

En el artículo se presentan las siguientes ecuaciones:

Predictor

$$r_{n+1} = r_n + h v_n + h^2 \sum_{p=1}^{q-1} b_p a_{n-q+1}$$

Corrector Posición

$$r_{n+1} = r_n + h v_n + h^2 \sum_{p=1}^{q-1} c_p a_{n-q+2}$$

$$h v_{n+1} = r_{n+1} - r_n + h^2 \sum_{p=1}^{q-1} d_p a_{n-q+1}$$

Sin embargo, las ecuaciones tienen un error ya que en las sumatorias, están términos a_{n-q+1} y a_{n-q+2} que dependen de q , y no p .

Se proponen las
siguientes ecuaciones
↓
corregidas:

Predictor

$$r_{n+1} = r_n + h v_n + h^2 \sum_{p=1}^{q-1} b_p a_{n-p+1}$$

Corrector posición

$$r_{n+1} = r_n + h v_n + h^2 \sum_{p=1}^{q-1} c_p a_{n-p+2}$$

$$h v_{n+1} = r_{n+1} - r_n + h^2 \sum_{p=1}^{q-1} d_p a_{n-p+2}$$

Cuando $q=3$

Predictor: $r_{n+1} = r_n + h v_n + h^2 \begin{pmatrix} b_1 a_n + b_2 a_{n-1} \end{pmatrix}$

Corrector: $r_{n+1} = r_n + h v_n + h^2 \begin{pmatrix} c_1 a_{n+1} + c_2 a_n \end{pmatrix}$

Corrector: $h v_{n+1} = r_{n+1} - r_n + h^2 \begin{pmatrix} d_1 a_{n+1} + d_2 a_n \end{pmatrix}$

Expandiendo
en serie de Taylor
con 3 terminos:

$$r_{n+1} = \frac{r_n}{0!} + \frac{v_n h}{1!} + \frac{h^2}{2!} (b_1 a_n + b_2 a_{n-1})$$

$$u_{n+1} = u_n + v_n h + \frac{h^2}{2!} (b_1 a_n + b_2 u_n)$$

$$u_{n+1} = \frac{u_n}{0!} + \frac{v_n h}{1!} + \frac{h^2}{2!} (c_1 a_n + c_2 u_n)$$

$$r_{n+1} = r_n + v_n h + \frac{h^2}{2} (c_1 a_n + c_2 u_n)$$

$$h v_{n+1} = \frac{h v_{n+1}}{0!} + \frac{v_n (-h)}{1!} + \frac{h^2}{2} (b_1 a_{n+1} + a_n)$$

Con eso se encuentran
los coeficientes

condición: $\frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}} \right) = 0$

Tarea 4)

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$$y' = f(t, y)$$

$$y(t_{n+1}) = y(t_n) + \int_{t_n}^{t_{n+1}} y'(t) dt$$

entonces:

$$A = \int_{t_n}^{t_{n+1}} y'(t) dt = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt$$

interpolando:

$$P(t) = f(t_n, y_n) \frac{(t - t_{n-1})(t - t_{n-2})}{(t_n - t_{n-1})(t_n - t_{n-2})} + f(t_{n-1}, y_{n-1}) \frac{(t - t_n)(t - t_{n-2})}{(t_{n-1} - t_n)(t_{n-1} - t_{n-2})} + f(t_{n-2}, y_{n-2}) \frac{(t - t_n)(t - t_{n-1})}{(t_{n-2} - t_n)(t_{n-2} - t_{n-1})}$$

decimos que $t_{n-1} - t_{n-2} = t_n - t_{n-1} = t_{n+1} - t_n = h$

$$\frac{f(t_n, y_n)}{2h^2} \int_{t_n}^{t_{n+1}} (t - t_{n-1})(t - t_{n-2}) dt = \frac{23}{12} h f(t_n, y_n)$$

$$-\frac{f(t_{n-1}, y_{n-1})}{h^2} \int_{t_n}^{t_{n+1}} (t - t_n)(t - t_{n-2}) dt = -\frac{4}{3} h f(t_{n-1}, y_{n-1})$$

$$\frac{f(t_{n-2}, y_{n-2})}{2h^2} \int_{t_n}^{t_{n+1}} (t - t_n)(t - t_{n-1}) dt = \frac{5}{12} h f(t_{n-2}, y_{n-2})$$

entonces: $A = \frac{23}{12} h f(t_n, y_n) - \frac{4}{3} h f(t_{n-1}, y_{n-1}) + \frac{5}{12} h f(t_{n-2}, y_{n-2})$

$$y(t_{n+1}) = y(t_n) + \frac{23}{12} h f(t_n, y_n) - \frac{4}{3} h f(t_{n-1}, y_{n-1}) + \frac{5}{12} h f(t_{n-2}, y_{n-2})$$

$$y_{n+1} = y_n + \frac{h}{12} (23f_n - 16f_{n-1} + 5f_{n-2})$$

Adams kushport 4 puntos:

$$y(n, y) = f_0 + h \nabla f_0 + \frac{n(n+1)}{2} \nabla^2 f_0 + \dots \rightarrow \textcircled{1}$$

$$x = x_0 + nh, \quad f_0 = f(x_0, y_0)$$

$$y_1 = y_0 + \int_{x_0}^{x_0+h} f(x, y) dx = y_0 + \int_{x_0}^{x_0+h} \left(f_0 + h \nabla f_0 + \frac{n(n+1)}{2} \nabla^2 f_0 + \dots \right) dx$$

$$= y_0 + \int_0^1 \left(f_0 + h \nabla f_0 + \frac{n(n+1)}{2} \nabla^2 f_0 + \dots \right) dx \text{ utilizando esta vez } dx = h dn$$

$$= y_0 + h \left[f_0 + \frac{n^2}{2} \nabla f_0 + \left(\frac{n^3}{3} + \frac{n^2}{2} \right) \nabla^2 f_0 + \dots \right]_0^1$$

$$= y_0 + h \left[f_0 + \frac{\nabla f_0}{2} + \frac{5}{12} \nabla^2 f_0 + \frac{3}{8} \nabla^3 f_0 + \dots \right]$$

$$\frac{\nabla f_0}{2} = (1 - E^{-1}) f_0 = f_0 - E^{-1} f_0 = f_0 - f_{-1}$$

$$\nabla f_0 = \nabla (f_0 - f_{-1}) = \nabla f_0 - \nabla f_{-1} = f_0 - f_{-1} - (f_{-1} - f_{-2})$$

$$= f_0 - 2f_{-1} + f_{-2} \quad \Delta^2 f_0 = f_0 - 3f_{-1} + 3f_{-2} - f_{-3}$$

Reemplazando:

$$y_1 = y_0 + \frac{f_0 - f_{-1}}{2} + \frac{5}{12} (f_0 - 2f_{-1} + f_{-2}) + \frac{3}{8} (f_0 - 3f_{-1} + 3f_{-2} - f_{-3})$$

$$f_0 + \frac{f_0}{2} - \frac{f_{-1}}{2} + \frac{5f_0}{12} - \frac{10f_{-1}}{12} + \frac{5f_{-2}}{12} + \frac{3f_0}{8} - \frac{9f_{-1}}{8} + \frac{9f_{-2}}{8} - \frac{3f_{-3}}{8}$$

resolviendo:

$$y_1 = y_0 + \frac{h}{24} [55f_0 - 59f_{-1} + 37f_{-2} - 9f_{-3}]$$

Adem malhon 4 puntos:

$$P_4(\tau) = f_{n-2} L_{n-2}(\tau) + f_{n-1} L_{n-1}(\tau) + f_n L_n(\tau) + f_{n+1} L_{n+1}(\tau)$$

donde

$$L_{n-2}(\tau) = \frac{(\tau - t_{n-1})(\tau - t_n)(\tau - t_{n+1})}{(t_{n-2} - t_{n-1})(t_{n-2} - t_n)(t_{n-2} - t_{n+1})} = -\frac{1}{6h^2} (\tau - t_{n-1})(\tau - t_n)(\tau - t_{n+1})$$

$$L_{n-1}(\tau) = \frac{(\tau - t_{n-2})(\tau - t_n)(\tau - t_{n+1})}{(t_{n-1} - t_{n-2})(t_{n-1} - t_n)(t_{n-1} - t_{n+1})} = \frac{1}{2h^3} (\tau - t_{n-2})(\tau - t_n)(\tau - t_{n+1})$$

$$L_n(\tau) = \frac{(\tau - t_{n-2})(\tau - t_{n-1})(\tau - t_{n+1})}{(t_n - t_{n-2})(t_n - t_{n-1})(t_n - t_{n+1})} = \frac{1}{2h^3} (\tau - t_{n-2})(\tau - t_{n-1})(\tau - t_{n+1})$$

$$L_{n+1}(\tau) = \frac{(\tau - t_{n-2})(\tau - t_{n-1})(\tau - t_n)}{(t_{n+1} - t_{n-2})(t_{n+1} - t_{n-1})(t_{n+1} - t_n)} = \frac{1}{6h^3} (\tau - t_{n-2})(\tau - t_{n-1})(\tau - t_n)$$

Entonces:

$$y_{n+1} = y_n + \int_{t_n}^{t_{n+1}} P_4(\tau) d\tau =$$

$$y_n + f_{n-2} \int_{t_{n-1}}^{t_n} L_{n-2}(\tau) d\tau + f_{n-1} \int_{t_n}^{t_{n+1}} L_{n-1}(\tau) d\tau + f_n \int_{t_n}^{t_{n+1}} L_n(\tau) d\tau$$

$$+ f_{n+1} \int_{t_n}^{t_{n+1}} L_{n+1}(\tau) d\tau$$

$$\tau = t_n + hu \quad d\tau = h du$$

$$u = \frac{\tau - t_n}{h}$$

Sabiendo $L_{n-2}(u) = \frac{1}{6} u(1-u^2)$

$$L_{n-1}(u) = -\frac{1}{2} u(u+2)(1-u)$$

$$L_n(u) = \frac{1}{2} (u+2)(1-u^2)$$

$$L_{n+1}(u) = \frac{1}{6} u(u+1)(u+2)$$

$$L_n(x) = \frac{(x - t_{n-2})(x - t_{n-1})(x - t_{n+1})}{(t_{n-2} - t_{n-1})(t_{n-2} - t_{n+1})} f_{n-2} + \frac{(x - t_{n-2})(x - t_{n+1})}{(t_{n-1} - t_{n-2})(t_{n-1} - t_{n+1})} f_{n-1} + \frac{(x - t_{n-2})(x - t_{n-1})}{(t_{n+1} - t_{n-2})(t_{n+1} - t_{n-1})} f_n + \frac{(x - t_{n-1})(x - t_{n-2})}{(t_{n+1} - t_{n-1})(t_{n+1} - t_{n-2})} f_{n+1}$$

$$\int_{t_n}^{t_{n+1}} L_{n-2}(x) dx = h \int_0^1 L_{n-2}(u) du = \frac{h}{6} \int_0^1 u(1-u)^2 du = \frac{1}{24} h$$

$$\int_{t_n}^{t_{n+1}} L_{n-1}(x) dx = h \int_0^1 L_{n-1}(u) du = -\frac{h}{2} \int_0^1 u(u+2)(1-u) du = -\frac{5}{24} h$$

$$\int_{t_n}^{t_{n+1}} L_n(x) dx = h \int_0^1 L_n(u) du = \frac{h}{2} \int_0^1 (u+2)(1-u)^2 du = \frac{19}{24} h$$

$$\int_{t_n}^{t_{n+1}} L_{n+1}(x) dx = h \int_0^1 L_{n+1}(u) du = \frac{h}{6} \int_0^1 u(u+1)(u+2) du = \frac{3}{8} h$$

entonces:

$$y_{n+1} = y_n + \frac{h}{24} (f_{n-2} - 5f_{n-1} + 16f_n + 9f_{n+1})$$

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interpolando:

$$\frac{(t-t_i)(t-t_{i-1})}{(t_{i+1}-t_i)(t_{i+1}-t_{i-1})} f_{i+1} + \frac{(t-t_{i+1})(t-t_{i-1})}{(t_i-t_{i+1})(t_i-t_{i-1})} f_i + \frac{(t-t_{i+1})(t-t_i)}{(t_{i-1}-t_{i+1})(t_{i-1}-t_i)} f_{i-1} dt \quad \text{donc} \quad f_{i+1} = f(t_{i+1}, w_{i+1})$$

$$f_i = f(t_i, w_i)$$

$$\underline{f_{i-1} = f(t_{i-1}, w_{i-1})}$$

integrando:

$$t_{i+1} = t_i + h$$

$$t_i = t_i$$

$$t_{i-1} = t_i - h$$

enonces:

$$\int_{t_i}^{t_{i+1}} \frac{(t-t_i)(t-(t_i-h))}{(t_i+h-t_i)(t_i+h-(t_i-h))} f_{i+1} + \frac{(t-(t_i+h))(t-(t_i-h))}{(t_i+h-(t_i+h))(t_i+h-(t_i-h))} f_i + \frac{(t-(t_i+h))(t-t_i)}{(t_i-h-(t_i+h))(t_i-h-t_i)} f_{i-1} dt$$

faisendo la substitution
 $t_{i+1} = 1$ y $t_i = 0$, $h = 1$

$$\frac{f_{i+1}}{h^2} \int_0^1 (t-t_i)(t-(t_i-h)) dt + \frac{f_i}{h^2} \int_0^1 (t-t_i-h)(t-t_i+h) dt + \frac{f_{i-1}}{2h^2} \int_0^1 (t-t_i-h)(t-t_i) dt$$

enonces

$$h \int_0^1 \frac{t(t+1)}{2} f_{i+1} dt + h \int_0^1 (t-1)(t+1) f_i dt + h \int_0^1 \frac{t(t-1)}{2} f_{i-1} dt$$

$$h \frac{f_{i+1}}{2} \left[\frac{t^3}{3} + \frac{t^2}{2} \right]_0^1 + h f_i \left[\frac{t^3}{3} - t^2 \right]_0^1 + h \frac{f_{i-1}}{2} \left[\frac{t^3}{3} - \frac{t^2}{2} \right]_0^1$$

$$h \frac{f_{i+1}^4}{2} \left(\frac{5}{6} \right) + h f_i \left(\frac{2}{3} \right) + h \frac{f_{i-1}^4}{2} \left(-\frac{1}{6} \right)$$

erlebens

$$y_{n+1} = y_n + \frac{h}{12} (5f_{n+1} + 8f_n - f_{n-1})$$