

# UBC Sailbot

## Software Technical Questions

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*Compress files and return to [control@ubcsailbot.org](mailto:control@ubcsailbot.org)*

### Python Section

*For the following questions, write one python file with a main that calls each function.*

1) An autonomous sailing program uses angles between -180 and 179. Your job is to write a python method

```
is_angle_between(input_angle, bound1, bound2)
```

The method returns true when the `input_angle` is within the bounds of the angle formed by `bound1` and `bound2` (choose the angle which is  $\leq 180$  degrees).

2) Write an efficient program that will return whether a GPS coordinate `coord1` (in decimal form) is less than or equal to distance `dist` (in meters) from another GPS coordinate `coord2`. Use *6,378,100m* for radius of the earth in meters.

Method name:

```
are_coords_within_distance(dist, coord1, coord2)
```

\*Be sure to have code that shows that your methods work!

### Git Section

*For the following questions, write out Git version control commands as you would from command line.*

*Answer in a file named `sailbot_git_questions.txt`*

1) How would you clone the repository <https://github.com/UBCSailbot/ubcsailbots> onto your computer?

2) Suppose you have changes with a desired message: "updated wind angles and added unit tests!" You have a modified file `wind_angles.txt` and added a new file `test_wind_angles.py`. How would you submit all of your changes to the remote repository you cloned above?