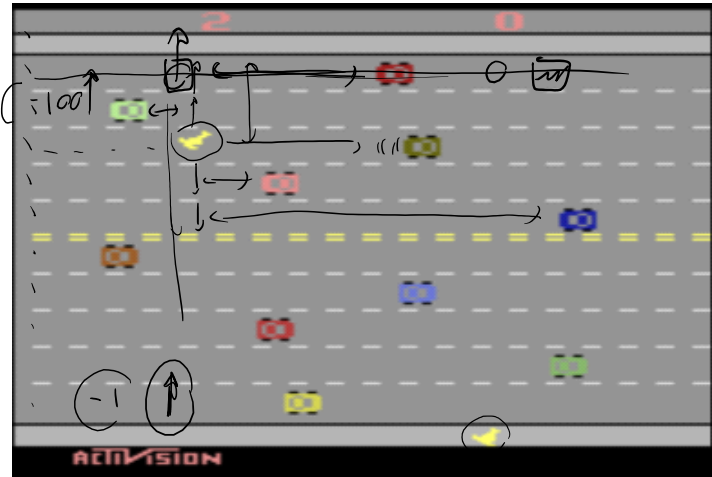


Q-Function Approximation

Friday, 21 September 2018 15:14 PM

[Learning to Play Freeway, using Reinforcement Learning](#)



Features and representation:

Feature vector: $f(s) = (f_1(s), \dots, f_n(s))$
 $f_i(s) = \max_D - \text{row}(s, cl)$

$$480^2 \times 2^{480} = 3.12 \times 10^{44}$$

(Distance), (up, 2up, 1up, 2Down)
 Distance, Distance,

Weight vector: $w = \begin{pmatrix} w_1^a & w_1^b \\ w_2^a & w_2^b \\ \vdots & \vdots \\ w_n^a & w_n^b \end{pmatrix} \quad n \times |A|$

Approximating $Q(s, a)$

$$Q(s, a) := f_1(s) \cdot w_1^a + f_2(s) \cdot w_2^a \dots f_n(s) \cdot w_n^a$$

$$\sum_i^n f_i(s) \cdot w_i^a$$

TD Update: $w_i^a \leftarrow w_i^a + \alpha [r + \gamma \max_{a'} \frac{Q(s', a')}{V(s')} - Q(s, a)] f_i(s)$

Example (Freeway):

Assume $Q(s, a) = 0$ for all s, a

Update:

$$w_i^a \leftarrow w_i^a + \alpha [r + \gamma \max_{a'} Q(s', a') - Q(s, a)] f_i(s)$$

$$5 \leftarrow 0 + 0.5 [10 + 0] \frac{1}{1}$$

Deep Q learning:

$$\partial_i \leftarrow \partial_i + \alpha [r + \gamma \max_{a'} Q(s', a') - Q(s, a)] \partial Q(s, a) / \partial \theta$$