

# psub\_map\_label

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## 1 Referencing Partial State Update Blocks labels to substeps in cadCAD

*Vitor Marthendal Nunes*

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This notebook shows how to use label metadata on PSUBs to do post-processing on the simulation. We use the key `label` as metadata to the partial state update blocks, so it's possible to map the substeps order to the PSUBs label. The used prey and predator model was taken from `minimal_prey_predator.ipynb`

### 1.1 Dependences

```
[1]: %%capture
      !pip install cadcad
```

```
[2]: import pandas as pd
      import matplotlib.pyplot as plt
      import numpy as np
      from cadCAD.configuration import Experiment
      from cadCAD.configuration.utils import config_sim
      from cadCAD.engine import ExecutionMode, ExecutionContext, Executor
```

### 1.2 Definitions

#### 1.2.1 Initial conditions and parameters

```
[3]: initial_conditions = {
      'prey_population': 100,
      'predator_population': 15
      }

      params = {
          "prey_birth_rate": [1.0],
          "predator_birth_rate": [0.01],
          "predator_death_const": [1.0],
          "prey_death_const": [0.03],
```

```

    "dt": [0.1] # Precision of the simulation. Lower is more accurate / slower
}

simulation_parameters = {
    'N': 1,
    'T': range(200),
    'M': params
}

```

### 1.2.2 Policies

```

[4]: def p_predator_births(params, step, sL, s):
    dt = params['dt']
    predator_population = s['predator_population']
    prey_population = s['prey_population']
    birth_fraction = params['predator_birth_rate'] + np.random.random() * 0.0002
    births = birth_fraction * prey_population * predator_population * dt
    return {'add_to_predator_population': births}

def p_pre_y_births(params, step, sL, s):
    dt = params['dt']
    population = s['prey_population']
    birth_fraction = params['prey_birth_rate'] + np.random.random() * 0.1
    births = birth_fraction * population * dt
    return {'add_to_pre_y_population': births}

def p_predator_deaths(params, step, sL, s):
    dt = params['dt']
    population = s['predator_population']
    death_rate = params['predator_death_const'] + np.random.random() * 0.005
    deaths = death_rate * population * dt
    return {'add_to_predator_population': -1.0 * deaths}

def p_pre_y_deaths(params, step, sL, s):
    dt = params['dt']
    death_rate = params['prey_death_const'] + np.random.random() * 0.1
    prey_population = s['prey_population']
    predator_population = s['predator_population']
    deaths = death_rate * prey_population * predator_population * dt
    return {'add_to_pre_y_population': -1.0 * deaths}

```

### 1.2.3 State update functions

```
[5]: def s_prey_population(params, step, sL, s, _input):
    y = 'prey_population'
    x = s['prey_population'] + _input['add_to_prey_population']
    return (y, x)

def s_predator_population(params, step, sL, s, _input):
    y = 'predator_population'
    x = s['predator_population'] + _input['add_to_predator_population']
    return (y, x)
```

### 1.2.4 State update blocks

```
[6]: partial_state_update_blocks = [
    {
        'label': 'Predator dynamics',
        'policies': {
            'predator_births': p_predator_births,
            'predator_deaths': p_predator_deaths
        },
        'variables': {
            'predator_population': s_predator_population
        }
    },
    {
        'label': 'Prey dynamics',
        'policies': {
            'prey_births': p_prey_births,
            'prey_deaths': p_prey_deaths
        },
        'variables': {
            'prey_population': s_prey_population
        }
    }
]
```

### 1.2.5 Configuration and Execution

```
[7]: sim_config = config_sim(simulation_parameters)

exp = Experiment()
exp.append_configs(sim_configs=sim_config,
                  initial_state=initial_conditions,
                  partial_state_update_blocks=partial_state_update_blocks)
```

```

from cadCAD import configs
exec_mode = ExecutionMode()
exec_context = ExecutionContext(exec_mode.local_mode)
executor = Executor(exec_context=exec_context, configs=configs)
(records, tensor_field, _) = executor.execute()

```

```

      -----
 /-----\ /-----\ /-----\
/-----\ /-----\ /-----\
/-----\ /-----\ /-----\
\-----/ \-----/ \-----/
by cadCAD

```

```

Execution Mode: local_proc
Configuration Count: 1
Dimensions of the first simulation: (Timesteps, Params, Runs, Vars) = (200, 5,
1, 2)
Execution Method: local_simulations
SimIDs   : [0]
SubsetIDs: [0]
Ns       : [0]
ExpIDs   : [0]
Execution Mode: single_threaded
Total execution time: 0.03s

```

### 1.2.6 Results

```

[8]: df = pd.DataFrame(records)
df

```

```

[8]:
   prey_population  predator_population  simulation  subset  run  substep \
0      100.000000      15.000000          0          0      1          0
1      100.000000      15.015392          0          0      1          1
2      103.047419      15.015392          0          0      1          2
3      103.047419      15.079086          0          0      1          1
4      106.922179      15.079086          0          0      1          2
..          ...          ...          ...    ...    ...
396      71.492635      13.422579          0          0      1          2
397      71.492635      13.044633          0          0      1          1
398      73.363427      13.044633          0          0      1          2
399      73.363427      12.703877          0          0      1          1
400      71.890824      12.703877          0          0      1          2

   timestep
0          0

```

```

1          1
2          1
3          2
4          2
..         ...
396        198
397        199
398        199
399        200
400        200

```

[401 rows x 7 columns]

```

[9]: # Mapping the substep order to the PSUB label
psubs = partial_state_update_blocks
psub_map = {order+1: psub['label'] for (order, psub) in enumerate(psubs)}

```

```

[10]: df['psubs'] = df.substep.map(psub_map)
df

```

```

[10]:      prey_population  predator_population  simulation  subset  run  substep  \
0          100.000000          15.000000           0         0     1         0
1          100.000000          15.015392           0         0     1         1
2          103.047419          15.015392           0         0     1         2
3          103.047419          15.079086           0         0     1         1
4          106.922179          15.079086           0         0     1         2
..         ...
396         71.492635          13.422579           0         0     1         2
397         71.492635          13.044633           0         0     1         1
398         73.363427          13.044633           0         0     1         2
399         73.363427          12.703877           0         0     1         1
400         71.890824          12.703877           0         0     1         2

```

```

      timestep      psubs
0           0         NaN
1           1  Predator dynamics
2           1    Prey dynamics
3           2  Predator dynamics
4           2    Prey dynamics
..         ...
396        198    Prey dynamics
397        199  Predator dynamics
398        199    Prey dynamics
399        200  Predator dynamics
400        200    Prey dynamics

```

[401 rows x 8 columns]

### 1.2.7 Filtering the results by the PSUB labels

```
[11]: df.query("psubs=='Predator dynamics'")
```

```
[11]:      prey_population  predator_population  simulation  subset  run  substep  \
1          100.000000          15.015392           0         0    1         1
3          103.047419          15.079086           0         0    1         1
5          106.922179          15.183327           0         0    1         1
7          101.542973          15.204592           0         0    1         1
9           95.307070          15.146123           0         0    1         1
..           ...           ...           ...   ...   ...   ...
391         66.405231          14.331045           0         0    1         1
393         65.991522          13.855685           0         0    1         1
395         68.729829          13.422579           0         0    1         1
397         71.492635          13.044633           0         0    1         1
399         73.363427          12.703877           0         0    1         1
```

```
      timestep      psubs
1           1  Predator dynamics
3           2  Predator dynamics
5           3  Predator dynamics
7           4  Predator dynamics
9           5  Predator dynamics
..          ...          ...
391        196  Predator dynamics
393        197  Predator dynamics
395        198  Predator dynamics
397        199  Predator dynamics
399        200  Predator dynamics
```

[200 rows x 8 columns]

```
[12]: df.query("psubs=='Prey dynamics'")
```

```
[12]:      prey_population  predator_population  simulation  subset  run  substep  \
2          103.047419          15.015392           0         0    1         2
4          106.922179          15.079086           0         0    1         2
6          101.542973          15.183327           0         0    1         2
8           95.307070          15.204592           0         0    1         2
10          94.403745          15.146123           0         0    1         2
..           ...           ...           ...   ...   ...   ...
392         65.991522          14.331045           0         0    1         2
394         68.729829          13.855685           0         0    1         2
396         71.492635          13.422579           0         0    1         2
398         73.363427          13.044633           0         0    1         2
400         71.890824          12.703877           0         0    1         2
```

	timestep	psubs
2	1	Prey dynamics
4	2	Prey dynamics
6	3	Prey dynamics
8	4	Prey dynamics
10	5	Prey dynamics
..	...	...
392	196	Prey dynamics
394	197	Prey dynamics
396	198	Prey dynamics
398	199	Prey dynamics
400	200	Prey dynamics

[200 rows x 8 columns]