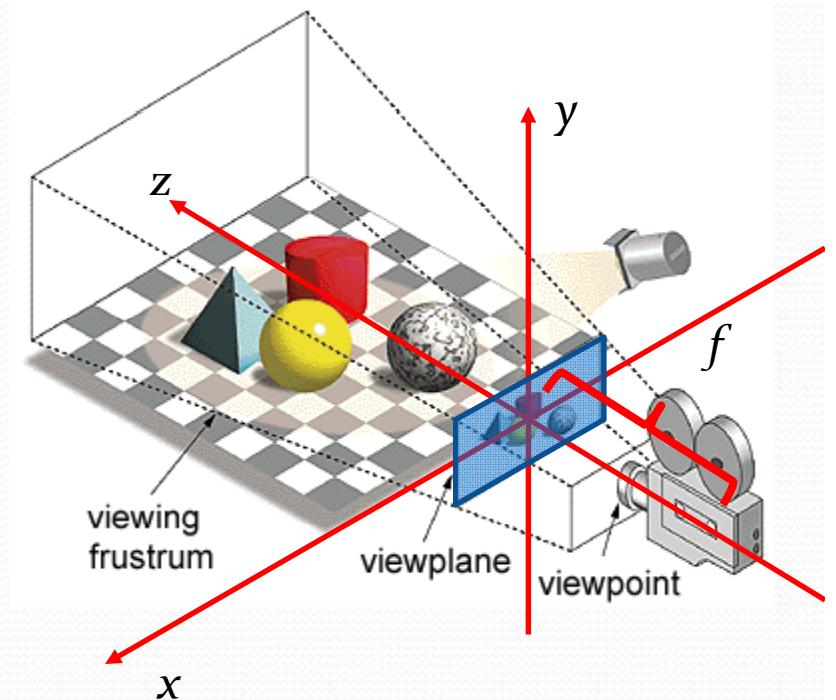


# Perspective Projection

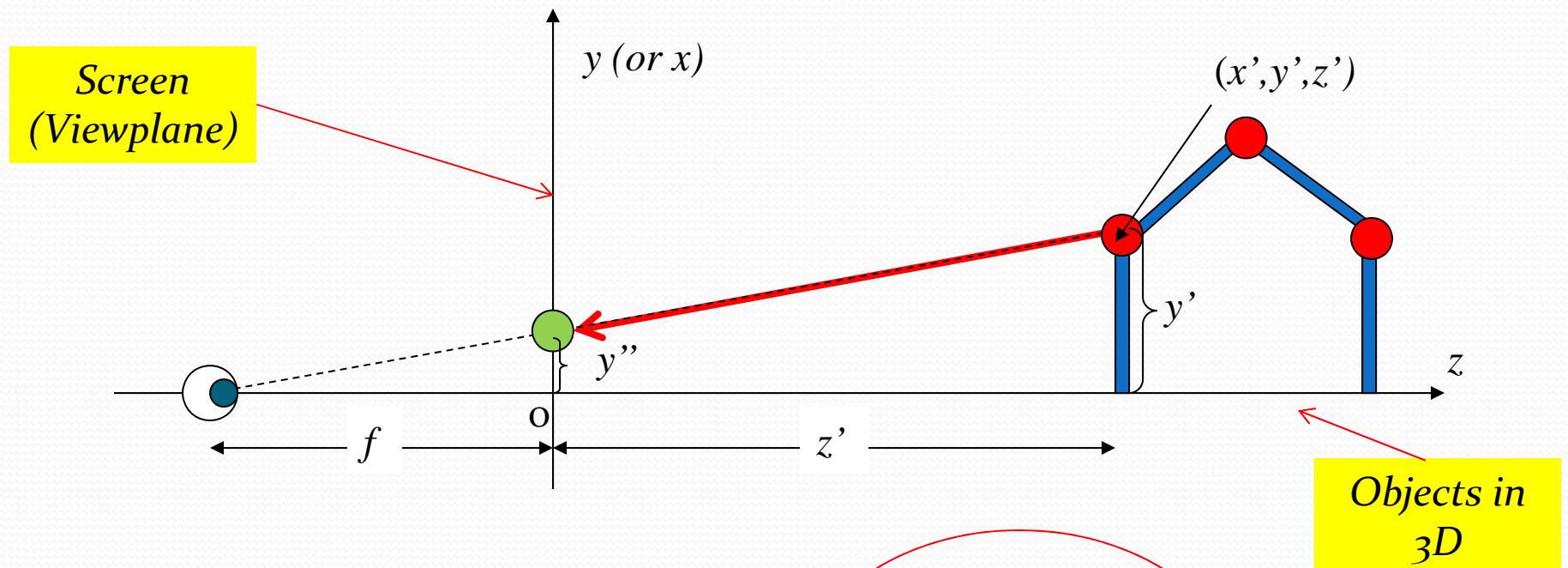


# Setting Up the “Stage”

- Assuming the viewpoint has
  - Position:  $(0,0,-f)$  for  $f > 0$
  - Its “up vector” is  $(0,1,0)$ 
    - Facing upwards as the  $y$ -axis
  - “Looking direction” vector is  $(0,0,1)$ 
    - Towards the positive direction of the  $z$ -axis
- The viewplane is the  $xy$ -plane



# Perspective Transformation



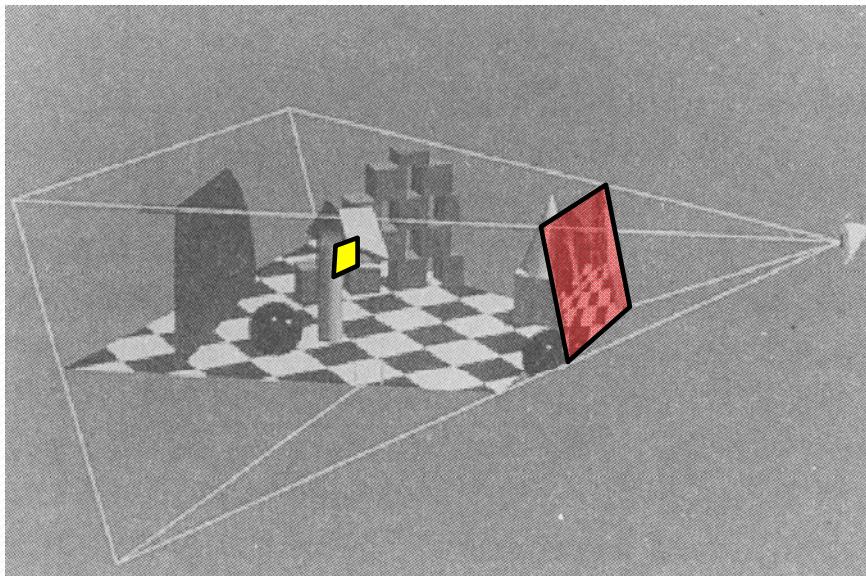
$$\frac{y''}{y'} = \frac{f}{f + z'} \Leftrightarrow y'' = \frac{y' f}{f + z'}$$

# Perspective Transformation Matrix

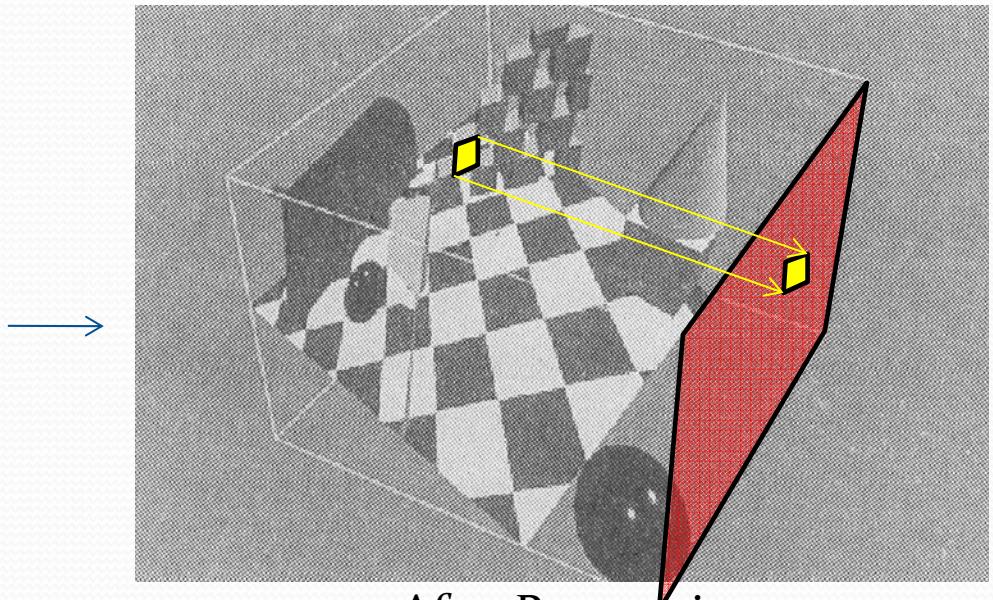
$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & \cancel{\frac{1}{f}} & 1 \end{pmatrix} \begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} x' \\ y' \\ z' \\ \frac{z'+f}{f} \end{pmatrix} \Rightarrow \begin{pmatrix} \frac{x'f}{z'+f} \\ \frac{y'f}{z'+f} \\ \frac{z'f}{z'+f} \\ \frac{z'f}{z'+f} \end{pmatrix}$$

Perspective Projection Matrix:  $P_f$

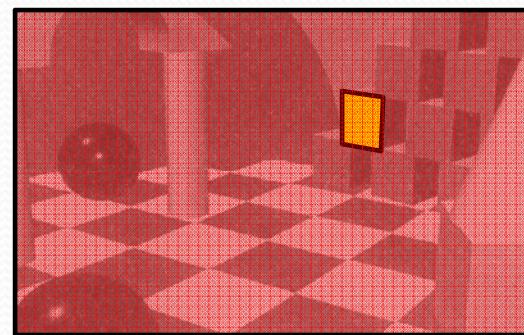
- Note that after the projection, objects are still “3D”
  - z-values are **NOT** zero
  - Distorted, e.g. a regular cube has no more right angles



Before Perspective Transformation



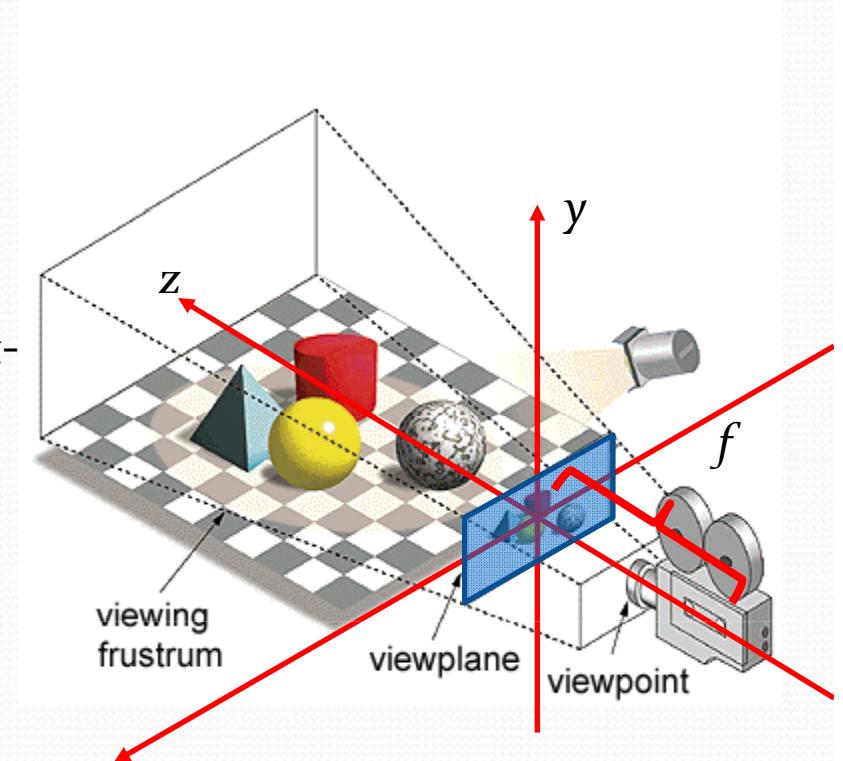
After Perspective Transformation



# Summary

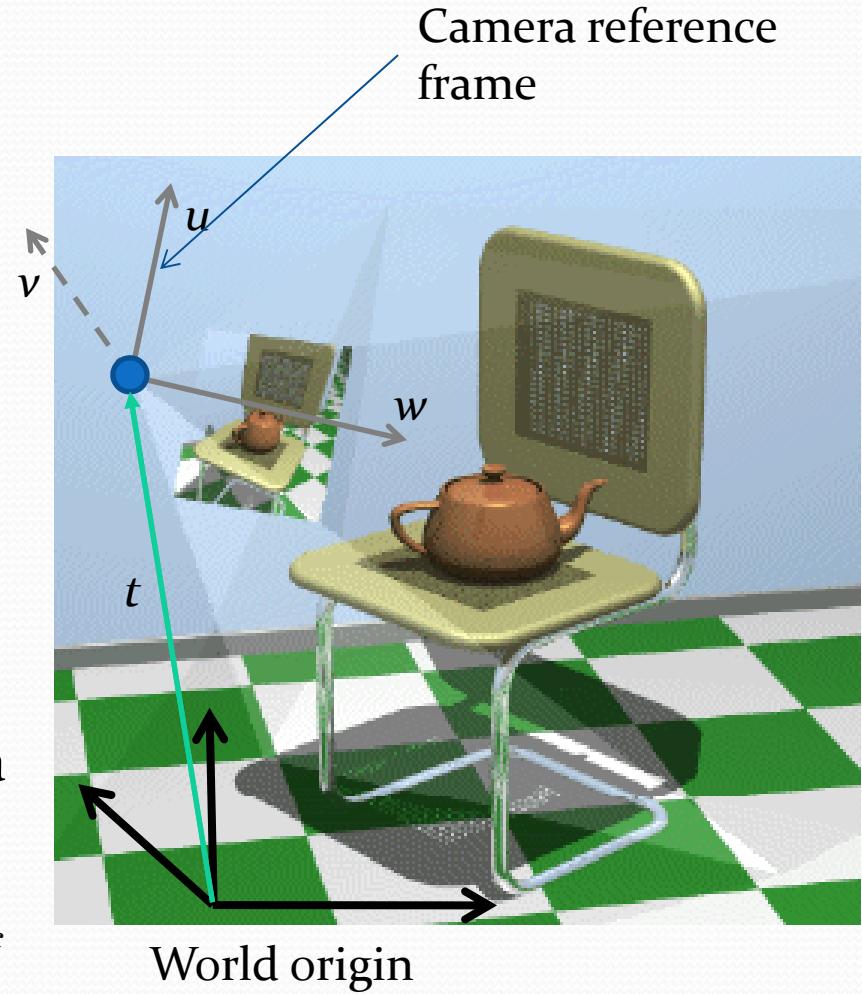
- The view point
  - Position:  $(0,0,-f)$  for  $f > 0$
  - It's "up vector" is  $(0,1,0)$ 
    - Facing upwards as the  $y$ -axis
  - "Looking at" vector is  $(0,0,1)$ 
    - Towards the positive direction of the  $z$ -axis
- The view plane is the  $xy$ -plane
- Then the projection matrix is

$$P_f = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/f & 1 \end{pmatrix}$$

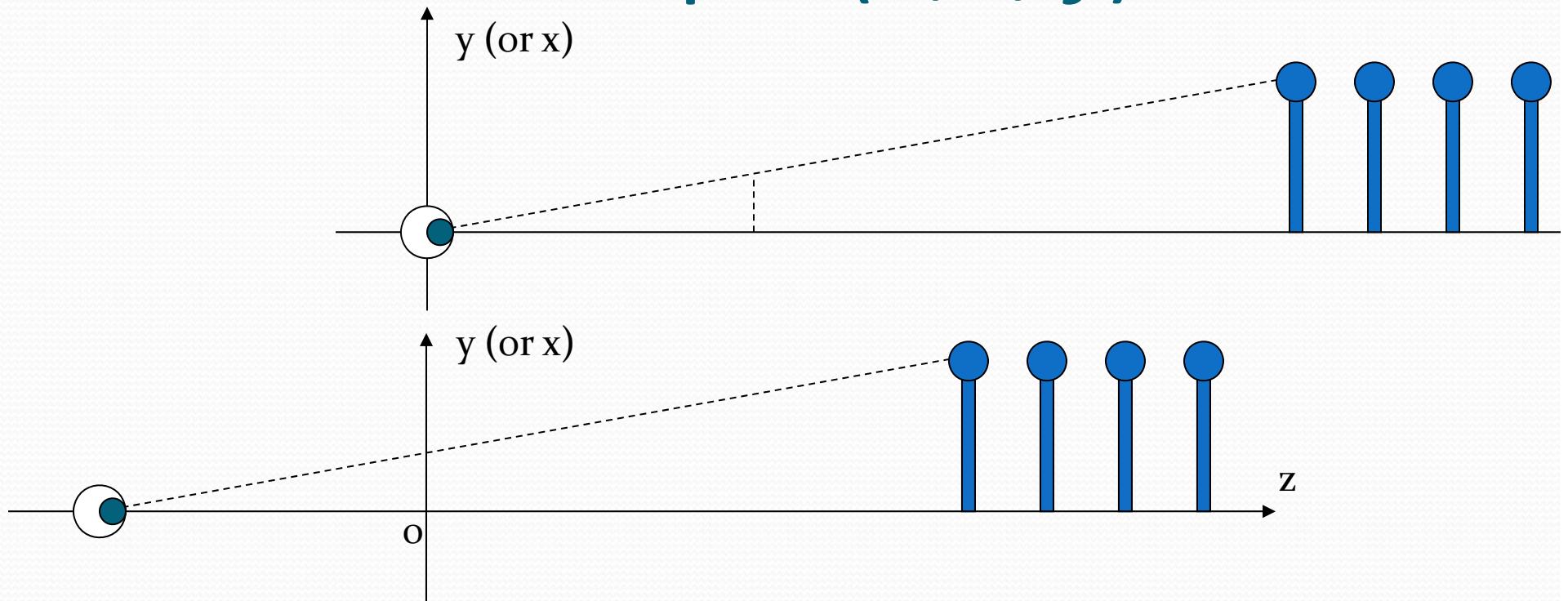


# However, the Camera can be at ANYWHERE, namely, not at $(0,0,-f)$

- Let the camera be
  - At position:  $t$
  - Look-at direction:  $w$
  - An UP vector:  $u$
  - “left” vector:  $v = u \times w$
  - Assuming  $w$ ,  $u$  and  $v$  are unit vectors
- Steps
  - Nothing new: move your reference frame to the “camera reference frame”
  - Let call this transformation  $M_c$



# One More Step: $T(0,0,-f)$



- All in all 
$$p' = P_f T(0,0,-f) M_c p$$
- And we draw the  $x$  and  $y$  coordinates of  $p'$  on the screen



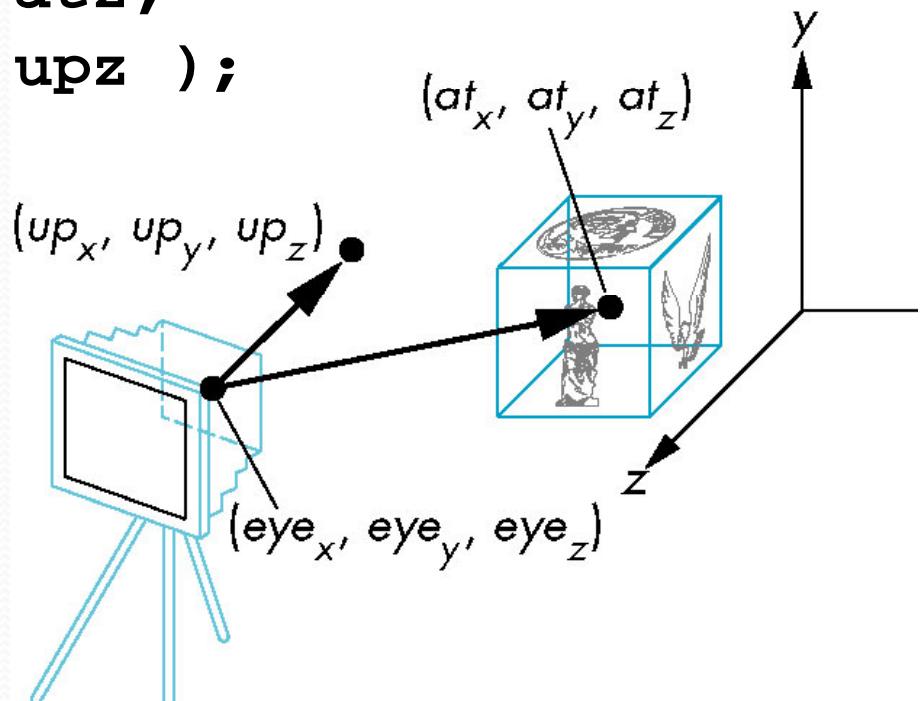
# OpenGL Viewing

# OpenGL Projection: Step 1 (Moving to the camera reference frame)

- First, when you are still in

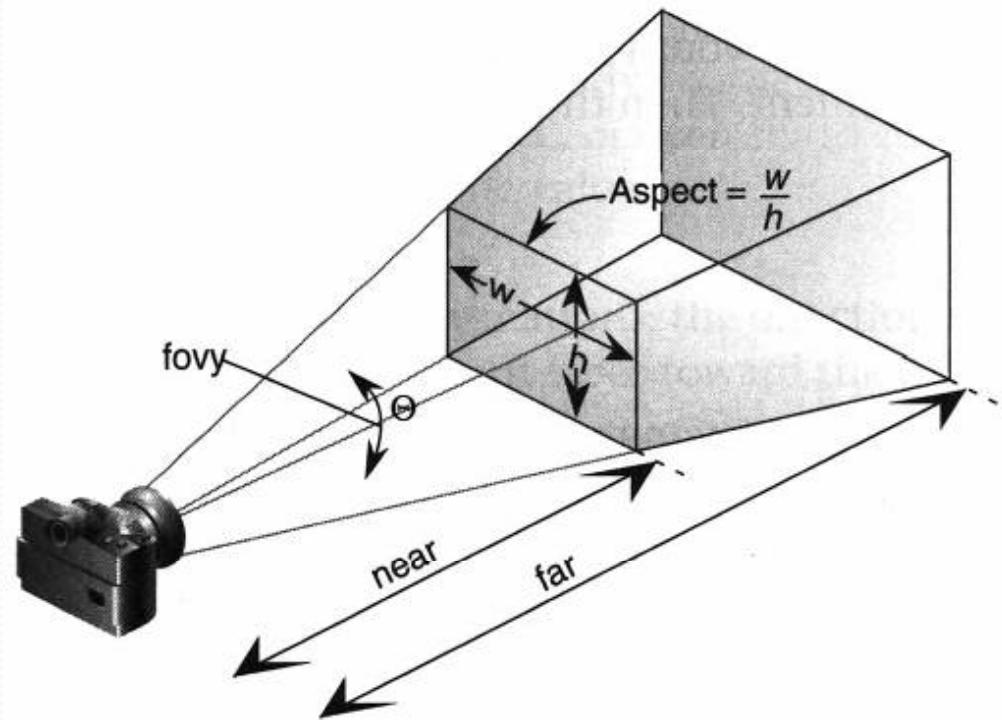
```
glMatrixMode(GL_MODELVIEW);  
  
gluLookAt( eye_x, eye_y, eye_z,  
           at_x, at_y, at_z,  
           up_x, up_y, up_z );
```

Note that it's not the  
“look-at  
direction/vector”



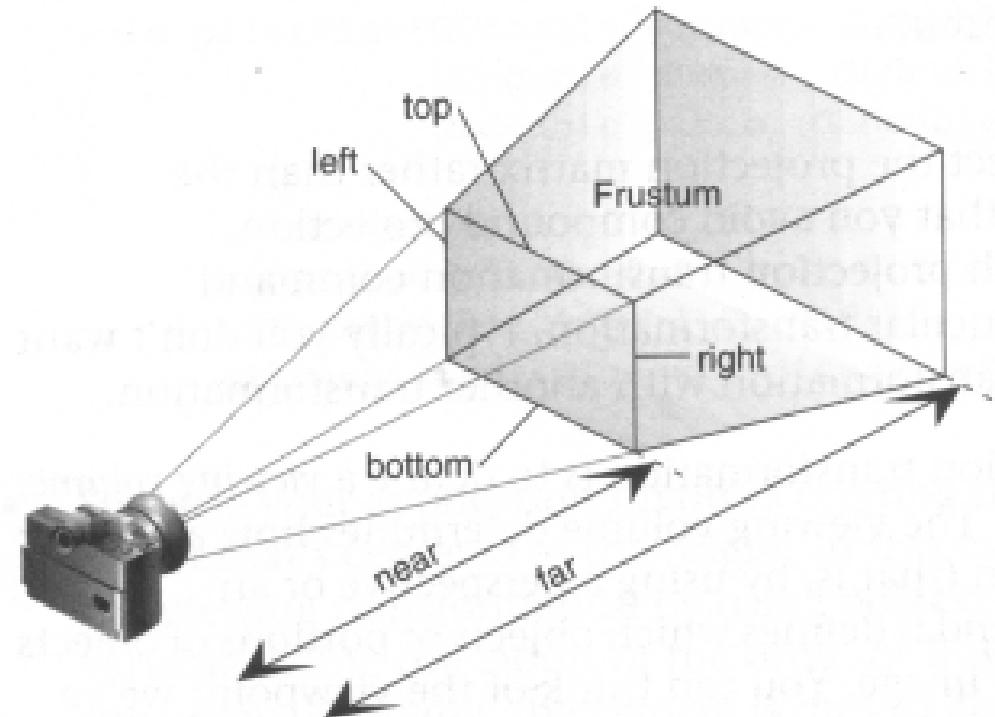
# OpenGL Projection: Step 2

- Then change it to the viewing matrix mode
  - `glMatrixMode(GL_PROJECTION);`  
`glLoadIdentity();`  
`gluPerspective(fovy, aspect, near, far );`



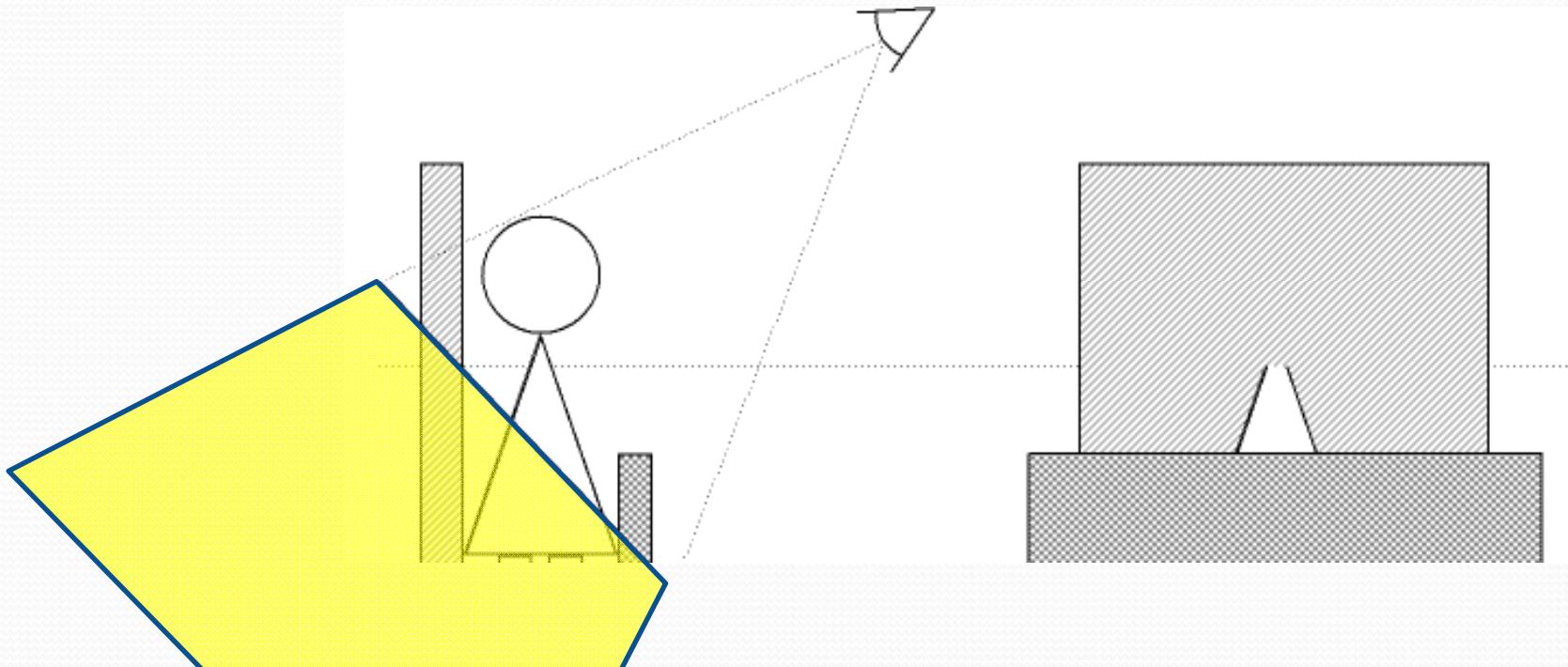
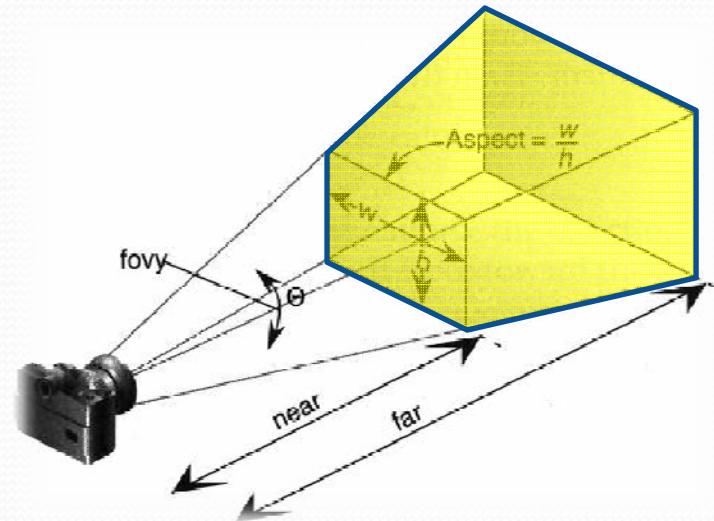
# OpenGL Projection: An Alternate Step 2

- Another way other than **gluPerspective**
  - **glFrustum(left,right,bottom,top,near,far);**



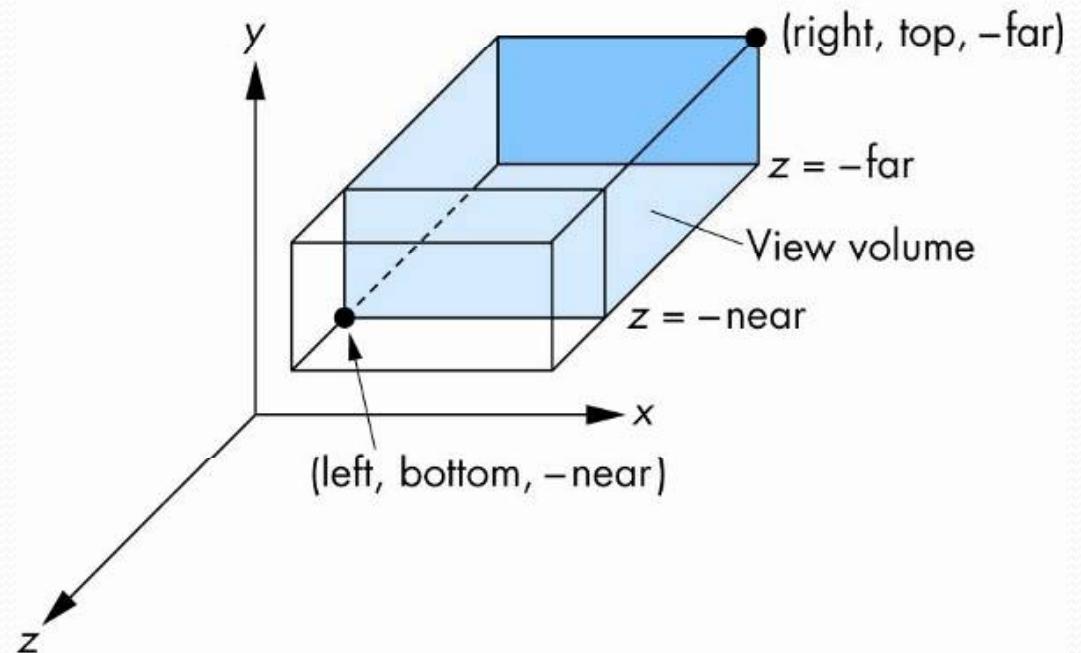
# Viewing Frustum

- Objects outside the frustum
  - will be clipped
  - Clipping must be done **before** the perspective projection



# Well, if you don't want to "put things in perspective"

- OpenGL Orthographic Projection
- Specified by defining a view using
  - `glOrtho( left, right, bottom, top, near, far );`
- Objects outside
  - Will be clipped



# Some Tricks on Projections



# How does Matrix make the freeze and rotate animation?

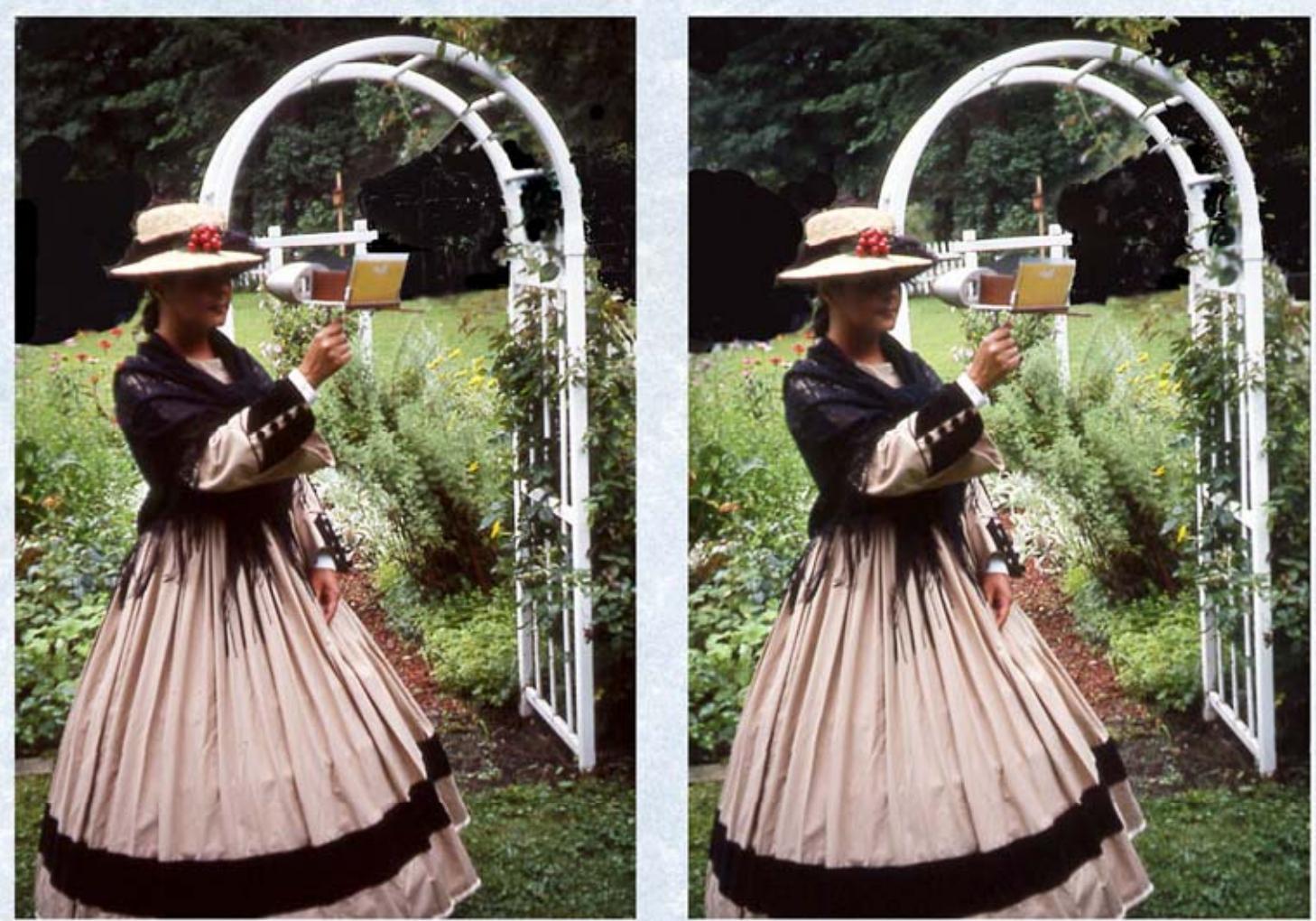


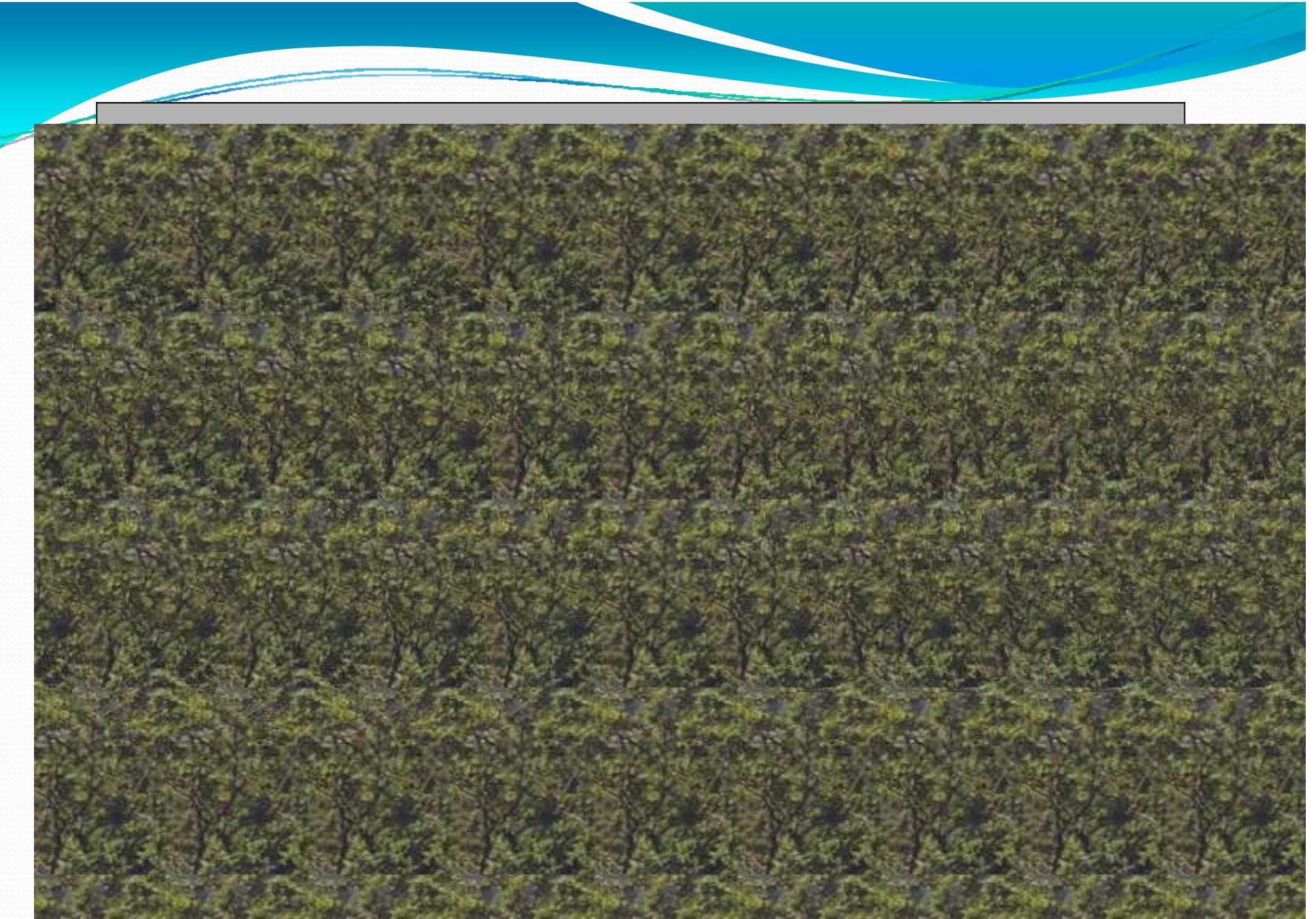
# How does 3D Movies Work?

- In normal daily life, we have two eyes, and actually each of them perceive a slightly different image
- Then our brain processes these two image in real time to reconstruct a 3D object in our mind
- 3D cinema/TV try to deliver two different images into your eyes
  - So the movies have to be filmed by two viewpoints
    - For CG movies that is easy
    - For real life movies, double lens



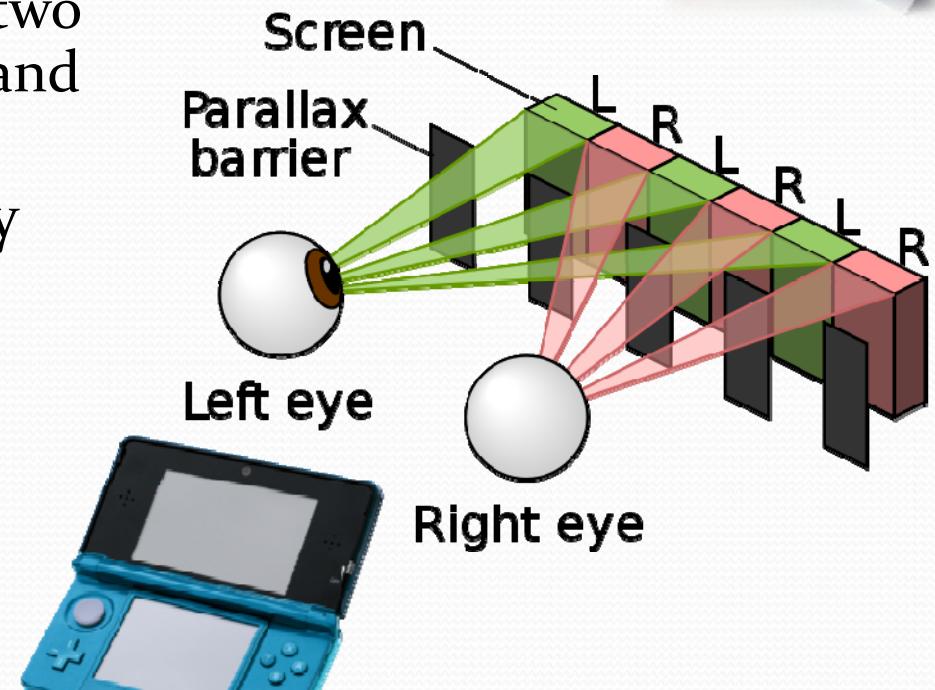
# Stereographic Photography





# Delivery of Two Different Images

- Anaglyph
  - Red and Blue channels
- Eclipse method
  - Goggle shutters left and right synchronizing with the screen
- Polarization systems
  - Two different images are by two different direction of waves and filtered by the goggle
- Interference filter technology
  - Different wave lengths
- Autostereoscopy
  - No goggle needed
  - Waves are shot with two slightly different directions



# Other Projections

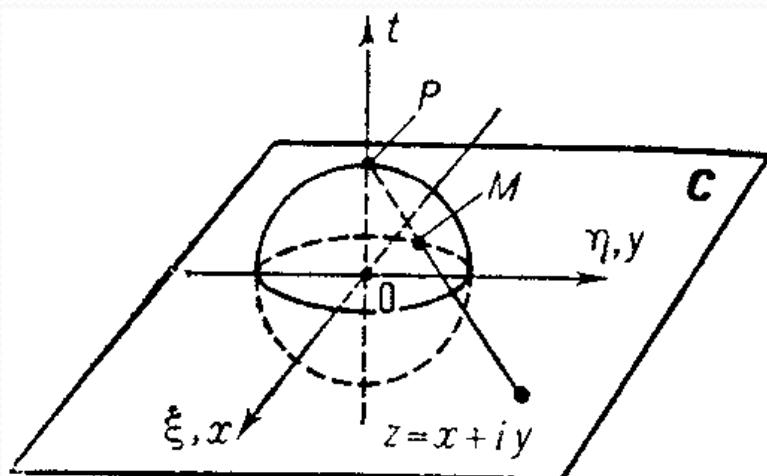
Perspective

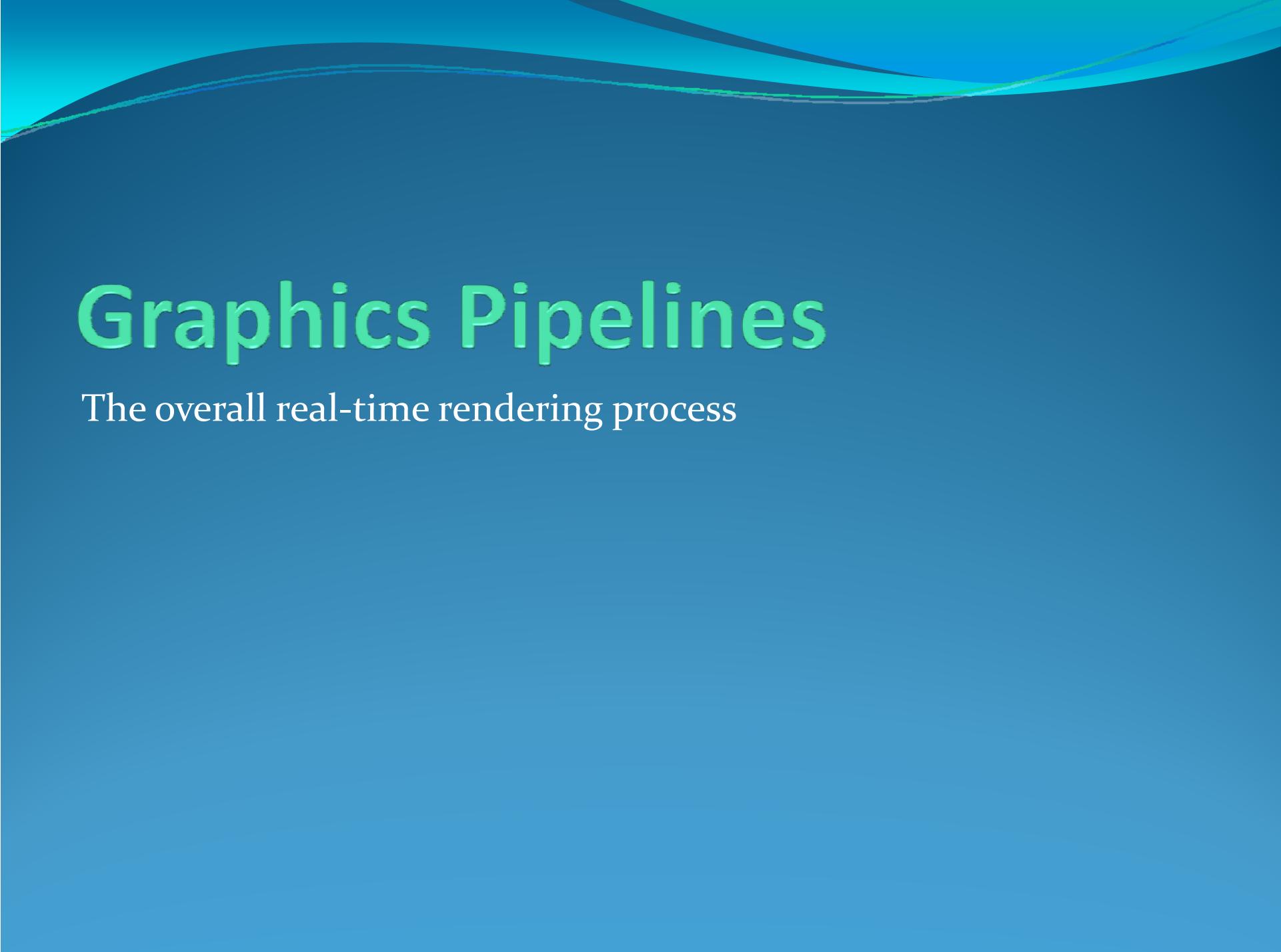


Stereographic



# Stereographic Projection

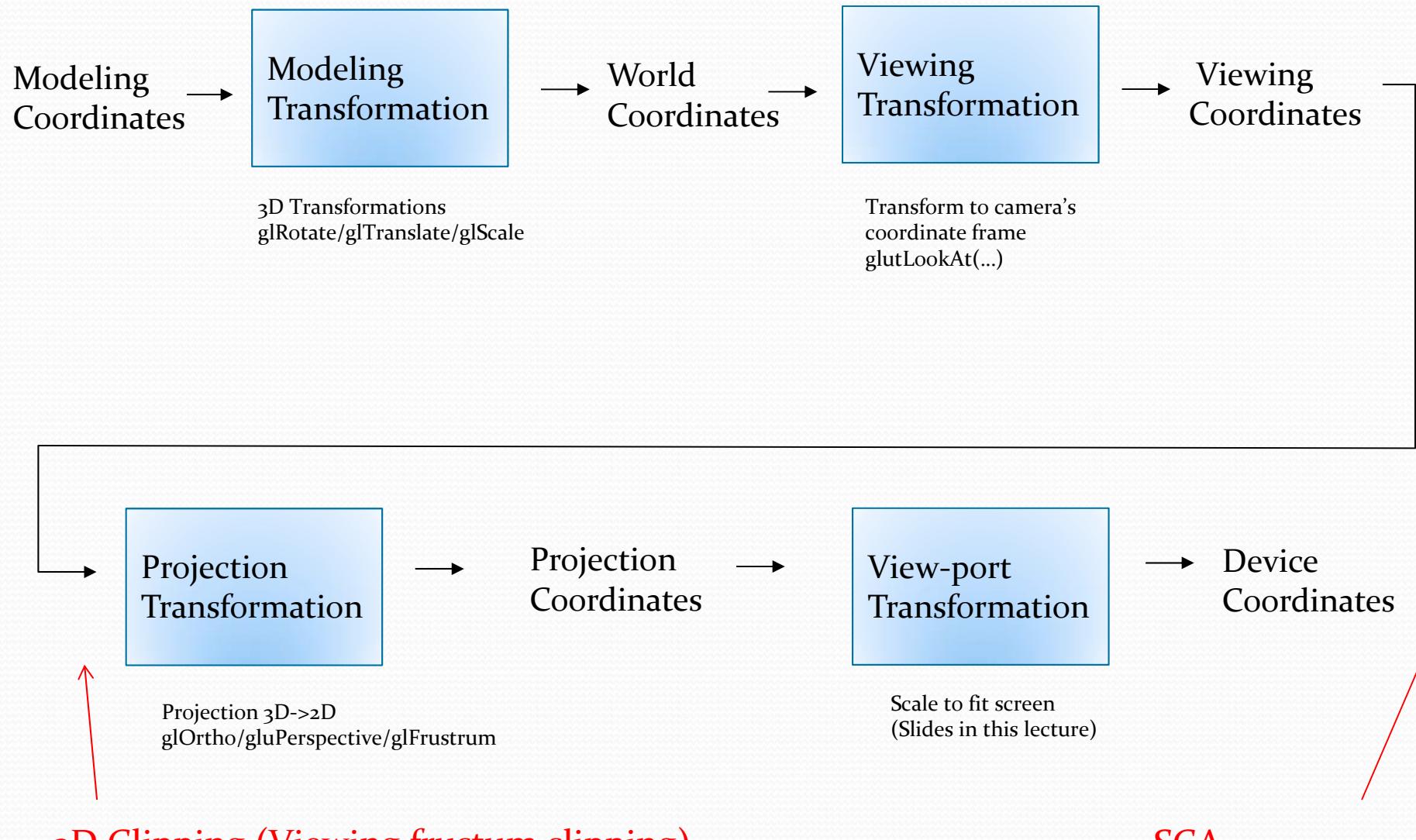




# Graphics Pipelines

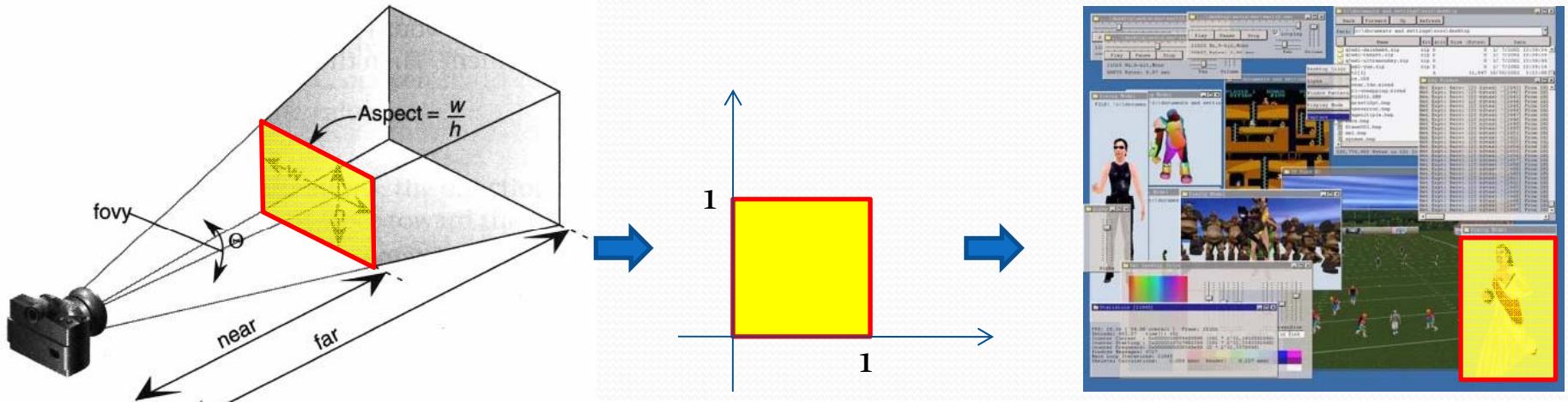
The overall real-time rendering process

# Graphic Pipeline



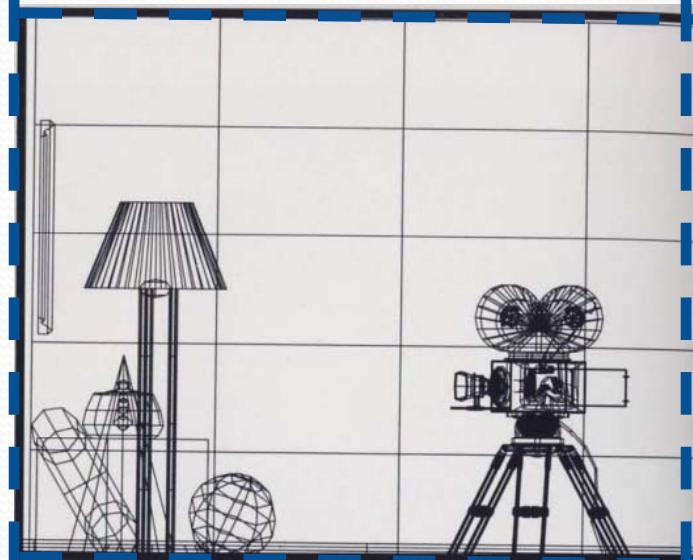
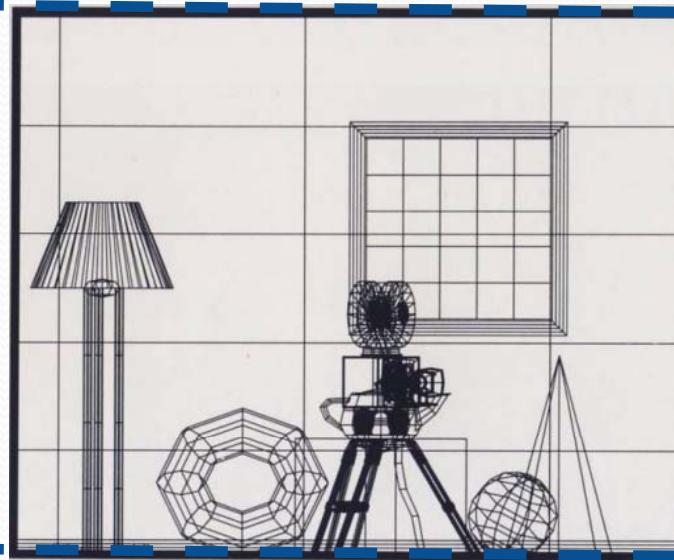
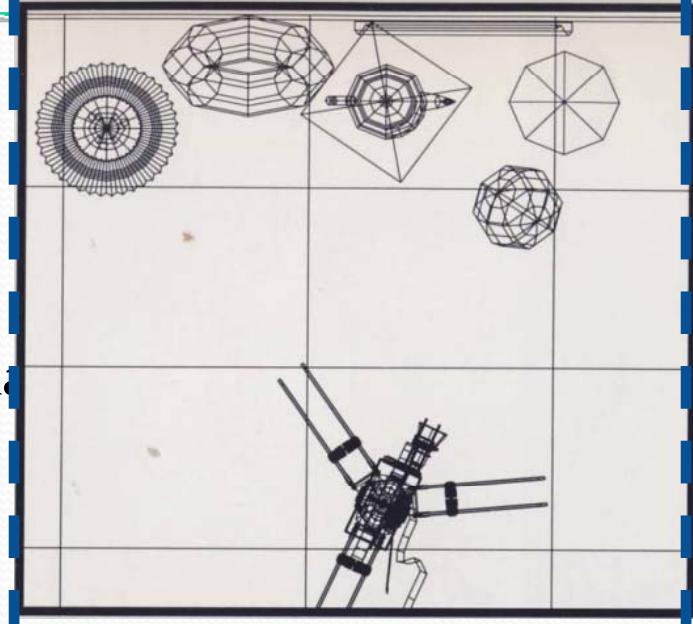
# View-port Transformation

- Screens can be reshape, panned, etc.
- After projection, OpenGL maps your screen to the unit-square
  - Normalized Device Coordinates
- Then map the square to your device, e.g. a window
  - **Scale to the window size then translate**

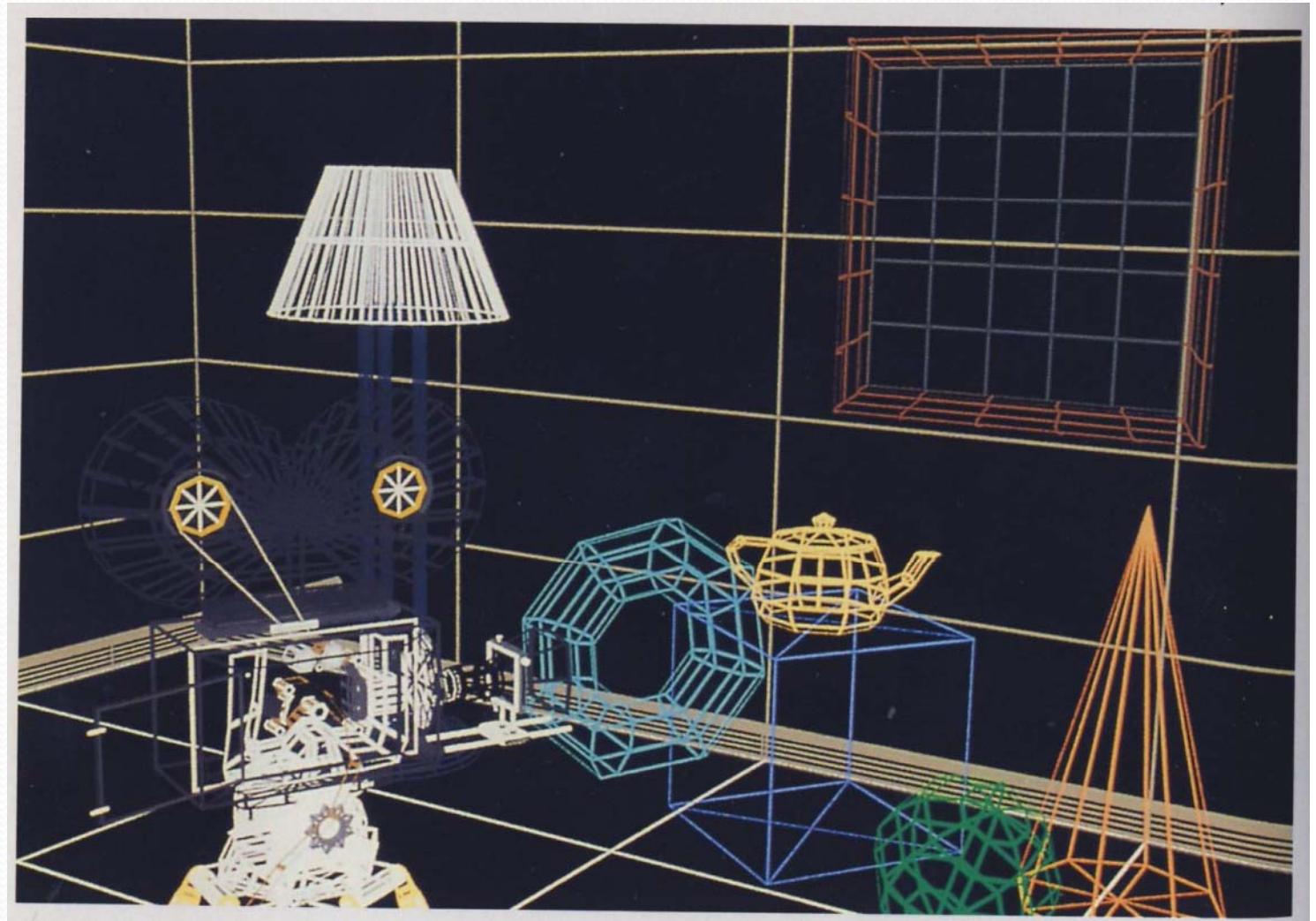


# Where are we?

- Object modeling (M,E)
  - Object Representation
    - Using different data structure/formats to represent objects
    - Geometric models

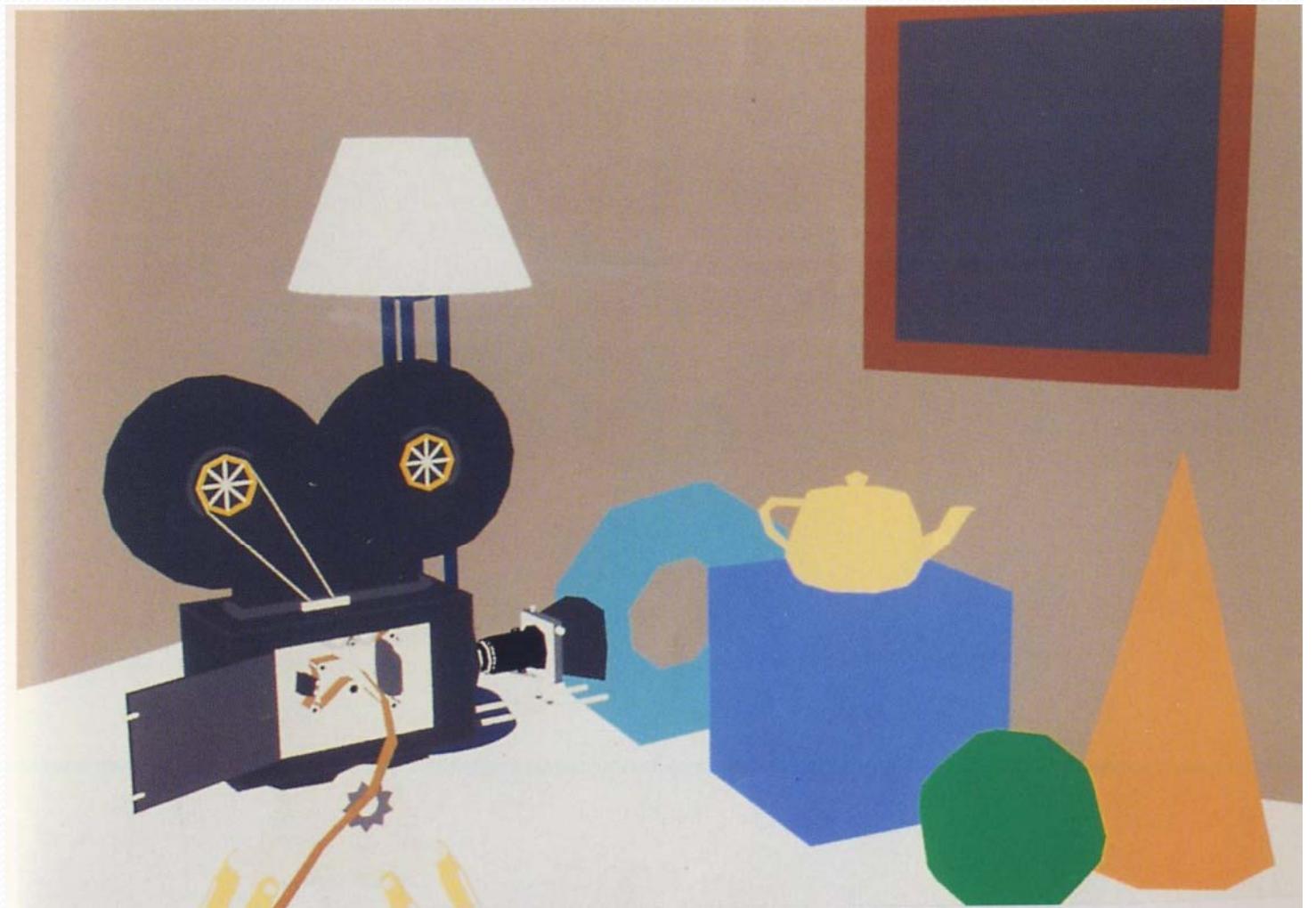


# Transformation/Viewing



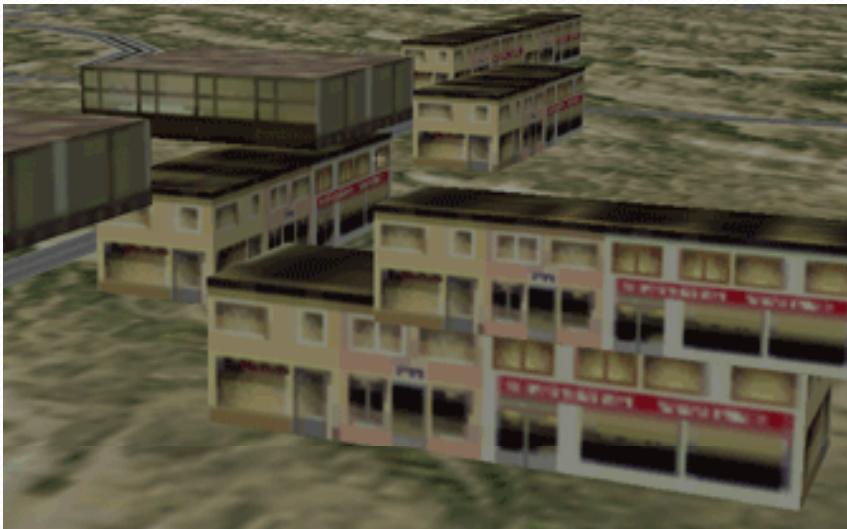
# Scan Convert Algorithm

- Next lecture: But how do we know the order?
  - What is in front of/behind of what?

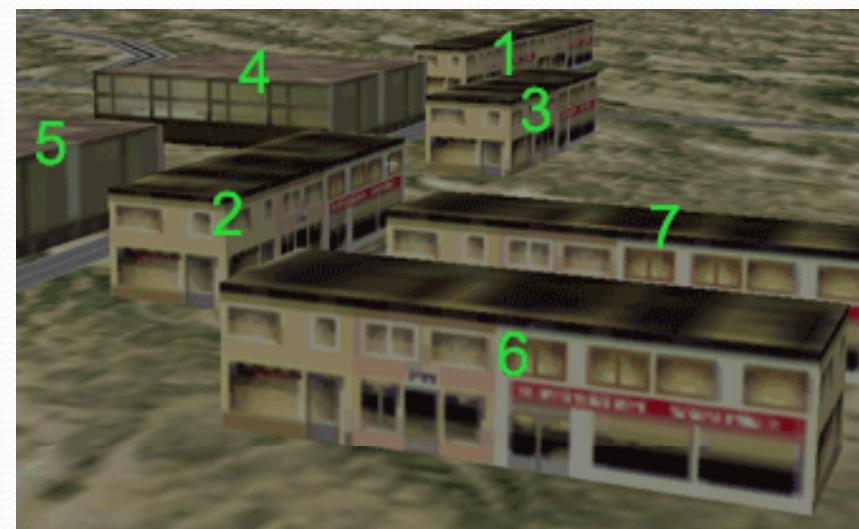


# Wrong Drawing Order

- How to draw objects correctly in the order of depth?



Wrong



Correct