

Exercise Session 10

Exercise 1.

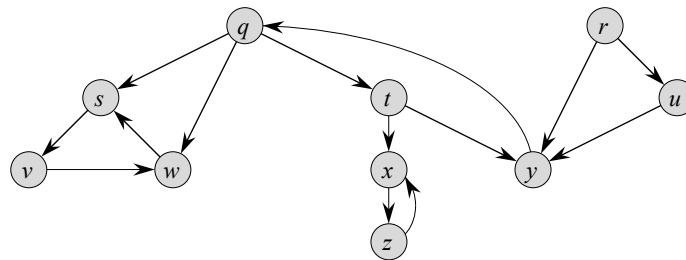
(CLRS 22.1-3) The transpose of a directed graph $G = (V, E)$ is the graph $G^T = (V, E^T)$, where $E^T = \{(v, u) \in V \times V : (u, v) \in E\}$. Describe efficient algorithms for computing G^T from G , for both adjacency-list and adjacency-matrix representations of G . Analyse the running times of your algorithms.

Exercise 2.

The diameter of a tree $T = (V, E)$ is defined as $\max_{u, v \in V} \delta(u, v)$, that is, the largest of all shortest-path distances in the tree. Give an efficient algorithm to compute the diameter of a tree, and analyse the running time of your algorithm.

Exercise 3.

Consider the graph G depicted below.



- Write the intervals for the discovery time and finishing time of each vertex in the graph obtained by performing a depth-first search visit of G .
- Write the corresponding “parenthesization” of the vertices in the sense of Theorem 22.7 in CLRS
- Assign with each edge a label T (tree edge), B (back edge), F (forward edge), C (cross edge) corresponding to the classification of edges induced by the DFS visit performed before.
- If G admits a topological sorting, then show the result of $\text{TOPOLOGICAL-SORT}(G)$.

Exercise 4.

(CLRS 22.4-5) Another way to perform topological sorting on a directed acyclic graph $G = (V, E)$ is to repeatedly find a vertex of in-degree 0, output it, and remove it and all of its outgoing edges from the graph. Explain how to implement this idea so that it runs in time $O(|V| + |E|)$. What happens to this algorithm if G has cycles?

Exercise 5.

Assume G is a directed acyclic graph. Give an efficient algorithm to compute the graph of strongly connected components of G , and analyse the running time of your algorithm.

Exercise 6.

(CLRS 22.5-1) How can the number of strongly connected components of a graph change if a new edge is added?