

Sprint : Déplacement du Robot Smart city, Livrable 2

Date: 20/10/2020

Nom de l'entreprise : Rob'oste

Nom du projet : Smart City

Groupe 8: - Hautier Benjamin

- Domingues Loïc

- Dieudonne Cesar

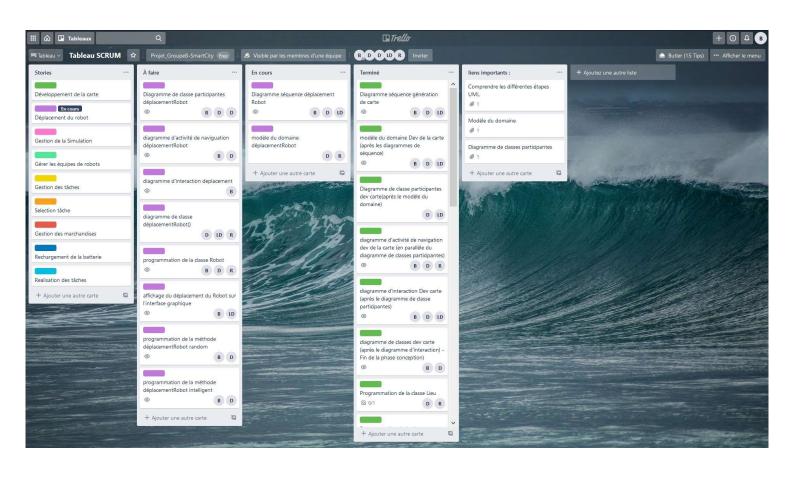
- Debuire Maxime

- Noizet Romain



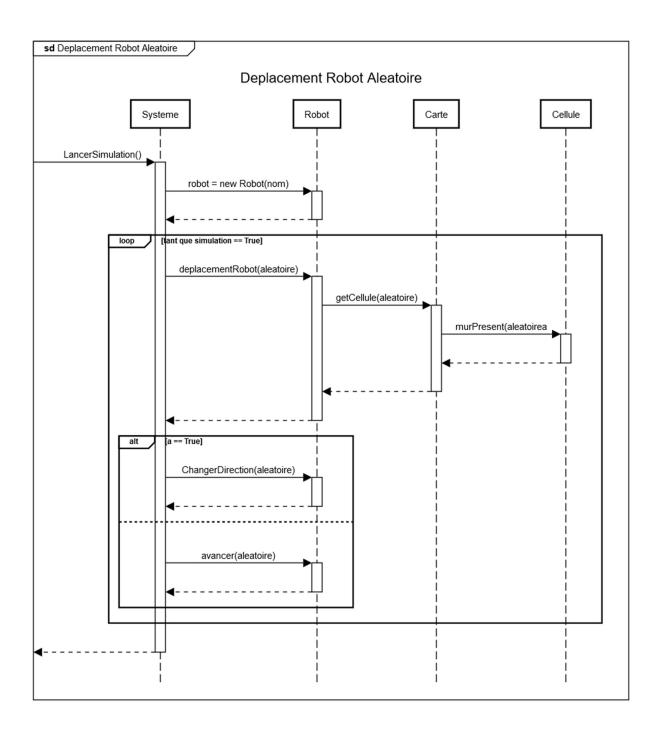
Livrable 2:

Résultat de la mélée n.1 (06/10) :



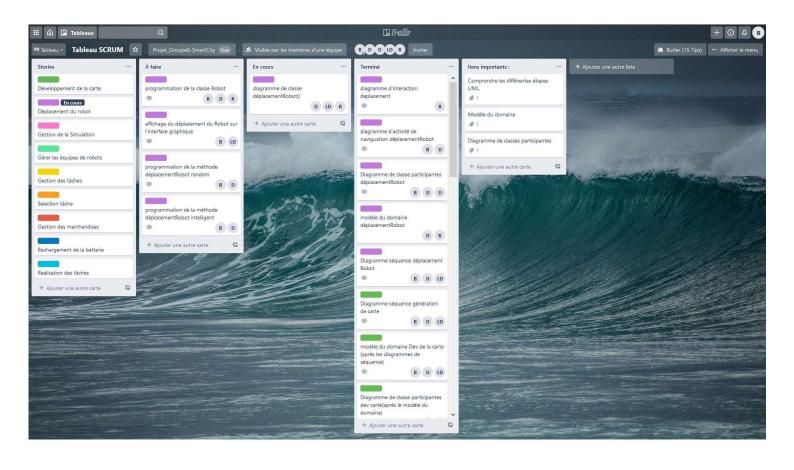


1. Diagramme de séquence :



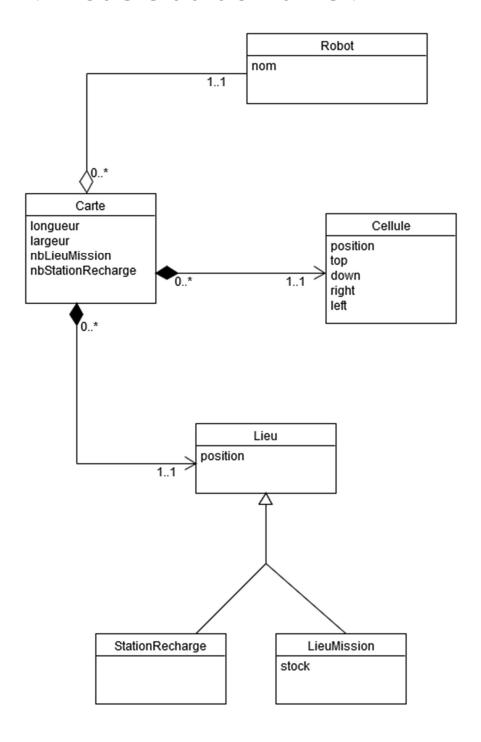


Résultat de la mélée n.2 (13/10) :



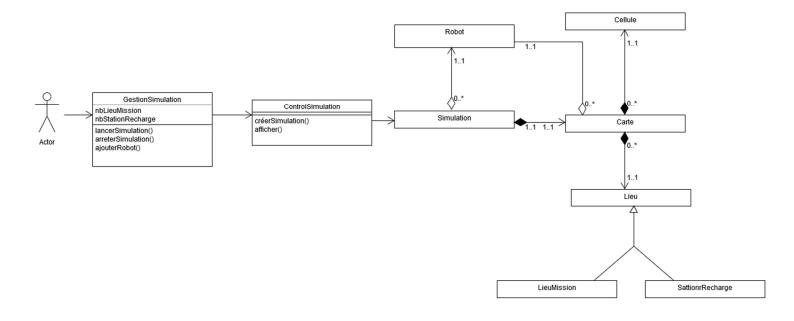


2. Modèle du domaine :

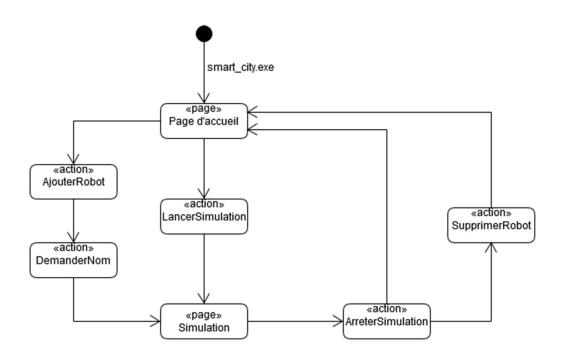




3. Diagramme de classes participantes :

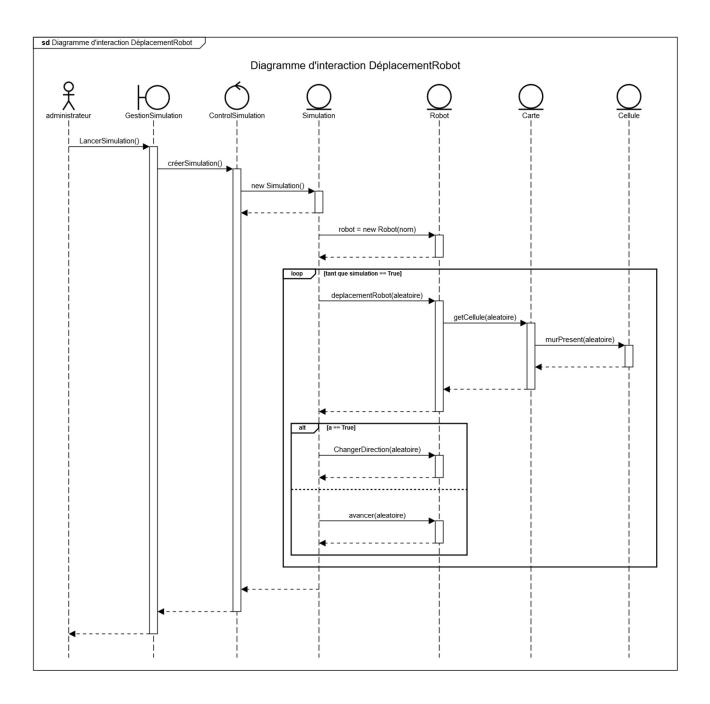


4. Diagramme naviguation IHM:



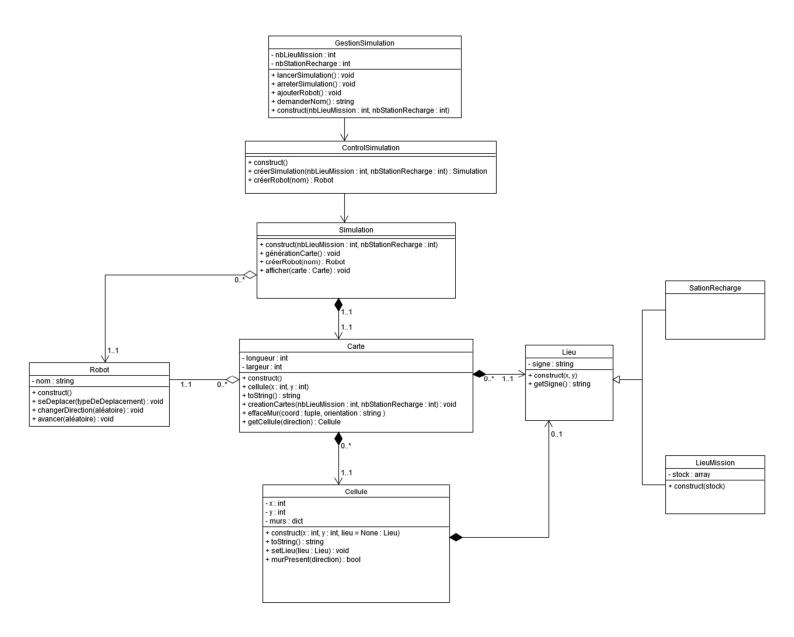


5. Diagramme d'interaction:





6. Diagramme de classe :





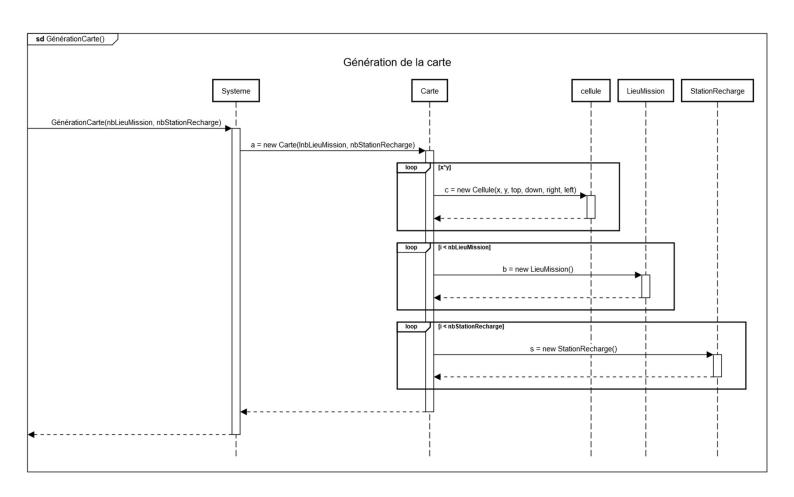
Résultat de la mélée n.3 (20/10) :



Livrable 1:

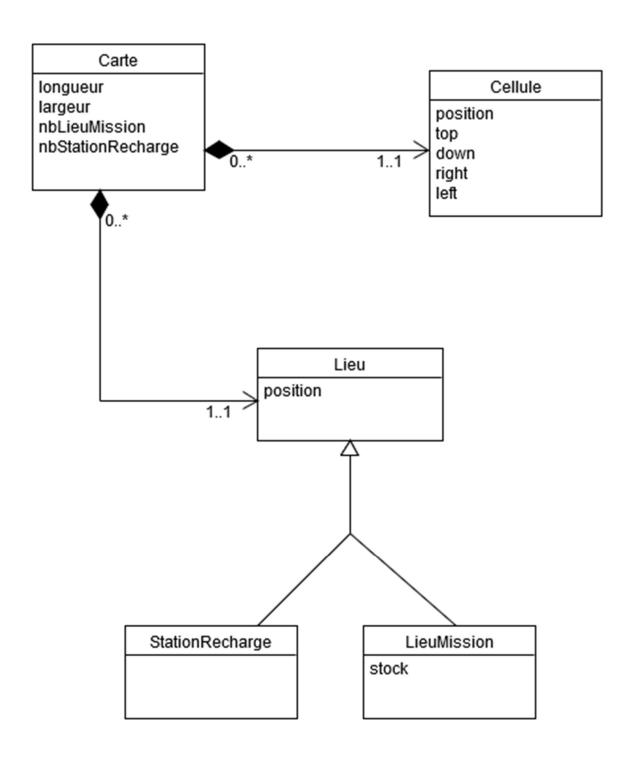
I – Phase conception

I-1. Diagramme de séquence :



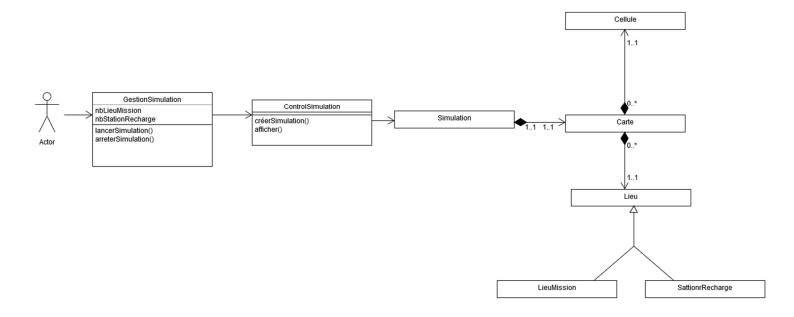


I-2. Modèle du domaine :

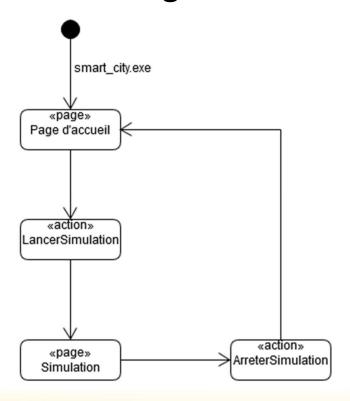




I-3. Diagramme de classes participantes :

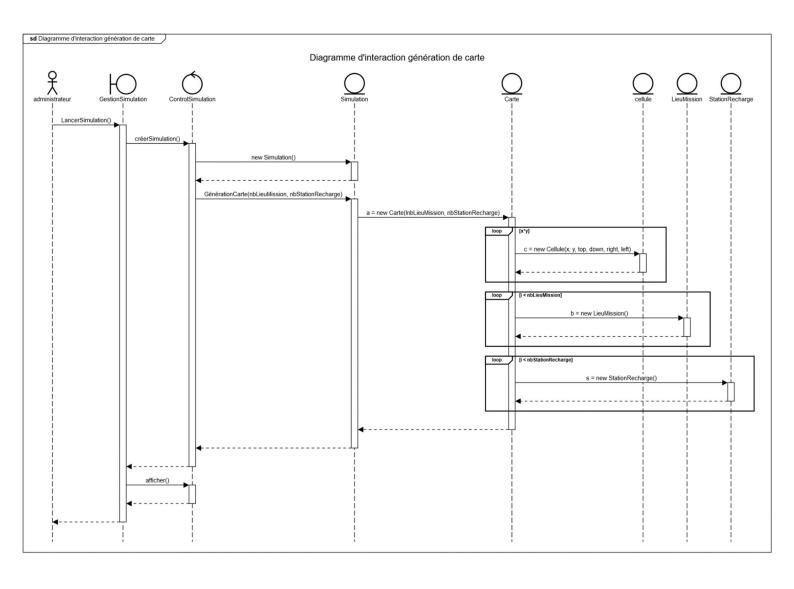


I-4. Diagramme naviguation IHM:



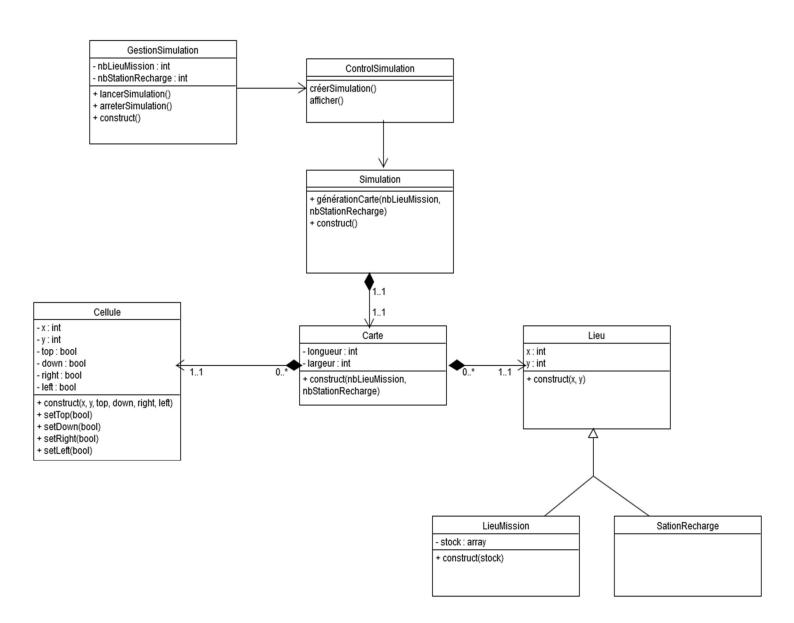


I-5. Diagramme d'interaction:





I-6. Diagramme de classe :





II - Phase programmation

Cf répertoire programmation sur gitlab pour voir le code

III - Annexe

III-1. Tableaux Scrum:

Tableau du 23/09:

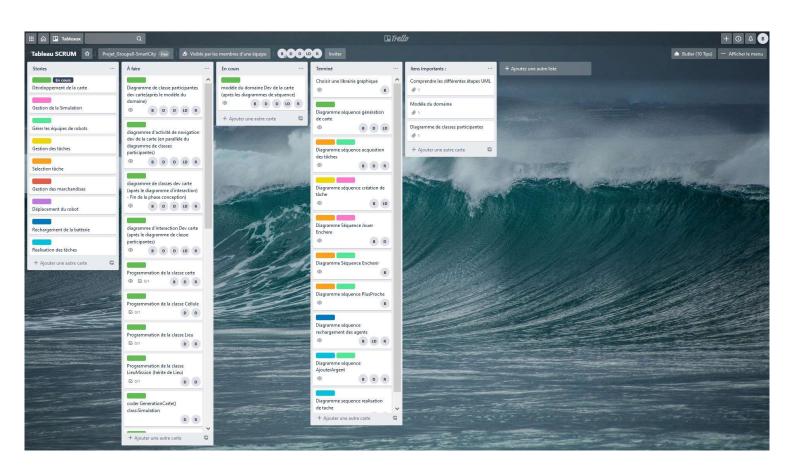




Tableau du 28/09

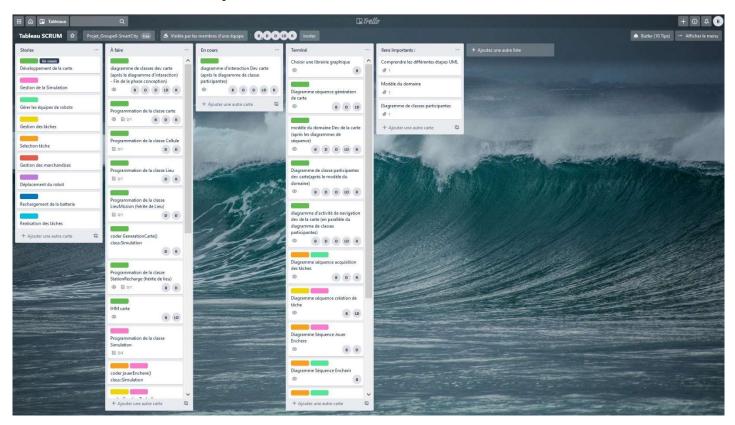


Tableau du 04/10:

