The force on a moving charge is

$$\mathbf{F} = q\left(\mathbf{E} + \mathbf{v} \times \mathbf{B}\right) \tag{1}$$

thus the torque on the same charge is given by $\mathbf{x} \times \mathbf{F}$, which is equal to the rate of change in the particle's angular momentum, i.e.,

$$\frac{\partial \mathcal{L}_{\text{mech}}}{\partial t} = \mathbf{x} \times (\rho \mathbf{E} + \mathbf{J} \times \mathbf{B}) \tag{2}$$

Using the equation above 6.116 in Jackson

$$\rho \mathbf{E} + \mathbf{J} \times \mathbf{B} = \epsilon \left[\mathbf{E} (\nabla \cdot \mathbf{E}) + \frac{1}{\mu \epsilon} \mathbf{B} (\nabla \cdot \mathbf{B}) - \mathbf{E} \times (\nabla \times \mathbf{E}) - \frac{1}{\mu \epsilon} \mathbf{B} \times (\nabla \times \mathbf{B}) \right] - \epsilon \frac{\partial}{\partial t} (\mathbf{E} \times \mathbf{B})$$
(3)

we can rewrite (2) as

$$\frac{d}{dt} \int_{V} \mathcal{L}_{\text{mech}} d^{3}x + \frac{d}{dt} \int_{V} \epsilon \mathbf{x} \times (\mathbf{E} \times \mathbf{B}) d^{3}x = \int_{V} \epsilon \mathbf{x} \times \left[\mathbf{E} (\nabla \cdot \mathbf{E}) + \frac{1}{\mu \epsilon} \mathbf{B} (\nabla \cdot \mathbf{B}) - \mathbf{E} \times (\nabla \times \mathbf{E}) - \frac{1}{\mu \epsilon} \mathbf{B} \times (\nabla \times \mathbf{B}) \right] d^{3}x$$
(4)

We shall identify

$$\mathcal{L}_{\text{field}} \equiv \epsilon \mathbf{x} \times (\mathbf{E} \times \mathbf{B}) = \mu \epsilon \mathbf{x} \times (\mathbf{E} \times \mathbf{H}) \tag{5}$$

as the density of angular momentum of the field.

Moreover, from (6.119) and (6.120), we can write

$$\epsilon \left[\mathbf{E} (\mathbf{\nabla} \cdot \mathbf{E}) + \frac{1}{\mu \epsilon} \mathbf{B} (\mathbf{\nabla} \cdot \mathbf{B}) - \mathbf{E} \times (\mathbf{\nabla} \times \mathbf{E}) - \frac{1}{\mu \epsilon} \mathbf{B} \times (\mathbf{\nabla} \times \mathbf{B}) \right] = \sum_{j} \frac{\partial}{\partial x_{j}} T_{ij} \hat{\mathbf{x}}_{i} = \mathbf{\nabla} \cdot \overset{\leftrightarrow}{\mathbf{T}}$$
(6)

then

$$\left[\mathbf{x} \times \left(\mathbf{\nabla} \cdot \stackrel{\leftrightarrow}{\mathbf{T}}\right)\right]_{k} = \sum_{i,j} \epsilon_{ijk} x_{i} \left(\sum_{l} \frac{\partial}{\partial x_{l}} T_{jl}\right) = \sum_{l} \frac{\partial}{\partial x_{l}} \left(\sum_{i,j} \epsilon_{ijk} x_{i} T_{jl}\right)$$
(7)

Per the note of the problem, the third-rank antisymmetric tensor $\mathbf{M}^{(3)}$ is defined by

$$M_{ijk} = T_{ij}x_k - T_{ik}x_j \tag{8}$$

This can be identified with the il component of the second-rank tensor $\mathbf{M}^{(2)}$ via

$$M_{il} \equiv \sum_{j,k} \epsilon_{jkl} T_{ij} x_k \tag{9}$$

Compare (9) with (7) we see

$$\left[\mathbf{x} \times \left(\mathbf{\nabla} \cdot \stackrel{\longleftrightarrow}{\mathbf{T}}\right)\right]_{k} = \sum_{l} \frac{\partial}{\partial x_{l}} \left(-M_{lk}\right) = -\mathbf{\nabla} \cdot \stackrel{\longleftrightarrow}{\mathbf{M}}$$
(10)

This makes the equivalent form of (4)

$$\frac{d}{dt} \int_{V} (\mathcal{L}_{\text{mech}} + \mathcal{L}_{\text{field}}) d^{3}x + \int_{V} \nabla \cdot \overset{\leftrightarrow}{\mathbf{M}} d^{3}x = 0 \qquad \Longrightarrow
\frac{d}{dt} \int_{V} (\mathcal{L}_{\text{mech}} + \mathcal{L}_{\text{field}}) d^{3}x + \oint_{S} \mathbf{n} \cdot \overset{\leftrightarrow}{\mathbf{M}} da = 0 \qquad \Longrightarrow
\frac{\partial}{\partial t} (\mathcal{L}_{\text{mech}} + \mathcal{L}_{\text{field}}) + \nabla \cdot \overset{\leftrightarrow}{\mathbf{M}} = 0 \qquad (11)$$