The consensus problem requires a set of processes to choose a single value. This module specifies the problem by specifying exactly what the requirements are for choosing a value.

7 EXTENDS Naturals, FiniteSets, TLAPS

We let the constant parameter Value be the set of all values that can be chosen.

13 CONSTANT Value

We now specify the safety property of consensus as a trivial algorithm that describes the allowed behaviors of a consensus algorithm. It uses the variable chosen to represent the set of all chosen values. The algorithm is trivial; it allows only behaviors that contain a single state-change in which the variable chosen is changed from its initial value $\{\}$ to the value $\{v\}$ for an arbitrary value v in Value. The algorithm itself does not specify any fairness properties, so it also allows a behavior in which chosen is not changed. We could use a translator option to have the translation include a fairness requirement, but we don't bother because it is easy enough to add it by hand to the safety specification that the translator produces.

A real specification of consensus would also include additional variables and actions. In particular, it would have Propose actions in which clients propose values and Learn actions in which clients learn what value has been chosen. It would allow only a proposed value to be chosen. However, the interesting part of a consensus algorithm is the choosing of a single value. We therefore restrict our attention to that aspect of consensus algorithms. In practice, given the algorithm for choosing a value, it is obvious how to implement the Propose and Learn actions.

For convenience, we define the macro Choose() that describes the action of changing the value of chosen from $\{\}$ to $\{v\}$, for a nondeterministically chosen v in the set Value. (There is little reason to encapsulate such a simple action in a macro; however our other specs are easier to read when written with such macros, so we start using them now.) The when statement can be executed only when its condition, $chosen = \{\}$, is true. Hence, at most one Choose() action can be performed in any execution. The with statement executes its body for a nondeterministically chosen v in Value. Execution of this statement is enabled only if Value is non-empty-something we do not assume at this point because it is not required for the safety part of consensus, which is satisfied if no value is chosen.

We put the Choose() action inside a while statement that loops forever. Of course, only a single Choose() action can be executed. The algorithm stops after executing a Choose() action. Technically, the algorithm deadlocks after executing a Choose() action because control is at a statement whose execution is never enabled. Formally, termination is simply deadlock that we want to happen. We could just as well have omitted the while and let the algorithm terminate. However, adding the while loop makes the TLA+ representation of the algorithm a tiny bit simpler.

The PlusCal translator writes the TLA+ translation of this algorithm below. The formula Spec is the TLA+ specification described by the algorithm's code. For now, you should just understand its two subformulas Init and Next. Formula Init is the initial predicate and describes all possible initial states of an execution. Formula Next is the next-state relation; it describes the possible state changes (changes of the values of variables), where unprimed variables represent their values in the old state and primed variables represent their values in the new state.

```
**** BEGIN TRANSLATION
80
     VARIABLE chosen
81
     vars \triangleq \langle chosen \rangle
                   Global variables
85
                  \land chosen = \{\}
86
     Next \triangleq \land chosen = \{\}
88
                  \land \exists v \in Value :
89
                        chosen' = \{v\}
90
     Spec \stackrel{\Delta}{=} Init \wedge \Box [Next]_{vars}
       **** END TRANSLATION
94
95 F
```

We now prove the safety property that at most one value is chosen. We first define the type-correctness invariant TypeOK, and then define Inv to be the inductive invariant that asserts TypeOK and that the cardinality of the set chosen is at most 1. We then prove that, in any behavior satisfying the safety specification Spec, the invariant Inv is true in all states. This means that at most one value is chosen in any behavior.

To prove our theorem, we need the following simple results about the cardinality of finite sets.

```
115 AXIOM EmptySetCardinality \triangleq IsFiniteSet(\{\}) \land Cardinality(\{\}) = 0
116 AXIOM SingletonCardinality \triangleq
117 \forall e : IsFiniteSet(\{e\}) \land (Cardinality(\{e\}) = 1)
```

Whenever we add an axiom, we should check it with TLC to make sure we haven't made any errors. To check axiom SingletonCardinality, we must replace the unbounded quantification with a bounded one. We therefore let TLC check that the following formula is true.

```
125 SingleCardinalityTest \triangleq
126 \forall e \in \text{SUBSET } \{\text{"a"}, \text{"b"}, \text{"c"}\} : IsFiniteSet(\{e\}) \land (Cardinality(\{e\}) = 1)
```

We now prove that Inv is an invariant, meaning that it is true in every state in every behavior. Before trying to prove it, we should first use TLC to check that it is true. It's hardly worth bothering to either check or prove the obvious fact that Inv is an invariant, but it's a nice tiny exercise. Model checking is instantaneous when Value is set to any small finite set.

To understand the following proof, you need to understand the formula Spec, which equals

```
Init \wedge \square[Next]\_vars
```

where vars is the tuple $\langle chosen, pc \rangle$ of all variables. It is a temporal formula satisfied by a behavior iff the behavior starts in a state satisfying Init and such that each step (sequence of states) satisfies $[Next]_vars$, which equals

```
Next \lor (vars' = vars)
```

Thus, each step satisfies either *Next* (so it is a step allowed by the next-state relation) or it is a "stuttering step" that leaves all the variables unchanged. The reason why a spec must allow stuttering steps will become apparent when we prove that a consensus algorithm satisfies this specification of consensus.

By default, a definition is not usable in a proof. If the a definition should be usable in the proof of a step, meaning that the prover can expand the definition, then that must be explicitly indicated—usually in the DEF clause of a BY statement. A DEF clause of a USE statement makes the definitions in it usable in the scope of that statement. The following USE statement makes the definition of lbl usable everywhere in the rest of the module. (There is a corresponding HIDE statement that makes definitions unusable in its scope.)

```
165 USE DEF lbl
```

The following lemma asserts that Inv is an inductive invariant of the next-state action Next. It is the key step in proving that Inv is an invariant of (true in every behavior allowed by) specification Spec.

```
LEMMA InductiveInvariance \stackrel{\triangle}{=}
172
                           Inv \wedge [Next]_{vars} \Rightarrow Inv'
173
       \langle 1 \rangle 1. Suffices assume Inv, [Next]_{vars}
174
                               PROVE Inv'
175
         OBVIOUS
176
       \langle 1 \rangle 2.CASE Next
177
          \langle 2 \rangle 1. PICK v \in Value : chosen' = \{v\}
178
               In the following BY proof, \langle 1 \rangle 2 denotes the case assumption Next
179
             BY \langle 1 \rangle 2 DEF Next
180
          \langle 2 \rangle 2. QED
181
               In the following BY proof, \langle 1 \rangle 1 refers to the assumptions
182
183
               Inv and [Next]\_vars
             BY \langle 1 \rangle 1, \langle 2 \rangle 1, Singleton Cardinality, 1 \leq 1 DEF Inv, TypeOK, Next, vars
184
       \langle 1 \rangle 4.CASE vars' = vars
185
         BY \langle 1 \rangle 1, \langle 1 \rangle 4 DEF Inv, TypeOK, Next, vars
186
       \langle 1 \rangle 5. QED
187
         BY \langle 1 \rangle 1, \langle 1 \rangle 2, \langle 1 \rangle 4 DEF Next
188
```

TLAPS does not yet handle temporal logic reasoning. Therefore, proofs of temporal steps are omitted. However, we indicate in comments what we expect the proofs to look like when TLAPS does prove temporal formulas.

```
THEOREM Invariance \triangleq Spec \Rightarrow \Box Inv

197 \langle 1 \rangle 1. Init \Rightarrow Inv

We usually have to use SimpleArithmetic to prove facts about numbers, but 0 \leq 1 is simple enough that Isabelle can prove it by itself.

BY EmptySetCardinality, 0 \leq 1 DEF Init, Inv, TypeOK

202 \langle 1 \rangle 2. QED

203 \langle 2 \rangle 1. Inv \wedge \Box [Next]_{vars} \Rightarrow \Box Inv

Typo corrected here 28 Jun 2016

BY InductiveInvariance, RuleINV1
```

```
PROOF OMITTED
```

205

217 H

```
213 \langle 2 \rangle2. QED
214 BY \langle 1 \rangle1, \langle 2 \rangle1
215 PROOF OMITTED
```

We now define LiveSpec to be the algorithm's specification with the added fairness condition of weak fairness of the next-state relation, which asserts that execution does not stop if some action is enabled. The temporal formula Success asserts that some value is eventually chosen. Below, we prove that LiveSpec implies Success This means that, in every behavior satisfying LiveSpec, some value is chosen.

```
226 LiveSpec \triangleq Spec \land WF_{vars}(Next)
227 Success \triangleq \diamondsuit(chosen \neq \{\})
```

For liveness, we need to assume that there exists at least one value.

232 ASSUME $ValueNonempty \triangleq Value \neq \{\}$

TLAPS does not yet reason about ENABLED . Therefore, we must omit all proofs that involve ENABLED formulas. To perform as much of the proof as possible, as much as possible we restrict the use of an ENABLED expression to a step asserting that it equals its definition. ENABLED A is true of a state s iff there is a state t such that the step $s \to t$ satisfies A. It follows from this semantic definition that ENABLED A equals the formula obtained by

- 1. Expanding all definitions of defined symbols in A until all primes are priming variables.
- 2. For each primed variable, replacing every instance of that primed variable by a new symbol (the same symbol for each primed variable).
- 3. Existentially quantifying over those new symbols.

```
Lemma EnabledDef \triangleq
252
                      TypeOK \Rightarrow
253
                        ((ENABLED \langle Next \rangle_{vars}) \equiv (chosen = \{\}))
254
       \langle 1 \rangle define E \triangleq
255
                \exists \ chosenp:
256
                          \land \land chosen = \{\}
257
                               \land \exists v \in Value : chosenp = \{v\}
258
                          \land \neg(\langle chosenp\rangle = \langle chosen\rangle)
259
       \langle 1 \rangle 1. E = \text{Enabled } \langle Next \rangle_{vars}
260
           By Def Next, vars
261
         PROOF OMITTED
262
       \langle 1 \rangle 2. Suffices assume TypeOK
263
                              PROVE E = (chosen = \{\})
264
265
        BY \langle 1 \rangle 1
         PROOF OMITTED
266
      \langle 1 \rangle 3. E = \exists chosenp : E!(chosenp)!1
```

```
BY \langle 1 \rangle 2 DEF TypeOK
268
      \langle 1 \rangle 4. @ = (chosen = \{\})
269
       BY \langle 1 \rangle 2, ValueNonempty DEF TypeOK
       \langle 1 \rangle 5. QED
271
272
       BY \langle 1 \rangle 3, \langle 1 \rangle 4
       Here is our proof that Livespec implies Success. It uses the standard TLA proof rules. For
       example RuleWF1 is defined in the TLAPS module to be the rule WF1 discussed in
            AUTHOR = "Leslie Lamport".
            TITLE
                        = "The Temporal Logic of Actions",
            JOURNAL = toplas,
            volume
            number
                        = 3,
            YEAR
                        = 1994,
            month
                        = may,
            PAGES
                        = "872--923"
       PTL stands for propositional temporal logic reasoning. We expect that, when TLAPS handles
       temporal reasoning, it will use a decision procedure for PTL.
      Theorem LiveSpec \Rightarrow Success
292
       \langle 1 \rangle 1. \Box Inv \wedge \Box [Next]_{vars} \wedge WF_{vars}(Next) \Rightarrow (chosen = \{\} \leadsto chosen \neq \{\})
293
          \langle 2 \rangle 1. \text{ SUFFICES } \Box [Next]_{vars} \wedge \text{WF}_{vars}(Next) \Rightarrow ((Inv \wedge chosen = \{\}) \rightsquigarrow chosen \neq \{\})
294
              OBVIOUS
295
            PROOF OMITTED
296
          \langle 2 \rangle 2. \ (Inv \land (chosen = \{\})) \land [Next]_{vars} \Rightarrow ((Inv' \land (chosen' = \{\})) \lor chosen' \neq \{\})
297
            By InductiveInvariance
298
          \langle 2 \rangle 3. \ (Inv \land (chosen = \{\})) \land \langle Next \rangle_{vars} \Rightarrow (chosen' \neq \{\})
299
            BY DEF Inv, Next, vars
300
          \langle 2 \rangle 4. \ (Inv \land (chosen = \{\})) \Rightarrow \text{ENABLED} \ \langle Next \rangle_{vars}
301
302
            BY EnabledDef DEF Inv
            PROOF OMITTED
303
          \langle 2 \rangle 5. QED
304
            By \langle 2 \rangle 2, \langle 2 \rangle 3, \langle 2 \rangle 4, RuleWF1
305
            PROOF OMITTED
306
       \langle 1 \rangle 2. (chosen = \{\} \rightsquigarrow chosen \neq \{\}) \Rightarrow ((chosen = \{\}) \Rightarrow \Diamond (chosen \neq \{\}))
307
308
          OBVIOUS
         PROOF OMITTED
309
       \langle 1 \rangle 3. QED
310
          By Invariance, \langle 1 \rangle 1, \langle 1 \rangle 2 Def LiveSpec, Spec, Init, Success
311
         PROOF OMITTED
312
313 |
      The following theorem is used in the refinement proof in module VoteProof.
      THEOREM LiveSpecEquals \stackrel{\triangle}{=}
318
                         \mathit{LiveSpec} \equiv \mathit{Spec} \land (\Box \Diamond \langle \mathit{Next} \rangle_{\mathit{vars}} \lor \Box \Diamond (\mathit{chosen} \neq \{\}))
319
       \langle 1 \rangle 1. \land Spec \equiv Spec \land \Box TypeOK
320
321
              \land LiveSpec \equiv LiveSpec \land \Box TypeOK
        BY Invariance DEF LiveSpec, Inv
322
```

```
PROOF OMITTED
323
           \begin{array}{l} \langle 1 \rangle 2. \Box \mathit{TypeOK} \Rightarrow ((\Box \Diamond \neg \mathtt{ENABLED} \ \langle \mathit{Next} \rangle_{\mathit{vars}}) \equiv \Box \Diamond (\mathit{chosen} \neq \{\})) \\ \underline{\langle 2 \rangle} 1. \Box \mathit{TypeOK} \Rightarrow \Box ((\neg \mathtt{ENABLED} \ \langle \mathit{Next} \rangle_{\mathit{vars}}) \equiv (\mathit{chosen} \neq \{\})) \end{array} 
324
325
             By EnabledDef
326
327
                 PROOF OMITTED
               \langle 2 \rangle 2. QED
328
             By \langle 2 \rangle 1
329
                 PROOF OMITTED
330
          \langle 1 \rangle 3. QED
331
             by \langle 1 \rangle 1, \langle 1 \rangle 2 def LiveSpec
332
333
             PROOF OMITTED
334 L
          \backslash * \ {\bf Modification} \ {\bf History}
          \ * Last modified Sat Nov 16 22:17:07 CST 2019 by hengxin
          \* Last modified \mathit{Tue}\ \mathit{Feb}\ 14\ 13:35:49\ \mathit{PST}\ 2012 by \mathit{lamport}
          \* Last modified Mon Feb 07 14:46:59 PST 2011 by lamport
```