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SL10. Bayesian Inference

Conditional Independence:

 Conditional Independence: x is conditionally independent of y given z if the probability distribution governing x is independent of the value of y given the value of z:

$$\forall x, y, z \quad P_r(X = x \mid Y = y, Z = z) = P_r(X = x \mid Z = z)$$

More compactly:

$$P_r(X \mid Y, Z) = P_r(X \mid Z)$$

- This means that x is conditionally independent of y given z.
- This comes originally from normal Independence and Chain Rule:

$$P_r(X,Y) = P_r(X).P_r(Y)$$

$$P_r(X,Y) = P_r(X \mid Y).P_r(Y)$$

$$P_r(X).P_r(Y) = P_r(X \mid Y).P_r(Y)$$
then \rightarrow

$$P_r(X \mid Y) = P_r(X)$$

Belief Networks:

- Belief Networks (aka Bayesian Networks or Probabilistic Directed Acyclic Graphical Models): A
 representation for probabilistic quantitates over complex spaces. It's a graphical representation of
 the conditional independence relationships between all the variables in a joint distribution, with
 nodes corresponding to the variables and edges corresponding to the dependencies.
 - Computations grow exponentially with adding more edges (dependencies).
 - A dependency relationship between two variables doesn't mean a causal relationship.
 - A Belief Network must have a topological order. We can't have cyclic relationships (two-way dependencies).
 - The Joint Probability of the graph is equal to the product of the probabilities of the variables in the graph:

$$P_r(y_1, ..., y_n) = \prod_n P_r(y_i \mid Parents(y_i))$$

- In belief networks, we define the Parents of a variable to be the variable's immediate predecessors in the network.

Sampling:

- Calculating independent probabilities of variables in a distribution from the graph.
- Why sampling from a distribution is useful?
 - Simulation of a complex process.
 - Approximate inference: What might happen given some conditions?
 - Facilitates visualizing the information provided by data.

Inferencing Rules:

• Marginalization:

$$P_r(x) = \sum_{v} P_r(x, y)$$

Chain Rule:

$$P_r(x,y) = P_r(x \mid y) \cdot P_r(y)$$

Bayes Rule:

$$P_r(y \mid x) = \frac{P_r(x \mid y)P_r(y)}{P_r(x)}$$

Naïve Bayes:

- Naïve Bayes classifiers are classifiers that represent a special case of the belief networks, but with stronger independence assumptions. For our classifier to be a Naïve Bayes classifier, we make the naïve assumption that every attribute variable is conditionally independent of every other attribute variable.
- For the classification variable V, we would like to find the most probable target value V_{map} , given the values for attributes (a_1, a_2, \dots, a_n) . We can write the expression for V_{map} and then use Bayes theorem to manipulate the expression as follows:

$$\begin{aligned} V_{map} &= argmax_{v_{j} \in V} P_{r}(v_{j} \mid a_{1}, a_{2}, \dots, a_{n}) \\ V_{map} &= argmax_{v_{j} \in V} \frac{P_{r}(a_{1}, a_{2}, \dots, a_{n} \mid v_{j}) P_{r}(v_{j})}{P_{r}(a_{1}, a_{2}, \dots, a_{n})} \\ V_{map} &= argmax_{v_{j} \in V} P_{r}(a_{1}, a_{2}, \dots, a_{n} \mid v_{j}) P_{r}(v_{j}) \end{aligned}$$

• Using the chain rule, and the naïve conditional assumption:

$$P_r(a_1, a_2, ..., a_n \mid v_j) = P_r(a_1, a_2, ..., a_n, v_j) P_r(a_2 \mid a_3, ..., a_n, v_j) ... P_r(a_n \mid v_j)$$

= $P_r(a_1 \mid v_j) P_r(a_2 \mid v_j) ... P_r(a_n \mid v_j)$

• Substituting into V_{map} :

$$V_{map} = argmax_{v_j \in V} P_r(v_j) \prod_{i} (a_i \mid v_j)$$

- Why Naïve Bayes is useful?
 - Inference is cheap: Each of the terms to be estimated is a one dimensional probability, which can be estimated with a smaller data set than the joint probability.
 - Few parameters: The total number of terms to be estimated is the number of attributes n multiplied by the number of distinct values that v can take.
 - We can estimate the parameters with labeled data.
 - Connects inference and classification.
 - Empirically successful and can handle missing attributes.
- Disadvantages:
 - Because of the strong conditional independence assumption placed on the attributes in the model, Naïve Bayes doesn't model the inner relationships between attributes.