

1. Comparing centrifugal and axial compressors, what is the reason in which centrifugal compressor presents higher pressure ratio per stage than axial compressors?

Solution: The main difference in a single stage of an axial compressor vs a centrifugal compressor is the how the airflow travels through the stage. With axial compressors, the flow runs parallel to throughout the stage, whereas in a centrifugal compressor the flow is turned. This extra turning allows for more kinetic energy to be increased more in the same amount of space. This radial acceleration of the flow imparts more total pressure and total velocity on the working gas in a single stage compared to an axial stage.

2. Based on a specific axial compressor design requirement, describe with details the procedure to obtain an adequate preliminary 3D turbomachine sizing. Also, create a diagram of this project process.

Solution:

$$\text{Design Point} = f(\phi, \psi, \bar{w}, M_{\text{tip}})$$

Where the ratio between the axial flow and the actual velocity across the blade is defined as:

$$\phi = \frac{V_{\text{axial}}}{U}$$

Work coefficient is the ratio of specific work over kinetic energy:

$$\psi = \frac{-\Delta h_0}{\frac{U^2}{2}} \Rightarrow 2\phi (\tan \alpha_1 - \tan \alpha_2)$$

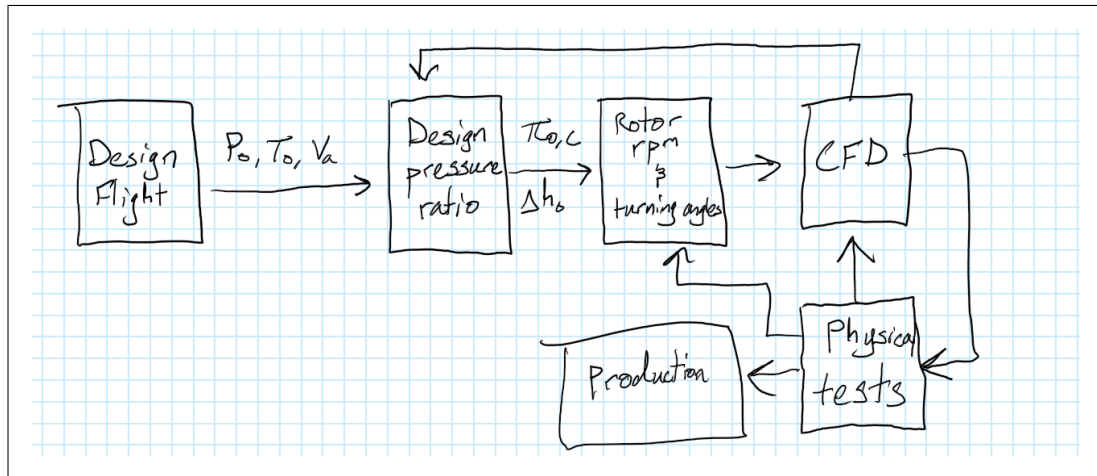
Load coefficient is $\bar{w} = \frac{\psi}{2}$ and Mach number at the rotor tip is $M_{\text{tip}} = \frac{U_{\text{tip}}}{\sqrt{\gamma RT}}$. These parameters are what we can design the compressor around in order to get the desired Δh_0 that we want.

The process to determine the initial design is to first identify the altitude and speed that the aircraft should be flying at for cruise. Then that will give us $\rho, T_0, P_0, V_{\text{axial}}$. From there we can choose a design $\pi_{0,C}$ and that will tell us the required Δh_0 with:

$$\pi_{0,C} = \frac{T_2^{\frac{\gamma}{\gamma-1}}}{T_1} \approx \frac{h_2^{\frac{\gamma}{\gamma-1}}}{h_1}$$

$$\therefore h_2 - h_1 = h_1 \pi_{0,C}^{\frac{\gamma-1}{\gamma}} - h_1$$

From there we can adjust the rpm, rotor, and stator angles until we get the design work coefficient. With the rpm, and the turning angles we can then make our 3-D design and do a CFD analysis to refine the desired pressure ratio. After the simulation model is finalized, then we can move on to wind tunnel testing. The wind tunnel testing will either verify our design, or make us change the rpm, and turning angles. This process repeats until we get something that can be pushed to production.



3. What is the objective in the use of variable geometry (VIGV and VSV)?

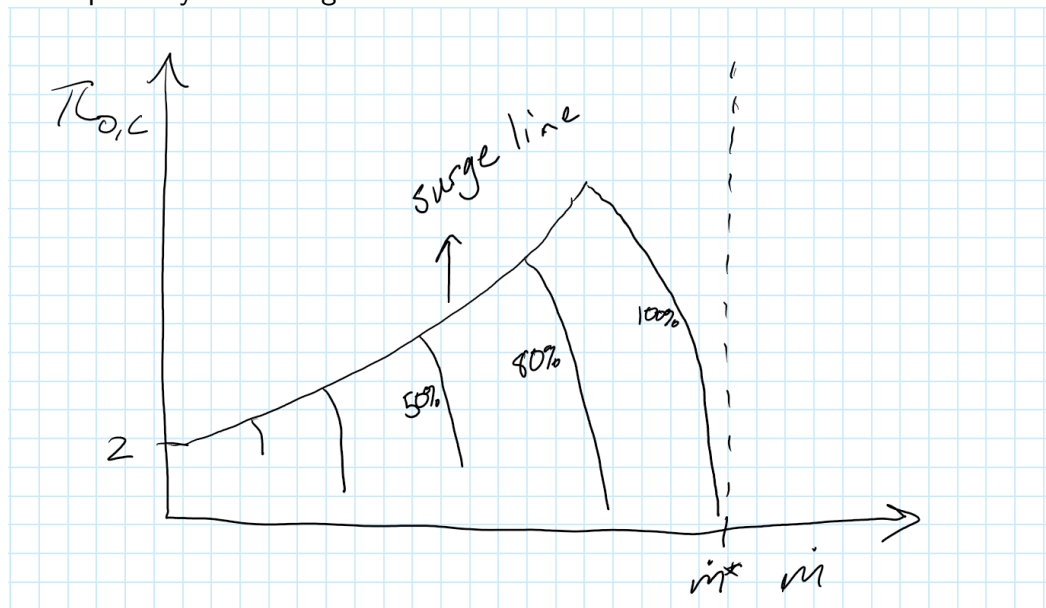
Solution: Due to a go amount of time that an engine will not operating at it's design point, we need to maximize the efficiency of the engine during these times.

$$\pi_{0C}, \eta_C = f \left(\frac{\dot{m} \sqrt{T_{01}}}{p_{01}}, M_{tip} \right).$$

The efficiency of the compressor is going to be dictated by avoiding un-wanted shock waves and flow separation we can increase the angles of the stators to impart more work on the gas at lower speeds than the design point and decrease the angles on the stators at higher speeds than the design point in order to prevent flow separation. Decreasing the angles of the stators at higher speeds also prevent strong shock waves from forming that dramatically decrease the total pressure coming out, which therefore would decrease the overall efficiency.

4. In a compressor operational map, for each rotational speed there are two limit points, stall and choke. Make a sketch of a compressor map with different rotational speeds, identifying these points including the stall/surge line and explain the physical aspects of stall, surge and choke.

Solution: The surge line is how far you can pull the angle of attack and the turning angles to maximize the pressure ratio of the compressor before flow separation overwhelms the compressor and not enough mass flow is making it to the turbine to keep the cycle running.



The \dot{m}^* that I show on the graph is the point at which the compressor becomes sonically choked, and therefore limiting the maximum amount of mass flow rate. From Dimensionless mass flow:

$$\frac{\dot{m} \sqrt{RT_0}}{P_0 \sigma} = \sqrt{\gamma} M \left(1 + \frac{\gamma-1}{2} M^2 \right)^{\frac{-(\gamma+1)}{2(\gamma-1)}}$$

Producing the choked mass flow rate of:

$$\dot{m}^* = \frac{P_0 \sigma \sqrt{\gamma}}{\sqrt{RT_0}} \left(1 + \frac{\gamma-1}{2} \right)^{\frac{-(\gamma+1)}{2(\gamma-1)}}$$