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# -*- coding: utf-8 -*-
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#%% Assignment 5 - Q2
import numpy as np
#%% A
def roachNeurons(r0, n, ai, a):
# The inputs of the code:
      →0 - baseline firing rate
      n - number of interneurons
      ai – vector of the preferred angle \alpha of each neuron
      a - real angle
# The output of the code:
      a_hat - the prediction of the neurons using population vector
    neurons = [np.maximum(r0*np.cos(a-ai[i]),0) for i in range(n)] # firing rate pe
    x_{n} = np.sum(neurons*np.sin(ai)/r0) # decode x direction
    y_hat = np.sum(neurons*np.cos(ai)/r0) # decode y direction
    a hat = np.arctan2(x hat, y hat) % (2*np.pi) # vector to angle
    return a_hat
```