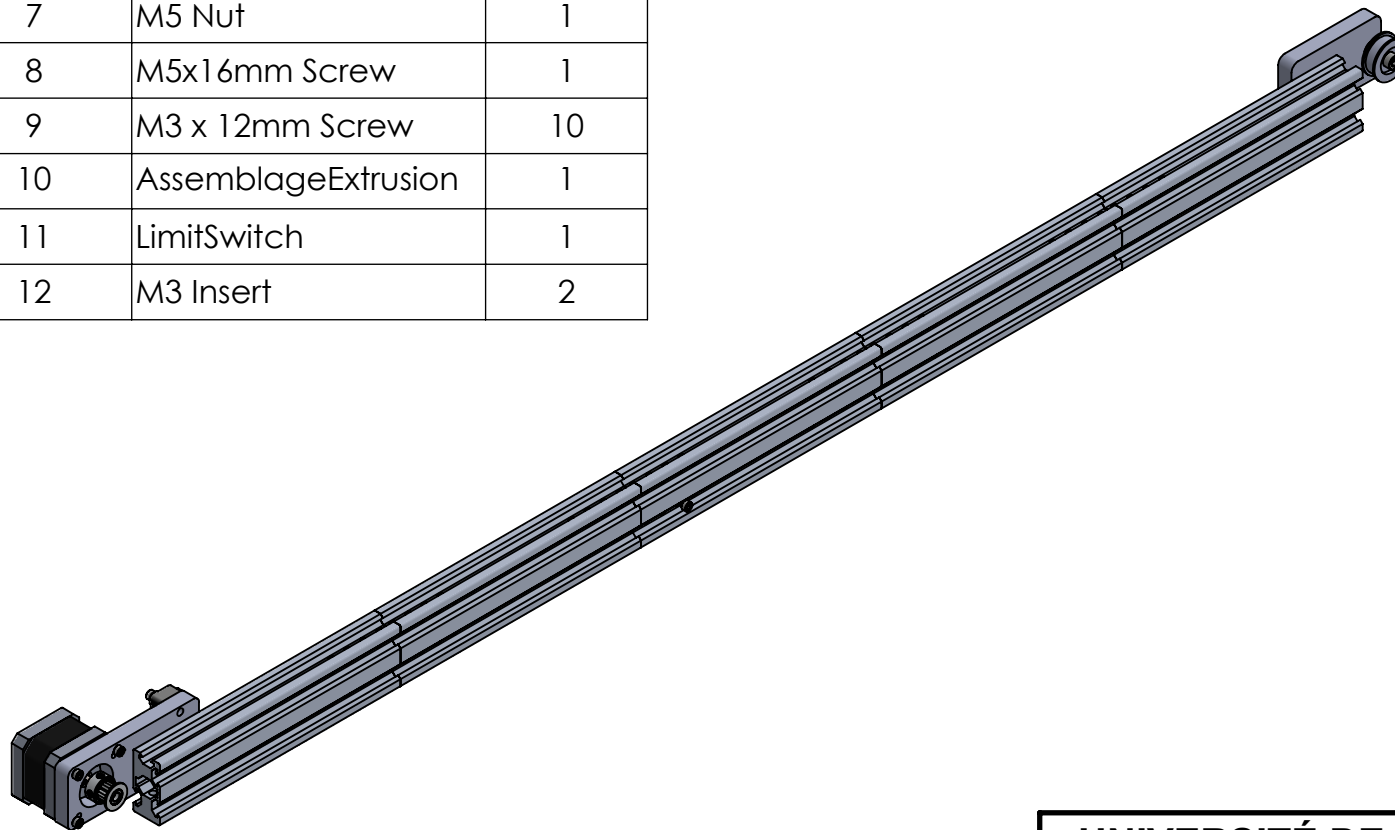


ITEM NO.	PART	QTY.
1	IdlerX_Plate	1
2	MotoX_Plate	1
3	Nema17	1
4	GT2 motor pulley	1
5	Poulie	1
6	BoisBottom	1
7	M5 Nut	1
8	M5x16mm Screw	1
9	M3 x 12mm Screw	10
10	AssemblageExtrusion	1
11	LimitSwitch	1
12	M3 Insert	2



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DÉPARTEMENT GÉNIE ROBOTIQUE



NAME: RAPHAËL CLOUTIER

DATE: 18/02/2021

PROJECT: SESSION PROJECT - S4 - TEAM 3

SCALE : 1 : 4

QTY: 1

TITLE: ASSEMBLAGEBASE

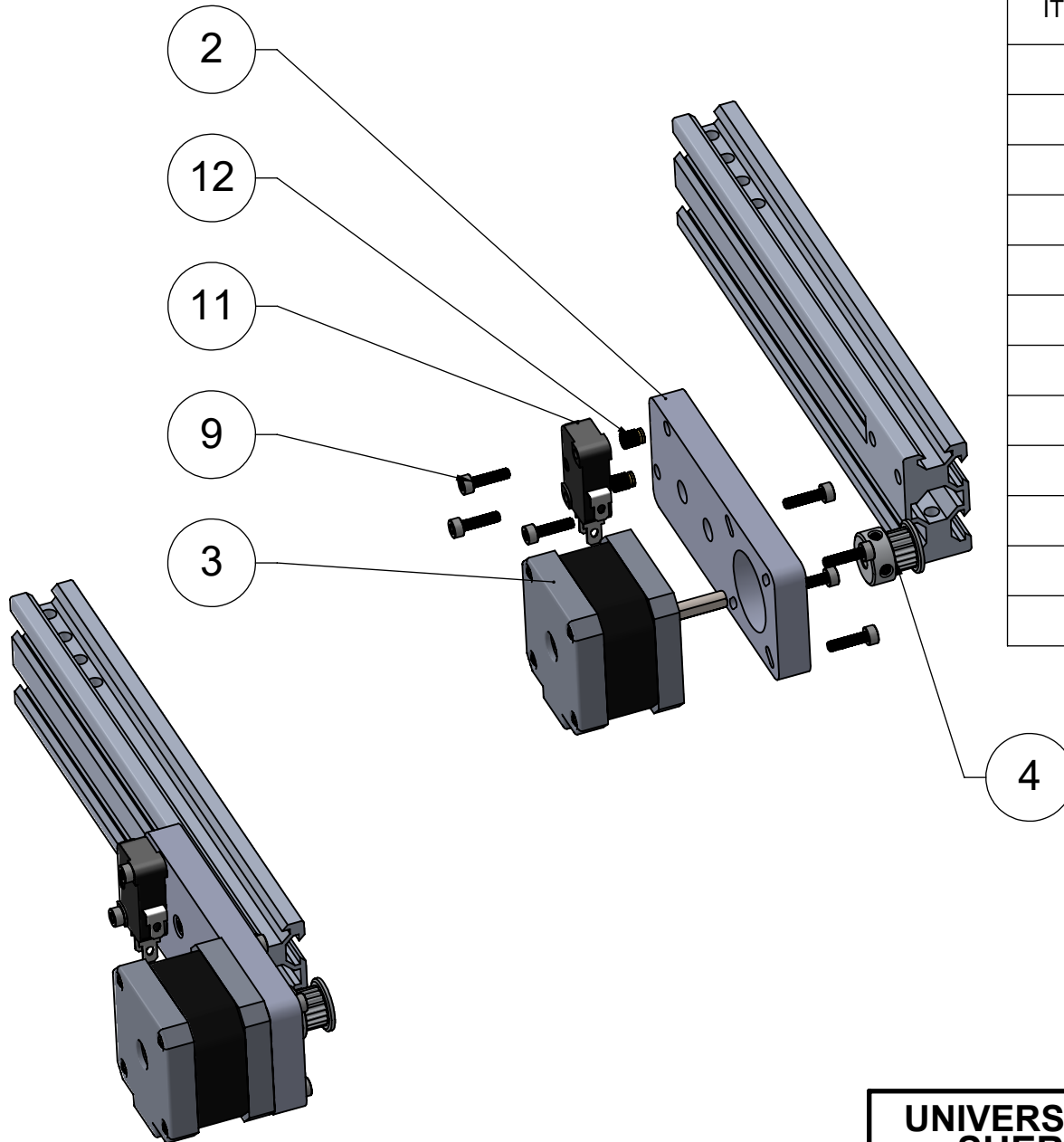
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FORMAT: A

NO DRAWING:

1/3



ITEM NO.	PART	QTY.
1	IdlerX_Plate	1
2	MotoX_Plate	1
3	Nema17	1
4	GT2 motor pulley	1
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NAME: RAPHAËL CLOUTIER

DATE: 18/02/2021

PROJECT: SESSION PROJECT - S4 - TEAM 3

SCALE : 1 : 2

QTY: 1

TITLE: ASSEMBLAGEBASE

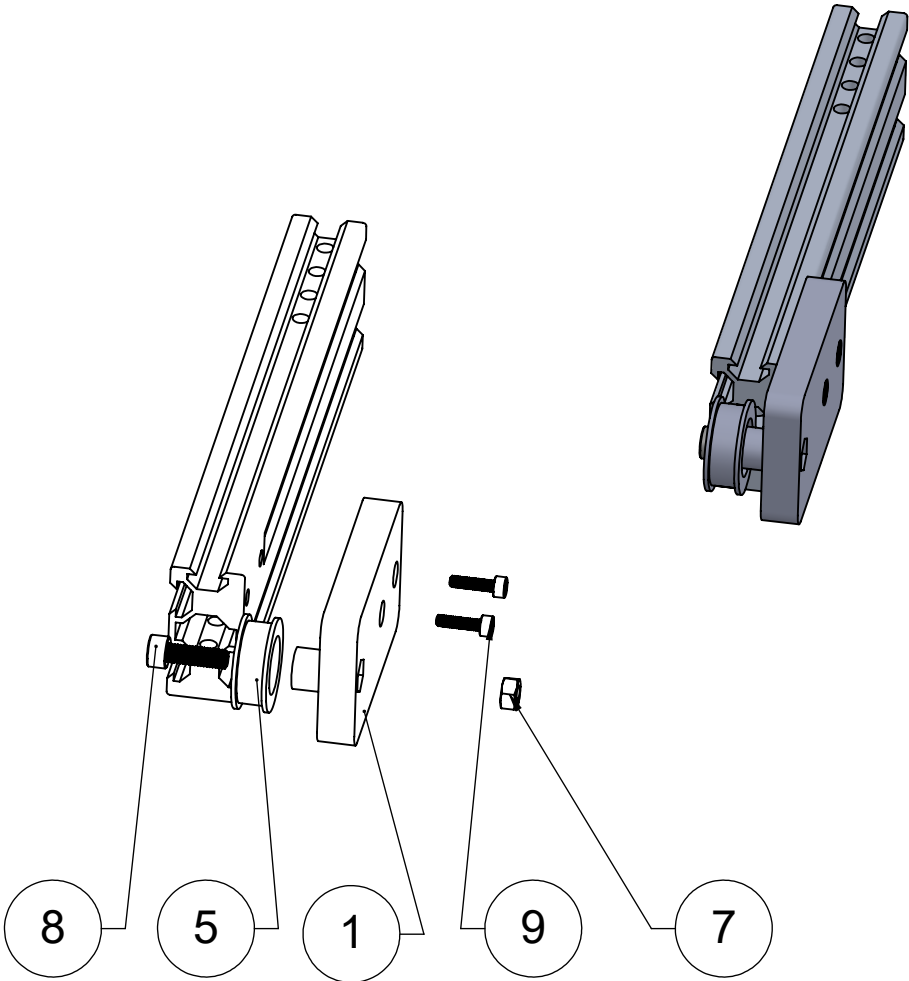



MATERIAL : MULTIPLE



FORMAT: A

NO DRAWING:

2/3

		ITEM NO.	PART	QTY.
		1	IdlerX_Plate	1
		2	MotoX_Plate	1
		3	Nema17	1
		4	GT2 motor pulley	1
		5	Poulie	1
		6	BoisBottom	1
		7	M5 Nut	1
		8	M5x16mm Screw	1
		9	M3 x 12mm Screw	10
		10	AssemblageExtrusion	1
		11	LimitSwitch	1
		12	M3 Insert	2
		<div><div>UNIVERSITÉ DE SHERBROOKE</div><div>FACULTÉ DE GÉNIE DÉPARTEMENT GÉNIE ROBOTIQUE</div></div>		
	NAME: RAPHAËL CLOUTIER	DATE: 18/02/2021	PROJECT: SESSION PROJECT - S4 - TEAM 3	
	SCALE : 1 : 2	QTY: 1	TITLE: ASSEMBLAGEBASE	
	MATERIAL : MULTIPLE	 	FORMAT: A	NO DRAWING: 3/3