

1. Se consideră STC cu graful din figură.

- i) Calculați f.d.t. (pentru sistemele de tip SISO) sau matricea de transfer (pentru sistemele de tip MIMO) a sistemului. (0.6 pt.)

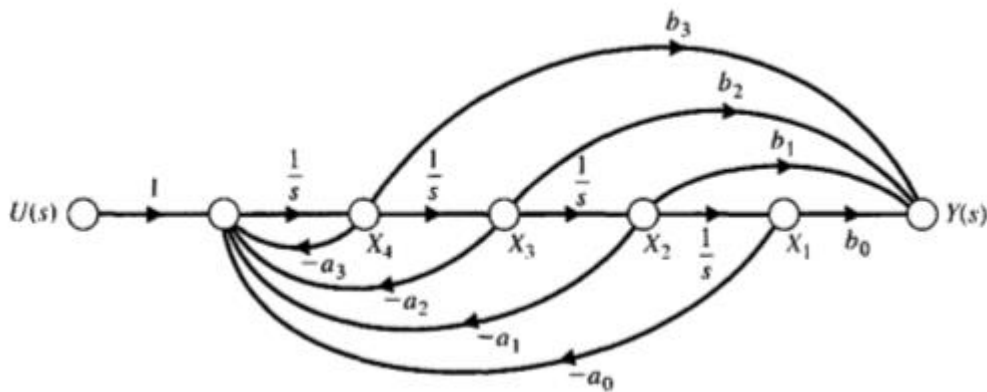
Matricea de transfer cuprinde toate f.d.t. corespunzătoare perechilor intrare-ieșire.

- ii) Stabiliți un MM-ISI (realizarea sistemică). $d \neq 8$: (0.55 pt), $d = 8$: (0.4 pt.)

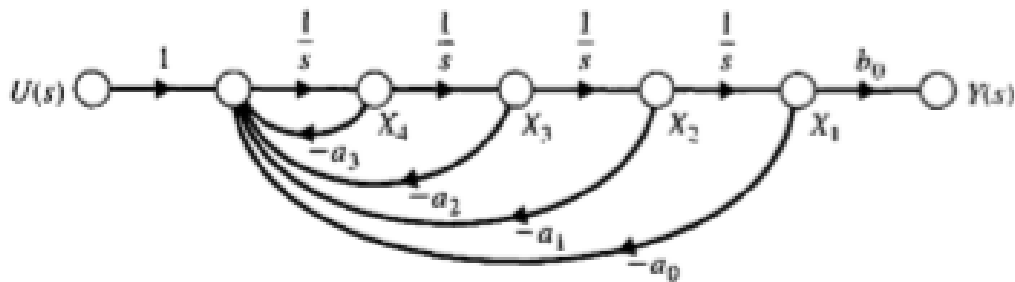
Dacă vă este mai ușor, în prealabil puteți asocia grafului o schemă bloc.

- iii) $d \neq 8$: Calculați polinomul caracteristic al sistemului (0.25 pt.). $d = 8$: Calculați polinomul caracteristic al sistemului. Analizați dacă sistemul poate avea o comportare de tip aperiodic, aperiodic critic și/sau oscilant amortizată (0.4 pt.)

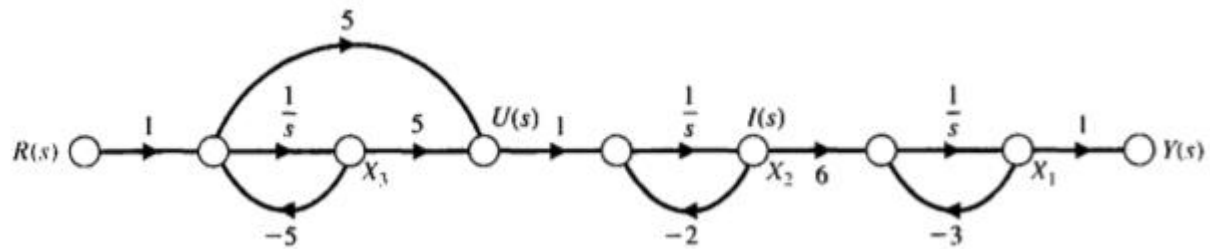
$d = 0$: Sistemul are orientarea $U \rightarrow Y$.



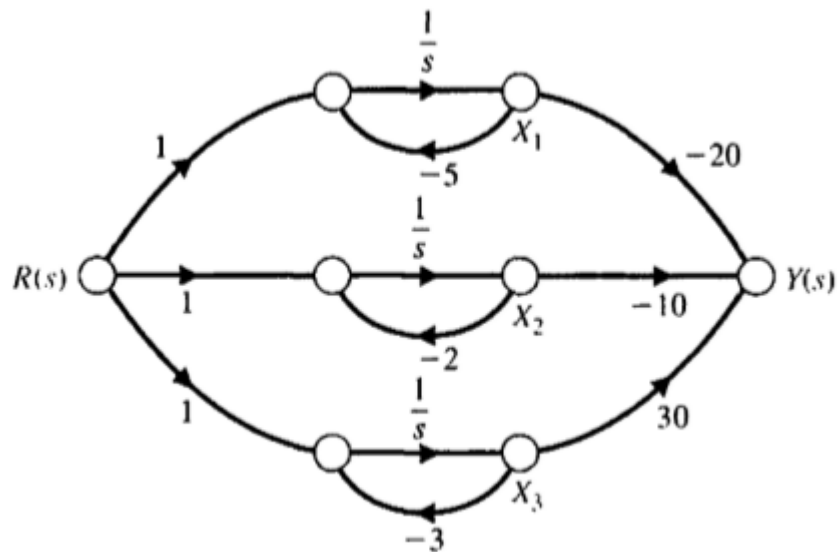
$d = 1$: Sistemul are orientarea $U \rightarrow Y$.



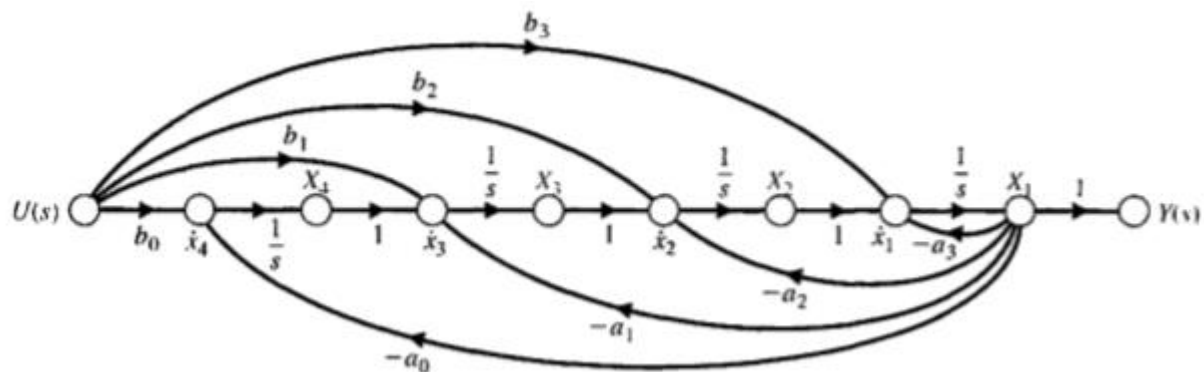
$d = 2$: Sistemul are orientarea $R \rightarrow Y$.



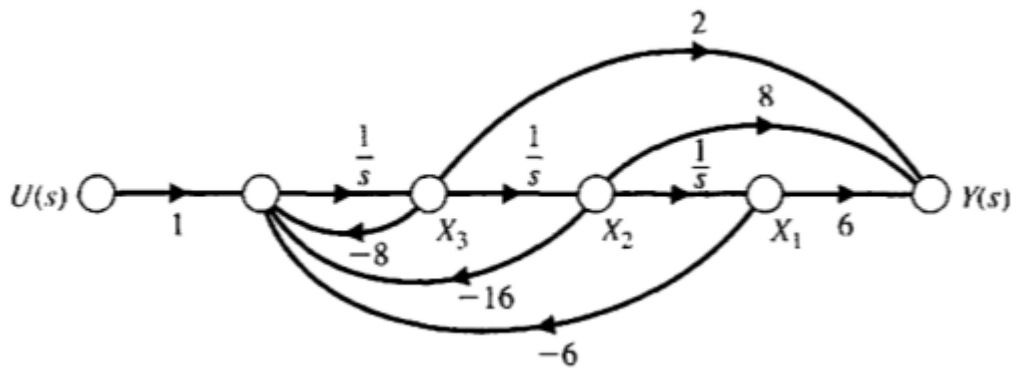
$d = 3$: Sistemul are orientarea $R \rightarrow Y$.



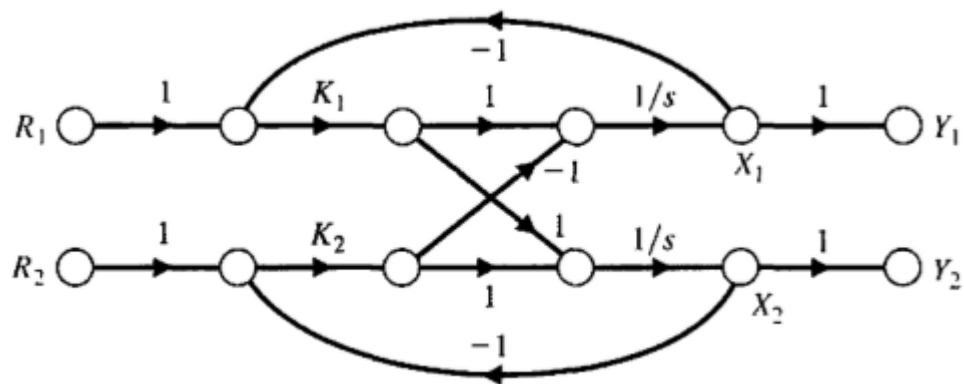
$d = 4$: Sistemul are orientarea $U \rightarrow Y$.



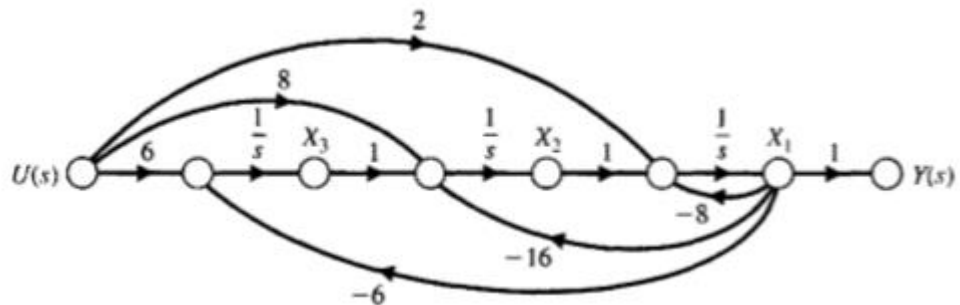
$d = 5$: Sistemul are orientarea $U \rightarrow Y$.



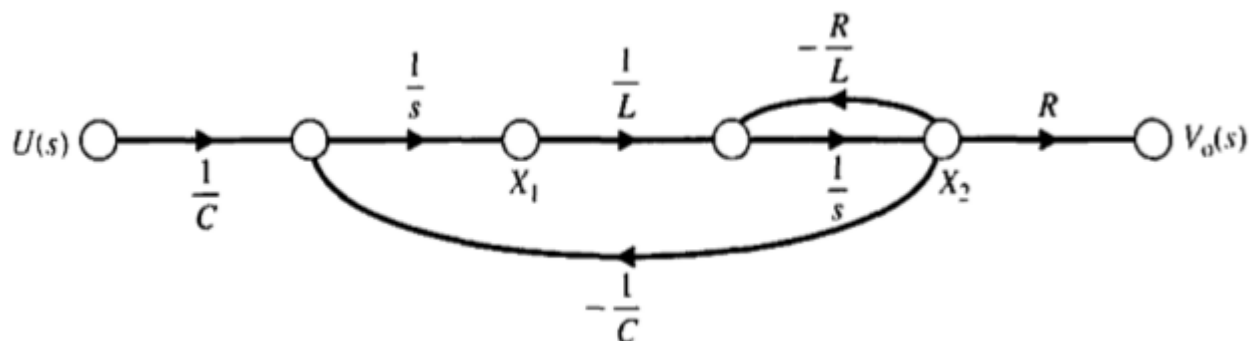
d = 6: Sistemul are orientarea $\{R_1, R_2\} \rightarrow \{Y_1, Y_2\}$



d = 7: Sistemul are orientarea $U \rightarrow Y$.



d = 8: Sistemul are orientarea $U \rightarrow V_0$.



d = 9: Sistemul are orientarea $\{U_1, U_2\} \rightarrow X_3$.

