Modbus Wizard - Read Me

Introduction

This document provides an overview of the Modbus Wizard program, its functionalities, and instructions on how to make it executable. The program integrates three main functionalities into a single tool for working with Modbus devices: Modbus TCP Register Scan, Brute Force Connection for Modbus RTU Devices, and Modbus RTU Scanner.

Libraries and Their Versions

Library	Version	Purpose
Tkinter	Built-in Python library	Provides the GUI framework for creating windows, dialogs, buttons, and other interface elements.
Pymodbus	2.5.3	A Python library for Modbus protocol support, enabling communication with Modbus devices. The specific version is required for the RTU handshake.
MinimalModbus	2.1.1	A simple and easy-to-use Modbus RTU/ASCII implementation for Python, used for the auto-detection wizard to brute force connection parameters.
PySerial	3.5	Provides serial port communication capabilities, used for the RTU connection.
Logging	Built-in Python library	Provides logging capabilities to track and debug the execution of the program.
Threading	Built-in Python library	Used to handle concurrent execution, allowing the program to perform scans in the background.
Struct	Built-in Python library	Provides functions to convert between Python

values and C structs represented as Python

bytes objects.

Time Built-in Python library Used to handle timing

functions such as delays.

FileDialog Built-in Python library Provides file dialog

interfaces to save and load

files.

Explanation of the Program

Modbus TCP Register Scan

Objective: Implement a comprehensive scan of all available registers on a Modbus TCP device. This is crucial because the registers provided by the manufacturer may sometimes be inaccurate or incomplete.

Implementation:

- Scan all available registers from the start to the end address.
- Include any register that is defined on the device.
- If a register is not defined, mark it as 'not defined'.
- The results are displayed in the GUI, showing defined and undefined registers.

Brute Force Connection for Modbus RTU Devices

Objective: Establish a connection to Modbus RTU devices when communication parameters (baud rate, parity, stop bits) are unknown.

Implementation:

- Use a brute force approach to try all possible communication settings (baud rate, parity, stop bits) until a successful connection is established.
- Display the connection settings used upon successful connection.
- The auto-detection wizard attempts various combinations of settings and scans the registers to verify connectivity.

Modbus RTU Scanner

Objective: Scan Modbus RTU devices using known communication parameters.

Implementation:

- Allow the user to specify the communication parameters (port, baud rate, parity, data bits, stop bits, timeout).
- Connect to the device and scan the specified range of registers.
- Display the defined and undefined registers in the GUI.
- Support for multiple formats (decimal, binary, hex, float, etc.) for displaying register values.

Drive to Make the Program

The motivation behind creating this program is to provide a comprehensive and user-friendly tool for working with Modbus devices. Many existing tools rely on manufacturer-provided registers and known communication parameters, which may not always be accurate or available. This program addresses these limitations by:

1. Ensuring Comprehensive Scans:

- Scanning all available registers ensures that users can identify all active registers on their Modbus devices, even if the manufacturer's documentation is incomplete or inaccurate.

2. Brute Force Connection:

- The brute force approach for Modbus RTU devices ensures that users can establish a connection even when the communication parameters are unknown, which is a common challenge in fieldwork.

3. Ease of Use:

- The integrated GUI makes it easy for users to interact with their Modbus devices without needing to write code or use complex command-line tools. The tool is designed to be accessible to both technical and non-technical users.

By combining these functionalities into a single program, users are provided with a robust and versatile tool for their Modbus communication needs.

Modbus Wizard - Modbus TCP Scanner User Guide

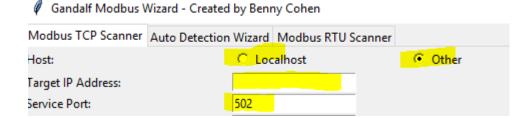
Overview

The Modbus TCP Scanner tab allows you to scan and read Modbus TCP registers easily. Here's a quick guide to using it.

Interface Elements & Usage

1. Host Selection:

- Localhost: For testing with simulated values from Modsim.
- Other: For real devices, select this and input the device's IP address.



2. Target IP Address:

Enter the IP address when "Other" is selected.

3. Service Port:

o Default is 502, commonly used for Modbus. Adjust if your device uses a different port.

4. Start and End Address:

 Define the range of registers to scan. You can scan hundreds of registers at once, more flexible than some tools.

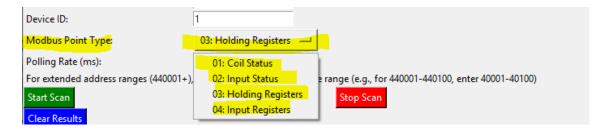
5. **Device ID**:

o Default is 1. Change if needed to match your device.

6. Modbus Point Type:

O

 Select from Coil Status, Input Status, Holding Registers, or Input Registers using the dropdown menu.



7. Polling Rate:

Set the scanning rate in milliseconds. Default is 50ms. Adjust if necessary.

8. **Buttons**:

- Start Scan: Begins the scanning process.
- o **Stop Scan**: Halts the scanning.
- o **Clear Results**: Clears the displayed results.
- O **Download Log:** Saves the log file for reviewing scan results and errors.

9. Result Display:

 Shows the results of the scan. Undefined registers or errors are displayed in red for easy identification.

10. Format Buttons:

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 Toggle between different formats (Decimal, Binary, Hex, Float, Swapped Float, Double, Swapped Double) to view the register values as per your requirement.

Show as Decimal Show as Binary Show as Hex Show as Float Show as Swapped Float Show as Double Show as Swapped Double

Overview

The Auto Detection Wizard helps you automatically detect Modbus RTU device settings and registers. This guide provides a quick overview of the interface elements and their usage.

Interface Elements & Usage

1. COM Port:

 Select from the dropdown list. Ensure your device is connected and drivers are installed if it is not listed.

2. Start Device ID / End Device ID:

o Define the range of slave IDs to scan. Modbus RTU devices often have IDs different from 1.

3. Baudrates:

Select common baud rates or enter a custom one. Multiple selections increase scan time.

4. Parities:

Choose from None (N), Even (E), Odd (O), or enter a custom parity.

5. Databits:

Typically set to 8, but ensure it matches your device settings.

6. Stopbits:

o Choose 1, 1.5, or 2 as per your device configuration.

7. **Register Type**:

Select either Holding Registers or Input Registers based on what you need to scan.

8. Register Read Range:

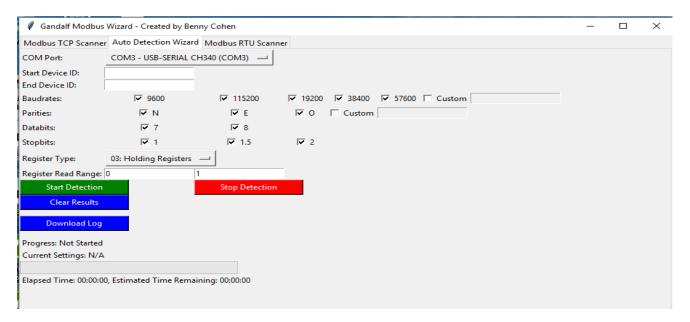
 Define the range of registers to scan. A minimum range of 2 registers is required to avoid handshake issues.

9. **Buttons**:

- o **Start Detection**: Begins the detection process.
- o **Stop Detection**: Stops the detection process.
- o **Clear Results**: Clears the displayed results.
- o **Download Log**: Saves the log file for reviewing detection results and errors.

10. Progress & Current Settings:

O Displays the progress, current settings, and estimated time remaining during the scan.



Modbus Wizard - Modbus RTU Scanner User Guide

Overview

The Modbus RTU Scanner helps you scan and read Modbus RTU devices by establishing a serial connection. This guide provides a brief overview of the interface elements and their usage.

Interface Elements & Usage

1. COM Port:

- Select the COM port from the dropdown list. Ensure your device is connected and drivers are installed if it is not listed.
- o If you used the Auto Detection Wizard first, the serial parameters will already be selected, and you should have an established serial connection.

2. Baud Rate:

o Choose the baud rate from the predefined options or enter a custom one if necessary.

3. **Parity**:

o Choose the parity bit: None (N), Even (E), Odd (O), or custom.

4. Data Bits:

Select the number of data bits, typically 8.

5. Stop Bits:

• Choose the number of stop bits, typically 1.

6. **Timeout (s)**:

Enter the timeout duration in seconds for communication.

7. Start Address / End Address:

o Define the range of registers to scan.

8. **Device ID**:

Enter the slave ID of the device.

9. **Modbus Point Type**:

o Select the type of Modbus point to scan, such as Holding Registers or Input Registers.

10. Polling Rate (ms):

Set the polling rate in milliseconds.

11. Batch Size:

• Define the number of registers to read in one batch.

12. **Buttons**:

- o **Connect**: Establishes the serial connection.
- o **Disconnect**: Terminates the serial connection.
- o **Start Scan**: Begins the scanning process.
- o **Stop Scan**: Stops the scanning process.
- o **Clear Results**: Clears the displayed results.
- o **Download Log**: Saves the log file for reviewing scan results and errors.

13. **Results Display**:

 Shows the scan results in the specified format (Decimal, Binary, Hex, Float, Swapped Float, Double, Swapped Double).

