Last Time

PZ Plots __ BIBO Stability Form of the step-resp.

· Dominant Pole Approx

Example

a)
$$G_1(s) = \frac{1}{s+2}$$

b)
$$G_{12}(s) = \frac{1}{s+2} \cdot \frac{20}{s+20}$$

Last class, Loe saw that they have similar step response

$$C_1(s) = R(s)G_1(s) = \frac{1}{s(s+2)}$$

$$= 0.6 - 0.5$$

$$= 8+2$$

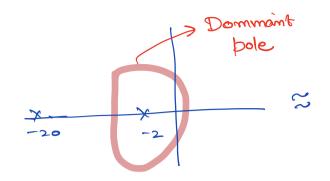
$$C_2(s) = 2(s)G_2(s) = \frac{20}{8(s+2)(s+20)}$$

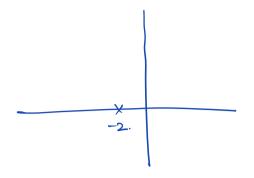
= $\frac{0.5}{8} - \frac{0.55}{s+2} + \frac{0.055}{s+20}$

$$C_1(t) = 0.5 - 0.5e^{-2t}$$

$$c_2(b) = 0.5 - 0.55e^{-2b} + 0.055e^{-20b}$$

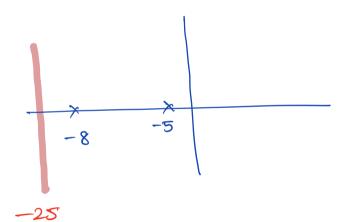




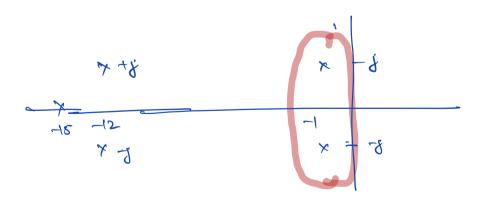


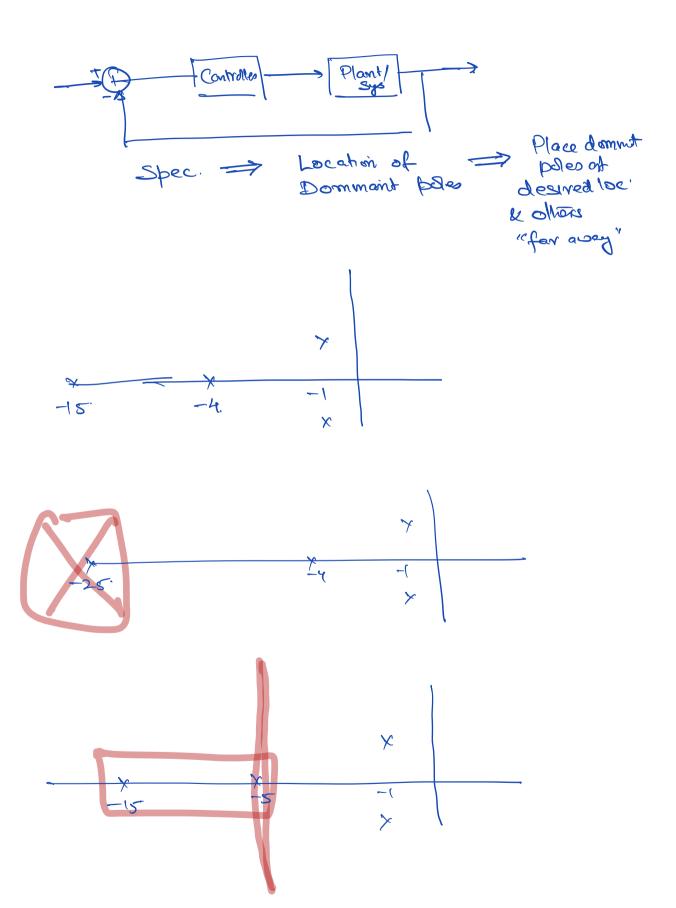
In the notes, it says 10

pr dominates p2 17 52 7501.



is dommont tole





Step response of 1st & 2nd oxder systems

1st car order

[Proper TF]

$$G(s) = \frac{b}{s+a} = \frac{b}{a} \frac{a}{s+a}$$

= K a [Comonical form of 1st order]

[Normalized TF)

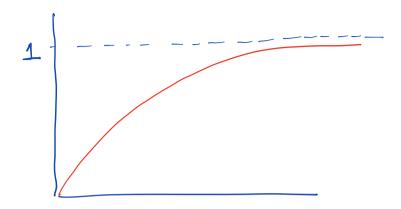


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Step zesponse _ > /s

$$C(s) = R(s)G(s) = 01$$
 $S(s+a)$

General,



Final value Thim

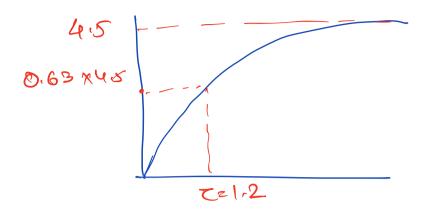
$$c(\infty) = \lim_{s\to 0} s(s)$$

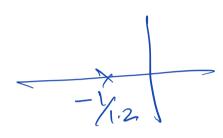
$$= \lim_{s\to 0} s \cdot \frac{1}{s}G(s)$$

Time Const

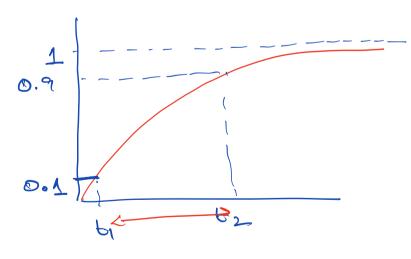
SYSTEM ID.

K a sta





Rise Time



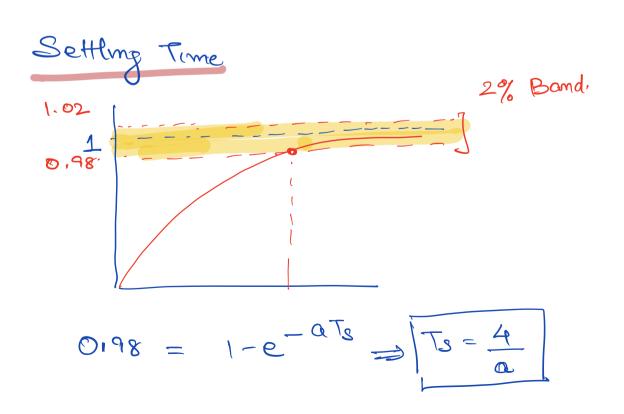
 $T_{\gamma} = t_2 - t_1$

$$C(t) = 1 - e^{-at}$$

$$0.1 = 1 - e^{-at}. \implies t_1 = 0.11/a$$

$$0.9 = 1 - e^{-at}. \implies t_2 = 2.31$$

$$0.9 = t_2 - t_1 = 2.2$$



Example.
$$G(s) = 100 = 40$$

 $S+50 = 40$
 $S+60 = 40$
 S

