

Packages Description

1、 To Use

Switch to the launch file of each function package and use the `roslaunch` command to start it. Take `driver_bringup.launch` as an example,

```
cd ~/drier_ws/src/yahboomcar_bringup/launch #The driver_ws here is my workspace,  
please modify it according to the actual situation  
roslaunch driver_bringup.launch
```

2、 Packages Description

imu_calib: To calibrate imu

imu_filter_madgwick: To filter fusion imu

yahboomcar_bringup: driver

yahboomcar_ctrl: keyboard control

yahboomcar_msgs: Relevant msg files

robot_localization: Kalman filter

yahboomcar_description: Related Simulation Model Files