PRAGMATIC OPTIMIZATION

IN MODERN PROGRAMMING A BIT OF COMPILER MAGIC

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OUTLINE

- Pragmatic approach
- Before we start...
- The magic box!
- How to learn optimization?

PRAGMATIC APPROACH

"Programmers waste enormous amounts of time thinking about, or worrying about, the speed of non-critical parts of their programs, and these attempts at efficiency actually have a strong negative impact when debugging and maintenance are considered. We should forget about small inefficiencies, say about 97% of the time; premature optimization is the root of all evil. Yet we should not pass up our opportunities in that critical 3%."

-Donald Knuth, Structured Programming With go to Statements

- 1. Find what to start from (3%)
- 2. Know when to stop (97%)

BEFORE WE START...

GETTING FEEDBACK

- Check wall-time of you application
 - If a compiler does it right, you will see some uplift
- Dump an assembly of your code (or/and IL)
 - Ensure instruction and register scheduling
 - Check for extra operations and register spills
- See compiler optimization report
 - All the compilers have some support for it
 - Some of them are able to generate very detailed reports about loop unrolling, auto-vectorization, VLIW slots scheduling, etc

CONSIDERED METRICS

Wall(-clock) time

is a human perception of the span of time from the start to the completion of a task.

Power consumption

is the electrical energy which is consumed to complete a task.

Processor time (or runtime)

is the total execution time during which a processor was dedicated to a task (i.e. executes instructions of that task).

ASSEMBLY

Assembler is a must-have to check the compiler but it is rarely used to write low-level code.

\$ gcc code.c -S -o asm.s

- Assembly writing is the least portable optimization
- Inline assembly limits compiler optimizations
- Assembly does not give overwhelming speedup nowadays
- Sometimes it is needed to overcome compiler bugs and optimization limitations

INTERMEDIATE LANGUAGE

Intermediate representation (IR) is a source code representation in some abstract Instruction Set Architecture (ISA), which is close to a classic RISC

High Level IR

is close to the source and can be easily generated from the source code. Some code optimizations are possible. It is not very suitable for target machine optimization.

Low Level IR

is close to the target machine and used for machinedependent optimizations: register allocation, instruction selection, peephole optimization.

GETTING IR

GENERIC and GIMPLE

GNU Compiler Collection

```
-fdump-tree-all-fdump-tree-optimized -fdump-tree-ssa
-fdump-rtl-all
```

LLVM IL

clang and other LLWM based compilers

-emit-11vm

CIL (C Intermediate Language)

Visual Studio cl.exe

GETTING IR

```
$ clang -Os -S -emit-llvm test.c -o test.ll
$ cat test.ll
```

```
for(; j <= width - 4; j += 4 )
{
    uchar t0 = tab[src[j]];
    uchar t1 = tab[src[j+1]];
    dst[j] = t0;
    dst[j+1] = t1;
    t0 = tab[src[j+2]];
    t1 = tab[src[j+3]];
    dst[j+2] = t0;
    dst[j+3] = t1;
}</pre>
```

GETTING IR

```
.lr.ph4:
                            ; preds = %0, %.lr.ph4
 %indvars.iv5 = phi i64 [ %indvars.iv.next6, %.lr.ph4 ], [ 0, %0 ]
 %6 = getelementptr inbounds i8* %src, i64 %indvars.iv5
 %7 = load i8* %6, align 1, !tbaa !1
 %8 = zext i8 \%7 to i64
 %9 = getelementptr inbounds i8* %tab, i64 %8
 %10 = load i8* %9, align 1, !tbaa !1
 %11 = or i64 %indvars.iv5, 1
 %12 = getelementptr inbounds i8* %src, i64 %11
 %30 = load i8* %29, align 1, !tbaa !1
 %31 = getelementptr inbounds i8* %dst, i64 %19
 store i8 %24, i8* %31, align 1, !tbaa !1
 %32 = getelementptr inbounds i8* %dst, i64 %25
 store i8 %30, i8* %32, align 1, !tbaa !1
 %indvars.iv.next6 = add nuw nsw i64 %indvars.iv5, 4
 %33 = trunc i64 %indvars.iv.next6 to i32
 %34 = icmp sqt i32 %33, %1
 br i1 %34, label %..preheader_crit_edge, label %.lr.ph4
```

Compiler don't care how many variables are used in code, register allocation is done after IR rotations.

GCC FEEDBACK OPTIONS

Enables optimization information printing

```
-fopt-info
-fopt-info-<optimized/missed/note/all>
-fopt-info-all-
<ipa/loop/inline/vec/optall>
-fopt-info=filename
```

- Controls the amount of debugging output the scheduler prints on targets that use instruction scheduling
 - -fopt-info -fsched-verbose=n
- Controls the amount of output from auto-vectorizer
 - -ftree-vectorizer-verbose=n

GCC FEEDBACK OPTIONS

Outputs all optimization info to stderr.

```
gcc -03 -fopt-info
```

 Outputs missed optimization report from all the passes to missed.txt

```
gcc -03 -fopt-info-missed=missed.txt
```

 Outputs information about missed optimizations as well as optimized locations from all the inlining passes to inline.txt.

```
gcc -03 -fopt-info-inline-optimized-
missed=inline.txt
```

GCC FEEDBACK EXAMPLE

```
1.cc:193:9: note: loop vectorized
1.cc:193:9: note: loop versioned for vectorization because of possib
le aliasing
1.cc:193:9: note: loop peeled for vectorization to enhance alignment
1.cc:96:9: note: loop vectorized
1.cc:96:9: note: loop peeled for vectorization to enhance alignment
1.cc:51:9: note: loop vectorized
1.cc:51:9: note: loop peeled for vectorization to enhance alignment
1.cc:193:9: note: loop with 7 iterations completely unrolled
1.cc:32:13: note: loop with 7 iterations completely unrolled
1.cc:96:9: note: loop with 15 iterations completely unrolled
1.cc:51:9: note: loop with 15 iterations completely unrolled
1.cc:584:9: note: loop vectorized
1.cc:584:9: note: loop versioned for vectorization because of possib
le aliasing
1.cc:584:9: note: loop peeled for vectorization to enhance alignment
1.cc:482:9: note: loop vectorized
1.cc:482:9: note: loop peeled for vectorization to enhance alignment
1.cc:463:5: note: loop vectorized
1.cc:463:5: note: loop versioned for vectorization because of possib
le aliasing
1.cc:463:5: note: loop peeled for vectorization to enhance alignment
```

THE MAGIC BOX!

FILLING/COPYING MEMORY BLOCKS

Compiler automatically uses the library functions memset and memcpy to initialize and copy memory blocks

```
static char a[100000];
static char b[100000];
static int at(int idx, char val)
 if (idx>=0 && idx<100000)
  a[idx] = val;
int main()
 int i;
 for (i=0; i<100000; ++i) a[i]=42;
 for (i=0; i<100000; ++i) at (i,-1);
 for (i=0; i<100000; ++i) b[i] = a[i];
```

FILLING/COPYING MEMORY BLOCKS

Compiler knows what you mean

```
main:
.LFB1:
  .cfi startproc
  subq $8, %rsp
  .cfi_def_cfa_offset 16
  movl $100000, %edx
  movl $42, %esi
  movl $a, %edi
  call memset
  movl $100000, %edx
  mov1 $255, %esi
  movl $a, %edi
  call memset
  movl $100000, %edx
  movl $a, %esi
  movl $b, %edi
  call memcpy
  addq $8, %rsp
  .cfi def cfa offset 8
  ret
```

FILLING/COPYING MEMORY BLOCKS

The same picture, if the code is compiled for ARM target

```
main:
  ldr r3, .L3
  mov r1, #42
  stmfd sp!, {r4, lr}
  add r3, pc, r3
  movw r4, #34464
  movt r4, 1
  mov r0, r3
  mov r2, r4
  bl memset(PLT)
  mov r2, r4
  mov r1, #255
  bl memset(PLT)
  mov r2, r4
  mov r3, r0
  ldr r0, .L3+4
  mov r1, r3
  add r0, pc, r0
  add r0, r0, #1792
  bl memcpy (PLT)
  ldmfd sp!, {r4, pc}
```

FUNCTION BODY INLINING

Replaces functional call to function body itself **Enables all further optimizations!**

```
int square(int x)
{
  return x*x;
}

for (int i = 0; i < len; i++)
  arr[i] = square(i);</pre>
```

Becomes

```
for (int i = 0; i < len; i++)
  arr[i] = i*i;</pre>
```

```
.L2:
   add x2, x4, :lo12:.LANCHOR0
   mov x1, 34464
   mul w3, w0, w0
   movk x1, 0x1, 1s1 16
   str w3, [x2,x0,1s1 2]
   add x0, x0, 1
   cmp x0, x1
   bne .L2
```

```
gcc -march=armv8-a+nosimd -fstrict-
aliasing -O3 -fopt-info 1.c -S -o 1.s
```

- Machine code generation that takes an advantage of vector instructions.
- Most of all modern architectures have vector extensions as a co-processor or as dedicated pipes
 - MMX, SSE, SSE2, SSE4, AVX, AVX-512
 - AltiVec, VSX
 - ASIMD (NEON), MSA
- Enabled by inlining, unrolling, fusion, software pipelining, inter-procedural optimization, and other machine independent transformations.

FUNCTION BODY INLINING

Let's compile the previous example with vector extension enabled **-march=armv8-a+simd**

```
int square(int x)
{
   return x*x;
}

for (int i = 0; i < len; i++)
   arr[i] = square(i);</pre>
```

Becomes

```
for (int i = 0; i < len; i++)
  arr[i] = i*i;</pre>
```

```
add x0, x0, :lo12:.LANCHOR0
movi v2.4s, 0x4
ldr q0, [x1]
add x1, x0, 397312
add x1, x1, 2688
.L2:
mul v1.4s, v0.4s, v0.4s
add v0.4s, v0.4s, v2.4s
str q1, [x0],16
cmp x0, x1
bne .L2
```

It is vectorized because of possibility to inline function call

```
void vectorizeMe(float *a, float *b, int len)
{
  int i;
  for (i = 0; i < len; i++)
    a[i] += b[i];
}</pre>
```

```
$ gcc -march=armv7-a -mfpu=neon-vfpv4 -
mfloat-abi=softfp -mthumb -O3 -fopt-info-
missed 1.c -S -o 1.s
```

NEON does not support full IEEE 754, so gcc cannot vectorize the loop, what it told us

```
.L3:
   fldmias r1!, {s14}
   flds s15, [r0]
   fadds s15, s15, s14
   fstmias r0!, {s15}
   cmp r0, r2
   bne .L3
```

```
1.c:64:3: note: not vectorized:
relevant stmt not supported:_13 =_9+_12;
```

But armv8-a does support, let's check it!

```
gcc -march=armv7-a -mfpu=neon-vfpv4 -
mfloat-abi=softfp -mthumb -O3 -fopt-info-
missed 1.c -S -o 1.s
```

```
.L6:
    ldr q1, [x3],16
    add w6, w6, 1
    ldr q0, [x7],16
    cmp w6, w4
    fadd v0.4s, v0.4s, v1.4s
    str q0, [x8],16
    bcc .L6
```

1.c:64:3: note: loop vectorized

FULL OPTIMIZER'S REPORT

```
1.c:66:3: note: loop vectorized
1.c:66:3: note: loop versioned for vectorization because of possible
  aliasing
1.c:66:3: note: loop peeled for vectorization to enhance alignment
1.c:66:3: note: loop with 3 iterations completely unrolled
1.c:61:6: note: loop with 3 iterations completely unrolled
```

Compiler versions the loop to allow optimized paths in case of aligned and non-aliasing pointers

KEYWORDS

Lit's follow the advice to put some keywords

```
void vectorizeMe(float* __restrict a_,
    float* __restrict b_, int len)
{
    int i;
    float *a = __builtin_assume_aligned(a_, 16);
    float *b = __builtin_assume_aligned(b_, 16);
    for (i = 0; i < len; i++)
        a[i] += b[i];
}</pre>
```

```
1.c:66:3: note: loop vectorized
1.c:66:3: note: loop with 3 iterations
completely unrolled
```

___restrict and ___builtin_assume_aligned keywords only eliminate some loop versioning, but are not very useful from the performance perspective nowadays

SCALARIZATION

Scalarization replaces branchy code with a branchless analogy, usually to allow auto-vectorization of a loop body

```
int branchy(int i)
{
   if (i > 4 && i < 42)
      return 1;
   return 0;
}
int branchless(int i)
{
   return (((unsigned)i) - 5 > 36);
}
```

```
branchy:
sub w0, w0, #5
cmp w0, 36
cset w0, 1s
ret
branchless:
sub w0, w0, #5
cmp w0, 36
cset w0, hi
ret
```

gcc -march=armv8-a+simd -03 1.c -S -o 1.s

Both snippets are compiled to the same instructions!

UNSWITCHING

Unswitching moves loop-invariant conditions out of its body

```
gcc -march=armv8-a+simd -O3 1.c -S -o 1.s
```

```
for (int i = 0; i < len; i++) {
  if (a > 32)
    arr[i] = a;
  else
    arr[i] = 42;
}
```

Becomes

```
if (a > 32) {
  for (int i = 0; i < len; i++)
    arr[i] = a;
} else {
  for (int i = 0; i < len; i++)
    arr[i] = 42;
}</pre>
```

```
cmp w2, 32
 bgt .L6
 mov x2, 0
 mov w3, 42
. T<sub>1</sub>4:
 str w3, [x0, x2, 1s1 2]
 add x2, x2, 1
 cmp w1, w2
 bqt .L4
.L1:
 ret
. I.6:
 mov x3, 0
.T.3:
  str w2, [x0, x3, 1s1 2]
 add x3, x3, 1
  cmp w1, w3
 bat .L3
```

LOOP-INDUCTION VARIABLES

Replacing address arithmetics with pointer arithmetics

```
gcc -march=armv7-a -mfpu=neon -mfloat-abi=softfp -01 1.c -S -o 1.s
```

```
void function(int* arr, int len)
{
  for (int i = 0; i < len; i++)
    arr[i] = 1;
}</pre>
```

```
void function(int* arr, int len)
{
  for (int* p = arr; p < arr + len; p++)
     *p = 1;
}</pre>
```

```
mov r3, r0
add r0, r0, r1, lsl #2
movs r2, #1
.L3:
str r2, [r3], #4
cmp r3, r0
bne .L3
```

```
add r1, r0, r1, lsl #2

movs r3, #1

.L8:

str r3, [r0], #4

cmp r1, r0

bhi .L8
```

Most hand-written pointer optimizations do not make sense with usage optimization levels higher than 00.

STRENGTH REDUCTION

Replaces complex expressions with a simpler analogy

```
double usePow(double x)
{
  return pow(x, 2.0);
}
```

```
usePow:
fmdrr d16, r0, r1
fmuld d16, d16, d16
fmrrd r0, r1, d16
bx lr
```

```
float usePowf(float x)
{
  return powf(x, 2.f);
}
```

```
usePowf:
  fmsr s15, r0
  fmuls s15, s15, s15
  fmrs r0, s15
  bx lr
```

```
gcc -march=armv7-a -mfpu=vfpv4 -mfloat-abi=softfp -mthumb -03 1.c -S -o 1.s
```

STRENGTH REDUCTION (ADVANCED)

Let's look at more complex expression.

```
float useManyPowf(
   float a, float b,
   float c, float d,
   float e, float f,
   float x)
{
  return
   a * powf(x,5.f)+
   b * powf(x,4.f)+
   c * powf(x,3.f)+
   d * powf(x,2.f)+
   e * x
   f;
}
```

```
useManyPowf:
push {r3, 1r}
flds s17, [sp, #56]
 fmsr s24, r1
 movs r1, #0
 fmsr s22, r0
movt r1, 16544
 fmrs r0, s17
 fmsr s21, r2
 fmsr s20, r3
 flds s19, [sp, #48]
 flds s18, [sp, #52]
 bl powf(PLT)
 mov r1, #1082130432
 fmsr s23, r0
 fmrs r0, s17
 bl powf (PLT)
```

```
movs r1, #0
movt r1, 16448
fmsr s16, r0
fmrs r0, s17
bl powf(PLT)
fmuls s16, s16, s24
vfma.f32 s16, s23, s22
fmsr s15, r0
vfma.f32 s16, s15, s21
fmuls s15, s17, s17
vfma.f32 s16, s20, s15
vfma.f32 s16, s19, s17
fadds s15, s16, s18
fldmfdd sp!, {d8-d12}
fmrs r0, s15
pop {r3, pc}
```

GCC was able partly reduce the complexity using vfma

HORNER'S RULE

gcc -march=armv7-a -mfpu=vfpv4 -mfloat-abi=softfp -mthumb -O3 1.c -S -o 1.s

```
applyHornerf:
  flds s15, [sp, #8]
  fmsr s11, r0
  fmsr s12, r1
  flds s14, [sp]
  vfma.f32 s12, s11, s15
  fmsr s11, r2
  flds s13, [sp, #4]
  vfma.f32 s11, s12, s15
  fcpys s12, s11
  fmsr s11, r3
  vfma.f32 s11, s12, s15
  vfma.f32 s14, s11, s15
  vfma.f32 s13, s14, s15
  fmrs r0, s13
  bx lr
```

CASE STUDY: FLOATING POINT

```
double power( double d, unsigned n)
{
  double x = 1.0;
  for (unsigned j = 1; j<=n; j++, x *= d);
  return x;
}
int main ()
{
  double a = 1./0x80000000U, sum = 0.0;
  for (unsigned i=1; i<= 0x80000000U; i++)
     sum += power( i*a, i % 8);
  printf ("sum = %g\n", sum);
}</pre>
```

flags-dp.c

OPTIMIZATION LEVELS

1. Compile it without optimization

```
$ gcc -std=c99 -Wall -O0 flags-dp.c -o flags-dp
$ time ./flags-dp
sum = 7.29569e+08
real 0m24.550s
```

2. Compile it with O1: ~3.26 speedup

```
$ gcc -std=c99 -Wall -O1 flags-dp.c -o flags-dp
$ time ./flags-dp
sum = 7.29569e+08
real 0m7.529s
```

OPTIMIZATION LEVELS

3. Compile it with O2: ~1.24 speedup

```
$ gcc -std=c99 -Wall -O2 flags-dp.c -o flags-dp
$ time ./flags-dp
sum = 7.29569e+08
real 0m6.069s
```

4. Compile it with O3: ~1.00 speedup

```
$ gcc -std=c99 -Wall -O3 flags-dp.c -o flags-dp
$ time ./flags-dp
sum = 7.29569e+08
real 0m6.067s
```

Total speedup is ~4.05

CASE-STUDY: INTEGER

```
int power( int d, unsigned n)
{
  int x = 1;
  for (unsigned j = 1; j<=n; j++, x*=d) ;
  return x;
}
int main ()
{
  int64_t sum = 0;
  for (unsigned i=1; i<0x80000000U; i++)
    sum += power( i, i % 8);
  printf ("sum = %ld\n", sum);
}</pre>
```

flags.c

OPTIMIZATION LEVELS

1. Compile it without optimization

```
$ gcc -std=c99 -Wall -O0 flags.c -o flags
$ time ./flags
sum = 288231861405089791
real 0m18.750s
```

2. Compile it with O1: ~2.64 speedup

```
$ gcc -std=c99 -Wall -O1 flag.c -o flags
$ time ./flags
sum = 288231861405089791
real 0m7.092s
```

OPTIMIZATION LEVELS

3. Compile it with O2:~0.97 speedup

```
$ gcc -std=c99 -Wall -O2 flags.c -o flags
$ time ./flags
sum = 288231861405089791
real 0m7.300s
```

4. Compile it with O3: ~1.00 speedup

```
$ gcc -std=c99 -Wall -O3 flags.c -o flags
$ time ./flags
sum = 288231861405089791
real 0m7.082s
```

WHY THERE IS NO IMPROVEMENT?

ASSEMBLY

Optimization level: -01

```
movl $1, %r8d
 movl $0, %edx
.L9:
 movl %r8d, %edi
 movl %r8d, %esi
 andl $7, %esi
 ie .L10
 movl $1, %ecx
 movl $1, %eax
.L8:
 addl $1, %eax
 imull %edi, %ecx @
 cmpl %eax, %esi @
 jae .L8
.L10:
 movl $1, %ecx
.L7:
 movslq %ecx, %rcx
 addg %rcx, %rdx
 addl $1, %r8d
 jns .L9
 @ printing is here
```

Optimization level: -02

```
$1, %esi
 movl
        $1, %r8d
   movl
        %edx, %edx
   xorl
   .p2align 4,,10
   .p2align 3
.L10:
   movl %r8d, %edi
   andl $7, %edi
   je .L11
          $1, %ecx
   movl
          $1, %eax
   mov1
   .p2align 4,,10
   .p2align 3
.L9:
   addl $1, %eax
   imull %esi, %ecx
          %eax, %edi
   cmpl
   jae .L9
   movslq %ecx, %rcx
```

```
.L8:

addl $1, %r8d

addq %rcx, %rdx

testl %r8d, %r8d

movl %r8d, %esi

jns .L10

subq $8, %rsp

@ printing is here

ret

.L11:

movl $1, %ecx

jmp .L8
```

Compiler overdone with branch twiddling and alignment

HELPING A COMPILER

Compiler usually applies optimization to the inner loops. In this example number of iterations in the inner loop depends on a value of an induction variable of the outer loop.

Let's help the compiler (flags-dp-tuned.c)

HELPING A COMPILER

```
/*power function is not changed*/
int main ()
{
    double a = 1./0x80000000U, s = -1.;
    for (double i=0; i<=0x80000000U-8; i += 8)
    {
        s+=power((i+0)*a,0);s+=power((i+1)*a,1);
        s+=power((i+2)*a,2);s+=power((i+3)*a,3);
        s+=power((i+4)*a,4);s+=power((i+5)*a,5);
        s+=power((i+6)*a,6);s+=power((i+7)*a,7);
    }
    printf ("sum = %g\n", s);
}</pre>
```

```
$ gcc -std=c99 -Wall -O3 flags-dp-tuned.c -o flags-dp-tuned
$ time ./flags-dp-tuned
sum = 7.29569e+08
real 0m2.448s
```

Speedup is ~2.48x.

HELPING A COMPILER

Let's try it for integers (flags-tuned.c)

```
/*power function is not changed*/
int main ()
{
   int64_t sum = -1;
   for (unsigned i=0; i<=0x80000000U-8; i += 8)
   {
      sum+=power(i+0, 0); sum+=power(i+1,1);
      sum+=power(i+2, 2); sum+=power(i+3,3);
      sum+=power(i+4, 4); sum+=power(i+5,5);
      sum+=power(i+6, 6); sum+=power(i+7,7);
   }
   printf ("sum = %ld\n", sum);
}</pre>
```

```
$ gcc -std=c99 -Wall -O3 flags-tuned.c -o flags-tuned
$ time ./flags-tuned
sum = 288231861405089791
real 0m1.286s
```

Speedup is ~5.5x.

HOW TO LEARN OPTIMIZATION?

HOW TO LEARN OPTIMIZATION?

Optimization is a **craft** rather than a **science**.

Practice more

Do not make practical knowledge too theoretical

Look, what other people do

Find use-cases of different approaches and techniques

Dig into an architecture

Hardware evolves rapidly, hence today's devices obsolete in a wink. Comprehensive knowledge helps to see beforehand

KNOWLEDGE WHICH IS REQUIRED

1. The code

- The problem, it solves
- The algorithm, it implements
- The algorithmic complexity

2. The compiler

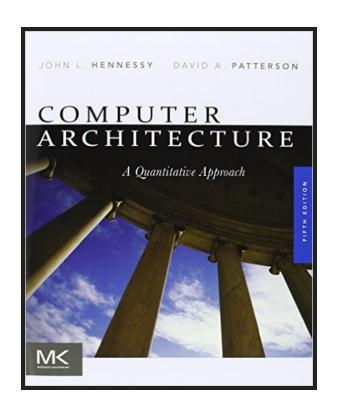
- Compilation trajectory
- Compiler's capabilities and obstacles

3. The platform

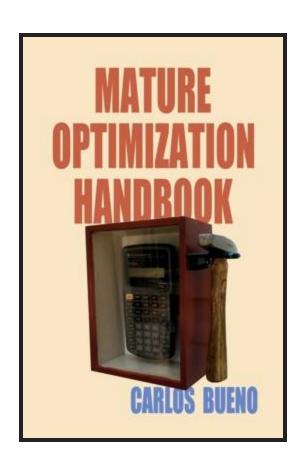
Architecture capabilities

 $I_{nstruction} S_{et} A_{rchitecture}$

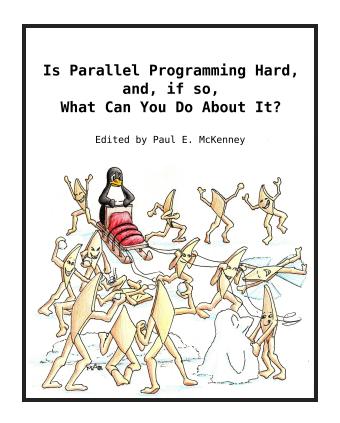
Micro-architecture specifics



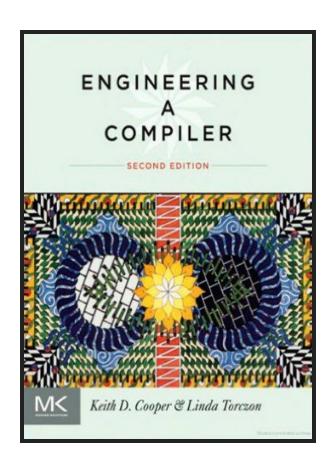
Computer Architecture, Fifth Edition:
A Quantitative Approach
by John L. Hennessy and David A. Patterson.



The Mature Optimization Handbook by Carlos Bueno



Is Parallel Programming Hard, And, If So, What Can You Do About It? by Paul E. McKenney



Engineering a Compiler by Keith Cooper and Linda Torczon

SUMMARY

- Compiler detects memcpy/memset, even if they are implement manually, and call library function instead. Library functions are usually more efficient.
- __restrict and __builtin_assume_aligned keywords only eliminate some loop versioning.
- For typical constructs a compiler usually does better job.
- Most hand-written pointer optimizations do not make sense with usage of optimization levels higher than O0.
- Function body inlining and loop unswitching enables all other optimizations.
- Compiler optimization is a multi-phase iterative process

SUMMARY

- Knowledge about the code, the compiler and the platform is a must-have.
- The main task of an optimizer is finding the bottleneck.
- Optimizer's mastership is to know where to stop.
- Stick to the high-to-low approach.
- Practice, look what others do, dig into an architecture.
- Express your intentions to the compiler clearly.
- Learn a compiler.
- A compiler is not aware of your program semantics.
- Write pure code!

THE END

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