

LEARNING CROSS-PRODUCTS OF LEARNABLE SETS

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ABSTRACT. We define and study the problem of modular concept learning, that is, learning a concept that is a cross product of component concepts. If an element’s membership in a concept depends solely on its membership in the components, learning the concept as a whole can be reduced to learning the components. We analyze this problem with respect to different types of oracle interfaces, defining different sets of queries. If a given oracle interface cannot answer questions about the components, learning can be difficult, even when the components are easy to learn with the same type of oracle queries. While learning from superset queries is easy, learning from membership, equivalence, or subset queries is harder. However, we show that these problems become tractable when oracles are given a positive example and are allowed to ask membership queries.

1. INTRODUCTION

Inductive synthesis or inductive learning is the synthesis of programs from examples or other observations. Most inductive synthesis follows the active learning model, where the learner is allowed to make queries about the target concept to an oracle. Using the correct set of oracles can result in the polynomial time learnability of otherwise unlearnable sets [1]. Recently, exact active learning has been applied to formal synthesis, where a program is automatically generated to fit a high-level specification [2]. This has been particularly useful in paradigms such as Counter-Example Guided Inductive Synthesis [3].

Most exact learning algorithms for synthesis are monolithic, that is, even if the concept (program) is made up of components, the algorithms seek to learn the entire concept from interaction with an oracle. In contrast, in this paper, we study the setting of modular concept learning, where an exact-learning problem is analyzed by breaking it into independent components. If an element’s membership in a concept depends solely on its membership in the components, learning the concept as a whole can be reduced to learning the components. We study concepts that are the cross-products of their component concepts. This can be thought of as learning conjunctions in that an element is part of a target concept if and only if its relevant variables are all of the component concepts.

We will focus on the oracle queries given in Table 1.

1.1. A Motivating Example. To illustrate the learning problem, consider the sketching problem given in figure 1. Say we wanted to find the set of possible initial values for x and y that can replace the ?? values so that the program satisfies Φ .

Looking at the structure of this program and specification, we can see that the correctness of these two variables are independent of each other. Correct x values are correct

Query Name	Symbol	Complexity	Oracle Definition
Single Positive Query	$1Pos$	$\#1Pos(c)$	Return a fixed $x \in c^*$
Positive Query	Pos	$\#Pos(c)$	Return an $x \in c^*$ that has not yet been given as a positive example (if one exists)
Membership Query	Mem	$\#Mem(c)$	Given string s , return true iff $s \in c^*$
Equivalence Query	EQ	$\#EQ$	Given $c \in C$, return true if $c = c^*$ otherwise return $x \in (c \setminus c^*) \cup (c^* \setminus c)$
Subset Query	Sub	$\#Sub(c)$	Given $c \in C$, return ‘true’ if $c \subseteq c^*$ otherwise return some $x \in c \setminus c^*$
Superset Query	Sup	$\#Sup(c)$	Given $c \in C$, return ‘true’ if $c \supseteq c^*$ otherwise return some $x \in c^* \setminus c$

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int x = ??;
int y = ??;
int a = f(x);
int b = g(y);

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$$\Phi = \phi_1(a) \wedge \phi_2(b)$$

FIGURE 1. A simple partial program to be synthesized to satisfy a specification Φ

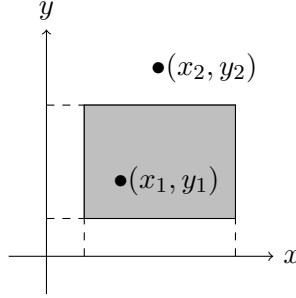


FIGURE 2. The correct set of initial values for x and y .

independent of y and vice-versa. Therefore, the set of settings will be the cross product of the acceptable settings for each variable. If an oracle can answer queries about correct x or y values separately, then the oracle can simply learn the acceptable values separately and take their cartesian-product.

If the correct values form intervals, the correct settings will look something like the rectangle shown in figure 2. An algorithm for learning this rectangle can try to simulate learning algorithms for each interval, by acting as the oracle for each sublearner. For

example, if both sublearners need a positive example, the learner can query the oracle for a positive example. Given the example (x_1, y_1) as shown in the figure, the learner can then pass x_1 and y_1 to the sublearners as positive examples. However, this does not apply to negative examples, such as (x_2, y_2) in the figure. In this example, x_2 is in its target interval, but y_2 is not. The learner has no way of knowing which subconcept a negative element fails on. Handling negative counterexamples is one of the main challenges of this paper.

2. NOTATION

In the following proofs, we assume we are given concept classes C_1, C_2, \dots, C_k defined over sets X_1, X_2, \dots, X_k . Each c_i^* in each C_i is learnable from algorithm A_i using queries to an oracle that can answer any queries in a set Q . For each query $q \in Q$, we say algorithm A_i makes $\#q_i$ many q queries to the oracle in order to learn concept c_i^* , dropping the index i when necessary. We replace the term $\#q$ with a more specific term when the type of query is specified. For example, an algorithm A might make $\#Mem$ many membership queries to learn c .

Unless otherwise stated, we will assume any index i or j ranges over the set $\{1 \dots k\}$. We write $\prod S_i$ to refer to the cartesian-product (i.e., cross-product) of sets S_i . Note that this is the k -ary cartesian product, and is not simply repeated applications of the binary cartesian product. So for example $\prod_{i=1}^3 S_i$ equals $\{(s_1, s_2, s_3) \mid s_1 \in S_1, s_2 \in S_2, s_3 \in S_3\}$ and not $\{((s_1, s_2), s_3) \mid s_1 \in S_1, s_2 \in S_2, s_3 \in S_3\}$. We use S^k to refer to $\prod_{i=1}^k S_i$.

We use vector notation \vec{x} to refer to a vector of elements (x_1, \dots, x_k) , $\vec{x}[i]$ to refer to x_i , and $\vec{x}[i \leftarrow x'_i]$ to refer to \vec{x} with x'_i replacing value x_i at position i . We define $\prod C_i := \{\prod c_i \mid c_i \in C_i, i \in \{1, \dots, k\}\}$. We write \vec{c} or $\prod c_i$ for any element of $\prod C_i$ and will often denote \vec{c} by (c_1, \dots, c_k) in place of $\prod c_i$. The target concept will be represented as c^* or $\prod c_i^*$ which equals (c_1^*, \dots, c_k^*) .

The results below answer the following question: For different sets of queries Q , can we bound the number of queries to learn $\prod C_i$ as a function of each $\#q_i$ for each $q \in Q$?

The proofs in this paper make use of the following simple observation:

Observation 1. *For sets S_1, S_2, \dots, S_k and T_1, T_2, \dots, T_k , we have $\prod S_i \subseteq \prod T_i$ if and only if $S_i \subseteq T_i$ for all i or $\prod S_i = \emptyset$.*

3. SIMPLE LOWER BOUNDS

This section introduces some fairly simple lower bounds. We will start with a lower-bound on learnability from positive examples.

Proposition 1. *There exist concepts C_1 and C_2 that are each learnable from constantly many positive queries, such that $C_1 \times C_2$ is not learnable from any number of positive queries.*

Proof. Let $C_1 := \{\{a\}, \{a, b\}\}$ and set $C_2 := \{\mathbb{N}, \mathbb{Z} \setminus \mathbb{N}\}$. To learn the set in C_1 , pose two positive queries to the oracle, and return $\{a, b\}$ if and only if both a and b are given as positive examples. To learn C_2 , pose one positive query to the oracle and return \mathbb{N} if and

only if the positive example is in \mathbb{N} . An adversarial oracle for $C_1 \times C_2$ could give positive examples only in the set $\{a\} \times \mathbb{N}$. Each new example is technically distinct from previous examples, but there is no way to distinguish between the sets $\{a\} \times \mathbb{N}$ and $\{a, b\} \times \mathbb{N}$ from these examples. \square

Now we will show lower bounds on learnability from *EQ*, *Sub*, and *Mem*. We will see later that this lower bound is tight when learning from membership queries, but not equivalence or subset queries.

Proposition 2. *There exists a concept C that is learnable from $\#q$ many queries posed to $Q \subseteq \{\text{Mem}, \text{EQ}, \text{Sub}\}$ such that learning C^k requires $(\#q)^k$ many queries.*

Proof. Let $C = \{\{j\} \mid j \in \{0 \dots m\}\}$.

We can learn C in m membership, subset, or equivalence queries by querying $j \in c^*$, $\{j\} \subseteq c^*$, or $\{j\} = c^*$, respectively.

However, a learning algorithm for C^k requires more than m^k queries. To see this, note that C^k contains all singletons in a space of size $(m+1)^k$.

So for each subset query $\{x\} \subseteq c^*$, if $\{j\} \neq c^*$, the oracle will return j as a counterexample, giving no new information. Likewise, for each equivalence query $\{j\} = c^*$, if $\{j\} \neq c^*$, the oracle can return j as a counterexample. Therefore, any learning algorithm must query $x \in c^*$, $\{x\} \subseteq c^*$, or $\{x\} = c^*$ for $(m+1)^k - 1$ values of x \square

4. LEARNING FROM SUPERSET QUERIES

Proposition 3. *If $Q = \{\text{Sup}\}$, then there is an algorithm that learns any concept $\prod c_i^* \in \prod C_i$ in $\sum \# \text{Sup}(c_i^*)$ queries.*

Proof. Algorithm 1 learns $\prod C_i$ by simulating the learning of each A_i on its respective class C_i . The algorithm asks each A_i for superset queries S_i , queries the product $\prod S_i$ to the oracle, and then uses the answer to answer at least one query to some A_i . Since at least one A_i receives an answer for each oracle query, at most $\sum \# \text{Sup}(c_i^*)$ queries must be made in total.

We will now show that each oracle query results in at least one answer to an A_i query (and that the answer is correct). The oracle first checks if the target concept is empty, if not it proceeds as normal. At each step, the algorithm poses query $\prod S_i$ to the oracle. If the oracle returns 'yes' (meaning $\prod S_i \supseteq \prod c_i^*$), then $S_i \supseteq c_i^*$ for each i by Observation 1, so the oracle answers 'yes' to each A_i . If the oracle returns 'no', it will give a counterexample $\vec{x} = (x_1, \dots, x_k) \in \prod c_i^* \setminus \prod S_i$. There must be at least one $x_i \notin S_i$ (otherwise, \vec{x} would be in $\prod S_i$). So the algorithm checks $x_j \in S_j$ for all x_j until an $x_i \notin S_i$ is found. Since $\vec{x} \in \prod c_i^*$, we know $x_i \in c_i^*$, so $x_i \in c_i^* \setminus S_i$, so the oracle can pass x_i as a counterexample to A_i .

Note that once A_i has output a correct hypothesis c_i , S_i will always equal c_i , so counterexamples must be taken from some $j \neq i$. \square

Result: Learn $\prod C_i$ from Superset Queries

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if  $\emptyset \in C_i$  for some  $i$  then
  | Query  $\emptyset \supseteq \prod c_i^*$ ;
  | if  $\emptyset \supseteq \prod c_i^*$  then
  |   | return  $\emptyset$ 
for  $i = 1 \dots k$  do
  | Set  $S_i$  to initial subset query from  $A_i$ 
while Some  $A_i$  has not completed do
  | Query  $\prod S_i$  to oracle;
  | if  $\prod S_i \supseteq c^*$  then
  |   | Answer  $S_i \supseteq c_i^*$  to each  $A_i$ ;
  |   | Update each  $S_i$  to new query;
  | else
  |   | Get counterexample  $\vec{x} = (x_1, \dots, x_k)$  for  $i = 1 \dots k$  do
  |     | if  $x_i \notin S_i$  then
  |       | Pass counterexample  $x_i$  to  $A_i$ ;
  |       | Update  $S_i$  to new query;
  |   | for  $i = 1 \dots k$  do
  |     | if  $A_i$  outputs  $c_i$  then
  |       | Set  $S_i := c_i$ ;
return  $\prod c_i$ ;

```

Algorithm 1: Algorithm for learning from Subset Queries

5. LEARNING FROM MEMBERSHIP QUERIES AND ONE POSITIVE EXAMPLE

Ideally, learning the cross-product of concepts should be about as easy as learning all the individual concepts. The last section showed this is not the case when learning with equivalence, subset, or membership queries. However, when the learner is given a single positive example and allowed to make membership queries, the number of queries becomes tractable. This is due to the following simple observation.

Observation 2. Fix sets S_1, S_2, \dots, S_k , points x_1, x_2, \dots, x_k and an index i . If $x_j \in S_j$ for all $j \neq i$, then $(x_1, x_2, \dots, x_k) \in \prod S_i$ if and only if $x_i \in S_i$.

So, given a positive example \vec{p} , we can see that $\vec{p}[j \leftarrow x_j] \in \text{targ}$ if and only if $x_j \in c_j^*$. This fact is used to learn using subset or equivalence queries with the addition of membership queries and a positive example. The algorithm is fairly similar for equivalence and subset queries, and is shown as a single algorithm in Algorithm 2.

Proposition 4. If $Q = \{\text{Sub}\}$ and a single positive example $\vec{p} \in \prod c_i^*$ is given, then $\prod c_i^*$ is learnable in $\sum \#\text{Sub}_i$ subset queries and $k \cdot \sum \#\text{Sub}_i$ membership queries.

Proof. The learning process is described in Algorithm 2. For each subset query $\prod S_i \subseteq \prod c_i^*$, the algorithm either returns ‘yes’ or gives a counterexample $\vec{x} = (x_1, \dots, x_k) \in \prod S_i \setminus \prod c_i^*$. If the algorithm returns ‘yes’, then by Observation 1 $S_i \subseteq c_i^*$ for all i , so the

algorithm can return 'yes' to each A_i . Otherwise, $\vec{x} \notin \prod c_i^*$, so there is an i such that $x_i \notin c_i^*$. By Observation 2 the algorithm can query $\vec{p}[j \leftarrow x_j]$ for all j until the $x_i \notin c_i^*$ is found.

Once the correct c_j is found for any j , S_j will equal c_j for all future queries, so any counterexamples must fail on an $i \neq j$.

Each subset query results in a correct answer being given to at least one learner A_i and at most k membership queries are made per subset query, yielding the desired bound on queries. \square

Proposition 5. *If $Q = \{\text{EQ}\}$ and a single positive example $\vec{p} \in \prod c_i^*$ is given, then $\prod c_i^*$ is learnable in $\sum \#\text{EQ}_i$ equivalence queries and $k \cdot \sum \#\text{EQ}_i$ membership queries.*

Proof. The proof for when $Q = \{\text{EQ}\}$ is analogous, with only two differences. If the oracle returns 'true' to an equivalence query, then we can assume each A_i returns the correct hypothesis the next step. Also, if the counterexample is some $\vec{x} \in \prod c_i^* \setminus \prod S_i$, then we can see the algorithm behaves correctly using the same argument as in the proof for superset queries. \square

Result: Learn $\prod C_i$ from Equivalence (or Subset) Queries, Membership Queries, and One Positive Example

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for  $i = 1 \dots k$  do
  | Set  $S_i$  to initial equivalence query from  $A_i$ 
while Some  $A_i$  has not completed do
  | Query  $\prod S_i$  to oracle;
  | if The Oracle returns 'True' then
  |   | Pass 'True' to each  $A_i$ ;
  | else
  |   | Get counterexample  $\vec{x} = (x_1, \dots, x_k)$ ;
  |   | if  $\vec{x} \in \prod c_i^* \setminus \prod S_i$  then
  |   |   | // Only happens if  $Q = \{\text{EQ}\}$ 
  |   |   | for  $i = 1 \dots k$  do
  |   |   |   | if  $x_i \notin S_i$  then
  |   |   |   |   | Pass counterexample  $x_i$  to  $A_i$ ;
  |   |   |   |   | Update  $S_i$  to new query from  $A_i$ ;
  |   | else
  |   |   | for  $i = 1 \dots k$  do
  |   |   |   | Query  $\vec{p}[i \leftarrow x_i] \in \prod c_i^*$ ;
  |   |   |   | if  $\vec{p}[i \leftarrow x_i] \notin \prod c_i^*$  and  $x_i \in S_i$  then
  |   |   |   |   | Pass counterexample  $x_i$  to  $A_i$ ;
  |   |   |   |   | Update  $S_i$  to new query from  $A_i$ ;

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Algorithm 2: Algorithm for learning from Equivalence (or Subset) Queries, Membership Queries, and One Positive Example

Finally, learning from only membership queries and one positive example is fairly easy.

Proposition 6. *If $Q = \{\text{Mem}\}$ and a single positive example $\vec{p} \in \prod c_i^*$ is given, then $\prod c_i^*$ is learnable in $k \cdot \sum \#\text{Mem}_i(c_i^*)$ membership queries.*

Proof. The algorithm learns by simulating each A_i in sequence, moving on to A_{i+1} once A_i returns a hypothesis c_i . For any membership query M_i made by A_i , $M_i \in c_i^*$ if and only if $\vec{p}[i \leftarrow M_i] \in \prod c_i^*$ by Observation 2. Therefore the algorithm is successfully able to simulate the oracle for each A_i , yielding a correct hypothesis c_i . \square

6. LEARNING FROM ONLY MEMBERSHIP QUERIES

We have seen that learning with membership queries can be made significantly easier if a single positive example is given. In this section we describe a learning algorithm using membership queries when no positive example is given. This algorithm makes $O(\max_i \{\#\text{Mem}_i(c_i)\}^k)$ queries, matching the lower bound given in a previous section.

For this algorithm to work, we need to assume that $\emptyset \notin C_i$ for all i . If not, there is no way to distinguish between an empty and non-empty concept. For example consider the classes $C_1 = \{\{1\}, \emptyset\}$ and $C_2 = \{\{j\} \mid j \in \mathbb{N}\}$. It is easy to know when we have learned the correct class in C_1 or in C_2 using membership queries. However, for any finite number of membership queries, there is no way to distinguish between the sets \emptyset and $\{(1, j)\}$ for some j that has yet to be queried.

The main idea behind this algorithm is that learning from membership queries is easy once a single positive example is found. So the algorithm runs until a positive example is found from each concept or until all concepts are learned. If a positive example is found, the learner can then run Algorithm 2 for learning from membership queries and a single positive example.

Proposition 7. *Algorithm 3 will terminate after making $O(\max_i \{\#\text{Mem}_i(c_i)\}^k)$ queries.*

Proof. The algorithm works by constructing sets S_i of elements and querying all possible elements of $\prod S_i$. We will get our bound of $O(\max_i \{\#\text{Mem}_i(c_i)\}^k)$ by showing the algorithm will find a positive example once $|S_i| > \max_i \{\#\text{Mem}_i(c_i)\}$ for all i . Since the algorithm queries all possible elements of $\prod S_i$, it is sufficient to prove that S_i will contain an element of c_i once $|S_i| > \#\text{Mem}_i(c_i)$.

Assume that each learner eventually terminates. Let $\vec{q}^i = q_1^i, q_2^i, \dots$ be the membership queries A_i makes assuming it only receives negative answers from an oracle. If \vec{q}^i is finite, then there is some set $N_i \in C_i$ that A_i outputs after querying all points in \vec{q}^i (and receiving negative answers). If N_i is non-empty let n_i be some element in N_i . Note that although sampling elements from a set might be expensive in general, this is only done for N_i and can therefore be hard-coded into the learning algorithm. If $c_i = N_i$, then by our assumption that $\prod c_i^* \neq \emptyset$, N_i contains some n_i . So S_i contains an element of c_i at the start of the algorithm. If $c_i \neq N_i$, by our assumption that A_i eventually terminates, A_i must eventually query some $q_j^i \in c_i$. So after j steps, S_i contains some element of c_i . Since $j < \#\text{Mem}_i(c_i)$, we have that S_i contains a positive example once $|S_i| > \#\text{Mem}_i(c_i)$, completing the proof. \square

Result: Learning with Membership Queries Only

for $i = 1 \dots k$ **do**

if N_i and n_i exist **then**

 Set $S_i := \{n_i\}$;

else

 Set $S_i := \{\}$;

Set $j = 0$;

while *True* **do**

for $i = \{1, \dots, k\}$ **do**

if $|\vec{q}^*| \geq j$ **then**

$S_i := S_i \cup \{q_j^i\}$;

for $\vec{x} \in \prod S_i$ **do**

 Query $\vec{x} \in \prod c_i^*$;

if $\vec{x} \in \prod c_i^*$ **then**

 Run Algorithm ?? using \vec{x} as a positive example;

$j := j + 1$;

Algorithm 3: Algorithm for Learning from Membership Queries Only

7. LEARNING FROM EQUIVALENCE OR SUBSET QUERIES IS HARD

The previous section showed that learning cross products of membership queries requires at most $O(\max_i \{\#Mem_i(c_i)\}^k)$ membership queries. A natural next question is whether this can be done for equivalence and subset queries. In this section, we answer that question in the negative. We will construct a class \mathfrak{C} that can be learned from n equivalence or membership queries but which requires at least k^n queries to learn \mathfrak{C}^k .

We define \mathfrak{C} to be the set $\{\mathfrak{c}(s) \mid s \in \mathbb{N}^*\}$, where $\mathfrak{c}(s)$ is defined as follows:

$$\begin{aligned} \mathfrak{c}(\lambda) &= \{\lambda\} \times \mathbb{N} \\ \mathfrak{c}(s) &= (\{s\} \times \mathbb{N}) \cup \mathfrak{c}_{sub}(s) \\ \mathfrak{c}_{sub}(sa) &= (\{s\} \times (\mathbb{N} \setminus \{a\})) \cup \mathfrak{c}_{sub}(s) \end{aligned}$$

For example, $\mathfrak{c}(12) = (\{12\} \times \mathbb{N}) \cup (\{1\} \times (\mathbb{N} \setminus \{2\})) \cup (\{\lambda\} \times (\mathbb{N} \setminus \{1\}))$.

An important part of this construction is that for any two strings $s, s' \in \mathbb{N}$, we have that $\mathfrak{c}(s) \subseteq \mathfrak{c}(s')$ if and only if $s = s'$. This implies that a subset query will return true if and only if the true concept has been found. Moreover, an adversarial oracle can always give a negative example for an equivalence query, meaning that oracle can give the same counterexample if a subset query were posed. So we will show that \mathfrak{C} is learnable from equivalence queries, implying that it is learnable from subset queries.

We prove a lower-bound on learning \mathfrak{C}^k from subset queries from an adversarial oracle. An adversarial equivalence query oracle can give the exact same answers and counterexamples, implying that \mathfrak{C}^k is hard to learn from equivalence queries.

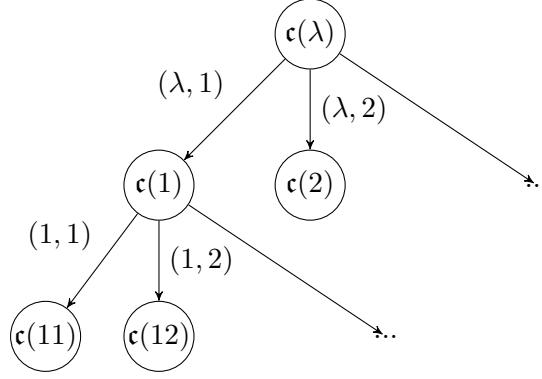


FIGURE 3. A tree representing Algorithm 4. Nodes are labelled with the queries made at each step, and edges are labelled with the counterexample given by the oracle.

Proposition 8. *There exist algorithms for learning from equivalence queries or subset queries such that any concept $c(s) \in \mathfrak{C}$ can be learned from $|s|$ queries.*

Proof. (proof sketch) Algorithm 4 shows the learning algorithm for equivalence queries, and Figure 7 show the decisions tree. As mentioned above, this algorithm is essentially the same for learning from subset queries. When learning $c(s)$ for any $s \in \mathbb{N}^*$, the algorithm will construct s by learning at least one new element of s per query. Each new query to the oracle is constructed from a string that is a substring of s . If a positive counterexample is given, this can only yield a longer substring of s . \square

Result: Learns \mathfrak{C}

Set $s = \lambda$;

while *True* **do**

 Query $c(s)$ to Oracle **if** Oracle returns ‘yes’ **then**

return $c(s)$

if Oracle returns $(s', m) \in c^* \setminus c(s)$ **then**

 Set $s = s'$;

if Oracle returns $(s, m) \in c(s) \setminus c^*$ **then**

 Set $s = sm$;

Algorithm 4: Learning \mathfrak{C} from equivalence queries.

7.1. Showing \mathfrak{C}^k is Hard to Learn. It is easy to learn \mathfrak{C} , since each new counterexample gives one more element in the target string s . When learning a concept, $\prod c(s_i)$, it is not clear which dimension a given counterexample applies to. Specifically A given counterexample \vec{x} could have the property that $\vec{x}[i] \in c(s_i)$ for all $i \neq j$, but the learner cannot infer the value of this j . It will then proceed considering all possible values of j , requiring exponentially more queries for longer s_i . This subsection will formalize this notion to prove an exponential lower bound on learning \mathfrak{C}^k . First, we need a couple definitions.

A concept $\prod \mathbf{c}(s_i)$ is *justifiable* if one of the following holds:

- For all i , $s_i = \lambda$
- There is an i and an $a \in \mathbb{N}$ and $w \in \mathbb{N}^*$ such that $s_i = wa$, and $\mathbf{c}(s_1) \times \cdots \times \mathbf{c}(w) \times \cdots \times \mathbf{c}(s_k)$ was justifiably queried to the oracle and received a counterexample \vec{x} such that $\vec{x}[i] = (w, a)$.

A concept is *justifiably queried* if it was queried to the oracle when it was justifiable.

For any strings $s, s' \in \mathbb{N}^*$, we write $s \leq s'$ if s is a substring of s' , and we write $s < s'$ if $s \leq s'$ and $s \neq s'$. We say that the *sum of string lengths* of a concept $\prod \mathbf{c}(s_i)$ is of size r if $\sum |s_i| = r$

Proving that learning is hard in the worst-case can be thought of as a game between learner and oracle. The oracle can answer queries without first fixing the target concept. It will answer queries so that for any n , after less than k^n queries, there is a concept consistent with all given oracle answers that the learning algorithm will not have guessed. The specific behavior of the oracle is defined as follows:

- It will always answer the same query with the same counterexample.
- Given any query $\prod \mathbf{c}(s_i) \subseteq c^*$, the oracle will return a counterexample \vec{x} such that for all i , $\vec{x}[i] = (s_i, a_i)$, and a_i has not been in any query or counterexample yet seen.
- The oracle never returns ‘yes’ on any query.

Example 1. Consider the following example when $k = 2$. First, the learner queries $(\mathbf{c}(\lambda), \mathbf{c}(\lambda))$ to the oracle and receives a counter-example $((\lambda, 1), (\lambda, 2))$. The justifiable concepts are now $(\mathbf{c}(1), \mathbf{c}(\lambda))$ and $(\mathbf{c}(\lambda), \mathbf{c}(2))$. The learner queries $(\mathbf{c}(1), \mathbf{c}(\lambda))$ and receives counterexample $((1, 3), (\lambda, 4))$. The learner queries $(\mathbf{c}(\lambda), \mathbf{c}(2))$ and receives counterexample $((\lambda, 5), (2, 6))$. The justifiable concepts are now $(\mathbf{c}(1), \mathbf{c}(4))$, $(\mathbf{c}(1 \cdot 3), \mathbf{c}(\lambda))$, $(\mathbf{c}(5), \mathbf{c}(2))$ and $(\mathbf{c}(\lambda), \mathbf{c}(2 \cdot 6))$. At this point, the only possible solutions constructible from strings of length 1 are $(\mathbf{c}(1), \mathbf{c}(4))$ and $(\mathbf{c}(5), \mathbf{c}(2))$. The graph of justifiable queries is given in Figure 7.1.

The following simple proposition can be proven by induction on sum of string lengths.

Proposition 9. *Let $\prod \mathbf{c}(s_i)$ be a justifiable concept. Then for all $w_i \leq s_i$, $\prod \mathbf{c}(w_i)$ has been queried to the oracle.*

Proposition 10. *If all justified concepts $\prod \mathbf{c}(s_i)$ with sum of string lengths equal to r have been queried, then there are k^{r+1} justified queries whose sum of string lengths equals $r + 1$*

Proof. This proof follows by induction on r . When $r = 0$, the concept $\prod \mathbf{c}(\lambda)$ is justifiable. For induction, assume that there are k^r justifiable queries with sum of string lengths equal to r . By construction, the oracle will always chose counterexamples with as-yet unseen values in \mathbb{N} . So querying each concept $\prod \mathbf{c}(s_i)$ will yield a counterexample \vec{x} where for all i , $\vec{x}[i] = (s_i, a_i)$ for new a_i . Then for all i , this query creates the justifiable concept $\prod \mathbf{c}(s'_i)$, where $s'_j = s_j$ for all $j \neq i$ and $s'_i = \mathbf{c}(s_i \cdot a_i)$. Thus there are k^{r+1} justifiable concepts with sum of string lengths equal to $r + 1$. \square

We are finally ready to prove the main theorem of this section.

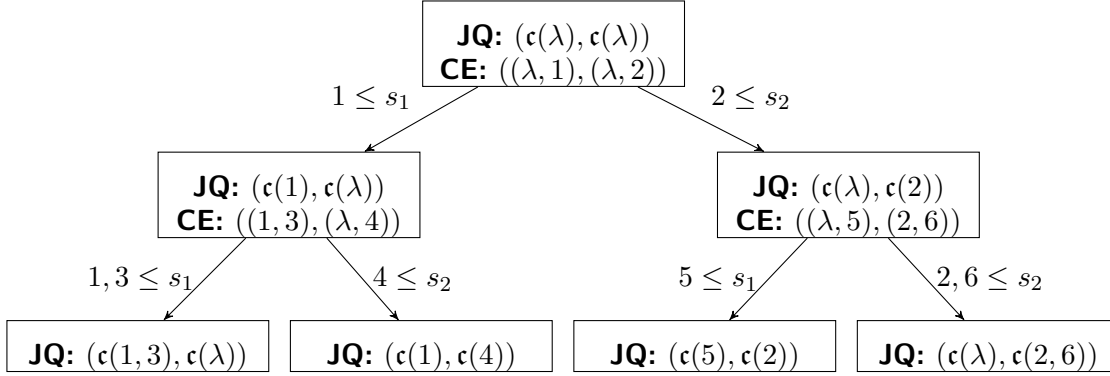


FIGURE 4. The tree of justifiable queries used in Example 1. Each node lists the justifiable query (JQ) and counterexample (CE) given for that query. The edges below each node are labelled with the possible inferences about s_1 and s_2 that can be drawn from the counterexample.

Theorem 1. *Any algorithm learning \mathfrak{C}^k from subset (or equivalence) queries requires at least k^r queries to learn a concept $\prod \mathfrak{c}(s_i)$, whose sum of string lengths is r . Equivalently, the algorithm takes $k^{\sum \#q_i}$ subset (or equivalence) queries.*

Proof. Assume for contradiction that an algorithm can learn with less than k^r queries and let this algorithm converge on some concept $c = \prod \mathfrak{c}(s_i)$ after less than k^r queries. Since less than k^r queries were made to learn c , by Proposition 10, there must be some justifiable concept $c' = \prod \mathfrak{c}(s'_i)$ with sum of string lengths less than or equal to r that has not yet been queried. By Proposition 9 we can assume without loss of generality that for all $w_i \leq s'_i$, $\prod \mathfrak{c}(w_i)$ has been queried to the oracle. We will show that c' is consistent with all given oracle answers, contradicting the claim that c is the correct concept. Let $c_v = \prod c_v$ be any concept queried to the oracle, and let \vec{x} be the given counterexample. If for all i , $v_i \leq s'_i$, then by construction, there is an i with $\vec{x}[i] = (v_i, a_i)$ such that $v_i \cdot a_i \leq s'_i$, so \vec{x} is a valid counterexample. Otherwise, there is an i such that $v_i \not\leq s'_i$. So $\{v_i\} \times \mathbb{N} \cap \mathfrak{c}(s'_i) = \emptyset$, so \vec{x} is a valid counterexample. Therefore, all counterexamples are consistent with c' being correct concept, contradicting the claim that the learner has learned c . \square

8. DISJOINT UNION

This section discusses learning disjoint unions of concept classes. This is generally much easier than learning cross-products of classes, since counterexamples belong to a single dimension in the disjoint union. This problem uses the same notation as the cross-product case, but we denote the disjoint union of two sets as $A \cup B$ and the disjoint union of many sets as $\bigcup A_i$. We define the concept class of disjoint unions as $C_\cup := \{\bigcup c_i \mid c_i \in C_i\}$.

The algorithm for learning from membership queries is very easy and won't be stated here. Algorithm 5 shows the learning procedure for when $Q \in \{\{Sub\}, \{Sup\}, \{EQ\}\}$. The correctness of this algorithm follows from the following simple facts. Assume we have

sets S_1, \dots, S_k and T_1, \dots, T_k . Then $\bigcup S_i \subseteq \bigcup T_i$ if and only if $S_i \subseteq T_i$ for all i . Likewise $\bigcup S_i = \bigcup T_i$ if and only if $S_i = T_i$ for all i .

Result: Learning Disjoint Unions

```

for  $i = 1 \dots k$  do
  | Set  $S_i$  to initial query from  $A_i$ 
while Some  $A_i$  has not terminated do
  | Query  $\bigcup S_i$  to oracle;
  | if Oracle returns 'yes' then
  |   | Pass 'yes' to each  $A_i$ ;
  |   | Get updated  $S_i$  from each  $A_i$ ;
  | else
  |   | Get counterexample  $x_i \in X_i$  for some  $i$ ;
  |   | Pass  $x_i$  as counterexample to  $A_i$ ;
  |   | Get updated  $S_i$  from each  $A_i$ ;
return  $\bigcup S_i$ ;

```

Algorithm 5: Learning Disjoint Unions

9. EFFICIENT PAC-LEARNING

This section discusses the problem of PAC-learning the cross products of concept classes.

Previously, van Der Vaart and Weller [4] have shown the following bound on the VC-dimension of cross-products of sets:

$$(hi) \quad \mathcal{VC}(\prod C_i) \leq a_1 \log(ka_2) \sum \mathcal{VC}(C_i)$$

Here a_1 and a_2 are constants with $a_1 \approx 2.28$ and $a_2 \approx 3.92$. As always, k is the number of concept classes included in the cross-product.

The VC-dimension gives a bound on the number of labelled examples needed to PAC-learn a concept, but says nothing of the computational complexity of the learning process. This complexity mostly comes from the problem of finding a concept in a concept class that is consistent with a set of labelled examples. We will show that the complexity of learning cross-products of concept classes is a polynomial function of the complexity of learning from each individual concept class.

First, we will describe some necessary background information on PAC-learning.

9.1. PAC-learning Background.

Definition 1. *Let C be a concept class over a space X . We say that C is efficiently PAC-learnable if there exists an algorithm A with the following property: For every distribution \mathcal{D} on X , every $c \in C$, and every $\epsilon, \delta \in (0, 1)$, if algorithm A is given access to $EX(c, \mathcal{D})$ then with probability $1 - \delta$, A will return a $c' \in C$ such that $\text{error}(c') \leq \epsilon$. A must run in time polynomial in $1/\epsilon$, $1/\delta$, and $\text{size}(c)$.*

We will refer to ϵ as the ‘accuracy’ parameter and δ as the ‘confidence’ parameter. All PAC-learners have a *sample complexity* function $m_C(\epsilon, \delta) : (0, 1)^2 \rightarrow \mathbb{N}$. The sample complexity is the number of samples an algorithm must see in order to probably approximately learn a concept with parameters ϵ and δ .

Given a set S of labelled examples in X , we will use $A(S)$ to denote the concept class the algorithm A returns after seeing set S .

A learner A is an *empirical risk minimizer* if $A(C)$ returns a $c \in C$ that minimizes the number of misclassified examples (i.e., it minimizes $|\{(x, b) \in S \mid c^*(x) \neq b\}|$).

Empirical risk minimizers are closely related to VC dimension and PAC-learnability as shown in the following theorem (Theorem 6.7 from [?])

Theorem 2. *If the concept class C has VC dimension d , then there is a constant a such that applying an Empirical Risk Minimizer A to $m_C(\epsilon, \delta)$ samples will PAC-learn in C , where*

$$m_C(\epsilon, \delta) \leq a \frac{d \cdot \log(1/\epsilon) + \log(1/\delta)}{\epsilon}$$

Finally, we will discuss the *growth function*. The growth function describes how well a concept class can differentiate

More formally, for a concept class C and $m \in \mathbb{N}$, the growth function $G_C(m)$ is defined by:

$$G_C(m) = \max_{x_1, x_2, \dots, x_m} |\{(c(x_1), c(x_2), \dots, c(x_m)) \mid c \in C\}|$$

The VC-dimension of a class C is the largest number d such that $G_C(d) = 2^d$.

We will use the following bound, sometimes called the PerlesSauerShelah Lemma, to bound the runtime of learning cross-products.

Lemma 1. *For any concept class C with VC-dimension d and $m > d + 1$:*

$$G_C(m) \leq (em/d)^d$$

9.2. PAC-Learning Cross-Products. We now have enough background to describe the strategy for PAC-learning cross-products. We will just describe learning the cross-product of two concepts. As above, we assume we have concept classes C_1 and C_2 and PAC-learners A_1 and A_2 .

Assume that C_1 and C_2 have VC-dimension d_1 and d_2 , respectively. We can use the bound from van Der Vaart and Weller to get an upper bound d on the VC-dimension of their cross-product. Assume the algorithm is given an ϵ and δ and there is a fixed target concept $c^* = c_1^* \times c_2^*$. Theorem 2 gives a bound on the sample complexity $m_{C_1 \times C_2}(\epsilon, \delta)$. The algorithm will take a sample of labelled examples of size $m_{C_1 \times C_2}(\epsilon, \delta)$. Our goal is to construct an Empirical Risk Minimizer for $C_1 \times C_2$. In our case, this means that for any sample S , the algorithm will yield a concept in $C_1 \times C_2$ that is consistent with S .

So let S be any such sample the algorithm takes. This set can easily be split into positive examples S^+ and negative examples S^- , both in $X_1 \times X_2$. The algorithm works by maintaining sets labeled samples L_1 and L_2 for each dimension. For any $(x_1, x_2) \in S^+$, it holds that $x_1 \in c_1^*$ and $x_2 \in c_2^*$ so (x_1, \top) and (x_2, \top) are added to L_1 and L_2 respectively.

For any $(x_1, x_2) \in S^-$, we know that $x_1 \notin c_1^*$ or $x_2 \notin c_2^*$ (or both), but it is not clear which is true. However, since the goal is only to create an Empirical Risk Minimizer, it is enough to find any concepts C_1 and C_2 that are consistent with these samples. In other words, we need to find a $c_1 \in C_1$ and a $c_2 \in C_2$ such that for every $(x_1, x_2) \in S^+$, $x_1 \in c_1$ and $x_2 \in c_2$ and for all $(x_1, x_2) \in S^-$, either $x_1 \notin c_1^*$ or $x_2 \notin c_2^*$. One idea would be to try out all possible assignments to elements in S^- and check if any such assignment fits any possible concepts. This, however, would be exponential in $|S^-|$.

Bounding the size of the growth function can narrow this search. Specifically, let $S_1^- = \{x \mid \exists y, (x, y) \in S^-\}$, let $m = |S_1^-|$ and order the elements of S_1^- by x_1, x_2, \dots, x_m . By the definition of the growth function and Lemma 1:

$$|\{(c(x_1), c(x_2), \dots, c(x_m)) \mid c \in C_1\}| \leq G_{C_1}(m) \leq (em/d)^d$$

In other words, there are less than $(em/d)^d$ assignments of truth values to elements of S_1^- that are consistent with some concept in C_1 . If the algorithm can check every $c_1 \in C_1$ consistent with S^+ and S_1^- , it can then call A_2 to see if there is any $c_2 \in C_2$ such that $(c_1 \times c_2)$ assigns true to every element in S^+ and false to every element in S^- .

To efficiently find the elements of C_1 consistent with S^+ and S_1^- can be accomplished by something like binary search, as shown in Algorithm 6.

Theorem 3. *Let C_1 and C_2 be concept classes and let A_1 and A_2 be PAC-learners with runtime $A_1(\epsilon, \delta)$ and $A_2(\epsilon, \delta)$, respectively. Let C_1 and C_2 have VC-dimension d_1 and d_2 , respectively. There exists a PAC-learner for $C_1 \times C_2$ that can learn any concept using a sample of size $m = ((d_1 + d_2) \cdot \log(1/\epsilon) + \log(1/\delta))/\epsilon$. The learner requires time $O(m_1^d(A_1(1/m, \log(\delta)) + A_2(1/m, \log(\delta))))$.*

Result: Find Subconcepts Consistent with Sample

Input: S^+ : Set of positive examples in $X_1 \times X_2$

S^- : Set of negative examples in $X_1 \times X_2$

δ : Confidence parameter in $(0, 1)$

FindSubconcepts (S^+ , S^- , δ)

$\delta' := \log(\delta) / (G_{C_1}(|S|) + G_{C_2}(|S|));$

$\epsilon' := 1/|S|;$

 // L_1 : Labelled samples in X_1

$L_1 := \{(x_1, \top) \mid \exists y, (x_1, y) \in S^+\};$

 // L_2 : Labelled samples in X_2

$L_2 := \{(x_2, \top) \mid \exists y, (y, x_2) \in S^+\};$

$U := S^-;$

return RecursiveFindSubconcepts($L_1, L_2, U, \epsilon', \delta'$);

RecursiveFindSubconcepts ($L_1, L_2, U, \epsilon', \delta'$):

 // Run once all labels are assigned to the first dimension of U

 // Attempts to find concept in C_2 consistent with all labels given in L_2

if $U = \emptyset$ **then**

if $A_2(L_2, \epsilon', \delta')$ **then**

return ($A_1(L_1, \epsilon', \delta'), A_2(L_2, \epsilon', \delta')$);

else

\perp ;

 Get $(x_1, x_2) \in U$;

$U := U \setminus \{(x_1, x_2)\};$

 // Attempts to label x_1 as false in c_1^*

if $A_1(L_1 \cup \{(x_1, \perp)\}, \epsilon', \delta') \neq \perp$ **then**

$c = \text{RecursiveFindSubconcepts}(L_1 \cup \{(x_1, \perp)\}, L_2, U, \epsilon', \delta');$

if $c \neq \perp$ **then**

return c ;

 // Attempts to label x_1 as true in c_1^*

if $A_1(L_1 \cup \{(x_1, \top)\}, \epsilon', \delta') \neq \perp$ **then**

$c = \text{RecursiveFindSubconcepts}(L_1 \cup \{(x_1, \top)\}, L_2 \cup \{(x_2, \perp)\}, U, \epsilon', \delta');$

if $c \neq \perp$ **then**

return c ;

10. CONCLUSION

The final collection of query complexities for learning cross products is given in Figure 5. All of the bounds are tight, except for learning with superset queries, membership queries, and one positive example. Additionally, learning disjoint unions from any $Q \in \{\{EQ\}, \{Sub\}, \{Sup\}\}$ requires as many queries as is needed to learn each concept separately,

$Q \downarrow$	Only Q	Q with Mem and $1Pos$	
	$\#q$	$\#Mem$	$\#q$
Pos	Not Possible	Not Possible	Not Possible
Sup	$\sum \#Sup$	0	$\sum \#Sup$
Mem	$(\max_i \{\#Mem_i\})^k$	$\sum \#Mem_i$	$\sum \#Mem_i$
Sub	$k \sum \#Sub_i$	$k \sum \#Sub_i$	$\sum \#Sub_i$
EQ	$k \sum \#EQ_i$	$k \sum \#EQ_i$	$\sum \#EQ_i$

FIGURE 5. Final collection of query complexities for learning cross products. The rows represents the set Q of queries needed to learn each C_i . The columns determine whether the cross product is learned from queries in just Q or $Q \cup \{Mem, 1Pos\}$. In the latter case, the column is separated to track the number of membership queries and queries in Q that are needed.

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