Strong connectivity in directed graphs

- Nodes u and v are mutually reachable if there is a path from u to v and a path from v to u
- A directed graph is strongly connected if every pair of nodes are mutually reachable

Lemma

Let s be any node in G. G is strongly connected \iff every node is reachable from s and s is reachable from any node.

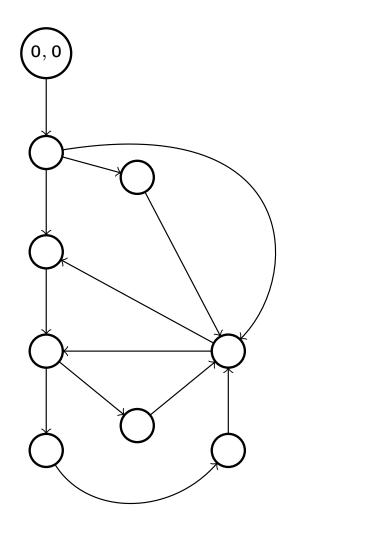
Proof.

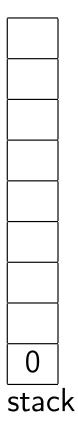
- \Rightarrow follows directly from the definition of strongly connected G. \Leftarrow follows by constructing two paths:
 - a path from u to v as p = (u, ..., s, ..., v), and
 - a path from v to u as q = (v, ..., s, ..., u).

Determining strong connectivity

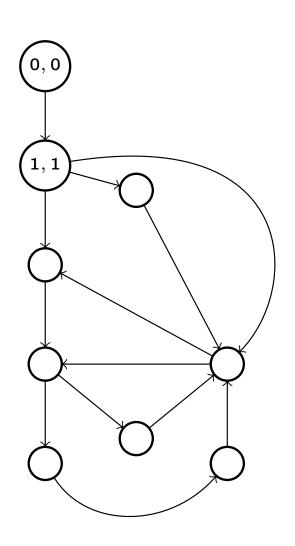
- Select any node $s \in V$
- Use BFS on G from s and check if all of V is reached
- \bullet Construct G^r from G by reversing all edges
- Use BFS on G^r from s and check if all of V is reached
- If s can reach a node u in G^r , then u can reach s in G.
- If all of V is reached in both searches, G is strongly connected
- \circ O(n+m)
- We will next see Tarjan's algorithm which instead uses depth first search and also lists all the strongly connected components

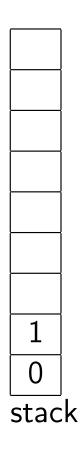
```
int
      dfnum
procedure strong connect(v)
      dfn(v) \leftarrow \overline{d}fnum
      lowlink(v) \leftarrow dfnum
      visited(v) \leftarrow true
      push(v)
      dfnum \leftarrow dfnum +1
      for each w \in succ(v) do
             if (not visited(w)) {
                    strong connect(w)
                    lowlin\overline{k}(v) \leftarrow min(lowlink(v), lowlink(w))
             } else if (dfn(w) < dfn(v) and w is on stack)
                    lowlink(v) \leftarrow min(lowlink(v), dfn(w))
      if (lowlink(v) = dfn(v))
             scc \leftarrow \emptyset
             do
                    w \leftarrow pop()
                    add w to scc
             while (w \neq v)
             process scc(scc)
end
```



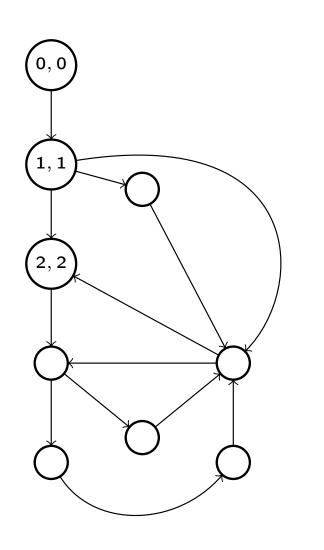


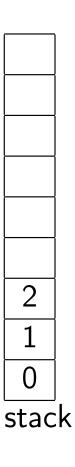
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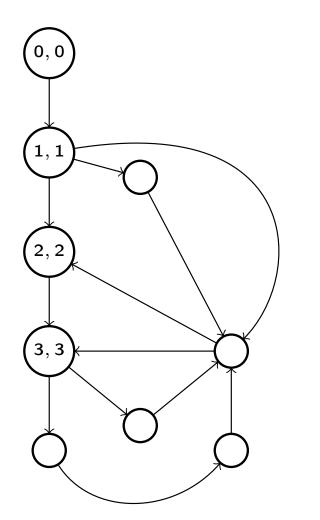


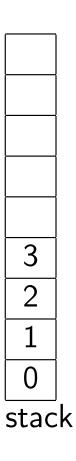
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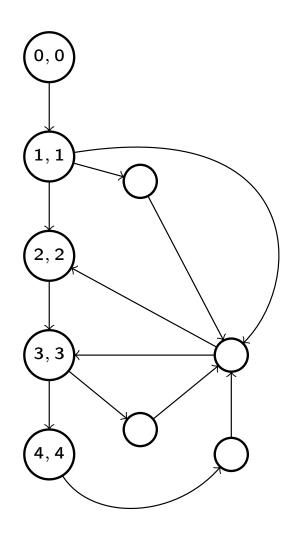


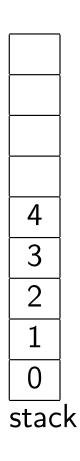
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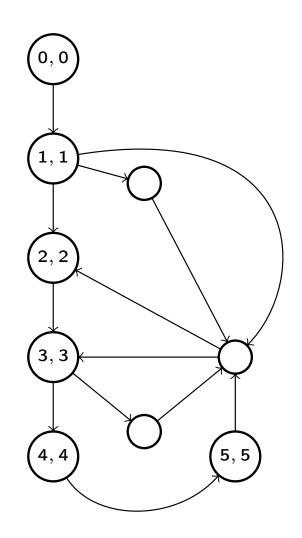


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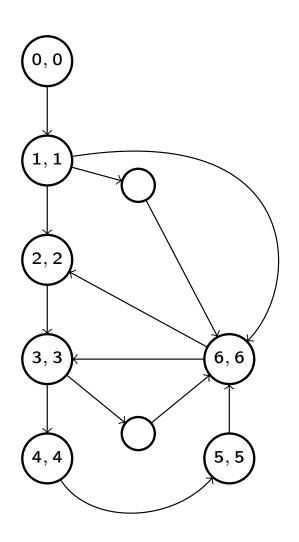


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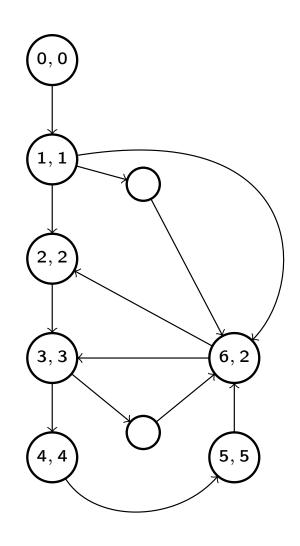


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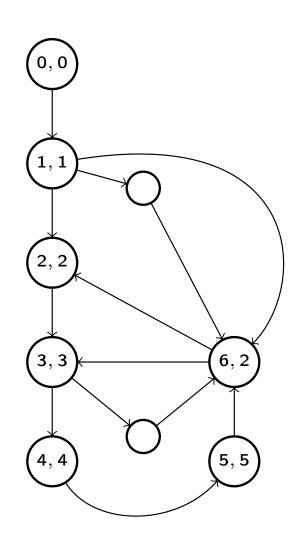


```
(6,2) \Rightarrow 6 in same scc as 2.
      dfnum
int
procedure strong connect(v)
      dfn(v) \leftarrow \overline{d}fnum
      lowlink(v) \leftarrow dfnum
      visited(v) \leftarrow true
      push(v)
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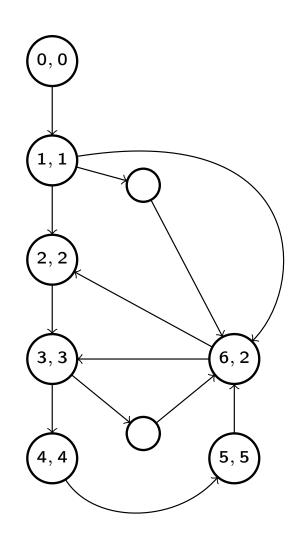
```
(6,3). no action.
      dfnum
int
procedure strong connect(v)
      dfn(v) \leftarrow \overline{d}fnum
      lowlink(v) \leftarrow dfnum
      visited(v) \leftarrow true
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end
```





• 6 remains on the stack.

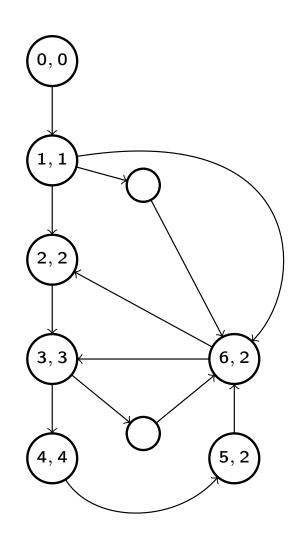
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end
```





New lowlink and remains.

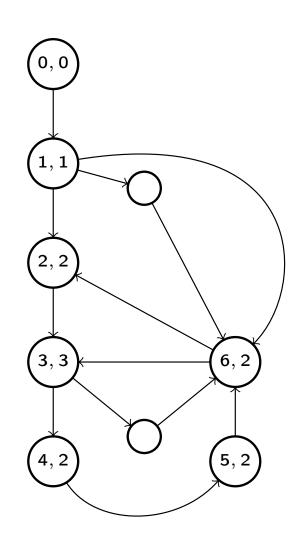
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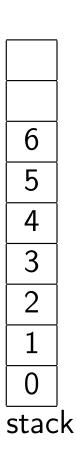




New lowlink and remains.

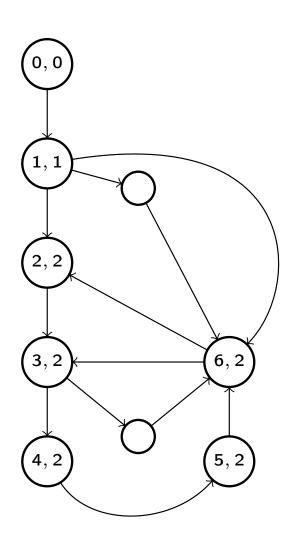
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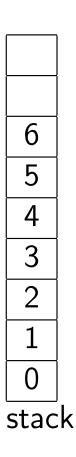




New lowlink. Next 7.

```
dfnum
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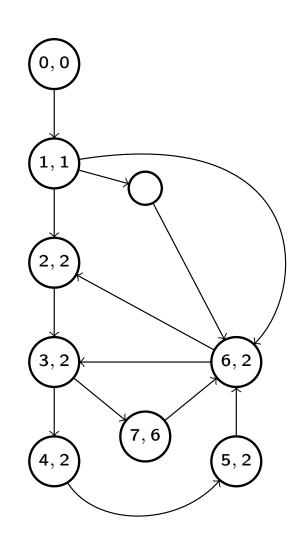




2024

Lowlink is set.

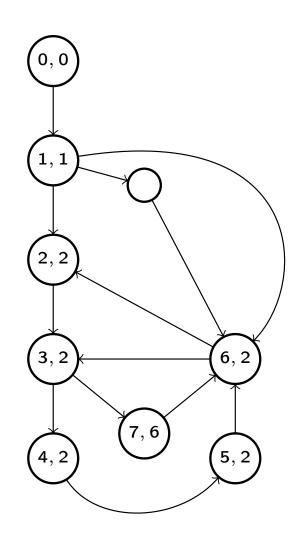
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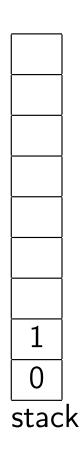




Remove SCC from stack

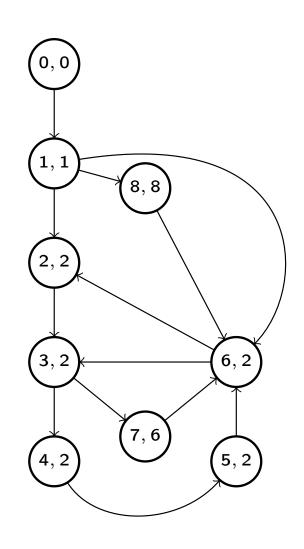
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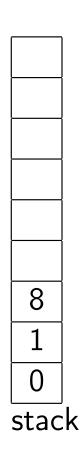




No path from 2 to 8.

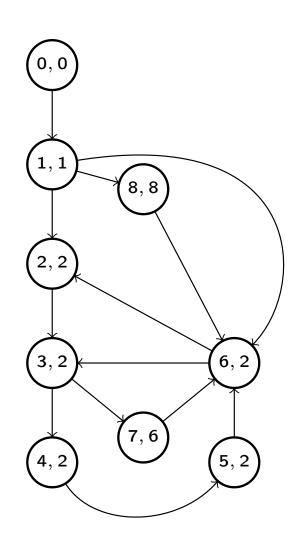
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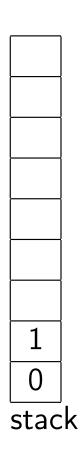




8 is its own SCC.

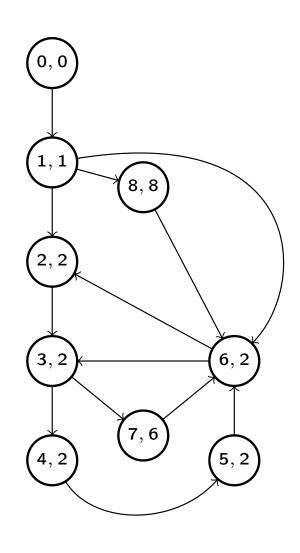
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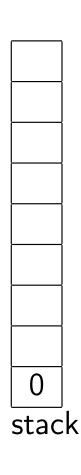




1 is its own SCC.

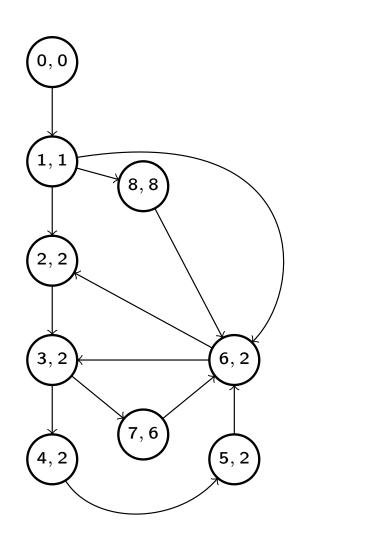
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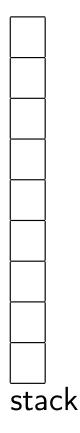




0 is its own SCC.

```
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                    add w to scc
             while (w \neq v)
             process scc(scc)
end
```





Tarjan's Algorithm: Remarks

- Consider the edge (v, w).
- When w is not yet visited we must visit it by calling strong connect(w).
- If w has been visited, we have two main cases:
 - \bullet w is not on the stack, because it has already found its SCC.
 - ② w is on the stack, because it's waiting for being popped.
 - If dfn(w) < dfn(v) then v must set its lowlink so it does not think it is its own SCC.
 - If $dfn(w) \ge dfn(v)$ then no more information for v is available. There is another path from v to w due to which they will belong to the same SCC.

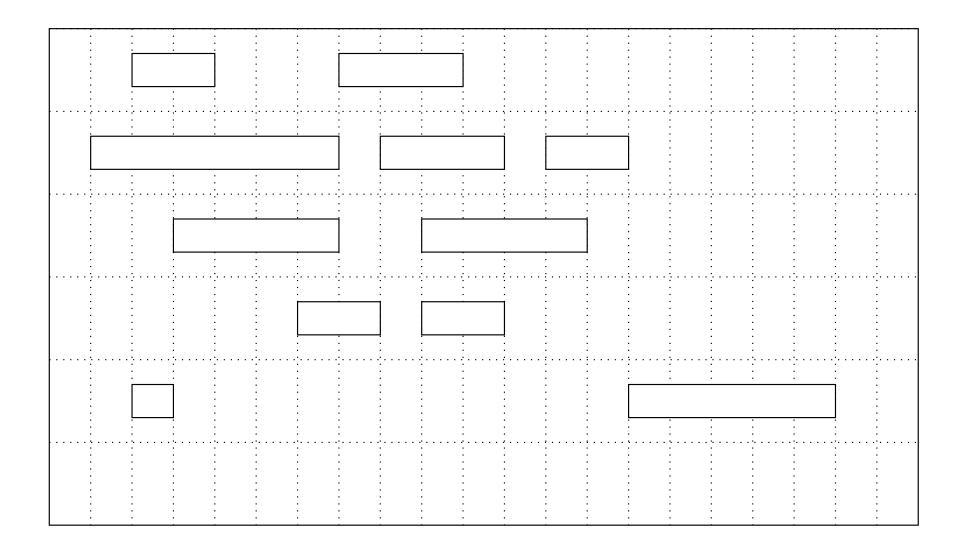
Greedy algorithms / Giriga algoritmer

- It is not trivial to define precisely what makes an algorithm greedy.
- The main idea is to use a simple rule to make decisions without taking "all" information into account.
- The challenge is to find a simple rule which solves a problem optimally
- Two approaches to prove that a greedy algorithm is optimal:
 - The greedy algorithm "stays ahead" by proving it is always at least as good as an optimal algorithm
 - Exchange argument (utbytesargument) transform the output of an optimal algorithm (without changing its quality) to the output of the greedy algorithm

Interval scheduling / Intervallschemaläggning

- One resource
- A set R of requests, r_i , with a start time s(i) and a finish time f(i)
- A set of requests is compatible if they do not overlap in time
- The interval scheduling problem is to find the largest subset $S \subseteq R$ such that S is compatible
- All requests have equal value and it is the size of S we want to maximize
- A compatible set of maximum size is called an optimal schedule

An example set R



A greedy algorithm for interval scheduling

```
procedure schedule(R)

S \leftarrow \emptyset \ / * S is a sequence */
while R \neq null

r \leftarrow select a request from R

remove r from R

add r to the end of S

remove all requests in R which overlap with r

return S
```

- Our problem is to figure out a clever select function
- Any suggestions?

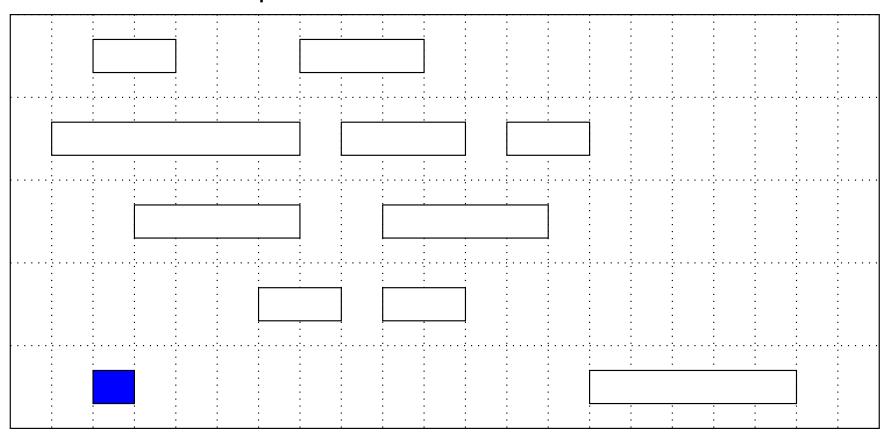
Ideas for the select function

- Take the request with shortest interval
- Take the request which starts first
- Take the request with fewest conflicts

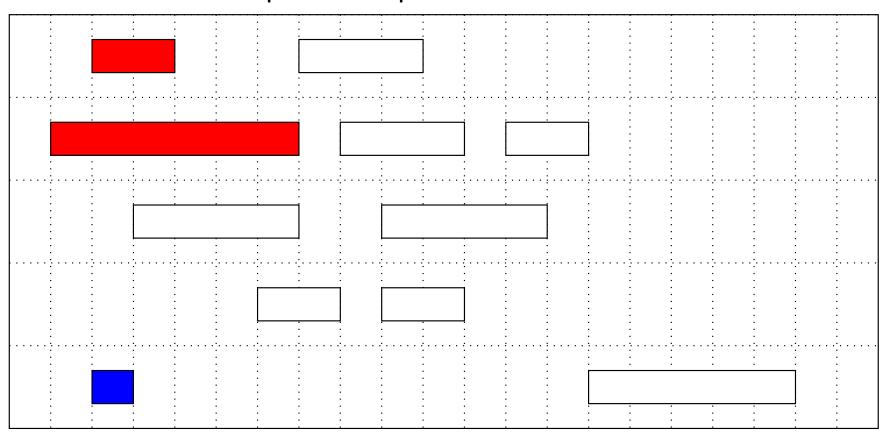
None of these lead to an optimal solution

A better select function

- Take the request which finishes earliest
- Is this optimal?
- Select first request:

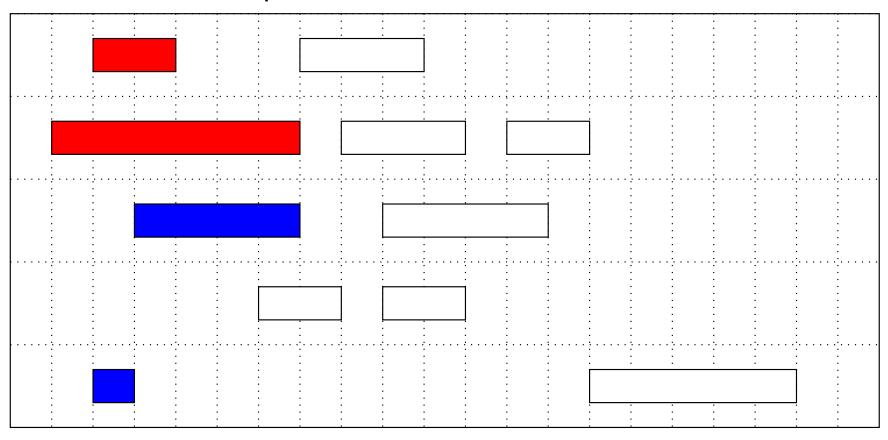


• Remove incompatible requests:



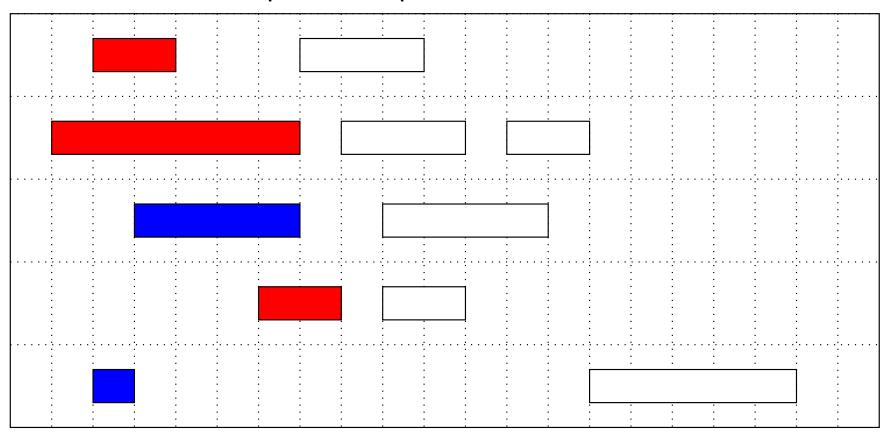
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• Select next request:



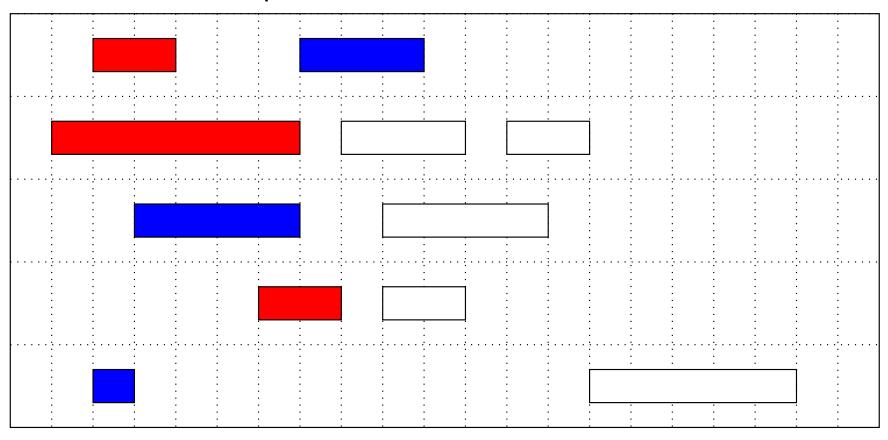
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• Remove incompatible request:



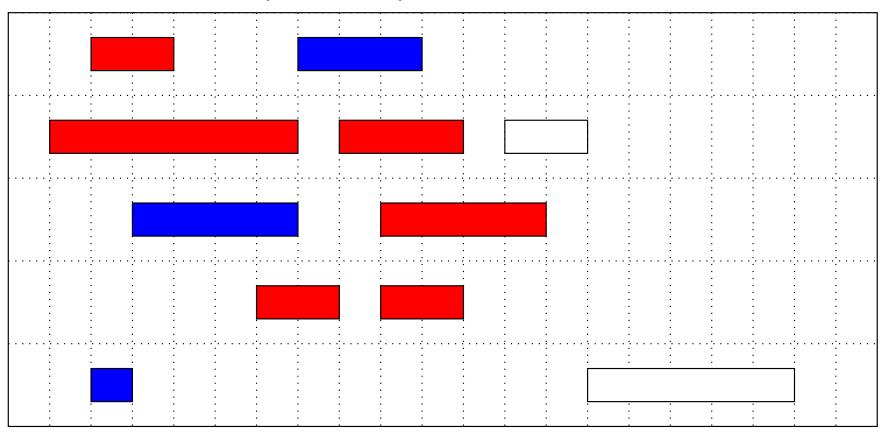
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• Select next request:



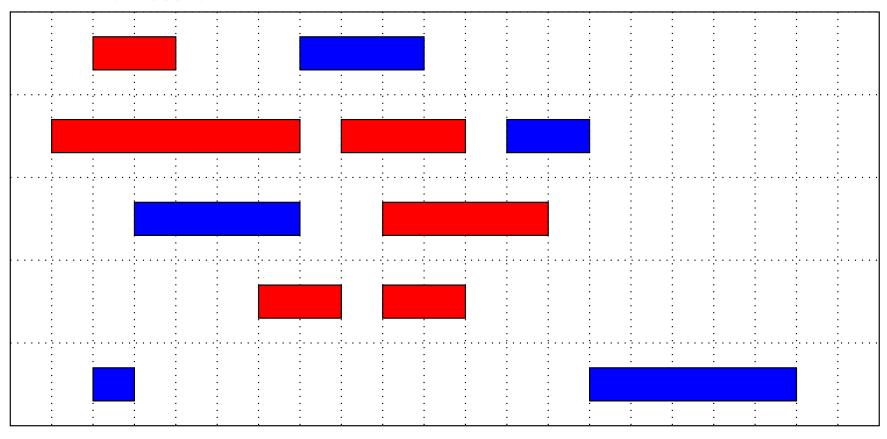
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• Remove incompatible requests:



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• End result:



Proving optimality of a greedy algorithm

- What should we prove?
- Can there exist several optimal schedules?
- Either show our algorithm is as good as an optimal (stays ahead), or output from an optimal algorithm can be transformed to the output of our algorithm.
- ullet For our problem, assume there is an optimal schedule represented as a sequence T sorted in order of increasing finish time
- We should not try to prove S = T
- Instead we should prove |S| = |T|
- We will use the first proof technique:
 "our algorithm stays ahead of an optimal solution"
- That is, $|S| \ge |T|$

Two solutions

- Our: $S = (r_1, r_2, ..., r_n)$
- Optimal: $T = (t_1, t_2, ..., t_m)$
- We want to show n = m
- S and T are both sorted by increasing finish time
- It is clear that $f(r_1) \leq f(t_1)$ since we select the request with earliest finish time
- There are at least n requests in T so we can aim at proving:
- $f(r_k) \leq f(t_k)$ $1 \leq k \leq n$

Comparing the solutions

Lemma

$$f(r_k) \leq f(t_k)$$
 $1 \leq k \leq n$

Proof.

- Proof by induction. $f(r_1) \leq f(t_1)$ is clear.
- For k > 1, assume (1): $f(r_{k-1}) \le f(t_{k-1})$.
- Since T is compatible (2): $f(t_{k-1}) \leq s(t_k)$
- From (1) and (2) follows (3): $f(r_{k-1}) \le s(t_k)$
- Our algorithm can select t_k as its r_k
- Our algorithm selects as r_k the request with earliest finish time, i.e. $f(r_k) \le f(t_k)$

|S| = |T|

- It remains to prove that |S| = |T|.
- Recall n = |S| and m = |T|.

Theorem

|S| = |T|.

Proof.

- Assume in contradiction that m > n.
- We know $f(r_n) \leq f(t_n)$
- Since m > n, T contains a request t_{n+1}
- We must have $s(t_{n+1}) \ge f(t_n) \ge f(r_n)$
- But this request should have been scheduled by our algorithm which contradicts the assumption that |S| = n so m = n and optimality has been proved

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Time complexity

- Our greedy algorithm can be implemented in time $O(n \log n)$
- First all requests are sorted in order of increasing finish time
- Then a linear pass finds the schedule

Scheduling to minimize delays

- Again one resource
- Consider now requests with a soft deadline d(r) and a time length t(r)
- It is not a disaster to fail a soft deadline compared with a hard deadline
- s(r) and f(r) are start and finish times and in this problem they are output and not input
- The delay of one request is $\max(0, f(r) d(r))$
- Our problem is to schedule requests so that the maximum delay of any request is minimized
- What is a simple rule to do that optimally?

Algorithm: select next with earliest deadline

- Request are renamed so that $d(r_1) \leq d(r_2)... \leq d(r_n)$
- Our algorithm simply is to schedule the requests in this order, or in other words, the earliest deadline first
- In addition, we schedule requests so that $s(r_{i+1}) = f(r_i)$, i.e. without a gap between r_i and r_{i+1}
- Thus there is no idle time between any two requests
- Consider any optimal schedule T. Can it have idle time?
- Yes, e.g. if $t(r_1) = 1$, $d(r_1) = 2$, $t(r_2) = 3$, $d(r_2) = 10$
- With $s(r_1) = 1$, $f(r_1) = 2$, $s(r_2) = 7$, $f(r_2) = 10$, the maximum delay is zero
- But there obviously exists a different optimal schedule without any gap
 just start the requests in the same order but as early as possible

Inversions

- Let $d(r_i) < d(r_j)$
- If r_i is scheduled before r_i , it is called an **inversion**
- Our algorithm creates no inversions
- But if $d(r_i) = d(r_{i+1})$ then it can schedule r_{i+1} before r_i

First part of our optimality proof

Lemma

All schedules with no idle time and no inversions have the same maximum delay

Proof.

- Consider two different schedules S and T without idle time and no inversions
- Then the only difference between S and T is the order in which requests with identical deadlines are scheduled
- In a sequence with such requests, the last has the maximal delay or no delay.
- The maximal delay is the same in both schedules.

An example

- Let all requests take one time unit
- Let all requests have deadline $d(r_i) = 3$
- $S = (r_1, r_2, r_3, r_4, r_5)$
- $T = (r_4, r_5, r_1, r_2, r_3)$
- In S r_1 , r_2 , r_3 have no delay, r_4 is delayed 1 and r_5 is delayed 2
- In T r_4, r_5, r_1 have no delay, r_2 is delayed 1 and r_3 is delayed 2
- Same maximum delay but for different requests

Second part

ullet We will prove that an optimal schedule T can be transformed to S

Lemma

Assume an optimal schedule Q has an inversion of r_i and r_i i.e. $d_i < d_i$ and r_i is scheduled before r_i . Then Q has a pair r_a and r_b of inverted requests scheduled immediately after each other.

• In (7, 8, 9, 1, 2, 3, 4, 5, 6) with i = 1, j = 7 we have a = 1, b = 9.

Proof.

- We have $(r_i, ..., r_i)$ with k requests scheduled between r_i and r_i , $k \ge 0$
- In this sequence of k+2 requests, since $d_i < d_i$, there must be a first pair r_a and r_b of inverted requests with r_b scheduled immediately before r_a such that $d_a < d_b$.

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Third part

Lemma

Let r_a and r_b be a pair of inverted requests scheduled consecutively in Q Swapping r_a and r_b into R, the maximum delay does not increase.

Proof.

- We have $Q = (..., r_b, r_a, ...)$ and $R = (..., r_a, r_b, ...)$.
- The delay of r_a cannot have increased in R
- Let $f^X(r)$ be the finish time in schedule X for request r
- Let $t = f^Q(r_a) = f^R(r_b)$ (i.e. finish time of last of them)
- The delay of r_a in Q is $f^Q(r_a) d(r_a) = t d(r_a)$
- The delay of r_b in R is $f^R(r_b) d(r_b) = t d(r_b)$
- Can r_b now be more late than r_a was? I.e. can $t d(r_b) > t d(r_a)$?
- $t d(r_b) > t d(r_a) \iff t + d(r_a) > t + d(r_b)$
- No, since by assumption $d(r_a) < d(r_b)$

Last part

Theorem

Our algorithm produces a schedule with minimum maximum delay.

Proof.

- We have just shown that there exists an optimal schedule T with no idle time and no inversions.
- Since all schedules with no idle time and no inversions have the same maximum delay, our algorithm is optimal.

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An exchange argument

- What did we do?
- We find an algorithm which seems to be optimal.
- We characterize optimal solutions.
- We exchange optimal solutions to produce an output which is identical to ours.
- Therefore our algorithm is optimal.
- Note that the schedules may be different but the maximum delay is the same.