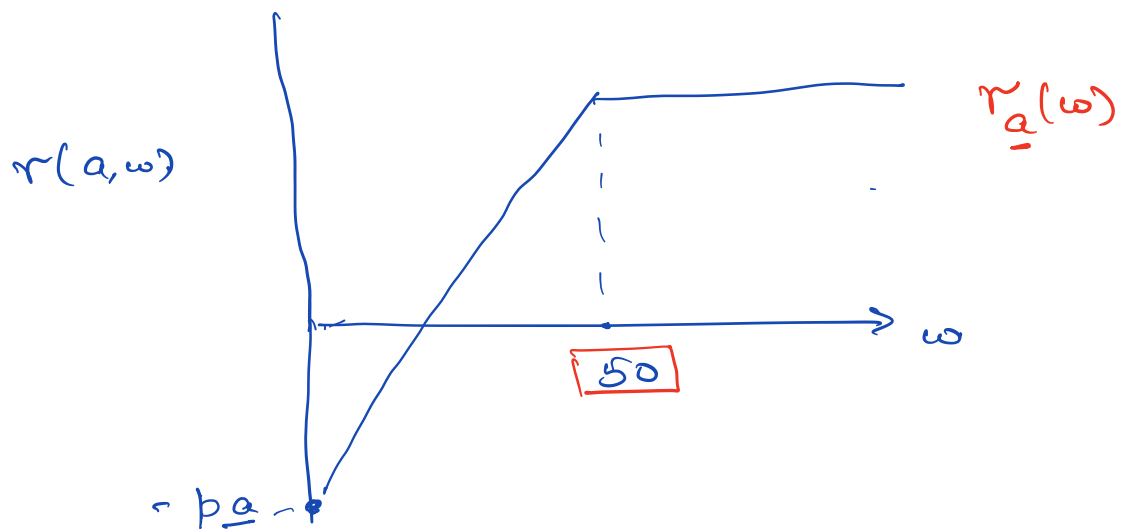
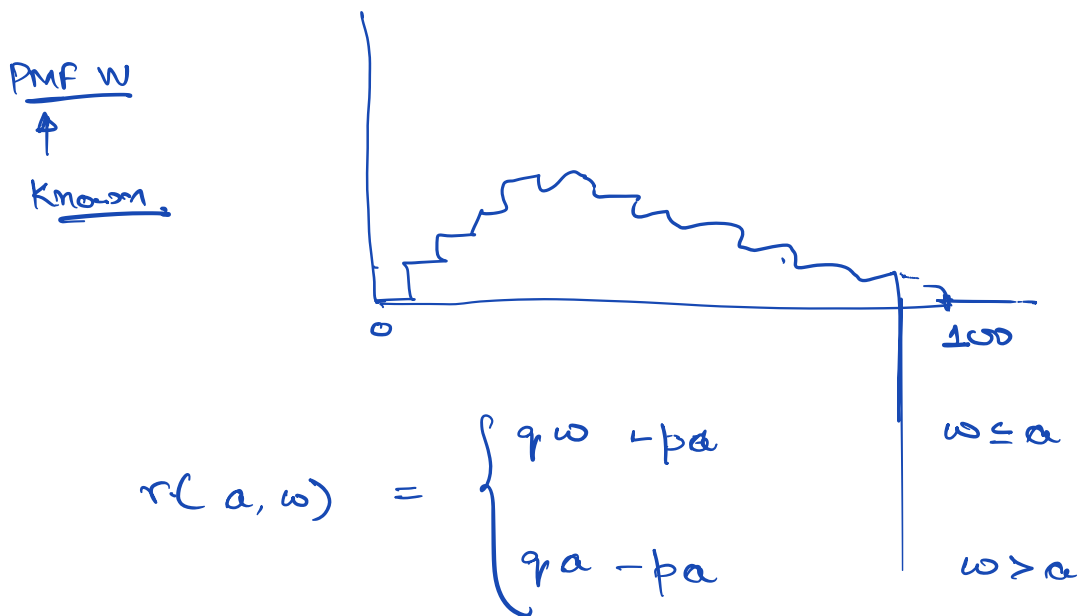


1) Newsvendor Problem

2) Blackwell's principle of irrelevance

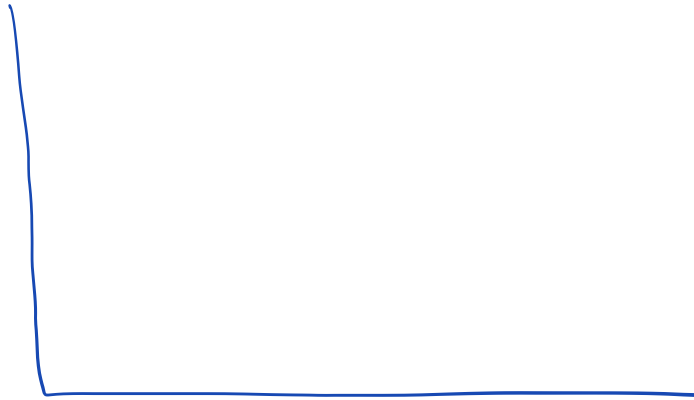
$\$p < \$q$   
Action:  $a$  Demand:  $w$



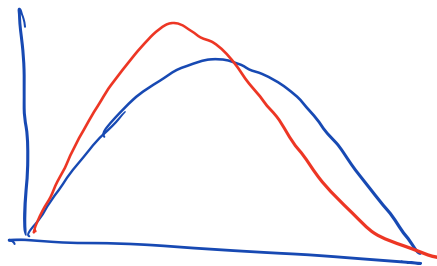
$$J(a) = E[r(a, \omega)]$$

↑

$$J(a) = \sum_{\omega \in \Omega} P_{\omega}(\omega) r(a, \omega)$$



Location 1  
Location 2

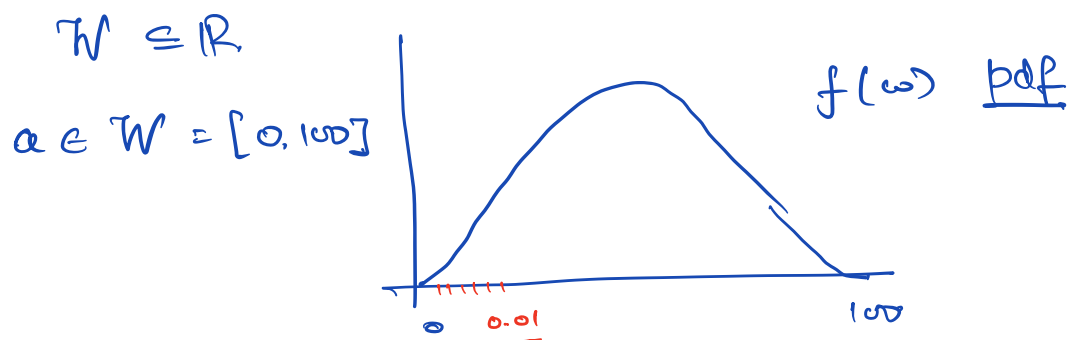


$$J^* = \max_{a \in A} J(a)$$

Opt. perf.

$$a^* = \arg \max_{a \in A} J(a)$$

Opt. action



$$J(a) = \int_0^{100} f(w) r(a, w) dw$$

$$a^* = \arg \max_{a \in A} J(a)$$

Plot it appears  
 $\nabla^2 J(a)$  is concave

$$\frac{d}{da} J(a) = 0 \quad \frac{d^2}{da^2} J(a) < 0$$

$$r(a, w) = \begin{cases} qw - pa & w \leq a \\ qa - pw & w > a \end{cases}$$

$$J(a) = \int_0^a f(w) [qw - pa] dw + \int_a^{100} f(w) [qa - pw] dw$$

$$\frac{d}{da} J(a) = \cancel{[qa - pa] f(a)} + \int_0^a [-p] f(w) dw - \cancel{[qa - pa] f(a)} + \int_a^{100} f(w) (q - p) dw$$

Leibniz integral rule:

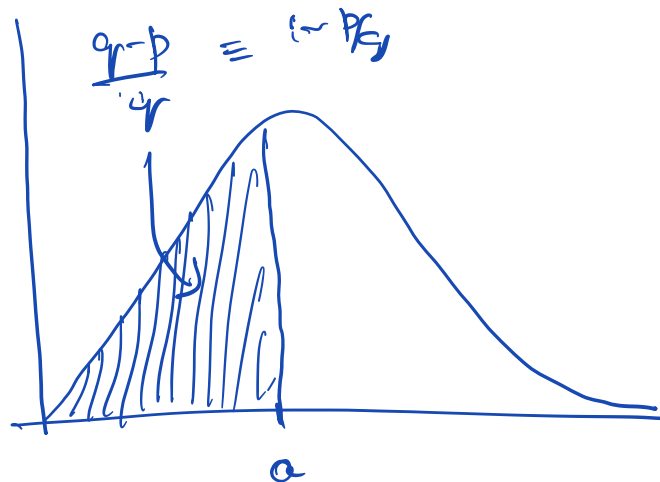
$$\frac{d}{dx} \left( \int_{p(x)}^{q(x)} f(x, t) dt \right) = f(x, q(x)) \frac{d}{dx} q(x) - f(x, p(x)) \frac{d}{dx} p(x) + \int_{p(x)}^{q(x)} \frac{\partial}{\partial x} f(x, t) dt$$

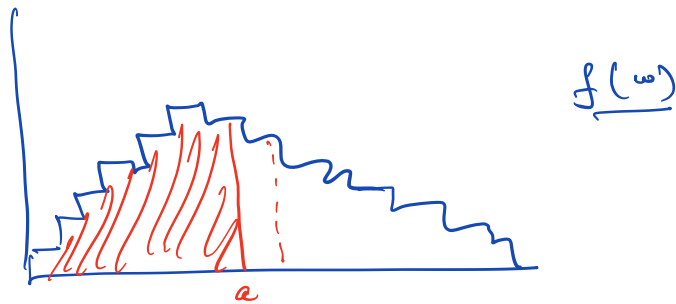
$$= -p F(a) + (q-p) [1 - F(a)]$$

$$= \underline{\underline{0}}$$

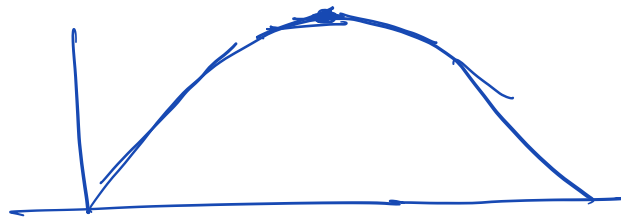
$$F(a) = \frac{q-p}{q} \equiv a = F^{-1} \left( \frac{q-p}{q} \right)$$

↑  
Critical fractile





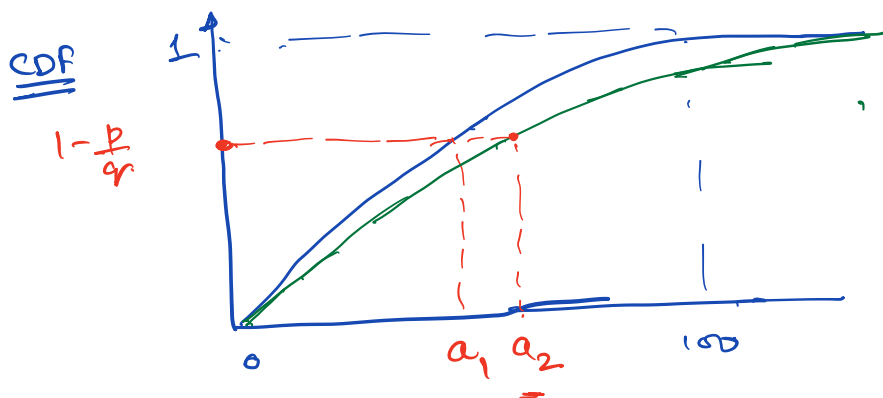
$$\underline{J(i+1) - J(i)} \geq 0$$



$$\max_i \{ i : \underline{J(i+1) - J(i)} \geq 0 \}$$

$$\max \{ i : F(i) \leq \frac{q-p}{q} \} \rightarrow \text{opt action}$$

Comparing  $a$  for multiple locations



Stochastic Monotonicity

$$F_2(\omega) \leq F_1(\omega)$$

$a_2$  vs  $a_1$

$$a_2 \geq a_1$$

# Making decision w/ info

$$c: \underbrace{S}_{\substack{\uparrow \\ \text{Info avail} \\ \text{to DM} \\ \text{"state"}}} \times \underbrace{A}_{\substack{\uparrow \\ \text{Action}}} \times \underbrace{W}_{\substack{\uparrow \\ \text{Uncertainty}}} \rightarrow \underline{\mathbb{R}_{\geq 0}} \rightarrow \text{known PMF}$$

$$\begin{aligned} c_i &\geq 0 \\ \sum_{i=0}^{\infty} c_i &\rightarrow \text{limit} \\ &\rightarrow \infty \\ &\rightarrow +\infty - \infty \\ &\text{Not define} \\ &\quad \uparrow \\ &\quad A \end{aligned}$$

$(\Omega, \mathcal{F}, P)$  Underlying prob. space.  
 $(S, W)$  are rv of  $(\Omega, \mathcal{F}, P)$

Policy  $\pi: S \rightarrow A$

$$\begin{aligned} J(\pi) &= \mathbb{E} [c(S, \pi(S), W)] \\ &= \sum_{(S, W) \in S \times W} P(S, W) c(S, \pi(S), W) \end{aligned}$$

Finitely many possibilities of  $\pi$ .  $|A|^{|S|}$

$$\pi^* = \arg \min_{\pi \in \Pi} J(\pi)$$

opt. policy



Functional optimization prob.

(P1)

$\forall s \in S$

$$\pi^0(s) = \arg \min_{a \in A} \underbrace{\mathbb{E} [c(s, a, W) | S=s]}_{Q(s, a)}$$

(P2)

1

$$\begin{aligned}
 \forall s, a \quad Q(s, a) &= \mathbb{E} [c(s, a, w) \mid s=s] \quad \downarrow \text{Comp } |S| \times |A| \\
 &= \sum_{w \in W} P_{w|s}(w|s) c(s, a, w)
 \end{aligned}$$

$$\pi^0(s) = \underset{a \in A}{\operatorname{argmin}} Q(s, a)$$

Claim 1  $\pi^0$  is optimal for PI

Proof Let  $\pi$  be any policy

$$\begin{aligned}
 J(\pi) &= \mathbb{E} [c(s, \pi(s), w)] \\
 &= \mathbb{E} \left[ \underbrace{\mathbb{E} [c(s, \pi(s), w) \mid s]} \right] \\
 &\geq \mathbb{E} \left[ \mathbb{E} [c(s, \pi^0(s), w) \mid s] \right] \\
 &= J(\pi^0)
 \end{aligned}$$

$\Rightarrow \pi^0$  is opt.

Claim 2  $P_s(s) > 0, \forall s.$

Then all opt. soln of (P1) are also  
soln of (P2).

Pf Proof by contradiction.

Let  $\mu^*$  is a opt policy that does not satisfy (P2)

$$\pi^0(s) = \arg \min_{a \in A} \underbrace{\mathbb{E}[c(s, a, w) | S=s]}_{Q(s, a)}$$

$$Q(s, \pi^0(s)) \leq Q(s, \mu^*(s))$$

$$\exists s^0 \text{ s.t. } Q(s^0, \pi^0(s^0)) < Q(s^0, \mu^*(s^0))$$

$$\mathbb{E}[c(s, \pi^0(s), w) | S=s] \leq \mathbb{E}[c(s, \mu^*(s), w) | S=s]$$

↑ strict for  $s^0$

$$\sum_{s \in S} P_s(s) \mathbb{E}[\dots] < \sum_{s \in S} P_s(s) \mathbb{E}[\dots]$$

$$P_s(s^0) > 0$$

$$\mathbb{E}[c(s, \pi^0(s), w)] < \mathbb{E}[c(s, \mu^*(s), w)]$$