Algoritmo 1-NN con umbral ajustable:

- **Procedure 1-NN with adjustable threshold**

- **Design parameter**: an adjustable distance threshold $\delta \approx 0$ to be optimized
- **Given** a memory of N landmarks ´ images and their corresponding normalized grey histograms:
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- [$(L_1 \rightarrow I_1 \rightarrow H_1)$ …….. $(L_N \rightarrow I_N \rightarrow H_N)$] ; where L are landmarks, I images and H normalized histograms

- For a new image [$I_{new} \rightarrow H_{new}$] to be recognized as a possible landmark **do**
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- Compute the Euclidean distance of H_{new} to all the normalized histograms stored in the memory and take the minimum distance d_{min}
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- **If** [$d_{min} \leq \delta$] **Then** [classify the new image as the landmark corresponding to the minimum **distance** d_{min}] **Else** [classify the new image as "unknown"]

- Note1: the adjustable distance threshold is meant to avoid false alarms and simultaneously to keep a good efficiency in the classification of the real landmarks. For its experimental tuning it is advisable to implement a search starting with a small value near zero ($\delta_{min} = 0,1$) up to a maximum value ($\delta_{max} = 1,0$) by means of small scanning steps $\approx 0,1) \rightarrow 0,1 \leq \delta \leq 1$
- Note 2 : the recognizer ´memory must be as big as possible and well-balanced(all the landmarks must have the same number of istances stored in the memory) .