

view_frames Result
Recorded at time: 236.795

odom

base_footprint

base_link

camera_rgb_frame

caster_back_link

caster_front_link

cliff_sensor_front_link

cliff_sensor_left_link

cliff_sensor_right_link

gyro_link

laser_sensor_link

pole_kinect_0_link

pole_kinect_1_link

wheel_left_link

wheel_right_link

camera_depth_frame

camera_link

camera_rgb_optical_frame

camera_depth_optical_frame

Broadcaster: /gazebo
Average rate: 20.241 Hz
Most recent transform: 236.769 (0.026 sec old)
Buffer length: 4.150 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (236.795 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (236.795 sec old)
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Average rate: 10000.000 Hz
Most recent transform: 0.000 (236.795 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 20.241 Hz
Most recent transform: 236.770 (0.025 sec old)
Buffer length: 4.150 sec

Broadcaster: /robot_state_publisher
Average rate: 20.241 Hz
Most recent transform: 236.770 (0.025 sec old)
Buffer length: 4.150 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (236.795 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (236.795 sec old)
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