Convergence Analysis

November 4, 2022

Notation & Definitions

- t : time index, $t \in \mathbb{Z}^+$.

- z_t : position of the target at time t, $z_t \in \mathbb{R}^d$.

- x_t : position of the agent at time t, $x_t \in \mathbb{R}^d$.

- $\ell_t(x, z)$: stochastic loss as evaluated by the zeroth-order oracle at time t, with the position of agent as x, and the position of target as z for $x, z \in \mathbb{R}^d$.

- $\ell_{\mu,t}(x, z) := \mathbb{E}_u[\ell_t(x + \mu u, z)]$ for $x, z \in \mathbb{R}^d$, $u \sim \mathcal{N}(0, I_d)$ and $\mu \in \mathbb{R}$.

- $\nabla \ell_{\mu,t}(x, z) := \mathbb{E}_u\left[g_{\mu,t}(x, z)\right]$ where $g_{\mu,t}(x, z) := \dfrac{\ell_t(x + \mu u, z) - \ell_t(x, z)}{\mu} u$ for $x, z \in \mathbb{R}^d$, $u \sim \mathcal{N}(0, I_d)$ and $\mu \in \mathbb{R}$.

- $\ell_t(x) := \mathbb{E}_z\left[\ell_t(x, z)\right]$ for $x, z \in \mathbb{R}^d$.

Assumptions

Assumption 1. *(Unbiased Stochastic Zeroth-Order Oracle) For any $t \in \mathbb{Z}^+$ and $x, z \in \mathbb{R}^d$, we have*

$$\mathbb{E}_z\left[\ell_t(x, z)\right] = \ell_t(x_t). \tag{1}$$

Assumption 2. *(Unbiased Stochastic First-Order Oracle) For any $t \in \mathbb{Z}^+$ and $x, z \in \mathbb{R}^d$, we have*

$$\mathbb{E}_z\left[\nabla \ell_t(x, z)\right] = \nabla \ell_t(x) \tag{2}$$

Assumption 3. *(L-smoothness) Each $\ell_t(x, z)$ is continuously differentiable and L-smooth over x on $\mathbb{R}^d$, that is, there exists an $L \geq 0$ such that for all $x, y, z \in \mathbb{R}^d$ and $t \in \mathbb{Z}^+$, we have*

$$\|\nabla \ell_t(x, z) - \nabla \ell_t(y, z)\| \leq L\|x - y\|. \tag{3}$$

We denote this by $\ell_t(x, z) \in C_L^{1,1}(\mathbb{R}^d)$.

Assumption 4. *(Contractive Compression) The compression function $\mathcal{C}$ is a contraction mapping, that is,*

$$\mathbb{E}_{\mathcal{C}}\left[\|\mathcal{C}(x) - x\|^2 \mid x\right] \leq (1 - \delta)\|x\|^2 \tag{4}$$

for all $x \in \mathbb{R}^d$ where $0 < \delta \leq 1$, and the expectation is over the randomness generated by compression $\mathcal{C}$.

Assumption 5. *(Bounded Stochastic Gradients) For any $t \in \mathbb{Z}^+$ and $x, z \in \mathbb{R}^d$, there exist $\sigma, M > 0$ such that*

$$\mathbb{E}_z \left[\|\nabla \ell_t(x, z)\|^2 \right] \leq \sigma^2 + M \|\nabla \ell_t(x)\|^2. \tag{5}$$

Assumption 6. *(Bounded Drift in Time) There exists a nonnegative sequence $\{\omega_t\}_{t=1}^T$ such that for all $t \in \mathbb{Z}^+$, $|\ell_t(x, z) - \ell_{t+1}(x, z)| \leq \omega_t$ for any $x, z \in \mathbb{R}^d$. Note that in the case where $\ell_{t+1} = \ell_t$, this assumption holds with $\omega_t = 0$.*

Lemmas

Suppose $\ell_t(x, z) \in C_L^{1,1}(\mathbb{R}^d)$ over x. We have the following results:

Lemma 1. *$\ell_{\mu,t}(x, z) \in C_{L_\mu}^{1,1}(\mathbb{R}^d)$ over x, where $L_\mu \leq L$.*

Lemma 2. *$\ell_{\mu,t}(x, z)$ has the following gradient with respect to x:*

$$\nabla \ell_{\mu,t}(x, z) = \frac{1}{(2\pi)^{d/2}} \int \frac{\ell_t(x + \mu u, z) - \ell_t(x, z)}{\mu} u e^{(-\frac{1}{2} \|u\|^2)} du, \tag{6}$$

where $u \sim \mathcal{N}(0, I_d)$.

Lemma 3. *For any $x, z \in \mathbb{R}^d$, we have*

$$|\ell_{\mu,t}(x, z) - \ell_t(x, z)| \leq \frac{\mu^2 L d}{2}. \tag{7}$$

Lemma 4. *For any $x, z \in \mathbb{R}^d$, we have*

$$\|\nabla \ell_{\mu,t}(x, z) - \nabla \ell_t(x, z)\| \leq \frac{\mu}{2} L (d+3)^{\frac{3}{2}}, \tag{8}$$

where the gradient is with respect to x.

Lemma 5. *For any $x, z \in \mathbb{R}^d$, we have*

$$\mathbb{E}_u \left[\left\| \frac{\ell_t(x + \mu u, z) - \ell_t(x, z)}{\mu} u \right\|^2 \right] \leq \frac{\mu^2}{2} L^2 (d+6)^3 + 2(d+4) \|\nabla \ell_t(x, z)\|^2, \tag{9}$$

where $u \sim \mathcal{N}(0, I_d)$ and the gradient is with respect to x.

Lemma 6. *(Young's inequality) For any $x, y \in \mathbb{R}^d$ and $\lambda > 0$, we have*

$$\langle x, y \rangle \leq \frac{\|x\|^2}{2\lambda} + \frac{\|y\|^2 \lambda}{2}. \tag{10}$$

EF-ZO-SGD Convergence Analysis

We work with the following algorithm:

Algorithm 1 EF-ZO-SGD

Input: Number of time steps $T \in \mathbb{Z}^+$, smoothing parameter $\mu \in \mathbb{R}$, initial source position $x_0 \in \mathbb{R}^d$, learning rate $\eta \in \mathbb{R}$, sequence of target positions $\{z_t\}_{t=1}^T \subset \mathbb{R}^d$.

Output: Sequence of optimal source positions $\{x_t\}_{t=1}^T \subset \mathbb{R}^d$.

1: $e_0 = 0$
2: **for** $t = 1, \ldots, T$ **do**
3: $\quad u_t \sim \mathcal{N}(0, I_d)$
4: $\quad g_{\mu,t}(x_t, z_t) = \dfrac{\ell_t(x_t + \mu u_t, z_t) - \ell_t(x_t, z_t)}{\mu} u_t$
5: $\quad p_t = g_{\mu,t}(x_t, z_t) + e_t$
6: $\quad x_{t+1} = x_t - \eta \mathcal{C}(p_t)$
7: $\quad e_{t+1} = p_t - \mathcal{C}(p_t)$
8: **end for**

In the analysis, we assume that $z_t \in \mathbb{R}^d$ are *i.i.d.* random variables for all $t \in \mathbb{Z}^+$.

Let $\tilde{x}_t$ be defined as follows (following the analysis in [1]):

$$\tilde{x}_t = x_t - \eta e_t. \tag{11}$$

From algorithm 1, we know that $e_{t+1} = p_t - \mathcal{C}(p_t)$ and $p_t = g_{\mu,t}(x_t, z_t) + e_t$, so we can rewrite $\tilde{x}_{t+1}$ as

$$
\begin{aligned}
\tilde{x}_{t+1} &= x_{t+1} - \eta p_t + \eta \mathcal{C}(p_t) \\
&= x_t - \eta \mathcal{C}(p_t) - \eta g_{\mu,t}(x_t, z_t) - \eta e_t + \eta \mathcal{C}(p_t) \\
&= x_t - \eta e_t - \eta g_{\mu,t}(x_t, z_t) \\
&= \tilde{x}_t - \eta g_{\mu,t}(x_t, z_t),
\end{aligned}
\tag{12}
$$

where $g_{\mu,t}(x_t, z_t) := \dfrac{\ell_t(x_t + \mu u_t, z_t) - \ell_t(x_t, z_t)}{\mu} u_t$ and $u_t \sim \mathcal{N}(0, I_d)$.

By definition, $\ell_{\mu,t}(x_t, z_t) := \mathbb{E}_{u_t}[\ell_t(x_t + \mu u_t, z_t)]$, so by assumption 3, we can write the following:

$$\ell_{\mu,t}(\tilde{x}_{t+1}, z_{t+1}) \le \ell_{\mu,t}(\tilde{x}_t, z_t) + \langle \nabla \ell_{\mu,t}(\tilde{x}_t, z_t), \tilde{x}_{t+1} - \tilde{x}_t \rangle + \frac{L}{2} \|\tilde{x}_{t+1} - \tilde{x}_t\|^2. \tag{13}$$

Now by assumption 6, we get:

$$\ell_{\mu,t+1}(\tilde{x}_{t+1}, z_{t+1}) \le \ell_{\mu,t}(\tilde{x}_t, z_t) - \eta \langle g_{\mu,t}(x_t, z_t), \nabla \ell_{\mu,t}(\tilde{x}_t, z_t) \rangle + \frac{L\eta^2}{2} \|g_{\mu,t}(x_t, z_t)\|^2 + \omega_t \tag{14}$$

Since $\nabla \ell_{\mu,t}(x_t, z_t) = \mathbb{E}_{u_t}[g_{\mu,t}(x_t, z_t)]$, we have the following:

$$
\begin{aligned}
\mathbb{E}_{u_t}[\langle g_{\mu,t}(x_t, z_t), \nabla \ell_{\mu,t}(\tilde{x}_t, z_t) \rangle] &= \langle \nabla \ell_{\mu,t}(x_t, z_t), \nabla \ell_{\mu,t}(\tilde{x}_t, z_t) \rangle \\
&= \frac{1}{2}\|\nabla \ell_{\mu,t}(x_t, z_t)\|^2 + \frac{1}{2}\|\nabla \ell_{\mu,t}(\tilde{x}_t, z_t)\|^2 - \frac{1}{2}\|\nabla \ell_{\mu,t}(x_t, z_t) - \nabla \ell_{\mu,t}(\tilde{x}_t, z_t)\|^2.
\end{aligned}
\tag{15}
$$

In the last step, we use the fact that $2\langle a, b \rangle = \|a\|^2 + \|b\|^2 - \|a - b\|^2$. Plugging this into (14), we get:

$$
\begin{aligned}
\ell_{\mu,t+1}(\tilde{x}_{t+1}, z_{t+1}) \le{}& \ell_{\mu,t}(\tilde{x}_t, z_t) - \frac{\eta}{2}\|\nabla \ell_{\mu,t}(x_t, z_t)\|^2 - \frac{\eta}{2}\|\nabla \ell_{\mu,t}(\tilde{x}_t, z_t)\|^2 \\
&+ \frac{L^2 \eta}{2}\|x_t - \tilde{x}_t\|^2 + \frac{L\eta^2}{2}\mathbb{E}_{u_t}[\|g_{\mu,t}(x_t, z_t)\|^2] + \omega_t.
\end{aligned}
\tag{16}
$$

Note that $\|\nabla \ell_{\mu,t}(x_t, z_t) - \nabla \ell_{\mu,t}(\tilde{x}_t, z_t)\|^2 \leq L^2 \|x_t - \tilde{x}_t\|^2$ because of lemma 1. Also, we can drop $-\frac{\eta}{2}\|\nabla \ell_{\mu,t}(\tilde{x}_t, z_t)\|^2$ because it is always nonpositive. Using the fact that $\tilde{x}_t - x_t = \eta e_t$, we get:

$$\underbrace{\frac{\eta}{2}\|\nabla \ell_{\mu,t}(x_t, z_t)\|^2}_{\text{Term III}} \leq \underbrace{[\ell_{\mu,t}(\tilde{x}_t, z_t) - \ell_{\mu,t+1}(\tilde{x}_{t+1}, z_{t+1})]}_{\text{Term II}} + \underbrace{\frac{L\eta^2}{2}\mathbb{E}_{u_t}\left[\|g_{\mu,t}(x_t, z_t)\|^2\right]}_{\text{Term I}} + \underbrace{\frac{\eta^3 L^2}{2}\|e_t\|^2}_{\text{Term IV}} + \omega_t. \tag{17}$$

We will put an upper bound to the terms I, II, IV and a lower bound to term III. Starting with **term I**, by lemma 5, we know that

$$\mathbb{E}_{u_t, z_t}\left[\|g_{\mu,t}(x_t, z_t)\|^2\right] \leq 2(d+4)\mathbb{E}_{z_t}\left[\|\nabla \ell_t(x_t, z_t)\|^2\right] + \frac{\mu^2 L^2}{2}(d+6)^3, \tag{18}$$

where $\mathbb{E}_{z_t}[\|\nabla \ell_t(x_t, z_t)\|^2] \leq M\|\nabla \ell_t(x_t)\|^2 + \sigma^2$ by assumption 5.

We can put the following upper bound to **term II** by means of a telescoping sum and subsequently applying lemma 3:

$$\sum_{t=1}^{T} [\ell_{\mu,t}(\tilde{x}_t, z_t) - \ell_{\mu,t+1}(\tilde{x}_{t+1}, z_{t+1})] = \ell_{\mu,1}(\tilde{x}_1, z_1) - \ell_{\mu,T+1}(\tilde{x}_{T+1}, z_{T+1})$$
$$\leq \mu L^2 d + \ell_1(\tilde{x}_1, z_1) - \ell_{T+1}(\tilde{x}_{T+1}, z_{T+1}) \tag{19}$$
$$= \mu L^2 d + \ell_1(x_1, z_1) - \ell_{T+1}(\tilde{x}_{T+1}, z_{T+1}),$$

where we use the fact that $\ell(x_1, z_1) = \ell_1(\tilde{x}_1, z_1)$ because $\tilde{x}_1 = x_1$ by definition. If we take the expectation of both sides with respect to $z_{1:T+1} = \{z_1, z_2, ..., z_{T+1}\}$, owing to the fact that z_t's are i.i.d., we get

$$\ell_{\mu,1}(\tilde{x}_1) - \ell_{\mu,T+1}(\tilde{x}^*) \leq \mu L^2 d + \ell_1(x_1) - \ell_{T+1}(\tilde{x}_{T+1})$$
$$\leq \mu L^2 d + \ell_1(x_1) - \ell_{T+1}(x_{T+1}^*), \tag{20}$$

where $x_{T+1}^* = \arg\min_x \ell_{T+1}(x)$.

We can put the following lower bound to **term III** by using lemma 4 and lemma 6:

$$\frac{1}{2}\|\nabla \ell_t(x_t, z_t)\|^2 - \frac{\mu^2 L^2}{4}(d+3)^3 \leq \|\nabla \ell_{\mu,t}(x_t, z_t)\|^2. \tag{21}$$

Lastly, we can put the following upper bound to **term IV** by assumption 4 and lemma 6:

$$\mathbb{E}_{u_{1:T}, z_{1:T}, \mathcal{C}_{1:T}}[\|e_{t+1}\|^2] = \|p_t - \mathcal{C}_t(p_t)\|^2 \leq (1-\delta)\|p_t\|^2 = (1-\delta)\|e_t + g_{\mu,t}(x_t, z_t)\|^2$$
$$\leq (1-\delta)(1+\varphi)\mathbb{E}_{u_{1:T}, z_{1:T}, \mathcal{C}_{1:T}}\left[\|e_t\|^2\right] + (1-\delta)(1+\frac{1}{\varphi})\mathbb{E}_{u_{1:T}, z_{1:T}}\left[\|g_{\mu,t}(x_t, z_t)\|^2\right]$$
$$= \sum_{i=1}^{t} [(1-\delta)(1+\varphi)]^{t-i}(1-\delta)(1+\frac{1}{\varphi})\mathbb{E}_{u_i, z_i}\left[\|g_{\mu,i}(x_i, z_i)\|^2\right], \tag{22}$$

for some $\varphi > 0$, $z_t, x_t, \mathcal{C}_t$ are i.i.d., and $\mathbb{E}_{\mathcal{C}_t}[\,\cdot\,]$ denotes the expectation over the randomness at time t due to the compression used. Note that by assumption 5 and using lemma 5,

$$\mathbb{E}_{u_t, z_t}[\|g_{\mu,t}(x_t, z_t)\|^2] \leq A\|\nabla \ell_t(x_t)\|^2 + B, \tag{23}$$

where

$$B = 2\sigma^2(d+4) + \frac{\mu^2 L^2}{2}(d+6)^3 \text{ and}$$

$$A = 2M(d+4).$$

(24)

So we can rewrite (22) as follows:

$$\mathbb{E}_{u_{1:T},z_{1:T},\mathcal{C}_{1:T}}\left[\|e_{t+1}\|^2\right] \le \sum_{i=1}^{t}\left[(1-\delta)(1+\varphi)\right]^{t-i}(1-\delta)(1+\frac{1}{\varphi})\left[A\|\nabla\ell_i(x_i)\|^2 + B\right].$$

(25)

If we set $\varphi := \frac{\delta}{2(1-\delta)}$, then $1 + \frac{1}{\varphi} \le \frac{2}{\delta}$ and $(1-\delta)(1+\varphi) = (1-\frac{\delta}{2})$, so we get:

$$\mathbb{E}_{u_{1:T},z_{1:T},\mathcal{C}_{1:T}}\left[\|e_{t+1}\|^2\right] \le \sum_{i=1}^{t}\left(1-\frac{\delta}{2}\right)^{t-i}\left[A\|\nabla\ell_i(x_i)\|^2 + B\right]\frac{2(1-\delta)}{\delta}.$$

(26)

If we sum through all $\mathbb{E}_{u_{1:T},z_{1:T},\mathcal{C}_{1:T}}[\|e_t\|^2]$, we get:

$$\sum_{t=1}^{T}\mathbb{E}_{u_{1:T},z_{1:T},\mathcal{C}_{1:T}}\left[\|e_t\|^2\right] \le \sum_{t=1}^{T}\sum_{i=1}^{t-1}\left(1-\frac{\delta}{2}\right)^{t-i}\left[A\|\nabla\ell_i(x_i)\|^2 + B\right]\frac{2(1-\delta)}{\delta}$$

$$\le \sum_{t=1}^{T}\left[A\|\nabla\ell_t(x_t)\|^2 + B\right]\sum_{i=0}^{\infty}\left(1-\frac{\delta}{2}\right)^{i}\frac{2(1-\delta)}{\delta}$$

$$\le \sum_{t=1}^{T}\left[A\|\nabla\ell_t(x_t)\|^2 + B\right]C,$$

(27)

where $C = \frac{2(1-\delta)}{\delta}\frac{2}{\delta} \le \frac{4}{\delta^2}$. If we define $\Delta := \ell_1(x_1) - \ell_{T+1}(x_{T+1}^*)$ and combine the upper bounds derived in (18), (19), (22), and the lower bound derived in (21) and plug them into (17), we get the following:

$$\sum_{t=1}^{T}\frac{\eta}{4}\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t,z_t)\|^2\right] - \frac{\eta\mu^2 L^2}{8}(d+3)^3 T$$

$$\le \mu L^2 d + \Delta + \frac{T\mu^2 L^3\eta^2}{4}(d+6)^3 + \frac{L\eta^2}{2}\sigma^2 T \times 2(d+4)$$

$$+ \frac{L\eta^2}{2}\times 2M(d+4)\sum_{t=1}^{T}\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t,z_t)\|^2\right] + \frac{\eta^3 L^2}{2}\times\frac{4}{\delta^2}T\left[2\sigma^2(d+4) + \frac{\mu^2 L^2}{2}(d+6)^3\right]$$

$$+ \frac{\eta^3 L^2}{2}\times\frac{4}{\delta^2}\sum_{t=1}^{T}2M(d+4)\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t,z_t)\|^2\right] + \sum_{t=1}^{T}\omega_t.$$

(28)

Now, since z_t's are *i.i.d.* for all $t \in \mathbb{Z}^+$, we have:

$$\frac{E}{T}\sum_{t=1}^{T}\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t,z_t)\|^2\right] \le \frac{\mu L^2 d + \Delta}{T} + \frac{\eta^2 L^3\mu^2(d+6)^3}{4} + L\eta^2\sigma^2(d+4) + \frac{\eta\mu^2 L^2(d+3)^3}{8}$$

$$+ \frac{\eta^3 L^2}{\delta^2}4\sigma^2(d+4) + \frac{\eta^3 L^2}{\delta^2}\mu^2 L^2(d+6)^3 + \frac{1}{T}\sum_{t=1}^{T}\omega_t,$$

(29)

where

$$E = \frac{\eta}{4} - LM\eta^2(d+4) - \frac{L^2\eta^3}{\delta^2}4M(d+4)$$
$$= \eta\left[\frac{1}{4} - LM\eta(d+4)\left(1 + \frac{4L\eta}{\delta^2}\right)\right]. \tag{30}$$

If $\eta \leq \frac{1}{4L}$, instead first upper bound will be:

$$1 + \frac{4L\eta}{\delta^2} \leq 1 + \frac{1}{\delta^2} = \frac{\delta^2+1}{\delta^2} \leq \frac{2}{\delta^2}. \tag{31}$$

We proceed to find an η such that

$$\frac{2}{\delta^2}LM\eta(d+4) \leq \frac{1}{8}. \tag{32}$$

Then, we get

$$\eta \leq \frac{\delta^2}{16LM(d+4)}, \tag{33}$$

which implies $E \geq \frac{\eta}{8}$. Multiplying all terms in the bound by $\frac{8}{\eta}$,

$$\frac{1}{T}\sum_{t=1}^{T}\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t, z_t)\|^2\right] \leq \frac{8\Delta}{(\eta T)} + \frac{8\mu L^2 d}{\eta T} + 2\eta L^3\mu^2(d+6)^3$$
$$+ 8L\eta\sigma^2(d+4) + \mu^2 L^2(d+3)^3 \tag{34}$$
$$+ \frac{32\eta^2 L^2}{\delta^2}\sigma^2(d+4) + \frac{8\eta^2 L^4\mu^2(d+6)^3}{\delta^2} + \frac{8}{\eta T}\sum_{t=1}^{T}\omega_t.$$

Let

$$\eta = \frac{1}{\sigma\sqrt{(d+4)MTL}} \quad \text{and} \quad \mu = \frac{1}{(d+4)\sqrt{T}}. \tag{35}$$

Then, for a numerical constant $C > 0$, we have

$$\frac{1}{CT}\sum_{t=1}^{T}\mathbb{E}_{z_t}\left[\|\nabla\ell_t(x_t, z_t)\|^2\right] \leq \frac{1}{\delta^2}\frac{dL\Delta}{T} + \sigma\sqrt{\frac{d}{T}L\Delta M} + \frac{1}{\eta T}\sum_{t=1}^{T}\omega_t. \tag{36}$$

Defining $\bar{\omega} := \sum_{t=1}^{T}\omega_t$, the number of times steps T to obtain a ξ-first order solution is

$$T = \mathcal{O}\left(\frac{d\sigma^2 L\Delta M}{\xi^2} + \frac{dL\Delta}{\delta^2\xi} + \frac{\bar{\omega}\sigma^2 dML}{\xi^2}\right). \tag{37}$$

Remark: In choosing $\eta = \frac{1}{\sigma\sqrt{(d+4)MTL}}$, we assumed that it satisfies (33). For this to hold, T can be made arbitrarily large as long as it does not exceed the bound we found in (37). (35) and (33) imply that

$$T = \Omega\left(\frac{dLM}{\delta^4\sigma^2}\right). \tag{38}$$

In practice, since $\xi \ll \delta$, this term is smaller than (36). This fact is also demonstrated by our experiments.

Lastly, if $\omega_t = 0$ for all $t \in \mathbb{Z}^+$, i.e., in the case where the loss function is time-invariant, the number of time steps T to obtain a ξ-first order solution is:

$$T = \mathcal{O}\left(\frac{d\sigma^2 L\Delta M}{\xi^2} + \frac{dL\Delta}{\delta^2\xi}\right). \tag{39}$$

References

[1] S. P. Karimireddy, Q. Rebjock, S. U. Stich, and M. Jaggi, "Error feedback fixes signsgd and other gradient compression schemes," 2019.

FED-EF-ZO-SGD Convergence Analysis

We work with the following algorithm in the experiments section of the paper:

Algorithm 2 FED-EF-ZO-SGD

Input: Number of time steps $T \in \mathbb{Z}^+$, number of agents $N \in \mathbb{Z}^+$, smoothing parameter $\mu \in \mathbb{R}$, initial agent positions $x_0^{1:N} \in \mathbb{R}^{Nd}$, learning rate $\eta \in \mathbb{R}$, sequence of target positions $\left\{ z^{1:N} \right\}_{t=1}^{T} \subset \mathbb{R}^{Nd}$.

Output: Sequence of optimal target positions $\left\{ x^{1:N} \right\}_{t=1}^{T} \subset \mathbb{R}^{Nd}$.

1: **for** $i = 1, \ldots, N$ **do**
2:    $e_0^i = 0$
3: **end for**
4: **for** $t = 1, \ldots, T$ **do**
   Runs on each agent:
5:    **for** $i = 1, \ldots, N$ **do**
6:       $\tilde{u}_t^i \sim \mathcal{N}(0, I_{Nd})$
7:       $u_t^i = \mathrm{mask}_{\mathcal{D}_t^i}(\tilde{u}_t^i)$
8:       $g_{\mu,t}^i(x_t^{1:N}, z_t^i) = \dfrac{\ell_t(x_t^{1:N} + \mu u_t^i, z_t^i) - \ell_t(x_t^{1:N}, z_t^i)}{\mu} u_t^i$
9:       $p_t^i = g_{\mu,t}^i(x_t^{1:N}, z_t^i) + e_t^i$
10:      $\tilde{g}_t^i = \mathcal{C}(p_t^i)$
11:      $e_{t+1}^i = p_t^i - \tilde{g}_t^i$
12:      transmit $\left(\tilde{g}_t^i \right)$
13:    **end for**
   Runs on the server:
14:    $\mathcal{G}_t = \frac{1}{N} \sum_{i=1}^{N} \tilde{g}_t^i$
15:    $x_{t+1}^{1:N} = x_t^{1:N} - \eta \mathcal{G}_t$
16:    transmit $\left(x_{t+1}^{1:N} \right)$
17: **end for**

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where $\mathrm{mask}_{\mathcal{D}_t^i}(\cdot)$ is a function for equating the coordinates corresponding to the coordinates of agents which are not in the neighborhood of the ith agent to 0.