

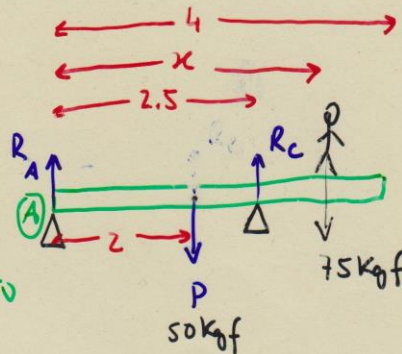
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$$\left. \begin{aligned} \sum \vec{F}_i &= 0 \\ \sum \vec{\tau}_i &= 0 \end{aligned} \right\} \text{EQUILIBRIO ESTATICO}$$

$$\Rightarrow R_A - 50 + R_C - 75 = 0$$

$$\Rightarrow 0 \times R_A - 2 \times 50 + 2.5 R_C - 75 \times x = 0$$

MOMENTOS CALCULADOS EM RELAÇÃO  
AO PONTO (A).



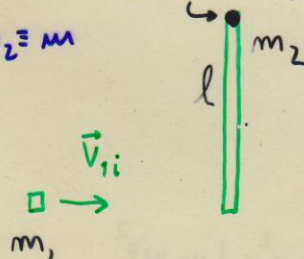
$$\Rightarrow R_C = 125 \text{ kgf}$$

$$x = 2.83 \text{ m}$$

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$$m_1 = m_2 = m$$

EIXO DE ROTAÇÃO



ANTES DO CHOQUE

$$L_{1i} = m_1 v_{1i} l ; L_{2i} = 0$$

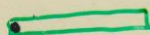
DEPOIS DO CHOQUE

$$\begin{aligned} L_f &= I_{\text{SIST.}} \omega = (I_1 + I_2) \omega \\ &= \left( \frac{1}{3} m l^2 + m l^2 \right) \omega \\ &= \frac{4}{3} m l^2 \omega \end{aligned}$$

BARRA:

$$I_{CM} = \frac{1}{12} M l^2$$

$$\begin{aligned} I &= I_{CM} + M \left( \frac{l}{2} \right)^2 \\ &= \frac{1}{3} M l^2 \end{aligned}$$



CONSERVAÇÃO DE L:

$$L_i = L_f \Rightarrow m v_{1i} l = \frac{4}{3} m l^2 \omega$$

$$\Rightarrow \omega = \frac{3}{4} \frac{v_{1i}}{l}$$

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IMEDIATAMENTE DEPOIS DO CHOQUE

$$L_i = \left( \frac{4}{3} m l^2 \right) \omega \quad (\text{DO PROB. 24})$$

$I_{\text{sist.}}$

NO FINAL ( $V=0$ )

$$L_f = 0$$

b)

$$\tau = I_{\text{sist.}} \alpha \Rightarrow \alpha = \frac{\tau}{I_{\text{sist.}}} = \frac{\tau}{\frac{4}{3} m l^2} = \frac{3 \tau}{4 m l^2}$$

a) EQ. CINEMÁTICAS DE ROTAÇÃO

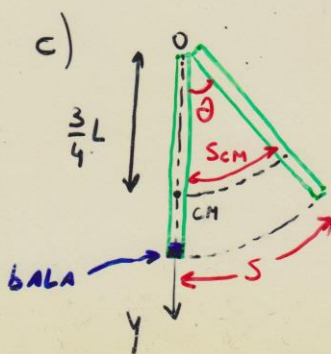
$$\begin{cases} \theta = \theta_0 + \omega_0 t - \frac{1}{2} \alpha t^2 \\ \omega = \omega_0 - \alpha t \end{cases} \Rightarrow \begin{cases} \theta = \omega_0 t - \frac{1}{2} \alpha t^2 \\ 0 = \omega_0 - \alpha t \end{cases} \Rightarrow \begin{cases} \frac{S}{l} = \omega_0 t - \frac{1}{2} \alpha t^2 \\ t = \frac{\omega_0}{\alpha} \end{cases}$$

$$\frac{S}{l} = \omega_0 \left( \frac{\omega_0}{\alpha} \right) - \frac{1}{2} \alpha \left( \frac{\omega_0}{\alpha} \right)^2 = \frac{1}{2} \frac{\omega_0^2}{\alpha}$$

$\omega_0 = \frac{3}{4} \frac{V_{ii}}{l}$  (DO PROB 24)

$$\frac{S}{l} = \frac{\left( \frac{3}{4} \frac{V_{ii}}{l} \right)^2}{2 \left( \frac{3 \tau}{4 m l^2} \right)} \Rightarrow S = \frac{3 m l V_{ii}^2}{8 \tau}$$

CORRIGIR SOLUÇÃO NAS FOLHAS TP.



$$y_{\text{CM}} = \frac{\sum m_i r_i^2}{\sum m_i} = \frac{m \frac{l}{2} + m l}{m + m} = \frac{3}{4} l$$

$$S = \theta l \Rightarrow \theta = \frac{S}{l}$$

$$S_{\text{CM}} = \theta \frac{3}{4} l$$

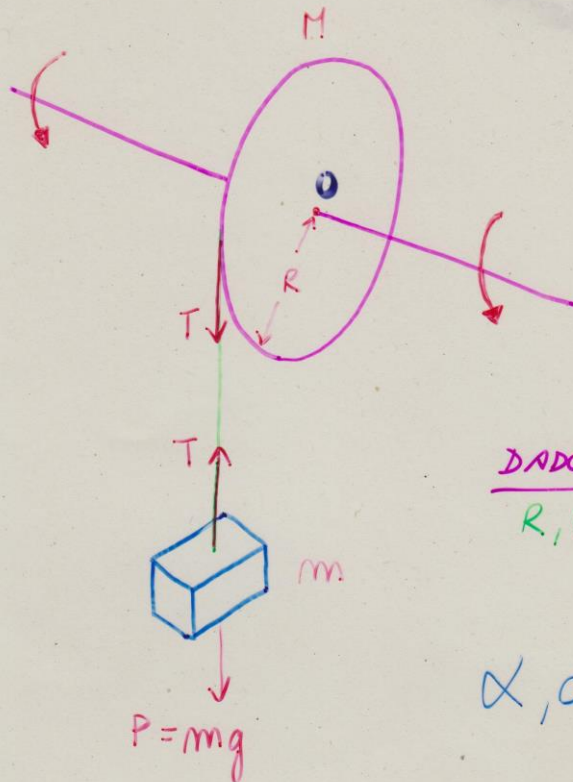
$$\Rightarrow S_{\text{CM}} = \frac{S 3 l}{4 l} = \frac{3}{4} S$$

**EXEMPLO**

PARA RESOLVER PROBLEMAS 19, 20 e 21 do

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CAP. 6.



DADOS SÃO:

$R, M, I$  e  $m$

$\alpha, a$  e  $T = ?$

$$\tau_{\text{total}} = I\alpha = T \cdot R \Rightarrow \alpha = \frac{TR}{I}$$

APLICANDO 2ª LEI DE NEWTON:

$$\sum F = T - mg = -ma \Rightarrow a = \frac{mg - T}{m}$$

$$a = R\alpha = \frac{TR^2}{I} = \frac{mg - T}{m}$$

$$\Rightarrow T = \frac{mg}{1 + \frac{mR^2}{I}} ; a = \frac{g}{1 + \frac{I}{mR^2}} ; \alpha = \frac{a}{R} = \frac{g}{R + \frac{I}{mR}}$$



### PROB 19

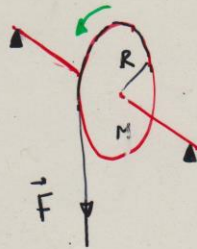
$$M = 20 \text{ kg}$$

$$R = 0.5 \text{ m}$$

$$\vec{F} = 9.8 \text{ N}$$

$$\alpha = ?$$

$$\omega(2) = ?$$



$$\gamma = I\alpha = TR$$

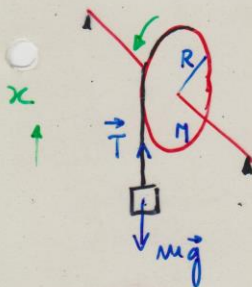
$$\Leftrightarrow \alpha = \frac{TR}{I} \quad \text{onde } \vec{T} \equiv \vec{F}$$

$$\Leftrightarrow \alpha = \frac{9.8 \times 0.5}{\frac{1}{2} \times 20 \times 0.5^2} = 1.96 \text{ rad/s}^2$$

$$\alpha = \frac{d\omega}{dt}, \text{ integrando: } \omega = \omega_0 + \alpha t \quad (\omega_0 = 0)$$

$$\omega = \alpha t = 1.96 \times 2 = 3.92 \text{ rad/s}$$

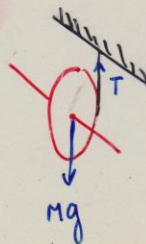
### PRO 20



$$\alpha = \frac{a}{R} = \frac{g}{R + \frac{I}{MR}} = \frac{9.8}{0.5 + \frac{\frac{1}{2} \times 20 \times 0.5^2}{1 \times 0.5}}$$

$$\Leftrightarrow \alpha = 1.8 \text{ rad/s}^2$$

### PRO 21



$$\alpha = \frac{TR}{I + MD^2} = \frac{20 \times 9.8 \times 0.5}{\frac{1}{2} \times 20 \times 0.5^2 + 20 \times 0.5^2} = 13.1 \text{ rad/s}^2$$

TEOREMA  
DE  
STEINER

$$a = \alpha R = 13.1 \times 0.5 = 6.5 \text{ m/s}^2$$