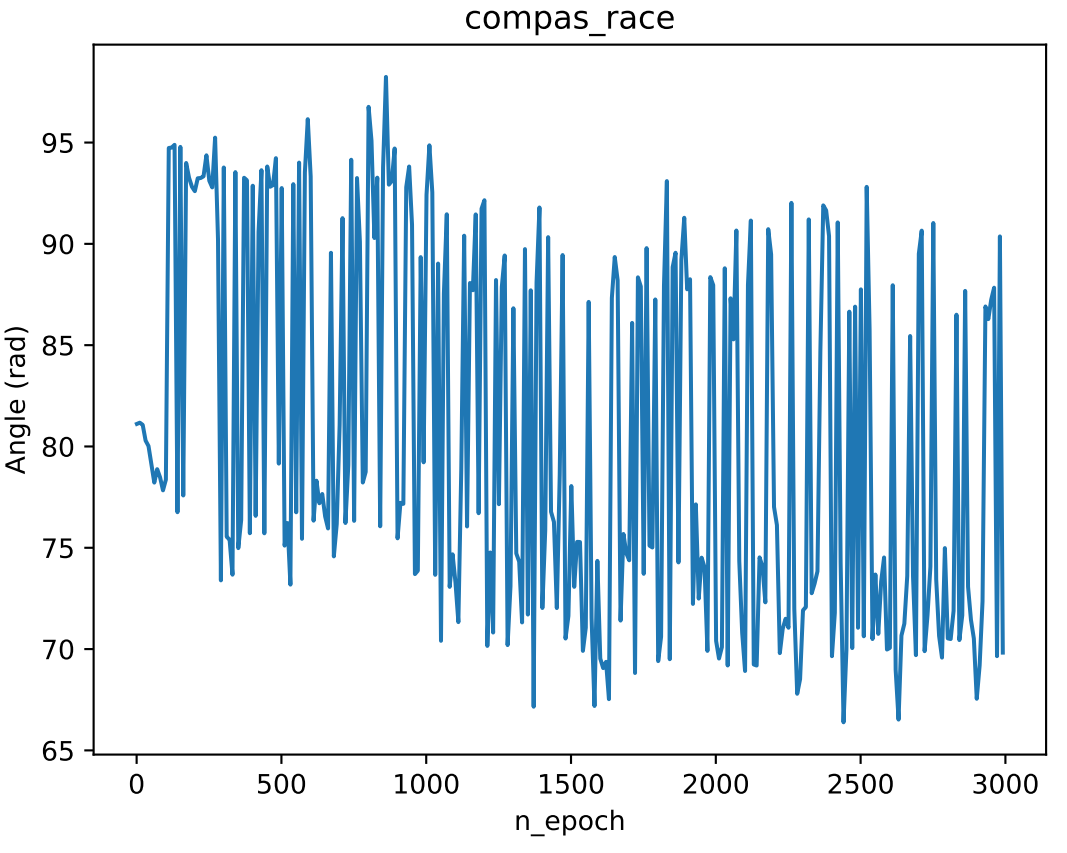
compas_race
Angle (rad)
95
90
85
80
75
70
65
0
500
1000
1500
2000
2500
3000
n_epoch