

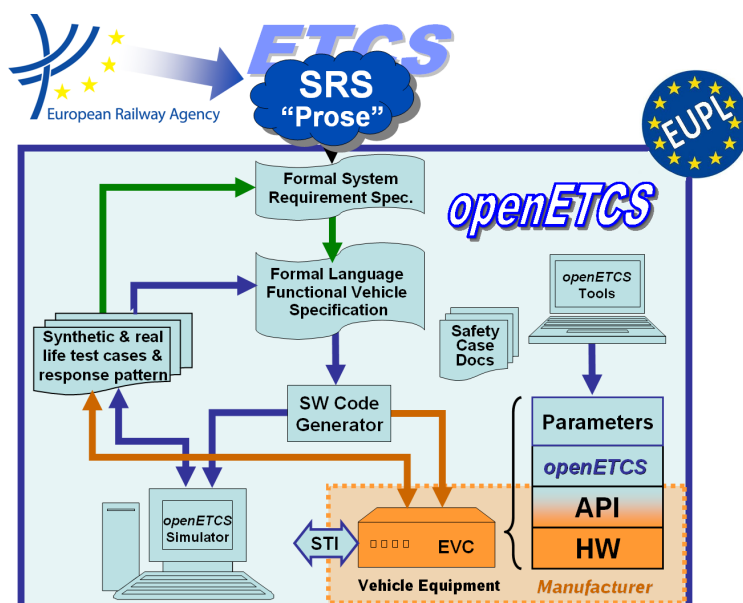
Work Package 4: “Validation & Verification Strategy”

openETCS Validation & Verification Plan

Version 00.03

Marc Behrens and Hardi Hungar and Stephan Jagusch

June 2013



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**OETCS/WP4/D4.1V00.03
June 2013**

openETCS Validation & Verification Plan

Version 00.03

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Abstract: This document describes strategy and plan of the verification and validation activities in the project openETCS. As the goals of the project include the selection, adaption and construction of methods and tools for a FLOSS development in addition to performing actual development steps, differing from the plan for a full development project, the plan covers also activities evaluating the suitability of methods and tools, and it makes provisions for incorporation of V&V of partial developments which are actually done.

The overall strategy is to support the design process as specified in D2.3 and its partial instantiations within openETCS. In accordance with the project approach, V&V shall be done in a FLOSS style, and it has to suit a model-based development. A further main consideration shall be to strive for conformance with the requirements of the standards (EN 50128 and further). This means that the contribution of all activities to a complete verification and validation shall be defined and assessed.

The plan details how to perform verification & validation for a complete development which follows the process sketch from D2.3, so that the result conforms to the requirements of the standards for a SIL 4 development. This includes a definition of activities, the documentation to be produced, the organisation structure, roles, a selection of methods and tools, a format for describing design artifacts subject to V&V, and a feedback format for the findings during V&V.

As D2.3 gives only a rough description of the development steps and not yet a complete list of design artifacts, nor one of methods applied and formats to be used, this first version of the V&V plan will also lack detail which will be added in later revisions as these informations become more concrete.

Besides the usual purpose of verification & validation activities, namely evaluating and proving the suitability of design artifacts, V&V in openETCS will also generate information on the suitability of the methods and tools employed. For that purpose, a format for describing methods and tools to be used in V&V and one for summarizing the findings about the suitability are defined.

The plan also contains partial instantiations of V&V which match partial developments that are realised within openETCS.

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1 Introduction

1.1 Purpose

The purpose of this document is to define the verification & validation activities in the project openETCS.

This document describes strategy and plan of the verification and validation activities in the project openETCS. As the goals of the project include the selection, adaption and construction of methods and tools for a FLOSS development in addition to performing actual development steps, differing from the plan for a full development project, the plan covers also activities evaluating the suitability of methods and tools, and it makes provisions for incorporation of V&V of partial developments which are actually done.

WP4-T1-G: A useful plan for WP 4, that is, one that defines a way to achieve the goals of WP 4:

WP4-G1: Identify and demonstrate methods and tools to handle the V&V of a FLOSS development of the EVC software

WP4-G2: Perform as much of V&V on the DAS2Vs produced in the project as possible

Detailed Goals and Means

WP4-T1-G1: The plan shall give an overview of and a structure to the things required from V&V for an openETCS (FLOSS-) development.

WP4-T1-M1: Identifies all (most) of the activities which have to be made for a full development according to the standards, in a form relevant to the approach of openETCS (FLOSS, participants). This may include alternatives.

WP4-T1-G2: The plan shall provide a framework into which the V&V activities which will be performed within the project do fit.

WP4-T1-M2-1: Design formats for collecting information about DAS2Vs (V&V tasks), about the results of V&V activities, about activities of V&V method and tool development, about the results of evaluations of V&V methods and tools. Sketch how all of the information is to be gathered and finally incorporated into the final V&V report (D4.4).

WP4-T1-M2-2: Identify potential variants of partial implementations of V&V processes which are likely going to be performed within the project. These may be (?should be?) related to design activities within the project which produce DAS2Vs.

WP4-T1-G3: The plan shall delineate means for V&V within openETCS

WP4-T1-M3-1: A partial V&V process (see WP4-T1-M2 above) consists of a set of related DASVs and V&V steps to be applied to them. A V&V step is described by input and output (result, purpose) with V&V methods and means.

WP4-T1-M3-2: The plan will prepare the selection of adequate methods and means (tools) by providing evaluation criteria and incorporating available evaluation results.

WP4-T1-M3-2-1: Definition of an evaluation format for tools and methods.

WP4-T1-G4: The plan shall incorporate currently available information on openETCS development process and means and be amendable to future changes and additions.

WP4-T1-M4-1: Use D2.3 in instantiating the general requirements laid down in the standards.

WP4-T1-M4-2: Use D2.1 for tools.

WP4-T1-M4-3: Identify open points and include delineations for things which are useful for a complete V&V but not yet planned or detailed by project activities already performed.

This document describes which verification and validation activities are needed for a full FLOSS development of the EVC software. It describes how the work performed within the project openETCS is to be organised to contribute to such a task, and how to demonstrate that it can be realised.

The document is only valid in conjunction with the Quality Assurance plan [1104G13-QA-plan]. It is supplemented by the safety plan, which focuses on the safety aspect. Verification and validation play an important role in the safety case. This document identifies the V&V activities which do contribute and refers to the safety plan for further details on the additional requirements to be met and a precise statement of what has to be established.

1.2 Document Structure

This document comprises both verification and validation plan, as these activities share some of their methods and tools, and in some case are applied to the same design artifacts. Nevertheless, these activities are intended to be and remain independent.

There are three main issues which make this plan different from an ordinary V&V plan for a software to develop. First, openETCS is not only concerned with the software part of the EVC. As part of the activities, a semi-formal model for SS 026 is to be developed and to be verified. As the SS 026 covers parts of the ETCS system beyond the software, also process steps on the system (not just software) level are to be performed. And in particular the design does not start with a clearly defined set of requirements on the software.

As a second point, openETCS will not only do development, but shall also be concerned with processes, methods and tools with the goal of being able to propose a complete SIL 4 compliant approach. As part of this, it has to be defined how to handle verification and validation. This is done in the sections addressing a “full development”. Due to the limited resources of the project, actually performing such a full development is out of the project’s scope. Instead, only some functions will be implemented, and only partial lines of development will be realised. V&V related to these activities is to be planned in the specific sections dedicated to “openETCS”.

1.3 Plan for Completing this Document

Terminology

DAS2V: *Design Artifact Subject to Verification or Validation*

G: *Goal*

M: *Means*

F: *Finding/Result/Action*

Detailed Goals and Means

WP4-T1-G1: *The plan shall give an overview of and a structure to the things required from V&V for an openETCS (FLOSS-) development.*

WP4-T1-M1: *Identify all (most) of the activities which have to be made for a full development according to the standards, in a form relevant to the approach of openETCS (FLOSS, participants). This may include alternatives.*

WP4-T1-G2: *The plan shall provide a framework into which the V&V activities which will be performed within the project do fit.*

WP4-T1-M2-1: *Design formats for collecting information about DAS2Vs (V&V tasks), about the results of V&V activities, about activities of V&V method and tool development, about the results of evaluations of V&V methods and tools. Sketch how all of the information is to be gathered and finally incorporated into the final V&V report (D4.4).*

WP4-T1-M2-2: *Identify potential variants of partial implementations of V&V processes which are likely going to be performed within the project. These may be (?should be?) related to design activities within the project which produce DAS2Vs.*

WP4-T1-G3: *The plan shall delineate means for V&V within openETCS*

WP4-T1-M3-1: *A partial V&V process (see WP4-T1-M2 above) consists of a set of related DASVs and V&V steps to be applied to them. A V&V step is described by input and output (result, purpose) with V&V methods and means.*

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WP4-T1-M4-1: *Use D2.3 in instantiating the general requirements laid down in the standards.*

WP4-T1-M4-2: *Use D2.1 for tools.*

WP4-T1-M4-3: *Identify open points and include delineations for things which are useful for a complete V&V but not yet planned or detailed by project activities already performed.*

Concrete First Steps (in SCRUM terminology: the backlog)

%%To Be Defined%% outdated—update tbd

WP4-T1-S1: *Assess the input material*

WP4-T1-S1-1: *Assess sketch of the V&V plan (partly done)*

WP4-T1-F1-1-1: *The current format is .doc*

WP4-T1-F1-1-2: *The plan currently lists mainly the requirements on the plan and does not yet detail much of the plan itself.*

WP4-T1-F1-1-3:

WP4-T1-S1-2: *Assess D2.3 “Process Definition” with definition of DAS2Vs and V&V steps*

WP4-T1-F1-2-1: *DAS2Vs and verification & validation steps defined on a high level*

WP4-T1-S1-3: *Assess D2.9 “Requirements for Verification & Validation”*

WP4-T1-F1-3-1: *very high-level, requirements included in the appendix for reference in further completion in relevant for future steps*

WP4-T1-S1-4: *Assess D2.1 (“Report on Existing Methodologies”)*

WP4-T1-F1-4-1: *Seems very sketchy*

WP4-T1-S1-5: *Assess development and V&V activities planned or already on the way for taking them into account in the V&V plan*

WP4-T1-S1-5-1: *Ask a lot of people (or the right people)*

WP4-T1-S1-5-1-1: *Design a query email (to be backed up by phone or personal inquiries)*

WP4-T1-S2: *Organize the writing*

WP4-T1-S2-1: *Make a detailed work plan*

WP4-T1-S2-1-1: *Transform the sketch to .tex*

WP4-T1-S2-1-2: *Revise the structure according to what is expected to be done - accommodating the info on the process (D2.3 -WP4-T1-S1-2) and on ongoing activities (WP4-T1-S1-5).*

WP4-T1-S2-1-3: *References to the requirements (D2.9 - WP4-T1-S1-3) are to be included*

WP4-T1-S2-1-4: *Tools and methods*

WP4-T1-S2-1-4-1: *Format for evaluation (formulate evaluation criteria, D4.1a)*

WP4-T1-S2-1-5: *Result collection*

WP4-T1-S2-1-5-1: *Sketch all the formats (purpose)*

WP4-T1-S2-1-5-2: *Sketch the process of information collection (T4.2 and T4.3 will have to do that)*

WP4-T1-S2-1-6: *Include section on V&V plan revision*

WP4-T1-S2-2: *Find contributors*

WP4-T1-S2-3: *Distribute the work*

WP4-T1-S3: *Do the work*

1.4 Background Information

%%Further Info, perhaps put the project context here %%

1.4.1 Definitions

Verification

Verification is an activity which has to be performed at each step of the design. It has to be verified that the design step achieved its goals. This consists at least of two parts:

- that the artifacts produced in the step are of the right type and contain all the information they should. E.g., that the SSRS identifies all components addressed in SS 026, specifies their interfaces in sufficient detail and has allocated the functions to the components (this should just serve an example and is based on a guess what the SSRS should do)
- that the artifact correctly implements the input requirements of the design step. These typically include the main output artifacts of the previous step. “Correctly implements” includes requirement coverage (tracing). This can and should be supported by some tools. Adequacy of such tools depends on things like format compatibility, degree of automation, functionality (e.g., ability to handle m-to-n relations). Depending on the design step (and the nature of the artifacts) different forms of verification will complement requirement coverage, with different levels of support. The step from SS 026 to the SSRS will mainly consist of manual activities besides things like coverage checks. Verifying a formal (executable) model against the SSRS can be supported by animation or simulation to e.g. execute test cases which have been designed to check compliance with the SSRS. Even formal proof tools may be employed to check or establish properties. Model-to-code steps offer far more options (and needs) for tool support. And tools or tool sets for unit test will support dynamic testing for requirement or code coverage. This may include test generation, test execution with report generation, test result evaluation and so on. Also, code generator verification (or qualification) may play a role, here. Integration steps mandate still other testing (or verification) techniques.

Summarizing, one may say that verification subsumes highly diverse activities, and may be realized in very many different forms.

Validation

Validation is name for the activity by which the compliance of the end result with the initial requirements is shown. In the case of openETCS, this means that the demonstrator (or parts of it) are checked against the SS 026 or one of its close descendants (i.e., SSRS), taking also further sources of requirements from operational scenarios and TSIs into account. This will consist of testing the equipment according to a test plan derived from the requirements and detailed into concrete test cases at some later stage. Tool support for validation will thus mainly concern test execution and evaluation, perhaps supplemented by test derivation or test management. Ambitious techniques like formal proof are most likely not applicable here.

Thus, the tool support for validation will not differ substantially from that for similar verification activities.

One might also consider “early” validation activities, e.g. “validating” an executable model against requirements from the SS 026. These are not mandated by the standards and can per se not replace verification of design steps. They may nevertheless be worthwhile as means for early defect detection.

Further (mostly complementary) information on V&V can be found in the report on the CEN-ELEC standards (D2.2).

2 Document Evolution

The verification and validation plan shall be revised in the course of the project as the design progresses and gets detailed and experiences with verification and validation are made. This is in accordance with the EN 50128, where it is required that the plan shall be maintained throughout the development cycle.

V01, T0+13: First version of the plan

V02, T0+17: First revision, based on the 1st V&V interim reports on applicability of the V&V approach to model and implementation/code (D4.2.1, D4.2.2)

V03, T0+25: Second revision, based on the internal reports on the applicability of the V&V approach to prototypes of design models and code

V04, T0+36: Final version as part of the final V&V report (D4.4)

3 Verification & Validation in the Design Process

Name the design stages and associated V&V steps, both for the ideal development (openETCS vision) and project realisation (where we end with a demonstrator).

D2.3 defines the openETCS process on an abstract level. It already defines the main steps. A slightly more detailed picture than the one given in D2.3 is given in Fig. 1.

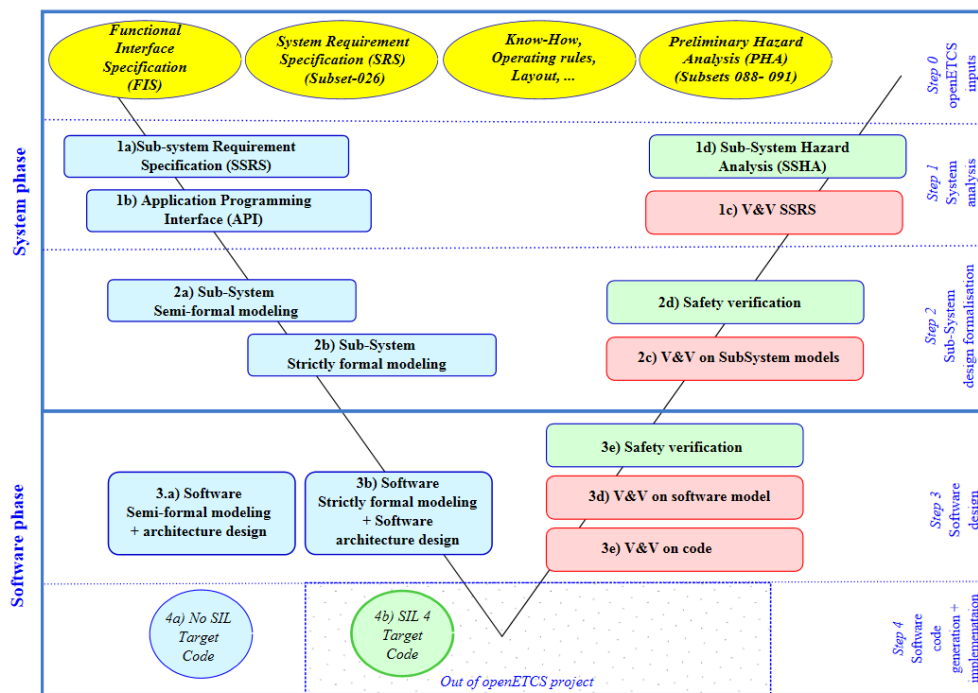


Figure 1. openETCS Process (rough view)

The figure needs to be detailed to include all the main design steps. E.g., the integration activities are subsumed within “3e) V&V on code”. For instance, the integration into the demonstrator should be made visible. In the end, the figure shall define merely the “full” development, this will be of more help than “openETCS implementation” of it.

4 Verification & Validation Strategy

Contributors to this chapter:

DLR Overall coherence, Safety interface

All4Tec aspects of model-based development, FLOSS, safety. Mainly in Sec. 4.1 (Full Development).

SQS ¿Contributions to all sections?

TUBS Safety interface

DB, SNCF, NS Operator role (scenarios, validation goals)

The overall strategy is to support the design process as specified in D2.3 and its partial instantiations within openETCS. In accordance with the project approach, V&V shall be done in a FLOSS style, and it has to suit a model-based development. A further main consideration shall be to strive for conformance with the requirements of the standards (EN 50128 and further). This means that the contribution of all activities to a complete verification and validation shall be defined.

4.1 Verification & Validation Strategy for a Full Development

Here, the ideal shall be described: What we would like to do in openETCS but cannot, because we do not know the right methods and tools yet

4.1.1 Verification Strategy for a Full Development

Define the strategy for verifying a full development of the EVC software from the requirements source (ss 026+TSIs+...). This ends with the verification of the software/hardware integration. The API is currently the best description of the interface

4.1.2 Validation Strategy for a Full Development

Classical validation starts after SW/HW integration. Sketch how this should look like for the openETCS architecture approach (with SSRS and API). Ideal would be a description of how a full openETCS EVC software could be taken up by some manufacturer and brought to life in a product (validation aspect only, of course). Validation will use tests covering operational scenarios. Not-so-classical validation can start earlier when executable models become available. If a model can be animated to run an operational scenario (perhaps with some additional environment/rest-of-system modeling), design defects may get unveiled before the real validation.

4.2 Verification & Validation Strategy for openETCS

The project will only perform part of the development, and thus also only a part of the V&V activities. These need to be defined and planned, of course.

5 Verification & Validation Plan for a Full Development

Contributors to this chapter:

DLR Overall coherence, revise structure of the Verification Report

All4Tec Role of model-based testing, ¿hopefully more?

SQS tbd

CEA Tools and methods Sec. 5.3)

U Bremen Tools and methods (model based testing, bounded model checking Sec. 5.3),
V&V process steps

Fraunhofer Tools and methods Sec. 5.3)

TUBS Safety Interface, general tool list

TWT, URO Tools and methods Sec. 5.3)

DB, SNCF, NS operator role (end user scenarios, validation requirements and contribution)

Institut Telecom Methods and Tools Sec. 5.3)

%%detail%%

Instantiate the generic Verification & Validation plan from the standard (and the draft) to openETCS. That is, provide the requirements, define the design steps, identify verification & validation activities to be performed and documents to be produced.

The plan details how to perform verification & validation for a complete development which follows the process sketch from D2.3, so that the result conforms to the requirements of the standards for a SIL 4 development. This includes a definition of activities, the documentation to be produced, the organisation structure, roles, a selection of methods and tools, a format for describing design artifacts subject to V&V, and a feedback format for the findings during V&V.

As D2.3 gives only a rough description of the development steps and not yet a complete list of design artifacts, nor one of methods applied and formats to be used, this first version of the V&V plan will also lack detail which will be added in later revisions as these informations become more concrete.

Besides the usual purpose of verification & validation activities, namely evaluating and proving the suitability of design artifacts, V&V in openETCS will also generate information on the suitability of the methods and tools employed. For that purpose, a format for describing methods and tools to be used in V&V and one for summarizing the findings about the suitability are defined.

The plan also contains partial instantiations of V&V which match partial developments that are realised within openETCS.

5.1 Verification & Validation Plan Overview

%%A list of all steps, with input and output from Jagusch, adapted to D2.3 steps%%

A short overview of the activities (Verification or Validation) which happen at the respective development steps, to be detailed in the subsequent sections. The numbering (e.g. 2e) refers to Fig. 1.

SSRS—Verification (1c): verification that the SSRS the requirements consistently extends the requirements base.

SSRS—Validation (1c): Deriving a sub-system test specification

SFM—Verification (2c): Verification that the model formalises the requirements

SFM—Validation (2c): Detailing the test specification, perhaps validating the model (e.g. via animation)

SW-SFM—Verification (3d): Verifying the SW-HW architecture definition (should be somewhere) and the software model

SW-SFM—Validation (3d): Perhaps validation of the software model

SW-FFM—Verification (3d): verification, employing also formal methods/tools

SW-FFM—Validation (3d): validation, may e.g. employ model checkers

Code—Verification (3e): verification depends on the code generation method (manual, generated, generated with validated tool), unit test requirements have to be met, afterwards code integration tests

Code—Validation (3e): no specific activities foreseen

The following steps need some coherent concept. A viable solution might look simpler / different.

EVC Software—Verification (tbd): Perform software system verification

EVC Software—Validation (tbd): Validation against user requirements/scenarios

SW/HW integration (tbd): ¿Use the API?

Final Validation (tbd): User requirements and scenarios (based on sub-system test specification)

5.2 Requirements Base

The requirements on the EVC software origin in the SS-026 and TSI specifications.

%%detail this, add references%%

5.3 Verification & Validation Methods and Tools

The project shall select / develop / describe a chain of methods and tools for doing verification & validation in a full development. Some will be suitable for both, verification & validation, tasks. Each proposal shall be labeled accordingly.

In common language, the notion “*formal*” is often used in a broad sense, meaning everything that can be described by rules, even if they are rather vague. Contrary to that, we use “*formal*” in the narrow sense of EN-50128 [1, Section D.28], meaning strictly mathematical techniques and methods. Since the Aerospace Standard DO-178C [2] follows a similar understanding, but gives more elaborate explanation in its supplementary document devoted to formal methods [3], our presentation closely follows the terminology of the latter.

Formal methods are mathematically based techniques for the specification, development, and verification of software aspects of digital systems. The mathematical basis of formal methods consists of formal logic, discrete mathematics, and computer-readable languages. The use of formal methods is motivated by the expectation that, as in other engineering disciplines, performing appropriate mathematical analyses can contribute to establishing the correctness and robustness of a design.

[3, Section 1.0, p.1]

5.3.1 Characterisation of Formal Methods

Based on rigorous mathematical notions, formal methods may be used to describe software systems’ requirements in an unambiguous way, thus supporting precise communication between engineers. Formally specified requirements can be checked for consistency and completeness by appropriate tools; also, compliance between different representation levels of specification can be verified. Formal methods allow one to check software properties like:

- Freedom from exceptions
- Freedom from deadlock
- Non-interference between different levels of criticality
- Worst case resource usage (execution time, stack, ...)
- Correct synchronous or asynchronous behaviour, including absence of unintended behaviour

In order to subsume this variety of applications under a single paradigm, the DO-178C considers a formal method to consist in applying a formal *analysis* to a formal *model*. Both analysis and model differs dependent on the particular method. For most methods, the model is just identical to the source code; however, it may also be e.g. a tool-internally generated abstract state space (used in the Abstract Interpretation method, cf. Section 5.3.2.1 below). For most methods, analysis tools need human advice; however, they may also be fully automatic (e.g. for Model Checking, cf. 5.3.2.3).

5.3.2 Formal Analysis Methods

In this section we present the three most common methods for formal analysis. The foundation of these analysis methods are well understood and they have been applied to many practical problems.

5.3.2.1 Abstract Interpretation

The abstract interpretation method [4] builds at every point of a given program a conservative¹ representation of the set of possible states that may occur there during any execution run. It determines particular effects of the program relevant for the properties to be analysed, but does not actually execute it. This allows one to statically determine dynamic properties of infinite-state programs. The main application is to check the absence of runtime errors, like e.g. dereferencing of null-pointers, zero-divides, and out-of-bound array accesses. While conventional ad-hoc static analysis tools such as PCLint or QAC++ are well-tailored for quick, but incomplete analyses, abstract-interpretation based tools require more computation time, but guarantee that *all* runtime errors are detected, due to the conservative approximation of state sets. Human intervention is required to improve the approximation accuracy w.r.t. those program points where *false alarms* have to be removed.

5.3.2.2 Deductive Verification

Deductive methods [5] [6] perform mathematical proofs to establish formally specified properties of a given program, thus providing rigorous evidence. Tools usually extract proof obligations from program code and property specifications and attempt to prove them, automated or interactively. Even automated prover tools usually need human assistance, e.g. by providing loop invariants.

5.3.2.3 Model Checking

Model checking [7] explores all possible behaviours of a program to determine whether a specified property is satisfied. It is applicable only to programs with reasonable small state spaces; the specifications are usually about temporal properties. If a property is unsatisfied, a counter-example can be generated automatically, showing a use case leading to property violation.

5.3.3 Verification with Formal Methods

In the railway domain, the standard EN 50128 highly recommends use of formal methods in requirements specification ([1, Table A.2]), software architecture (A.3), software design and implementation (A.4), verification and testing (A.5), data preparation (A.11), and modelling (A.17) for Safety Integrity Level SIL 3 and above. However, functional/black-box testing is still mandatory in verification; this constraint may be considered as discouraging from the use of formal methods.

Until recently, the situation was quite similar in the aerospace domain. J. Joyce, a member of the RTCA standardisation committee SC-205, described Airbus' problems in certifying their "unit-proof for unit-test" approach:

"Formal methods were used for certification credit in development of the A380, but apparently it was not a trivial matter to persuade certification authorities that this was

¹i.e. guaranteeing soundness

acceptable even with the reference to formal methods in DO-178B as an alternative method.”

Such experiences eventually caused the more detailed treatment of formal method issues in the revision C of DO-178 that appeared in late 2011. The DO-178C considers formal methods as special cases of reviews and analyses; thus incorporating them without major structural changes of the software development recommendations. For an employed formal method, the standard requires to justify its unambiguity, its soundness², and any additional assumptions³ needed by the method. The DO-178C admits formal property verification on object code as well as on source code, the latter additionally needing evidence about property preservation of the source-to-object code compiler. However, *“functional tests executed in target hardware are always required to ensure that the software in the target computer will satisfy the high-level requirements”* [3, FM.12.3.5].

As a consequence of subsuming formal methods under general reviews and analyses, no deviating special rules to qualify tools are necessary: *“Any tool that supports the formal analysis should be assessed under the tool qualification guidance required by DO-178C and qualified where necessary.”* [3, FM.1.6.2]. Of course, for the railway domain, the rules of EN 50128 for supporting software tools and languages must be taken into account [1, Section 6.7].

During the last 15 years, formal methods have grown out of academic playgrounds and become practically relevant in several applications domains. Below, we sketch a few different tools, also to indicate the variety of issues formal methods can be applied for. Many of the tools mentioned below provide formal verification for programs written in C. There is currently insufficient support for the programming language C++, which is predominantly used in Thales’ RBC product. A list of free software tools for formal verification can be found at [9]. The list is not meant to be complete. It is structured by tool purpose, and each tool is briefly introduced.

5.3.3.1 The Frama-C Source Code Analysis Suite

Frama-C is a suite of tools from CEA-LIST⁴, dedicated to the analysis of the source code of software written in C. *Frama-C* gathers several static analysis techniques in a single collaborative framework. Its *WP* plug-in implements a weakest precondition calculus for *ACSL*⁵ annotations through C programs. For each code annotation, this technique generates a bundle of proof obligations, i.e. mathematical first-order logic formulas that are submitted to automated or interactive theorem provers.

5.3.3.2 Microsoft’s Verifier for Concurrent C (VCC)

VCC is a tool from Microsoft Research to prove correctness of annotated concurrent C programs. It was mainly developed to verify Microsoft’s *Hyper-V* hypervisor. It supports an own annotation language providing e.g. contracts, pre- and postconditions, and type invariants. It uses the Boogie tool to generate proof obligations, and the automatic prover Z3 to prove them. If an obligation is violated, the Model Viewer tool can generate a counter-example use case. VCC is available for non-commercial use from [10].

5.3.3.3 The Proof Assistants Coq and Isabelle

²i.e., that the method never asserts a property to be true when it actually may be not true

³e.g. data range limits

⁴Commissariat à l’énergie atomique et aux énergies alternatives

⁵ANSI/ISO C SPECIFICATION LANGUAGE, a notation to express program properties written in C

Coq is an interactive theorem prover and proof checker, developed at INRIA, and based on higher-order logic and the natural deduction calculus. It provides the formal language *Gallina*, in which mathematical definitions can be expressed as well as executable algorithms and theorems. The supporting tool for tactics-based semi-interactive development of proofs is available from [11].

Isabelle, maintained at Cambridge University, and its predecessor *HOL*⁶, are similar tactic-oriented interactive theorem provers. *Isabelle* is available from [12]. While *Isabelle* is not yet supported in the Frama-C environment, *Coq* is.

5.3.3.4 The Model Checker NuSMV

*SMV*⁷ has been the first model checker based on binary decision diagrams. *NuSMV* is a reimplementation by the Fondazione Bruno Kessler that is in addition capable of performing SAT-based model-checking. It supports both Linear Temporal Logic (LTL) and Computation Tree Logic (CTL). *NuSMV*'s source code is available under an LGPL license from [13].

5.3.3.5 Formal Verification of Real-Time Aspects based on Timed Automata

Verifying system properties involving time is difficult with traditional model checking methods. Commonly used *temporal logics*, such as LTL or CTL catch discrete and qualitative aspects of time and allow to formulate properties such as⁸

- X** At the next point in time a property holds.
- F** At some future point in time a property holds.
- G** Always/generally (now and at any future point in time) a property holds.
- U** A property *p* holds until a property *q* holds.

While it is possible to state properties that must be satisfied at individual (discrete) points in time, continuous and quantitative aspects of time as in the safety requirement

“The delay between receiving an emergency message and the issuing of a brake order is less than 1 second.”

are a real challenge. The problem does not stem from discrete vs. continuous time, as any physical realisation of a real-time system is inherently discretised by its clock. Instead, an operator for expressing arbitrary temporal quantities or differences is missing. Thus, for LTL and a clock of 1 kHz, it would be required to use the operator **X** 1000 times. This notation is rather unhandy, as it enforces to express a functional property relative to a particular system.

This lack of expressivity is not merely a matter of notation, i.e., LTL or CTL, but also of the underlying semantics. Before introducing a better suited logic we will first consider a formalism that serves as this logic's semantics – namely *timed automata*.

⁶Higher Order Logic

⁷Symbolic Model Verifier

⁸The prefixes are the corresponding linear time operators.

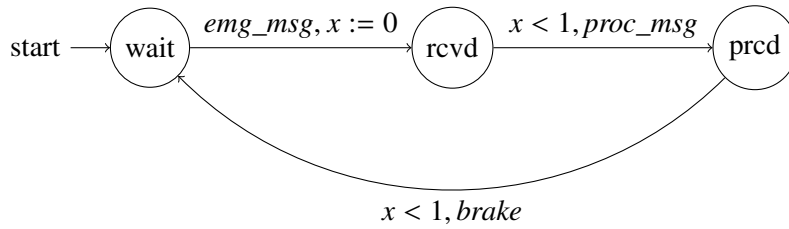


Figure 2. First (faulty) version of a timed automaton for processing emergency messages

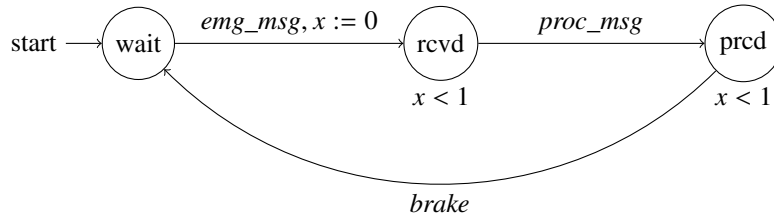


Figure 3. Corrected version of the timed automaton for processing emergency messages

Timed Automata

Timed automata [14] are essentially finite automata extended with a finite set of clocks that all proceed at the same rate. Clocks may be individually reset to zero. Clock variables can be part of constraint expressions that may be used as transition guards. A transition can only be taken if its guard is fulfilled. Similarly, it is possible to specify an invariant for a state that must be satisfied when the automaton is in this state. Thus, we can enforce time constraints for the runs of the automaton.

An Example

The timed automaton in Figure 2 depicts an automaton representing an over-simplified version of an OBU subsystem processing emergency messages. It has three states, one clock x and three actions, *emg_msg* (reception of an emergency message), *proc_msg* (processing the message, e.g. raising an alarm) and *brake* (issuing the brake order). Upon receiving an emergency message the clock x is reset. The *proc_msg*-transition is guarded by the clock constraint $x < 1$ preventing the transition to be taken if $x \geq 1$. The same holds for the *brake*-transition.

One might think that the automaton from Figure 2 thus fulfills the safety requirement stated above. Due to the operational semantics of timed automata this is not true: a timed automaton in a given state can either take a transition or wait for an arbitrary amount of time. Thus, if automaton waits in state *rcvd* and x exceeds one second, the system will deadlock as the next transition is guarded by the constraint $x < 1$. A run of the automaton that could serve as counterexample is, e.g.

$$(\text{wait}, 0) \rightarrow (\text{wait}, 0.5) \rightarrow (\text{rcvd}, 0.5) \rightarrow (\text{rcvd}, 2) \rightarrow \text{DEADLOCK}$$

A solution to this problem is to force the automaton to proceed by placing *progress* constraints on the states. This has been done in Figure 3. The transition guards have been omitted as they are not necessary anymore. Now the safety property “The delay between receiving an emergency message and the issuing of a brake order is less than 1 second.” is fulfilled.

UPPAAL

UPPAAL is a tool for modelling and verifying timed automata developed by the universities of Uppsala and Aalborg [15]. This toolkit is under constant development and comes with an academic as well as a commercial licence. Moreover, there is a comparably large body of literature featuring UPPAAL, providing introductory and industrial examples.

UPPAAL extends timed automata with synchronisation enabling concurrent, communicating automata representing different parts of a system. In addition, variables other than clocks are supported making the modelling language more powerful. The logic used for expressing real-time properties is a subset of TCTL (Timed Computation Tree Logic). Nesting of temporal operators is not supported leading to a restriction in expressiveness.

From SysML/UML to Timed Automata

Timed automata and statecharts in SysML/UML are both based on the concept of finite automata. Thus, it is reasonable to extract timed automata from existing statecharts which is addressed in the literature [16, 17, 18]. In this way, safety properties – formalised as TCTL formulae – can be verified in an automated fashion for a given statechart.

To be continued

5.3.4 Simulation-based Approaches

5.3.4.1 Simulation with SystemC

5.4 Verification for a Full Development

for each of the verification steps identified in the plan overview, the following has to be instantiated:

5.4.1 DASV Verification

5.4.1.1 Task

5.4.1.2 Documents to Be Produced

5.4.1.3 Phase Specific Activities

5.4.1.4 Techniques and Measures

Here the verification plan begins

5.4.2 SSRS Verification (1c)

5.4.2.1 Task

The SSRS (sub-system requirement specification) outlines the subsystem which is going to be modeled within the project. The SSRS describes the architecture of the subsystem (functions and their I/O) and the requirements allocated to these functions. If necessary, the requirements are rewritten in order to address the I/O and to correspond to the allocation. It also provides the

classification into vital and non vital requirements and data streams. The architecture part is described in a semi-formal language, and the requirements are described in natural language.

The SSRS is to be viewed as a supplement to the SS-026 and the TSIs and is not intended to replace them. The verification has to check that a complete and consistent set of functionalities have been identified and that the architecture is adequate.

%%Verify hazard analysis too?%%

5.4.2.2 Documents to Be Produced

SSRS verification report.

5.4.2.3 Phase Specific Activities

5.4.2.4 Techniques and Measures

Due to the informal nature of the SSRS, mainly manual techniques are to be applied.

¿Review?

5.4.3 SFM Verification (2c)

5.4.3.1 Task

5.4.3.2 Documents to Be Produced

5.4.3.3 Phase Specific Activities

5.4.3.4 Techniques and Measures

%%further verification phases%%

5.5 Structure of the Verification Report

%%To Be Defined%% the following is a draft which is to be adapted to the *The verification and validation plan covers the following central topics:*

Header *containing all information to identify, this report, the authors, the approbation and reviewing entities.*

Executive Summary *giving an overview of the major elements from all sections.*

Problem Statement *describing the challenges to be answered by Verification & Validation as well as the decisions to be taken based on the V&V results as well as how to cope with potentially faulty output. It further describes the accreditation scope based on the risk assessment done on V&V-level.*

V&V Requirements Traceability Matrix *links every V&V artifact back to the requirements to measure e.g. test coverage and to directly link V&V results to the requirements.*

Acceptability Criteria, *describing the criteria for acceptance of the artifact into the Verification & Validation process e.g. as the direct translation of the requirements into metrics to measure success, are used e.g. for burndown charts within the process.*

Assumptions *that are identified during the design of the verification and validation strategy and how these assumptions have an impact on the verdict by listing capabilities and limitations.*

Risks and Impacts *that come across the execution of V&V tasks together with the impacts foreseen.*

V&V Design *states how the V&V process builds up including data preparation, execution and evaluation.*

V&V Methodologies *giving a step-by-step walkthrough of all possible V&V activities including the assumptions, and verdict-relevant limitations and criteria for, e.g., model verification, model-to-code verification, unit testing, integration testing and final validation (according to the standard, this involves running the software on the target hardware).*

V&V Issues *describing unsolved V&V issues and their impact on the affected proof or verdict.*

Peer Reviews *going into details on how the community can take part and how official bodies and partners are integrated into the development and review process.*

Test Plan Definition *going into the details of testing by describing among other things:*

Title *as a unique identifier to the test plan.*

Description *of the test and the test-item giving information about version and revision.*

Features *to be tested and not to be tested in combination are listed together with information background.*

Entry Criteria *which have to be met by the EVC before a test can be started, e.g. that the EVC has to be in level 3 limited supervision with the order to switch to level 2.*

Suspension criteria and resumption requirements *are the central key to a smooth automation of the tests covering topics like when exiting this test before step 10, which entry criteria does it comply to or which resumption sequence has to be executed to continue testing.*

Walkthrough *covering a step-by-step approach of the test plan.*

Environmental requirements *going into the details of what is needed concerning the test environment, e.g. tools, adapter, data preparation.*

Discrepancy Reports *identifying the defects.*

Key Participants *describing the assignment and task for each role involved.*

Accreditation of Participants *describing who was accredited to which role during the Verification & Validation phase.*

V&V Participants *listing the partners participating in V&V activities,*

Other participants *including other interest groups such as reviewer by affiliate partners⁹.*

Timeline *giving the timeline for the baselines as input to the V&V process and identifying when each artifact should be created.*

5.6 Validation for a Full Development

for each of the validation steps identified in the plan overview, the following has to be instantiated:

⁹affiliate partners are non-funded companies who signed the project cooperation agreement and with it get read access to the repositories starting from incubation phase to contribute e.g. by reviewing

5.6.1 DASV Validation

5.6.1.1 Task

5.6.1.2 Documents to Be Produced

5.6.1.3 Phase Specific Activities

5.6.1.4 Techniques and Measures

5.6.2 SFM Validation (3d)

5.6.2.1 Task

The formalisation of the requirements in form of a semi-formal model enables a systematic check of the completeness and consistency of the system test specification.

The model itself can perhaps be animated (depending on the concrete form which is not yet fixed). This offers the chance to an early (preliminary) validation of the design.

5.6.2.2 Documents to Be Produced

1. Revised System Test Specification
2. SFM validation report

5.6.2.3 Phase Specific Activities

%%To Be Defined%%

5.6.2.4 Techniques and Measures

%%To Be Defined%%

5.6.3 Final Validation (tbd)

5.6.3.1 Task

The final validation shall ascertain that the end result of the development—the EVC software in its specified environment—behaves as required.

5.6.3.2 Documents to Be Produced

1. System Test Definition (based on System Test Specification)
2. System Validation Report

5.6.3.3 Phase Specific Activities

Testing the software against the user requirements.

5.6.3.4 Techniques and Measures

¿Testing in a validated testbed (including API animation/simulation)?

5.7 Implementation of Verification & Validation

The verification & validation has to be performed in cooperation with WP 3, which produces DAS2Vs (models and code), and with WP 7, where methods and tools are defined and developed.

To exchange information with WP 3, formats are needed for collecting information about DAS2Vs (V&V tasks) and for giving back information about the results of V&V activities. Similarly, with WP 7 communication shall use formats to describe V&V methods and tools (input from WP 7) and the results of evaluations of V&V methods and tools.

%%Formats, activity organisation%%

6 Verification & Validation Plan for openETCS

Contributions to this chapter

DLR overall coherence, lab test description

U Bremen RT Tester application, ¿more?

Siemens Application story (to be detailed)

SQS tbd

CEA Application story (to be detailed)

All4Tec Application story (to be detailed)

DB, SNCF, NS Validation requirements

%%Describe how to proceed in openETCS to achieve the most. Include all partial V&V instantiations with their re

- *verification & validation for partial developments*
- *evaluation*
- *demonstration story of capabilities*

6.1 Verification Plan for openETCS

6.2 Validation Plan for openETCS

Appendix A: Requirements on Verification & Validation

%%Explain the requirement chapter.%%

- *Requirements from D2.9.*
- *Take the lists from the draft from 121207, retain the structure (at least preliminarily).*

A.1 Requirements on Verification & Validation from D2.9

%%Adapt the intro text%%

The already provided requirements require a safety plan compliant to the CENELEC EN 50126, 50128 and 50129. This pulls a number of requirements on V&V, including Verification and Validation plans. On the topic of compliance to EN 50128, one shall also refer to the D2.2 document.

R-WP2/D2.6-02-061 A Verification plan shall be issued and complied with.

R-WP2/D2.6-02-061.01 The verification plan shall provide a method to demonstrate the requirements covering all the development artifacts.

R-WP2/D2.6-02-061.02 The verification plan shall state all verification activities required for each of these development artifacts.

R-WP2/D2.6-02-062 A Validation Plan shall be issued and complied with.

R-WP2/D2.6-02-062.01 The validation plan shall provide a method to validate all functional and safety requirements over all development artifacts.

R-WP2/D2.6-02-062.02 The validation plan shall state all validation activities required for each of these development artifacts.

R-WP2/D2.6-01-021 The test plan shall comply the mandatory documents of the SUBSET-076, restricted to the scope of the OpenETCS project.

Justification. It will possibly be difficult to model all the tests in the course of the project, but the test plan should at least be complete.

R-WP2/D2.6-02-063 Each design artifact needs a reference artifact which it implements (e.g. code to detailed model, SFM to SSRS model. . .)

R-WP2/D2.6-02-063.01 The implementation between them relation shall be specified in detail.

e.g. for state machine and a higher level state machine mapping of interfaces, states and transition is required. This includes additional invariants, input assumptions and further restrictions. This information is the basis for verification activities.

R-WP2/D2.6-02-063.02 The design of the artifacts shall be made such to allow verifiability as far as possible.

R-WP2/D2.6-02-064 The findings from the verification shall be traced, and will be adequately addressed (taken into consideration, or postponed or discarded with a justification).

A.2 General Requirements on Verification

%%To Be Defined%% Reformulate text taken from the EN 50128 to avoid copyright infringements.

Excerpt from EN 50128:2011 [N01]	Requirement	Project Relevance
5.3.2.7	For each document, traceability shall be provided in terms of a unique reference number and a defined and documented relationship with other documents.	fully applicable
5.3.2.8	Each term, acronym or abbreviation shall have the same meaning in every document. If, for historical reasons, this is not possible, the different meanings shall be listed and the references given.	
5.3.2.9	Except for documents relating to pre-existing software (see 7.3.4.7), each document shall be written according to the following rules: <ul style="list-style-type: none"> it shall contain or implement all applicable conditions and requirements of the preceding document with which it has a hierarchical relationship; it shall not contradict the preceding document. 	
5.3.2.10	Each item or concept shall be referred to by the same name or description in every document.	
6.5.4.14	Traceability to requirements shall be an important consideration in the validation of a safety-related system and means shall be provided to allow this to be demonstrated throughout all phases of the lifecycle.	

Excerpt from EN 50128:2011 [N01]	Requirement	Project Relevance
6.5.4.15	<p>Within the context of this European Standard, and to a degree appropriate to the specified software safety integrity level, traceability shall particularly address</p> <ul style="list-style-type: none"> a) traceability of requirements to the design or other objects which fulfil them, b) traceability of design objects to the implementation objects which instantiate them. c) traceability of requirements and design objects to the tests (component, integration, overall test) and analyses that verify them. <p>Traceability shall be the subject of configuration management.</p>	
6.5.4.16	In special cases, e.g. pre-existing software or prototyped software, traceability may be established after the implementation and/or documentation of the code, but prior to verification/validation. In these cases, it shall be shown that verification/validation is as effective as it would have been with traceability over all phases.	This requirement does not apply to the project.
6.5.4.17	Objects of requirements, design or implementation that cannot be adequately traced shall be demonstrated to have no bearing upon the safety or integrity of the system.	

Excerpt from EN 50128:2011 [N01]	Requirement
6.1.4.1	Tests performed by other parties such as the Requirements Manager, Designer or Implementer, if fully documented and complying with the following requirements, may be accepted by the Verifier.
6.1.4.2	Measurement equipment used for testing shall be calibrated appropriately. Any tools, hardware or software, used for testing shall be shown to be suitable for the purpose.
6.1.4.3	Software testing shall be documented by a Test Specification and a Test Report, as defined in the following.
6.2.4.2	A Software Verification Plan shall be written, under the responsibility of the Verifier, on the basis of the necessary documentation.
6.2.4.3	The Software Verification Plan shall describe the activities to be performed to ensure proper verification and that particular design or other verification needs are suitably provided for
6.2.4.4	During development (and depending upon the size of the system) the plan may be subdivided into a number of child documents and be added to, as the detailed needs of verification become clearer.
6.2.4.5	The Software Verification Plan shall document all the criteria, techniques and tools to be used in the verification process. The Software Verification Plan shall include techniques and measures chosen from Table A.5, Table A.6, Table A.7 and Table A.8. The selected combination shall be justified as a set satisfying 4.8, 4.9 and 4.10
6.2.4.6	The Software Verification Plan shall describe the activities to be performed to ensure correctness and consistency with respect to the input to that phase. These include reviewing, testing and integration.

Excerpt from EN 50128:2011 [N01]	Requirement
6.2.4.7	In each development phase it shall be shown that the functional, performance and safety requirements are met.
6.2.4.8	The results of each verification shall be retained in a format defined or referenced in the Software Verification Plan.
6.2.4.9	<p>The Software Verification Plan shall address the following:</p> <ul style="list-style-type: none"> a) the selection of verification strategies and techniques (to avoid undue complexity in the assessment of the verification and testing, preference shall be given to the selection of techniques which are in themselves readily analysable); b) selection of techniques from Table A.5, Table A.6, Table A.7 and Table A.8; c) the selection and documentation of verification activities; d) the evaluation of verification results gained; e) the evaluation of the safety and robustness requirements; f) the roles and responsibilities of the personnel involved in the verification process; g) the degree of the functional based test coverage required to be achieved; h) the structure and content of each verification step, especially for the Software Requirement Verification (7.2.4.22), Software Architecture and Design Verification (7.3.4.41, 7.3.4.42), Software Components Verification (7.4.4.13), Software Source Code Verification (7.5.4.10) and Integration Verification (7.6.4.13) in a way that facilitates review against the Software Verification Plan.

%%Insert other tables.%%

A.3 Glossary

DAS2V: Design Artifact Subject to Verification or Validation

EVC European Vital Computer

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