Benjamin Hinchliff

Experienced and Versatile Computer Scientist

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EDUCATION

California Polytechnic State University, San Luis Obispo B.S./M.S. Computer Science GPA 3.96 (President's Honors List)

Dec 2025

EXPERIENCE

ANRE Technologies NASA Jet Propulsion Laboratory Intern (Full Time)

Jun 2025 - Sept 2025

- Developed RSVPLite telemetry backend to allow storage of future mission telemetry in arbitrary databases, such as TimescaleDB or SQLite
- · Created machine learning model to predict for Perseverance rover slippage from orbital imagery and rover tilt data

ANRE Technologies NASA Jet Propulsion Laboratory Intern (Full Time)

Jun 2024 - Sept 2024

- Continued to work on M2020 (Perseverance) Rover Simulation Software (RSVP Suite)
- Developed custom stereo processing pipeline to experiment with usage of more advanced stereo matching algorithms in operations
- Added Looking Glass support to enhance stereo viewer (QARD)

ANRE Technologies NASA Jet Propulsion Laboratory Intern (Part Time)

Oct 2023 - Jun 2024

· Brought on part time after internship to continue RSVP development

Caltech NASA Jet Propulsion Laboratory Intern (Full Time)

June - Sept 2023

- Worked to Develop and Maintain Mars Rover Simulation Software (RSVP Suite)
- Ported simulation software from RedHat Enterprise Linux (RHEL) 7 to RHEL 8
- · Fixed major issues including crashing bugs, logic bugs, data format incompatibilities, and more
- Developed new terrain searching features

Versational | Full-stack Software Developer

June - Sept. 2021

· Assisted development of Deep Learning "Gems" identification models based on BERT

PROJECTS EXAMPLES

Full (uncurated) list at benjaminhinchliff.com/projects

WebGPU Accelerated Raytracer | C++20, CMake, Dawn

- · A GPU accelerated Raytracer based on Google's Dawn WebGPU implementation
- Supports creation of scenes program side
- multiple primitives and materials supported using dynamically generated WGSL shaders

BanjOS | C11, x86_64 Asm, GRUB Bootloader

- Minimal x86_64 operating system written from scratch targeting the QEMU emulator
- Supports features including: VGA console output, interrupts & interrupt driven keyboard & serial drivers, dynamic memory allocation with on-demand paging (physical, virtual, & kmalloc), cooperative multitasking, and Ext2 file reading

Reinforcement Learning BalatroBot Experiments | Pytorch

- Full report in the Balatrobot repository
- Experiments with building a reinforcement learning agent for Balatro
- Based on an extended version Balatrobot botting framework for the Balatro game
- · Communicates with a Pytorch model over websockets to send commands to Balatro mod
- · Learned simple hand combinations and performed moderately better than baseline

SKILLS

Programming

- Arduino C++ & MicroPython microcontroller programming
- Simulation and kinematics modeling Fundamentals
- · Computer Science Fundamentals e.g. Data Structures, Algorithms, Theory
- C, C++, Python, Haskell Comfortable with a broad range of languages
- · Web Development React, Vue, Svelte, ¡Query, vanilla JS, etc

Tools/Others

• Scripting (Bash, Python), git, CI/CD (Github Actions & Jenkins), Linux/Unix, Later, vim/nano, VS(Code)