



Towards a Factorised Solution of the Yang-Baxter Equation with $U_q(\mathfrak{sl}_n)$ Symmetry

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Introduction



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- Yang-Baxter Equation (YBE) - RLL -method



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- ▶ Symmetry Algebras:



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 - ▶ Undeformed: \mathfrak{sl}_n - Differential Representation



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 - ▶ q -Deformed: $U_q(\mathfrak{sl}_n)$ - q -Difference Representations



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- ▶ Parameter Permutation and YBE



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- ▶ Symmetry Algebras:
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- ▶ Parameter Permutation and YBE
 - ▶ Permutation Operators
 - ▶ Symmetric Group Relations



Yang-Baxter Equation

The (parameter dependent) YBE on $\text{End}(V_1 \otimes V_2 \otimes V_3)$ is

$$\begin{aligned} R_{V_1, V_2}(u_1, u_2) R_{V_1, V_3}(u_1, u_3) R_{V_2, V_3}(u_2, u_3) \\ = R_{V_2, V_3}(u_2, u_3) R_{V_1, V_3}(u_1, u_3) R_{V_1, V_2}(u_1, u_2), \end{aligned}$$

$(R_{V_i, V_j}(u_i, u_j) \text{ invertible}).$

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$(R_{V_i, V_j}(u_i, u_j))$ invertible).

Additive dependence $\Rightarrow R_{V_i, V_j}(u_i, u_j) = R_{V_i, V_j}(u_i - u_j)$

$$R_{V_1, V_2}(u - v) R_{V_1, V_3}(u) R_{V_2, V_3}(v) = R_{V_2, V_3}(v) R_{V_1, V_3}(u) R_{V_1, V_2}(u - v).$$

Yang-Baxter Equation

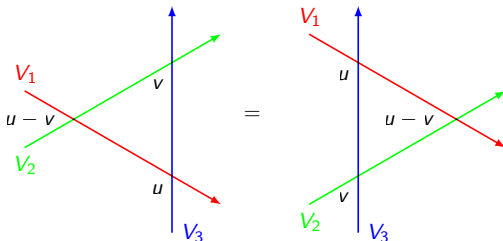
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RLL -Method


Our Goal: construct an R -matrix $\mathcal{R}(u) \in \text{End}(\mathcal{V} \otimes \mathcal{V})$,

$$\mathcal{R}_{12}(u) = \begin{array}{c} \begin{array}{c} \uparrow \\ \text{---} \text{---} \text{---} \end{array} \\ \begin{array}{c} \text{---} \text{---} \text{---} \\ \downarrow \end{array} \end{array}.$$

1
 u
2


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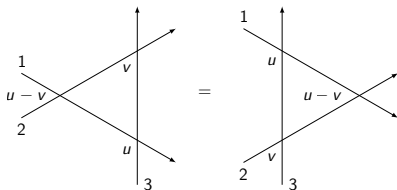
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
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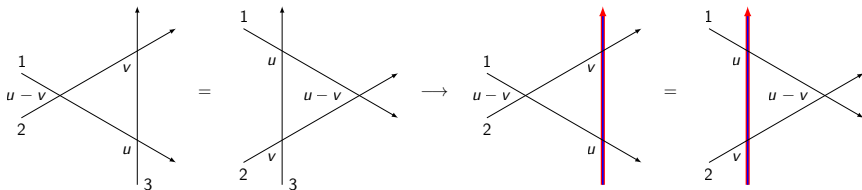
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
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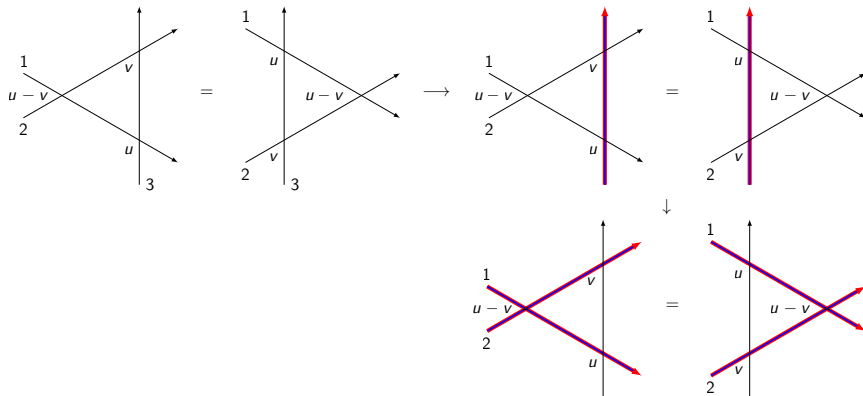
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
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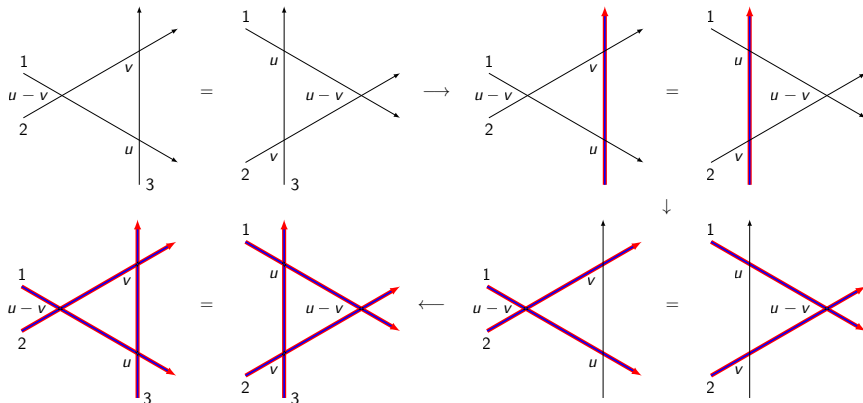
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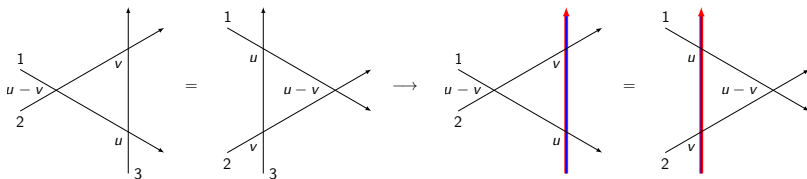
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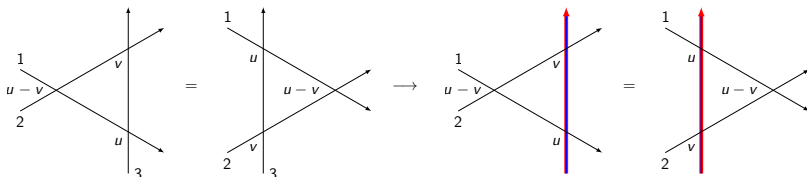
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Fundamental R -Matrix and L -operators

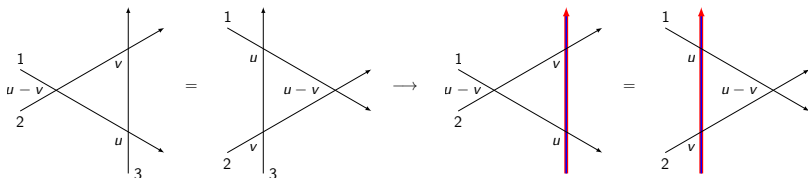


Fundamental R -Matrix and L -operators



This requires two matrices:

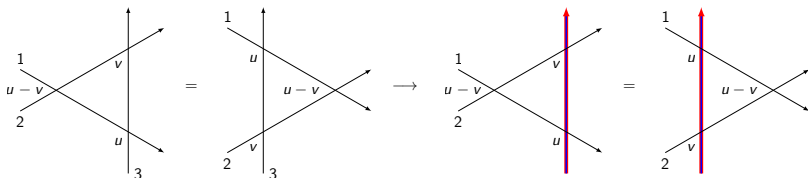
Fundamental R -Matrix and L -operators



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► $R_{12}(u) = \begin{array}{c} \nearrow \\ \text{1} \quad \text{u} \\ \text{---} \\ \text{2} \end{array} \in \text{End}(\mathbb{C}^n \otimes \mathbb{C}^n) \text{ (an } n^2 \times n^2 \text{ matrix).}$

Fundamental R -Matrix and L -operators



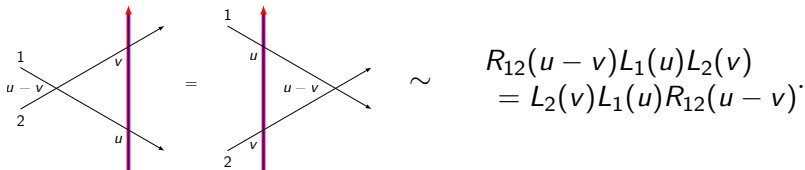
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► $L_1(u) = \begin{array}{c} 1 \\ \diagup \quad \diagdown \\ u \\ \diagdown \quad \diagup \\ 2 \end{array} \in \text{End}(\mathbb{C}^n) \otimes \mathcal{A}, \text{ where } \mathcal{A} \subset \text{End}(\mathcal{V}). \text{ An } n \times n \text{ matrix with values in } \mathcal{A}.$

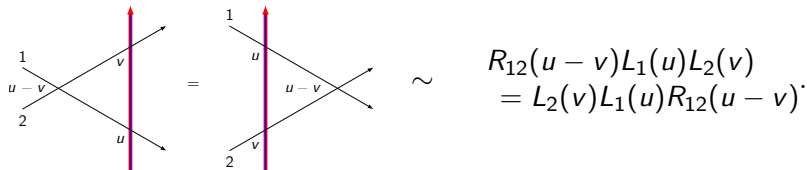


Fundamental R -Matrix and Universal L -operators



$$\begin{array}{c}
 \begin{array}{c} 1 \\ u-v \\ 2 \end{array} \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} v \\ \text{red line} \end{array} = \begin{array}{c} 1 \\ u \\ 2 \end{array} \begin{array}{c} \searrow \\ \nearrow \end{array} \begin{array}{c} v \\ \text{red line} \end{array} \sim \\
 R_{12}(u-v)L_1(u)L_2(v) \\
 = L_2(v)L_1(u)R_{12}(u-v)
 \end{array}$$

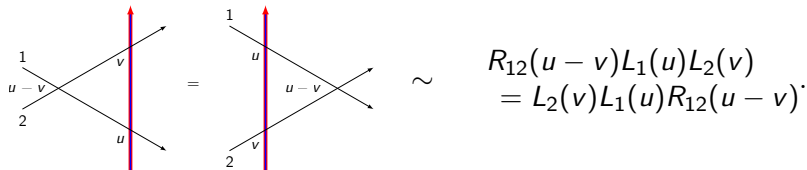
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$$\begin{array}{c}
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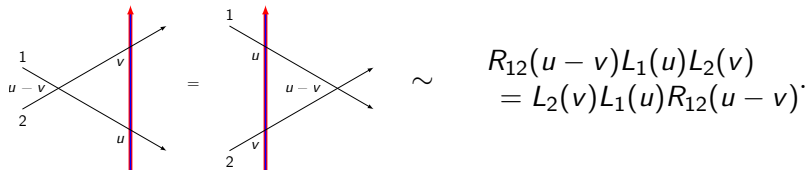


$$\begin{array}{c} \text{Diagram 1} \end{array} = \begin{array}{c} \text{Diagram 2} \end{array} \sim R_{12}(u-v)L_1(u)L_2(v) = L_2(v)L_1(u)R_{12}(u-v)$$

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$$(L_1(u)L_2(v))_{ij,lk} = L_{i,l}(u)L_{j,k}(v).$$

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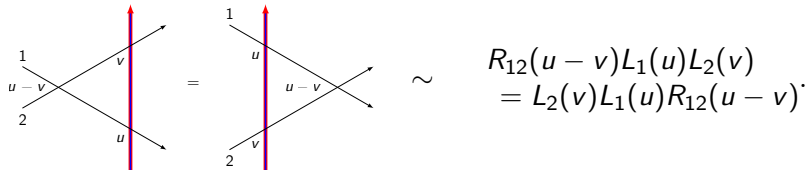
$$\begin{array}{c} \text{Diagram 1: Crossing of lines 1 and 2, with parameters } u \text{ and } v, \text{ separated by a vertical red line.} \\ \text{Diagram 2: Crossing of lines 1 and 2, with parameters } v \text{ and } u, \text{ separated by a vertical red line.} \end{array}
 =
 \begin{array}{c} \text{Diagram 3: Crossing of lines 1 and 2, with parameters } u \text{ and } v, \text{ separated by a vertical red line.} \end{array}
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\Rightarrow RLL relation reduces to quadratic algebra relations. Can think of it as expressing the defining algebra relations for \mathcal{A} .

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Why YBE for R ? This is a consistency condition for associativity of \mathcal{A} .



Undeformed Case: \mathfrak{sl}_n



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The universal enveloping algebra (UEA) $\mathcal{A} = U(\mathfrak{sl}_n)$ has a fundamental R -matrix

$$R_{12}(u) = u \cdot \text{id}_{n^2} + P_{12} : \mathbb{C}^n \otimes \mathbb{C}^n \rightarrow \mathbb{C}^n \otimes \mathbb{C}^n,$$

where, P_{12} is the flip $P_{12}(x_1 \otimes x_2) = x_2 \otimes x_1$,



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where, P_{12} is the flip $P_{12}(x_1 \otimes x_2) = x_2 \otimes x_1$, and a universal L -operator

$$L(u) = u \cdot \text{id}_n \otimes 1_{\mathcal{A}} + \sum_{i,j=1}^n e_{ij} \otimes E_{ji},$$

where e_{ij} is the matrix unit.



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where e_{ij} is the matrix unit. Here $\{E_{ij}\}$ is the Cartan-Weyl basis for \mathfrak{sl}_n :

$$h_i = E_{ii} - E_{i+1,i+1}, \quad \sum_i E_{ii} = 0, \quad E_{i,i+1} = e_i, \quad E_{i+1,i} = f_i, \\ [E_{ij}, E_{kl}] = \delta_{jk} E_{il} - \delta_{ik} E_{lj}.$$



Differential Representation of \mathfrak{sl}_n

For n -parameters $\boldsymbol{\rho} \in \mathbb{C}^n$ with $\sum_i \rho_i = n(n-1)/2$, we can define a representation on $\mathbb{C}[x_{ij} \mid 1 \leq j < i \leq n]$



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$$Z = \begin{pmatrix} 1 & & & & \\ x_{21} & 1 & & & \\ x_{31} & x_{32} & 1 & & \\ \vdots & \vdots & \ddots & \ddots & \\ x_{n1} & x_{n2} & \dots & x_{n,n-1} & 1 \end{pmatrix}, \quad D(-\boldsymbol{\rho}) = \begin{pmatrix} -\rho_n & P_{21} & P_{31} & \dots & P_{n1} \\ & -\rho_{n-1} & P_{32} & \dots & P_{n2} \\ & & \ddots & \ddots & \vdots \\ & & & -\rho_2 & P_{n,n-1} \\ & & & & -\rho_1 \end{pmatrix},$$



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where the P_{ij} are first order linear differential operators:

$$P_{ij} = -\partial_{ij} - \sum_{k=i+1}^n x_{ki} \cdot \partial_{kj}.$$



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[Derkachov and Manashov, 2006]



Differential Representation of \mathfrak{sl}_n

E.g. $n = 2$ case: Taking $N_x = x\partial_x$ and $m = \rho_2 - \rho_1 + 1$,

$$f = -\partial_x, \quad e = x \cdot (N_x + m), \quad h = 2N_x + m.$$



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- ▶ It is reducible if some $m_i \in \mathbb{Z}_{\leq 0}$. It contains a finite dimensional irreducible subrep iff true for all m_i .
- ▶ It has a factorised L -operator!

$$L(\mathbf{u}) = ZD(\mathbf{u})Z^{-1} = \begin{array}{c} \uparrow \\ \text{---} u \text{---} \\ \downarrow \end{array},$$

$$\mathbf{u} = (u_i), \text{ where } u_i = u - \rho_i.$$



q -Deformed Case: $U_q(\mathfrak{sl}_n)$

The q -deformed UEA $U_q(\mathfrak{sl}_n)$: For some $q = e^h \in \mathbb{C} \setminus \{0, \pm 1\}$



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The q -deformed UEA $U_q(\mathfrak{sl}_n)$: For some $q = e^h \in \mathbb{C} \setminus \{0, \pm 1\}$

- Generators: e_i, f_i , and invertible $k_i = q^{h_i}$ for $i = 1, 2, \dots, n-1$
- Relations:

$$[k_i, k_j] = 0, \quad k_i e_j k_i^{-1} = q^{a_{ij}} e_j, \quad k_i f_j k_i^{-1} = q^{a_{ij}} f_j,$$

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- Notation: $[x]_q = (q^x - q^{-x}) / (q - q^{-1})$



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Now specialise:

Is there an analogous class of representations for $U_q(\mathfrak{sl}_n)$? How about a factorised L -operator?



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\mathfrak{sl}_n : differential representation $\leftrightarrow U_q(\mathfrak{sl}_n)$: “ q -difference”
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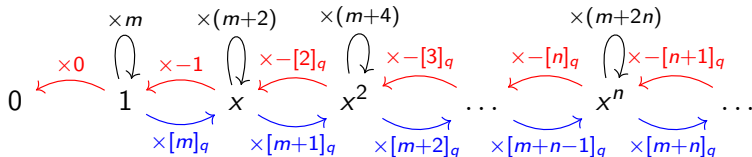
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$n = 2$ case: Just one variable $x_{21} = x$

$$f = -D_x, \quad e = x[m + N_x]_q, \quad h = 2N_x + m,$$





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$$e_i^{(n)}$$

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[Awata, Noumi, and Odake, 1994]



Factorised L -operator?



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$$\underline{\mathfrak{sl}_n}: L(\mathbf{u}) = ZD(\mathbf{u})Z^{-1}$$

$$Z = \begin{pmatrix} 1 & & & & \\ x_{21} & 1 & & & \\ x_{31} & x_{32} & 1 & & \\ \vdots & \vdots & \ddots & \ddots & \\ x_{n1} & x_{n2} & \dots & x_{n,n-1} & 1 \end{pmatrix}, \quad D(\mathbf{u}) = \begin{pmatrix} u_n & P_{21} & P_{31} & \dots & P_{n1} \\ & u_{n-1} & P_{32} & \dots & P_{n2} \\ & & \ddots & \ddots & \vdots \\ & & & u_2 & P_{n,n-1} \\ & & & & u_1 \end{pmatrix},$$



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$$\underline{U_q(\mathfrak{sl}_n)}: \text{Postulate } L(\mathbf{u}) = Z_1(\mathbf{u})D(\mathbf{u})Z_2(\mathbf{u})^{-1}$$

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$$P_{ij} = -D_{ij}q^{b_{ij}} - \sum_{k=i+1}^n x_{ki} D_{kj} q^{b_{ijk}}, \quad Z_i(\mathbf{u}) = \begin{pmatrix} 1 & & & \\ x_{21} q^{a_{21}^{(i)}} & 1 & & \\ \vdots & \ddots & \ddots & \\ x_{n1} q^{a_{n1}^{(i)}} & \dots & x_{n,n-1} q^{a_{n,n-1}^{(i)}} & 1 \end{pmatrix},$$



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$n=2$: Yes [Derkachov, Karakhanyan, and Kirschner, 2007]

$$L(u_1, u_2) = \begin{pmatrix} 1 & 0 \\ q^{u_1 - N_x} & 1 \end{pmatrix} \begin{pmatrix} [u_2]_q q^{-N_x - 1} & -D_x q^{N_x} \\ 0 & [u_1]_q q^{N_x} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -q^{u_2 - N_x} & 1 \end{pmatrix}.$$



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$n=3$: Yes [Valinevich et al., 2008], $L(u_1, u_2, u_3) = Z_1 D Z_2^{-1}$ with

$$D = \begin{pmatrix} [u_3]_q q^{-N_{21} + N_{31}} & (D_{21} + x_{32} D_{31} q^{N_{31} - N_{32} - 1}) q^{N_{21} + N_{31}} & D_{31} q^{N_{31}} \\ 0 & [u_2]_q q^{N_{21} - N_{32}} & D_{32} q^{u_2 - N_{31} + N_{32}} \\ 0 & 0 & [u_1]_q q^{N_{32} + N_{31}} \end{pmatrix},$$

$$Z_1 = \begin{pmatrix} 1 & 0 & 0 \\ q^{u_2 - N_{31} + N_{32} - N_{21}} x_{21} & 1 & 0 \\ q^{-u_1 - N_{31} + N_{32}} x_{31} & q^{u_1 - u_2 - N_{32}} x_{32} & 1 \end{pmatrix}, \quad Z_2 = \begin{pmatrix} 1 & 0 & 0 \\ q^{c_{21}} x_{21} & 1 & 0 \\ q^{c_{31}} x_{31} & q^{c_{32}} x_{32} & 1 \end{pmatrix},$$

$$c_{21} = u_3 - N_{21}, \quad c_{31} = -u_3 - N_{31} - N_{21} - 1, \quad c_{32} = N_{21} + N_{31} - N_{32}.$$



Factorised L -operator?

$n=4$:



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“Controlled deformation” breaks - We have “pure quantum phenomena” in the Cartan-Weyl elements:

$$E_{42} = [f_3, f_2]_q = -D_{42}q^{N_{21}-N_{32}-N_{41}-1} - x_{21}D_{41}q^{-(1+N_{31})} \\ + (q - q^{-1})x_{31}D_{41}D_{32}q^{N_{21}-N_{31}-1}.$$

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Such terms cannot arise from our ansatz.



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$n=4$: A modified factorisation $L(\mathbf{u}) = Z_1(\mathbf{u})D(\mathbf{u})Z_2(\mathbf{u})^{-1}$

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Factorised L -operator?

General n : Order of highest term in $(q - q^{-1})$

$$\mathcal{O}(L^+(\mathbf{u})) \sim \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\ & & 0 & 0 & 1 & 2 & 2 & 2 \\ & & & 0 & 0 & 1 & 2 & 3 \\ & & & & 0 & 0 & 1 & 2 \\ & & & & & 0 & 0 & 1 \\ & & & & & & 0 & 0 \\ & & & & & & & 0 \end{pmatrix}$$

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Potentially can be factored further into elementary row/column matrices which are only first order.

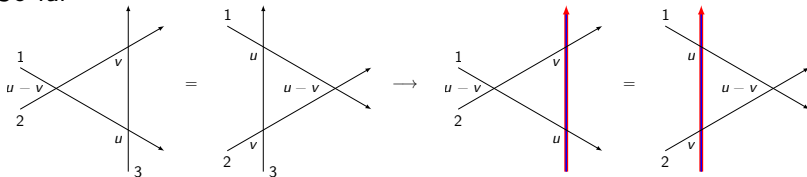


Parameter Permutations and YBE



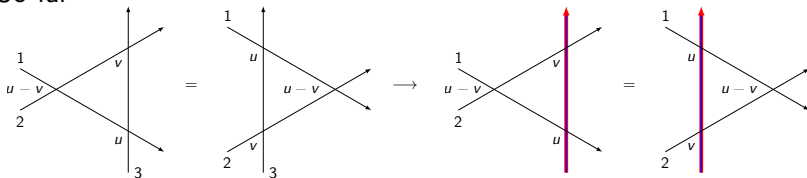
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
So far



Parameter Permutations and YBE

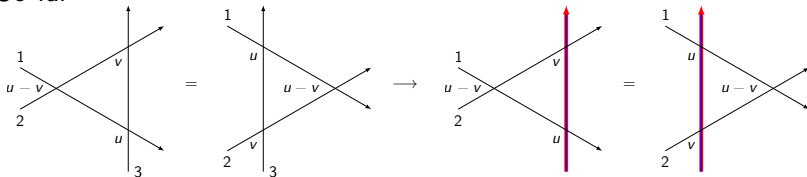
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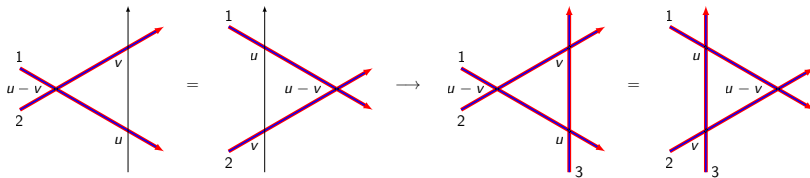
Now we're seeking $\mathcal{R}(u) =$

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Parameter Permutations and YBE

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Parameter Permutations and YBE

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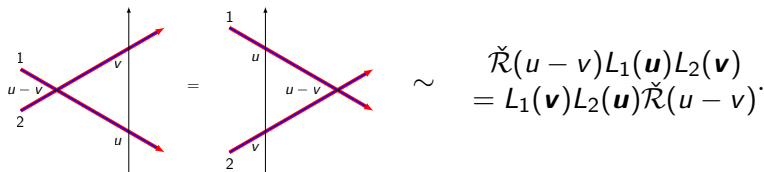
Parameter Permutations and YBE

For $\check{\mathcal{R}}(u) := P \circ \mathcal{R}(u) \in \text{End}(\mathcal{V}_\rho \otimes \mathcal{V}_\sigma)$ the defining RLL -relation is

$$\begin{array}{c} \text{Diagram 1} \end{array} = \begin{array}{c} \text{Diagram 2} \end{array} \sim \check{\mathcal{R}}(u-v) L_1(\mathbf{u}) L_2(\mathbf{v}) = L_1(\mathbf{v}) L_2(\mathbf{u}) \check{\mathcal{R}}(u-v).$$

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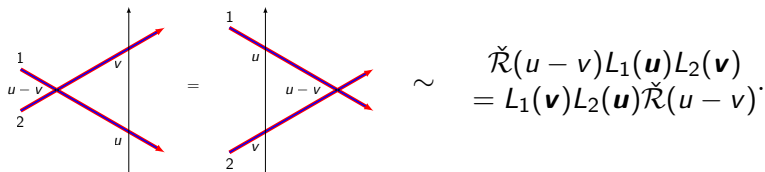


$$\begin{array}{c} 1 \\ u-v \\ 2 \end{array} \begin{array}{c} \nearrow \\ \searrow \end{array} \begin{array}{c} v \\ u \end{array} = \begin{array}{c} 1 \\ u \\ 2 \end{array} \begin{array}{c} \searrow \\ \nearrow \end{array} \begin{array}{c} u-v \\ v \end{array} \sim \check{\mathcal{R}}(u-v)L_1(\mathbf{u})L_2(\mathbf{v}) \\ = L_1(\mathbf{v})L_2(\mathbf{u})\check{\mathcal{R}}(u-v).$$

$\check{\mathcal{R}}$ realises the permutation $(\mathbf{u}, \mathbf{v}) \mapsto (\mathbf{v}, \mathbf{u}) \in \text{Perm}(\mathbf{u}, \mathbf{v}) \simeq S_{2n}$.

Parameter Permutations and YBE

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IDEA: Factorise $\check{\mathcal{R}}(u-v)$ in terms of elementary transposition operators $\mathcal{S}_i \in \text{End}(\mathcal{V}_\rho \otimes \mathcal{V}_\sigma)$

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Simplification: Can just find $n - 1$ -“intertwining” operators

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and a single “exchange” operator:

$$\mathcal{S}_n(\mathbf{u}, \mathbf{v}) L_{12}(\mathbf{u}, \mathbf{v}) = \mathcal{S}_n(\mathbf{u}, \mathbf{v}) L_{12}(u_1, \dots, u_{n-1}, v_1, u_n, v_2, \dots, v_n).$$



Parameter Permutations and YBE



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These operators should define an action of S_{2n} , i.e.,

$$s_{i_j} \dots s_{i_2} s_{i_1} \mapsto \mathcal{S}_{i_j}(s_{i_{j-1}} \dots s_{i_1}(\mathbf{u}, \mathbf{v})) \dots \mathcal{S}_{i_2}(s_{i_1}(\mathbf{u}, \mathbf{v})) \mathcal{S}_{i_1}(\mathbf{u}, \mathbf{v}),$$

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YBE then follows from equivalence of the decompositions in $\text{Perm}(\mathbf{u}, \mathbf{v}, \mathbf{w})$

$$(\mathbf{u}, \mathbf{v}, \mathbf{w}) \xrightarrow{\check{\mathcal{R}}_{12}} (\mathbf{v}, \mathbf{u}, \mathbf{w}) \xrightarrow{\check{\mathcal{R}}_{23}} (\mathbf{v}, \mathbf{w}, \mathbf{u}) \xrightarrow{\check{\mathcal{R}}_{12}} (\mathbf{w}, \mathbf{v}, \mathbf{u}),$$

$$(\mathbf{u}, \mathbf{v}, \mathbf{w}) \xrightarrow{\check{\mathcal{R}}_{23}} (\mathbf{u}, \mathbf{w}, \mathbf{v}) \xrightarrow{\check{\mathcal{R}}_{12}} (\mathbf{w}, \mathbf{u}, \mathbf{v}) \xrightarrow{\check{\mathcal{R}}_{23}} (\mathbf{w}, \mathbf{v}, \mathbf{u}).$$



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$U_q(\mathfrak{sl}_2)$ Case: [Derkachov, Karakhanyan, and Kirschner, 2007]

$U_q(\mathfrak{sl}_3)$ Case: [Valinevich et al., 2008]



q -Deformed Case

Proposition

The intertwiners for the $U_q(\mathfrak{sl}_n)$ ($|q| < 1$) L -operator are given by

$$\mathcal{T}_{n-i}^{(n)}(\alpha) = \left(\Lambda_{n-i}^{(n)} \right)^\alpha \frac{e_{q^2}(q^{2(N_{i+1,i}+1)} \mathbf{x}_{n-i}^{(n)})}{e_{q^2}(q^{2(N_{i+1,i}+1-\alpha)} \mathbf{x}_{n-i}^{(n)})},$$

$$e_{q^2}(\mathbf{Z}) = ((\mathbf{Z}; q^2)_\infty)^{-1} = [(1 - \mathbf{Z})(1 - q^2 \mathbf{Z})(1 - q^{2 \cdot 2} \mathbf{Z}) \dots]^{-1},$$

$$\frac{e_{q^2}(\mathbf{Z})}{e_{q^2}(q^{-\alpha} \mathbf{Z})} = \sum_{j=0}^{\infty} \frac{(q^{-\alpha}; q)_j}{(q; q)_j} \mathbf{Z}^j, \quad \Lambda_{n-i}^{(n)} = (x_{i+1,i})^{-1} q^{\beta_i}$$

where $\alpha = u_{n-i} - u_{n+1-i}$, and

$$\mathbf{x}_{n-i}^{(n)} = 1 + x_{i+1,i} \sum_{j=i+2}^n \frac{x_{j,i+1}}{x_{ji}} (q^{N_{ij}} - q^{-N_{ij}}) q^{\gamma_i}.$$



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Obtained using an approach from [Valinevich et al., 2008].



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Proof.

The only non-trivial relation is the braid relation

$$\mathcal{T}_i(\alpha)\mathcal{T}_{i+1}(\alpha + \beta)\mathcal{T}_i(\beta) = \mathcal{T}_{i+1}(\beta)\mathcal{T}_i(\alpha + \beta)\mathcal{T}_{i+1}(\alpha).$$

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After a series expansion it is reduced to a family of (terminating) q -series identity relating rank $i + 1$ and rank $2i - 1$ q -Lauricella series. □



q -Series Identity



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(Type D) q -Lauricella Function: q -Lauricella functions are a family of multivariable hypergeometric series:



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$$\begin{aligned}
& \Phi_D^{(n)}[b; a_1, \dots, a_n; c; q; x_1, \dots, x_n] \\
&= \sum_{m_1=0}^{\infty} \dots \sum_{m_n=0}^{\infty} \frac{(b; q)_M (a_1; q)_{m_1} \dots (a_n; q)_{m_n}}{(c; q)_M (q; q)_{m_1} \dots (q; q)_{m_n}} x_1^{m_1} \dots x_n^{m_n}, \quad (\star)
\end{aligned}$$

where $M = \sum_{i=1}^n m_i$ and

$$(x; q)_m = (1 - x)(1 - qx) \dots (1 - q^{m-1}x).$$



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[Andrews, 1972] gives a general transformation formula allowing us to rewrite (\star) in terms of a ${}_{n+1}\phi_n$ hypergeometric series.



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For $n \geq 1$ and non-negative integer tuples

$$\mathbf{k} = (k_0, \dots, k_n) = (k_0, \tilde{\mathbf{k}}), \quad \mathbf{l} = (l_1, \dots, l_n), \quad \mathbf{m} = (m_1, \dots, m_{n-1}),$$

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The identity we need is the equality $\Theta_{\mathbf{k}, \mathbf{l}, \mathbf{m}} = \Omega_{\mathbf{k}, \mathbf{l}, \mathbf{m}}$

$$\Theta_{\mathbf{k}, \mathbf{l}, \mathbf{m}} = \frac{(\xi; q)_{L+M}}{(\xi \zeta; q)_{L+M}} \Phi_D^{(2n-1)} \left[\zeta; q^{-\mathbf{l}}, q^{-\mathbf{m}}; q^{1-L-M}/\xi; q^{\mathbf{r}+\mathbf{l}+(\mathbf{m}, 0)}, q^{(\mathbf{r}_i, \hat{r}_n)+\mathbf{m}} \right],$$

$$\Omega_{\mathbf{k}, \mathbf{l}, \mathbf{m}} = \zeta^{k_0} \frac{(\xi; q)_K}{(\xi \zeta; q)_K} \Phi_D^{(n+1)} \left[\zeta; q^{-\mathbf{k}}; q^{1-K}/\xi; q^{1+k_0-K}/(\xi \zeta), q^{\mathbf{p}+\tilde{\mathbf{k}}} \right],$$

for arbitrary complex parameters ξ, ζ .



Exchange Operator



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$$S_n L_1(\textcolor{red}{u}_n) L_2(\textcolor{green}{v}_1) = L_1(\textcolor{green}{v}_1) L_2(\textcolor{red}{u}_n) S_n.$$

Recall the (postulated) factorisation for $L(\mathbf{u})$. This can be put into the form:

$$L_1(\mathbf{u}) = Z_1(\textcolor{green}{u}_1) D Z_2(\textcolor{red}{u}_n)^{-1}.$$



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Now we can reduce the defining relation to

$$\begin{aligned} Z_2^{(x, \tilde{\mathbf{u}})}(\mathbf{v}_1) \left[(D^{(x, \tilde{\mathbf{u}})})^{-1} S_n D^{(x, \tilde{\mathbf{u}})} \right] \left(Z_2^{(x, \tilde{\mathbf{u}})}(\mathbf{u}_n) \right)^{-1} \\ = Z_1^{(y, \tilde{\mathbf{v}})}(\mathbf{u}_n) \left[D^{(y, \tilde{\mathbf{v}})} S_n (D^{(y, \tilde{\mathbf{v}})})^{-1} \right] \left(Z_1^{(y, \tilde{\mathbf{v}})}(\mathbf{v}_1) \right)^{-1}, \end{aligned}$$

if $S_n^{(x, y)}$ commutes (element wise) with $Z_1^{(x)}$ and $Z_2^{(y)}$.



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Recall in the $n \geq 4$ case the postulated ansatz for the factorisation was inconsistent - the outer most factors will now have q -difference terms.



Exchange Operator

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Recall in the $n \geq 4$ case the postulated ansatz for the factorisation was inconsistent - the outer most factors will now have q -difference terms.

This seems to represent a serious obstruction to constructing the exchange operator - unclear whether to expect a multiplication operator (by shifted variables) to work or not



Summary



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- We introduced the RLL -method as a means for obtaining solutions to the YBE in the class of differential (q -difference) representations of \mathfrak{sl}_n ($U_q(\mathfrak{sl}_n)$). A key feature here is a factorisation property of the L -operators.



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- ▶ We described explicitly all but one of the transposition operators in the $U_q(\mathfrak{sl}_n)$ case, and prove they obey the necessary symmetric group relations.
- ▶ We explain how the failure of the factorisation property for the $U_q(\mathfrak{sl}_4)$ L -operator represents an obstruction to constructing the missing “exchange” operator.



Thank You!










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Questions?



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