

Directed hypergraph connectivity augmentation by hyperarc re-orientations

Combinatorial Optimization and Graph Theory

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- Connectivity problems, characterisations
- Hypergraphs

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 - ▶ Exhibiting a sequence of orientations such that :
 - The arc-connectivity does not decrease, and the arc-connectivity of the last element of the sequence is k .
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 - The sequence can be obtained in polynomial time (in the size of the directed graph).

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Side note : This article generalise the results of **Ito et al.**, as directed graphs are special case of hypergraphs.

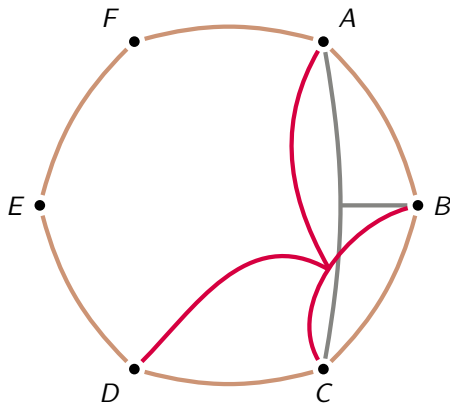
Hypergraphs



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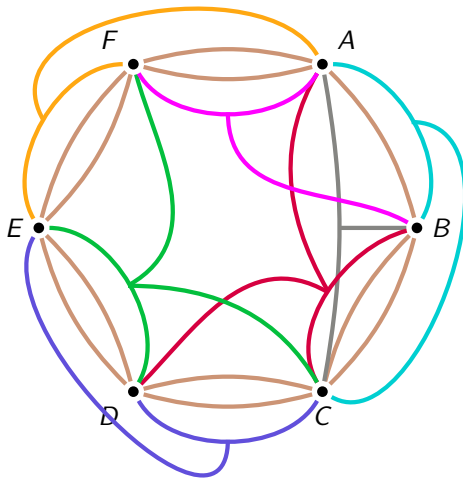


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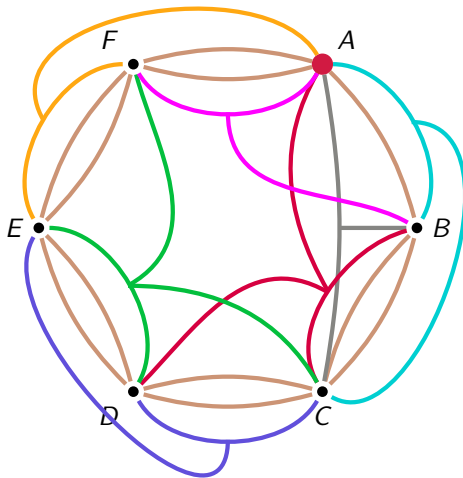
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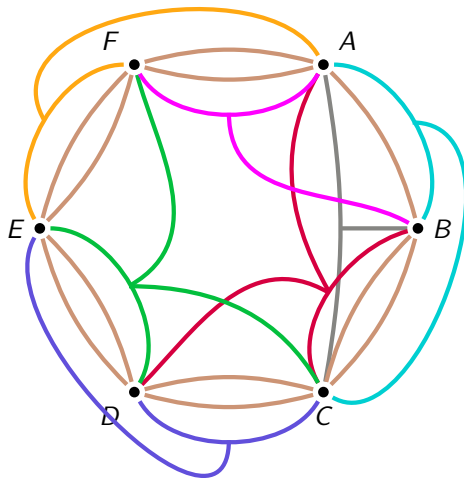


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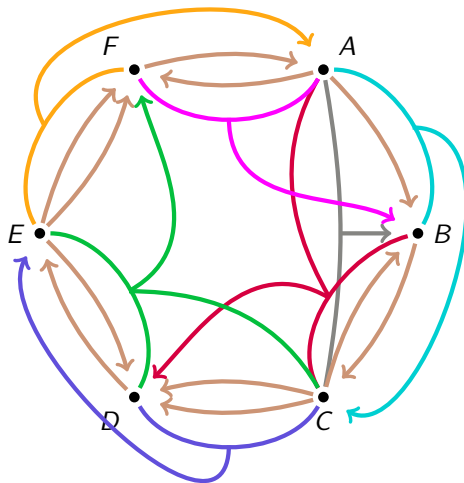
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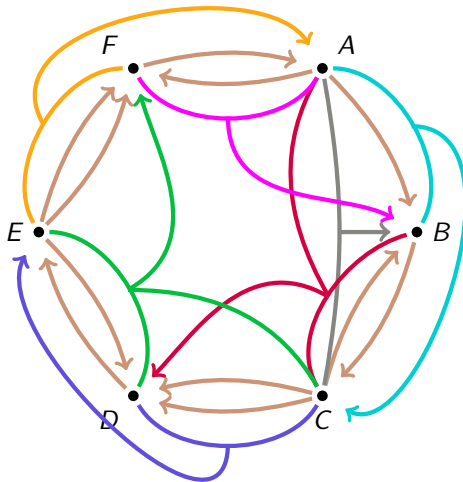


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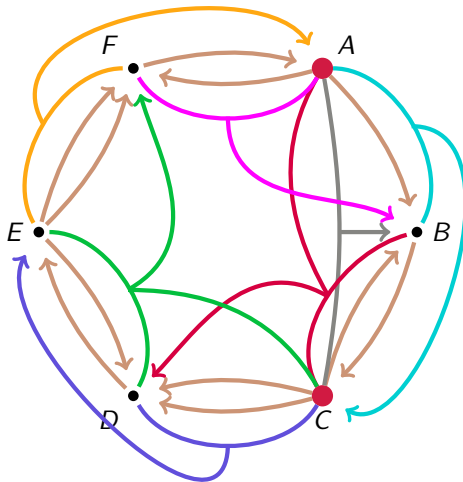
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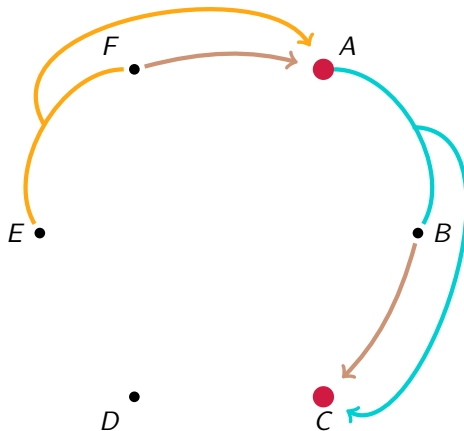
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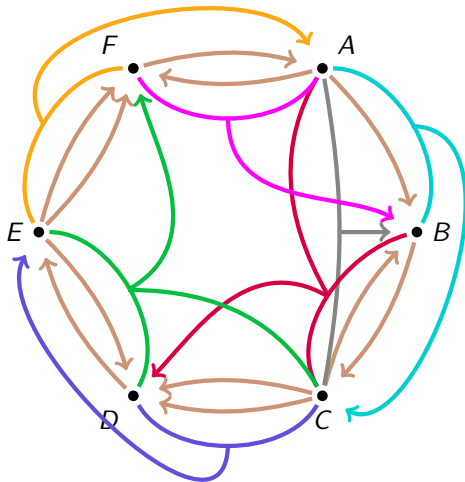
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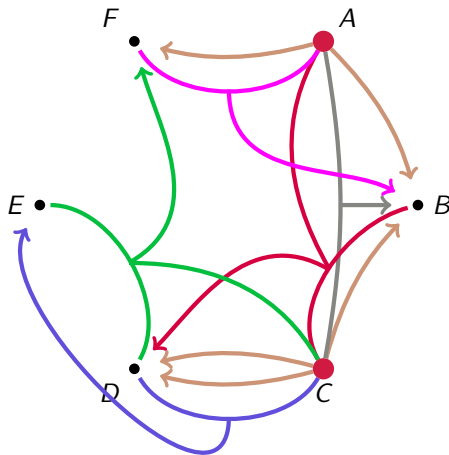
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Hyperarc-connectivity and (k, k) -partition connected hypergraphs

- $\vec{\mathcal{H}}$ is k -hyperarc-connected, if, $\forall e \in \mathcal{E}, d_{\vec{\mathcal{H}}}^+(e) \geq k$.
- The hyperarc-connectivity of a graph, denoted $\lambda(\vec{\mathcal{H}})$, is the maximum value of k such that $\vec{\mathcal{H}}$ is k -hyperarc-connected.

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We use a result of Frank : \mathcal{H} is (k, k) -partition-connected if and only if it admits a k -hyperarc-connected orientation.

Main result

Main result (Theorem 7)

Let $\mathcal{H} = (V, E)$ be a $(k + 1, k + 1)$ -partition-connected hypergraph and $\vec{\mathcal{H}}$ is a k -hyperarc orientation of \mathcal{H} . Then there exists a sequence of hyperarcs $(\vec{\mathcal{H}}_i)_{i \in 0 \dots \ell}$ such that $\vec{\mathcal{H}}_{i+1}$ is obtained from $\vec{\mathcal{H}}_i$ by reorienting exactly one hyperarc and $\lambda(\vec{\mathcal{H}}_{i+1}) \geq \lambda(\vec{\mathcal{H}}_i)$ and $\lambda(\vec{\mathcal{H}}_\ell) = k + 1$. Such a sequence of orientations can be obtained with $\ell \leq |V|^3$ and found in polynomial time (in the size of \mathcal{H}).

Main result

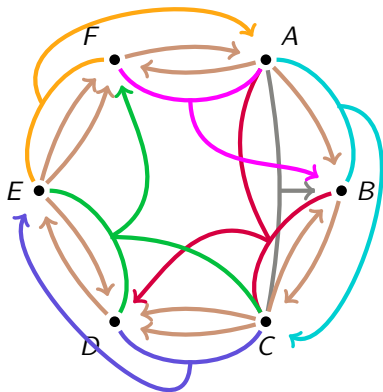
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Generalization of **Ito et al.**, as digraphs are special cases of hypergraphs.

"High-Level"-running of the algorithm

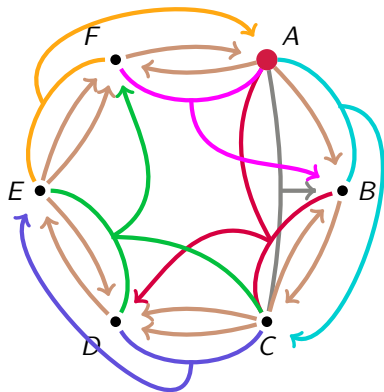
Our algorithm will provide a 3-hyperarc-connected orientation of \mathcal{H} , starting from a 2-hyperarc-connected.



- 1 Take r in $V(\mathcal{H})$.
- 2 Compute sets of vertices.
- 3 Stopping Criteria
- 4 Select a set R (cf. 2.)
- 5 Find an admissible (s, t) -hyperpath in R to reorient
- 6 Reorient the corresponding hyperpath.
- 7 Goto (2.)

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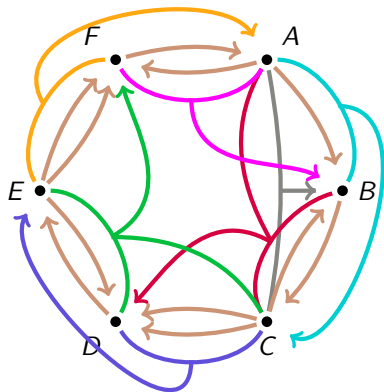
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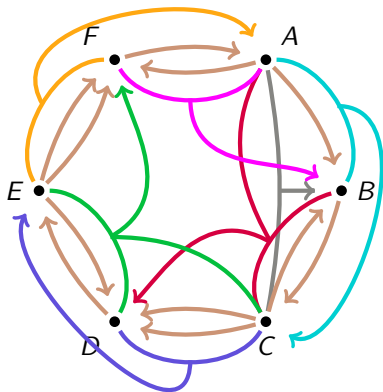
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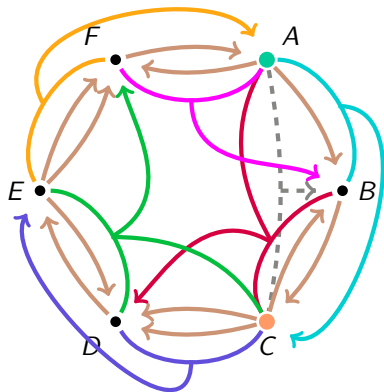
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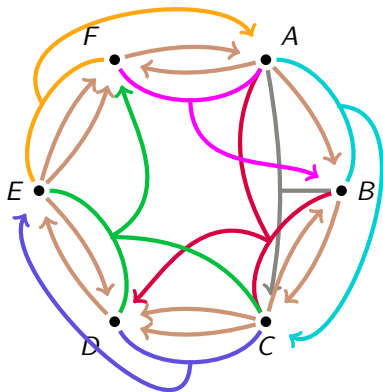
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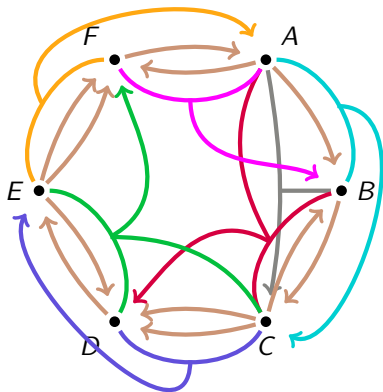
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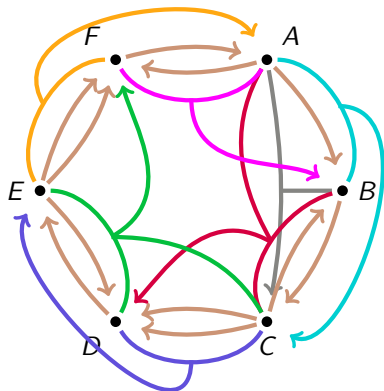
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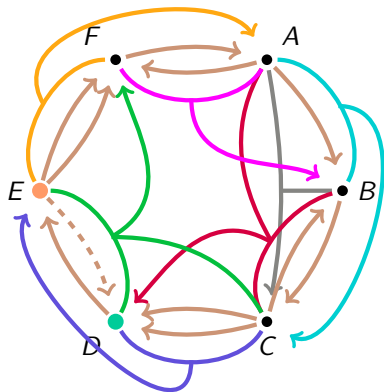
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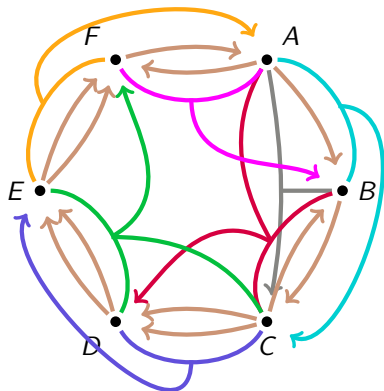
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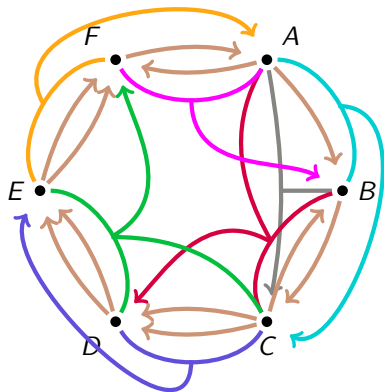
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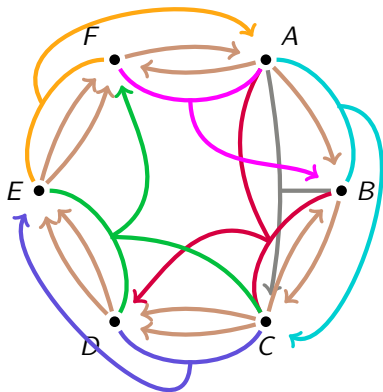
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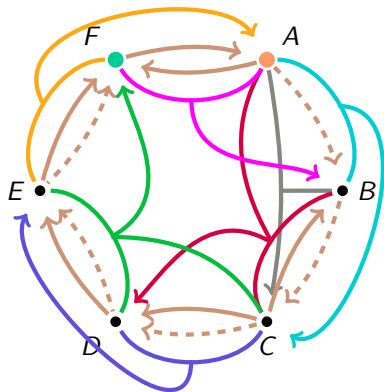
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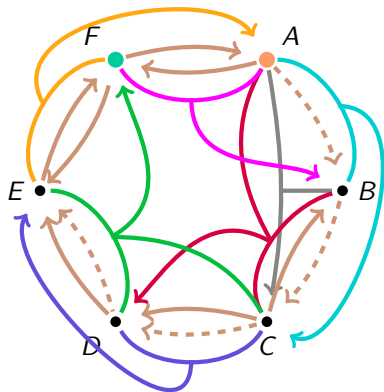
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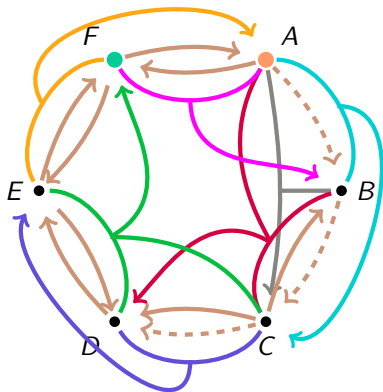
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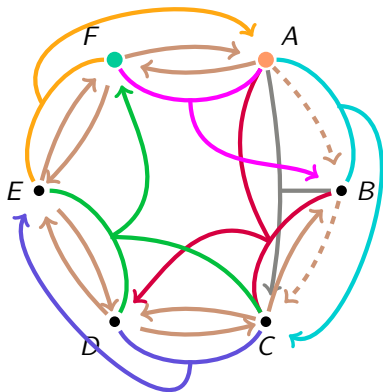
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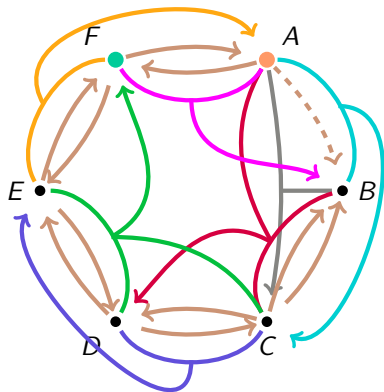
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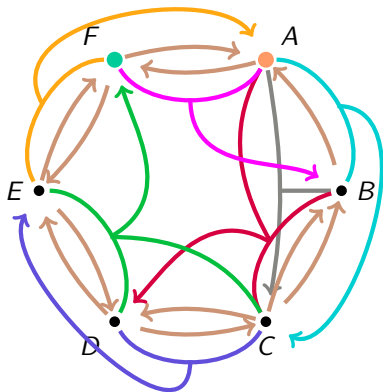
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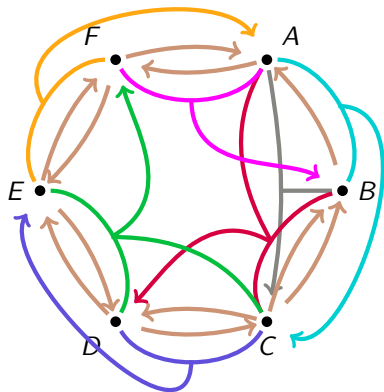
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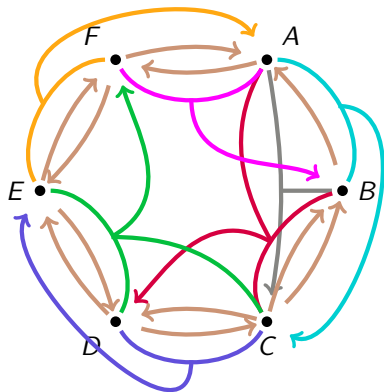
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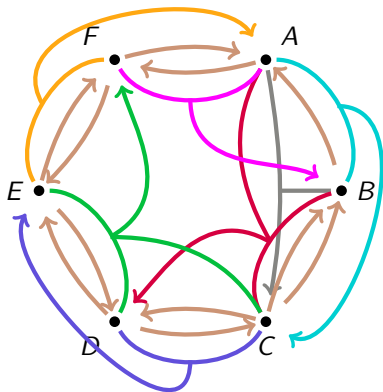
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Finding *admissible* (s, t) -hyperpaths in R

- Crucial segment of the algorithm.
- Three criterion for P to be an admissible (s, t) -hyperpath in R :
 - ① s is a safe source in $S \subseteq R$, t is a safe sink in $T \subseteq R$.
 - ② Reorient each hyperarc, **one by one**, does not decrease the hyperarc-connectivity.
 - ③ After reorientation of P , there is a set whose cardinality is a guarantee that the algorithm will stop.

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What are **safe sources** and **safe sinks** ?

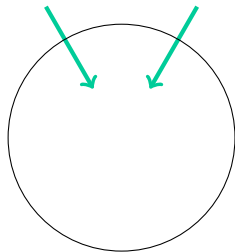
A brief detour...

Tight and Dangerous sets

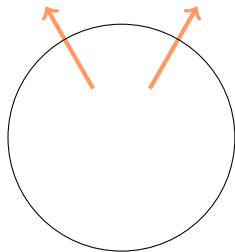
Remainder of the algorithm :

- Input : A k -hyperarc-connected orientation of a $(k + 1, k + 1)$ -partition-connected hypergraph.
- Output : A $k + 1$ -hyperarc-connected hypergraph.

Tight and Dangerous sets



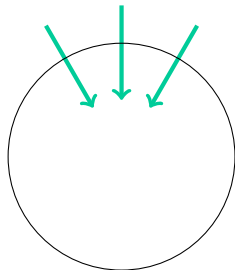
In-Tight sets



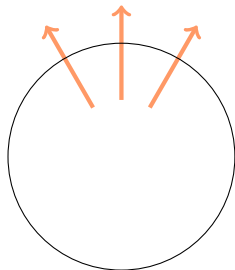
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Tight and Dangerous sets



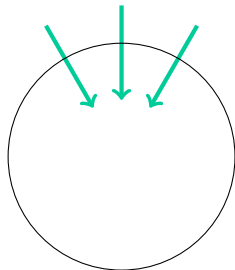
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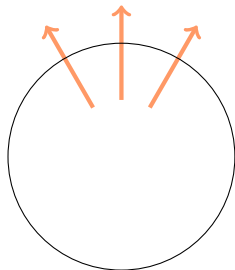
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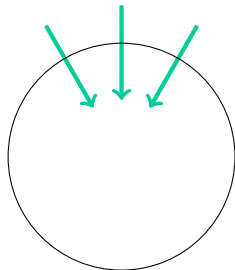
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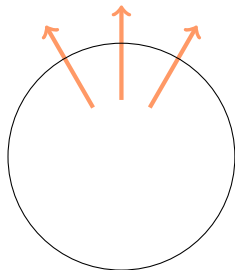
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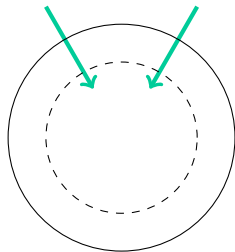
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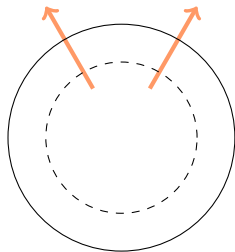
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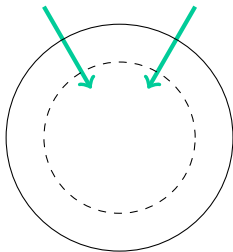
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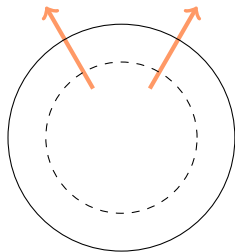
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Tight and Dangerous sets



Minimal In-Tight sets



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