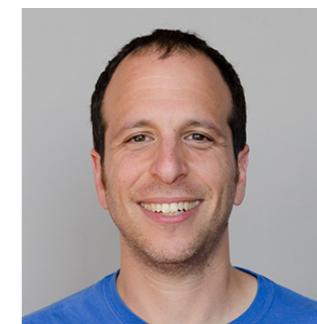
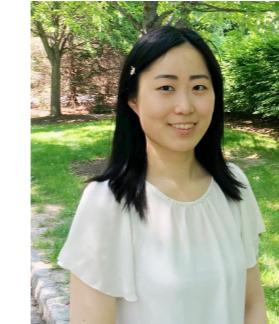
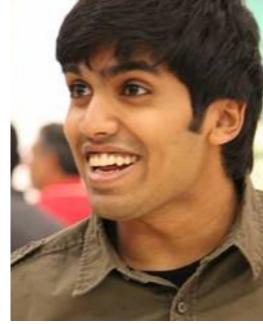


MOSAIKS:

A generalizable and accessible approach to
machine learning with global satellite imagery

Esther Rolf*, Jonathon Proctor*, Tamara Carleton*, Ian Bolliger*, Vaishaal
Shankar*, Miyabi Ishihara, Benjamin Recht, Solomon Hsiang



*Presented at:
AI + Climate Seminar
November 30, 2021*

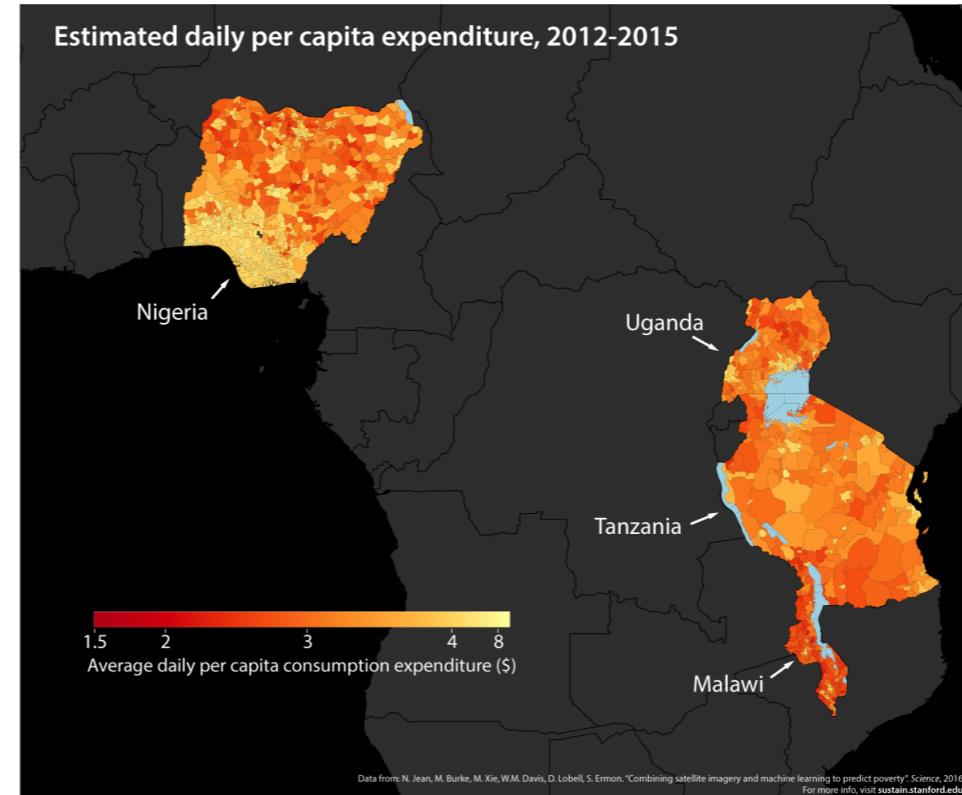
700+ satellites are orbiting the earth, collecting over **90TB** of data daily, enabling researchers to monitor our world across multiple domains:



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Poverty mapping

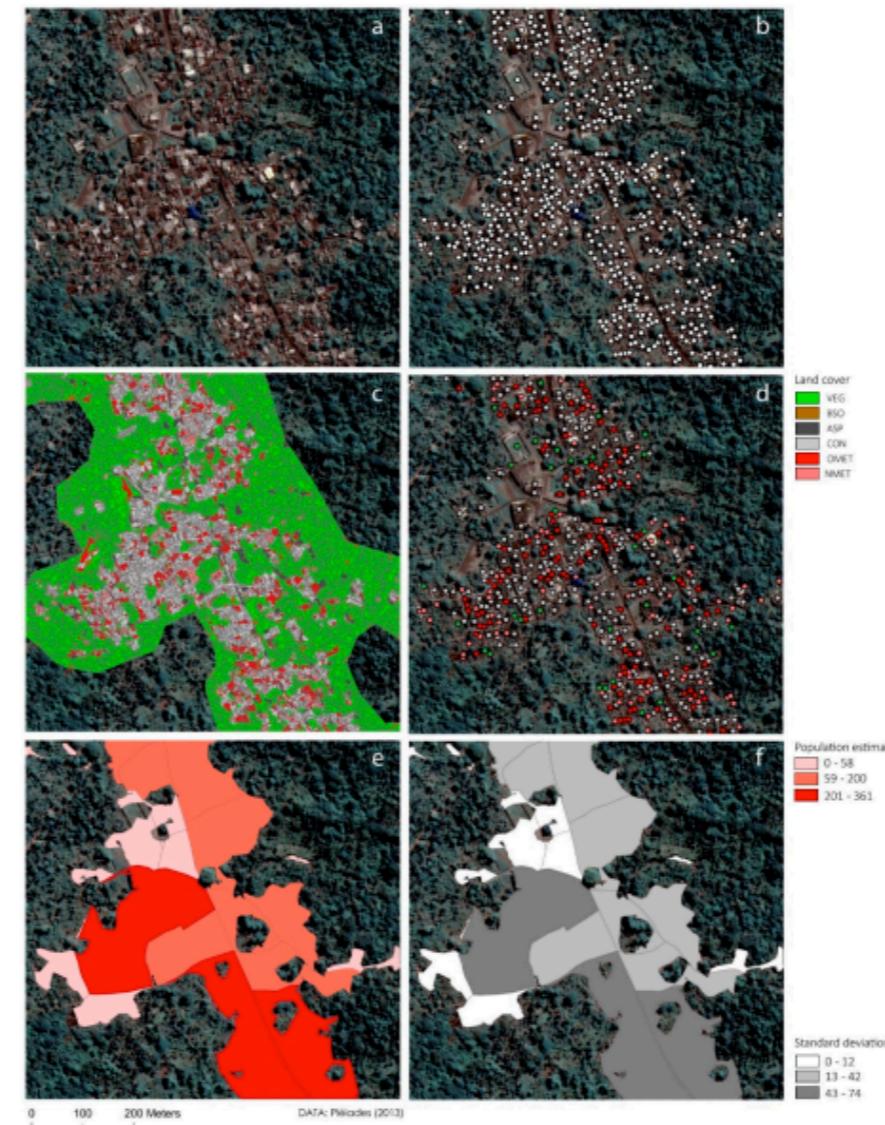


Jean et al. 2016, Science

700+ satellites are orbiting the earth, collecting over **90TB** of data daily, enabling researchers to monitor our world across multiple domains:



Mapping Population Distribution

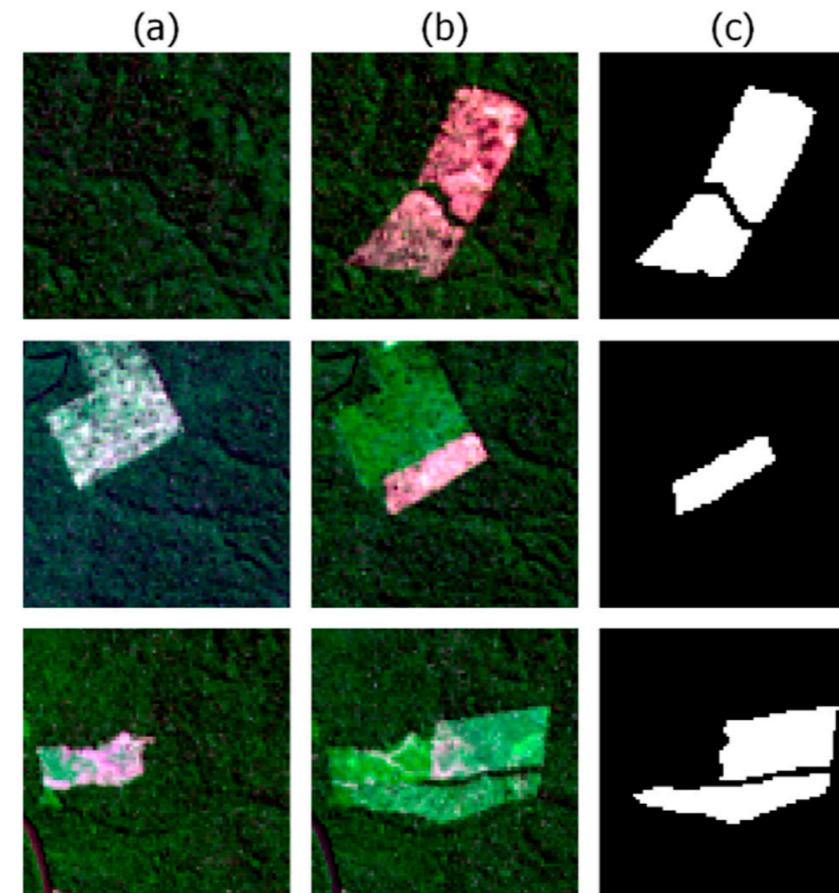


*Mossoux et al.
2018*

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Monitoring Deforestation

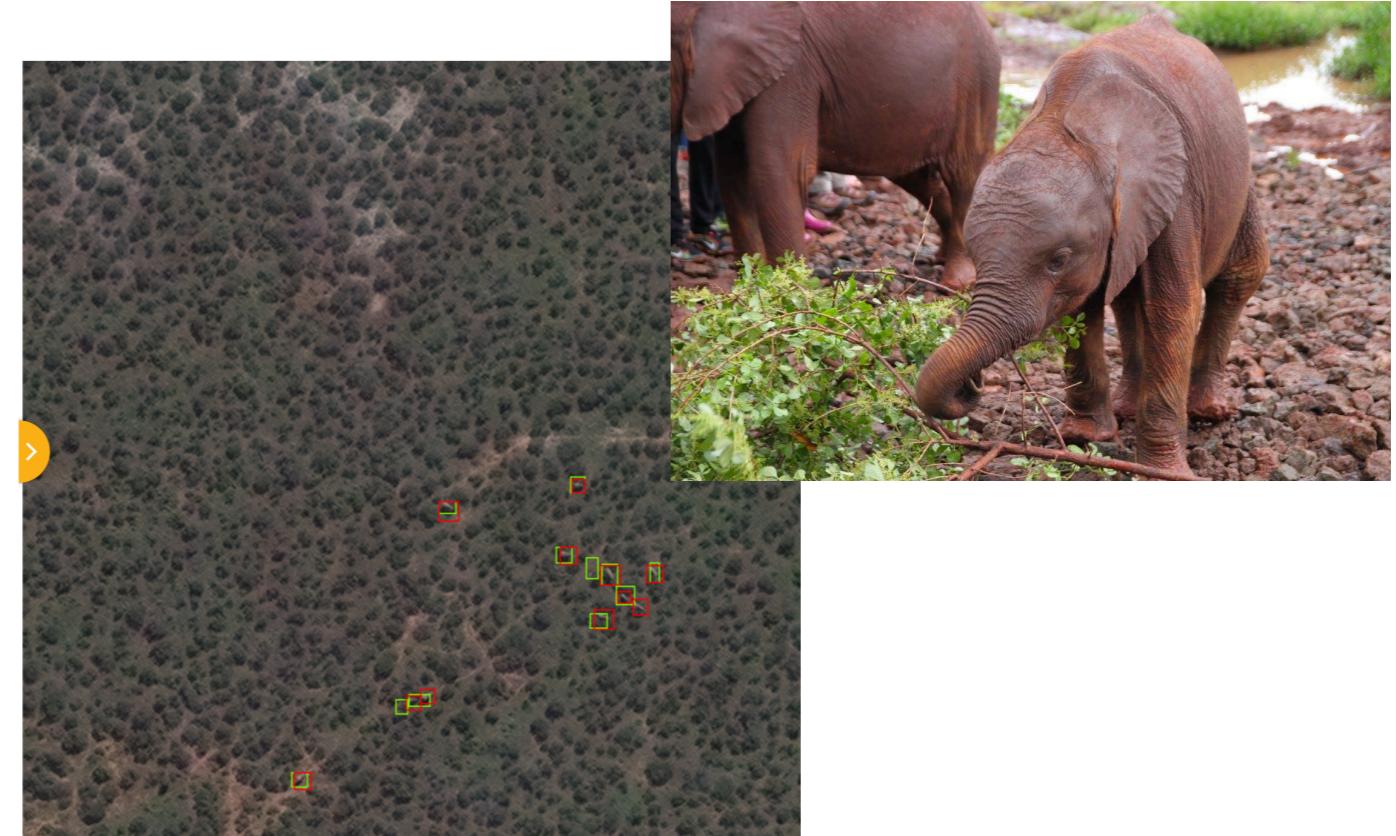


de Bem et al. 2020

700+ satellites are orbiting the earth, collecting over **90TB** of data daily, enabling researchers to monitor our world across multiple domains:

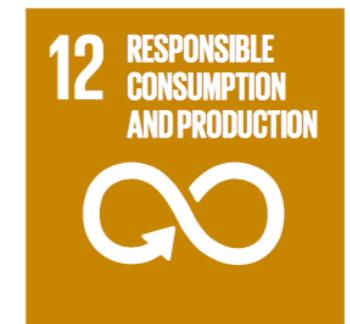


Wildlife Detection and Monitoring



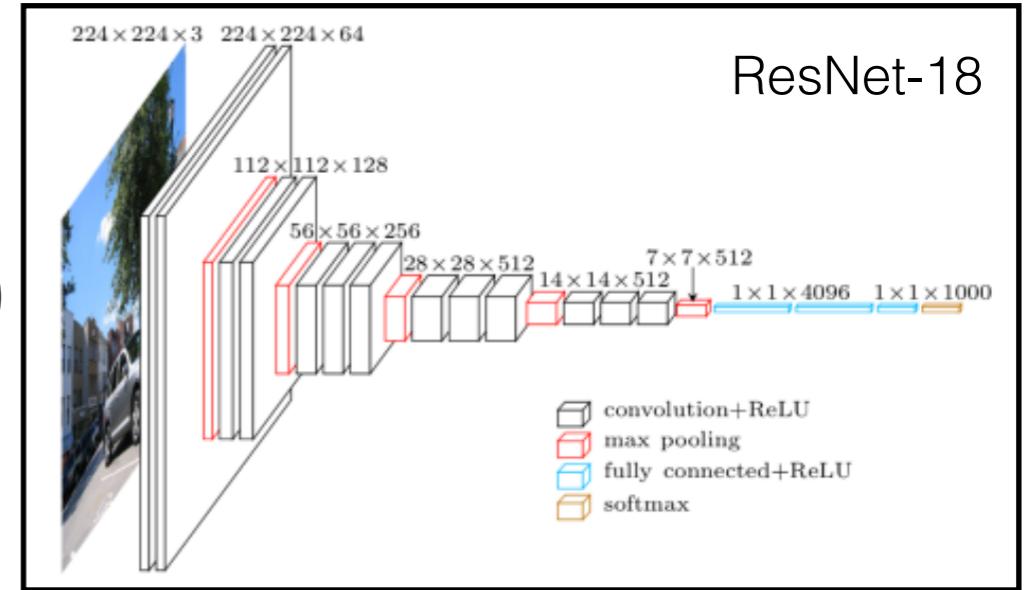
Duporge et al. 2020

700+ satellites are orbiting the earth, collecting over **90TB** of data daily, enabling researchers to monitor our world across multiple domains:



700+ satellites are orbiting the earth, collecting over **90TB** of data daily, enabling researchers to monitor our world across multiple domains:

However, transforming satellite imagery into relevant statistics is **costly** (computation and expertise) and most solutions are domain-specific.



Our approach: a general method that allows researchers to easily predict any variable from space.

In this talk:

goal: **learn** functions that take in *satellite images*, and **predict** *variables of interest*

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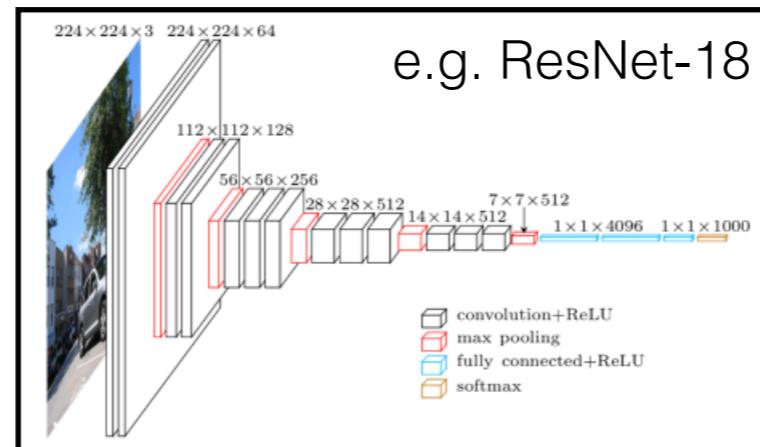
$$g(\text{satellite image}) \approx 14 \text{ ships}$$

In this talk:

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$f(\text{satellite image}) \approx 45\% \text{ forest}$

$g(\text{satellite image}) \approx 14 \text{ ships}$



MOSAIKS design goals

Multi-task Observation using Satellite Imagery & Kitchen Sinks

Accessibility

Simplicity

Generalizability

MOSAIKS design goals

Accessibility

Simplicity

Generalizability

The machine learning system should be **simple to use** and **computationally efficient** for users.

MOSAIKS design goals

Accessibility

Simplicity

Generalizability

The **algorithms** behind the prediction system should be as simple as possible.

MOSAIKS design goals

Accessibility

Simplicity

Generalizability

One machine learning system could be useful for many prediction **tasks**, using a common source of satellite imagery

MOSAIKS design goals

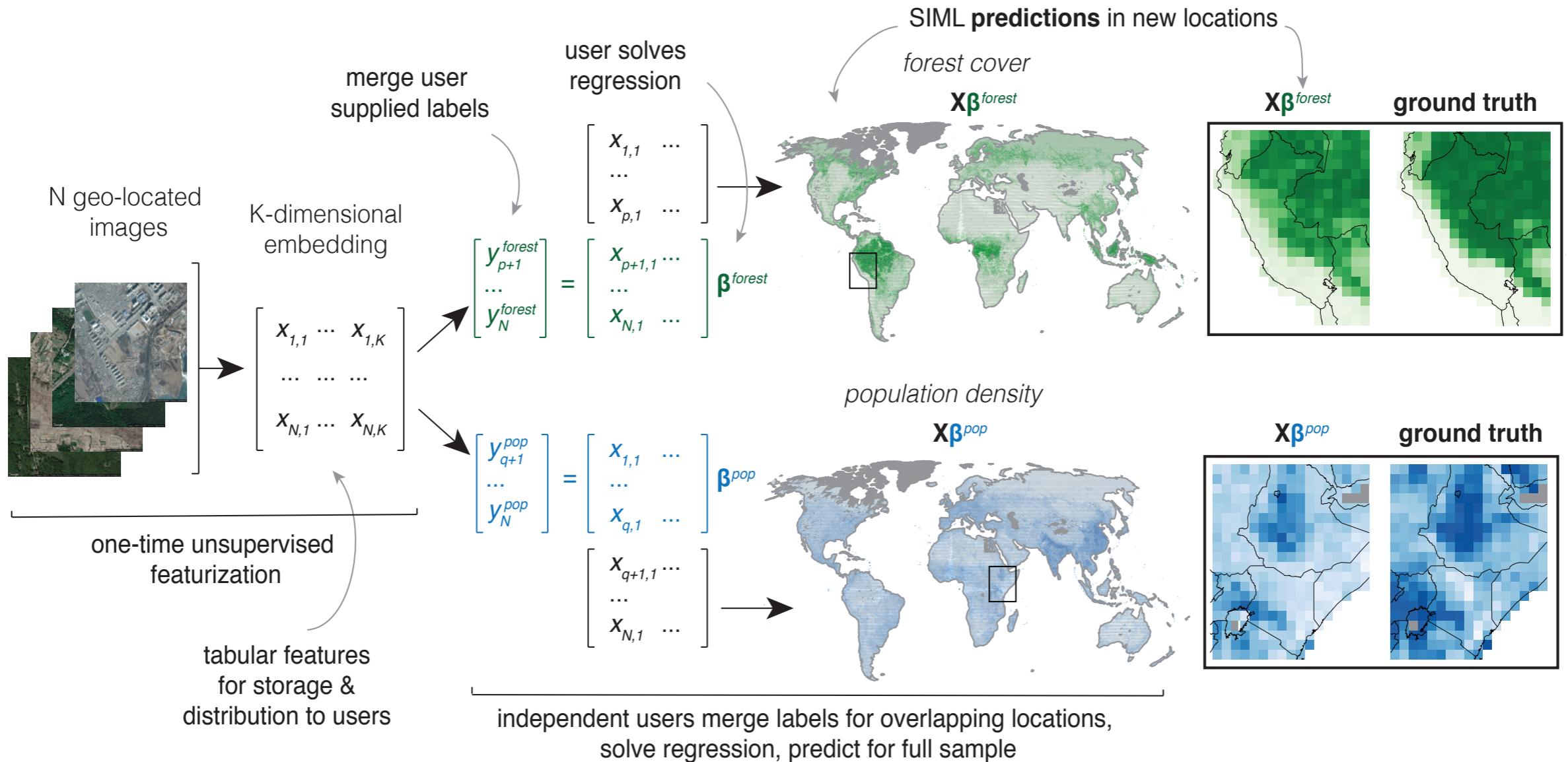
Accessibility

Simplicity

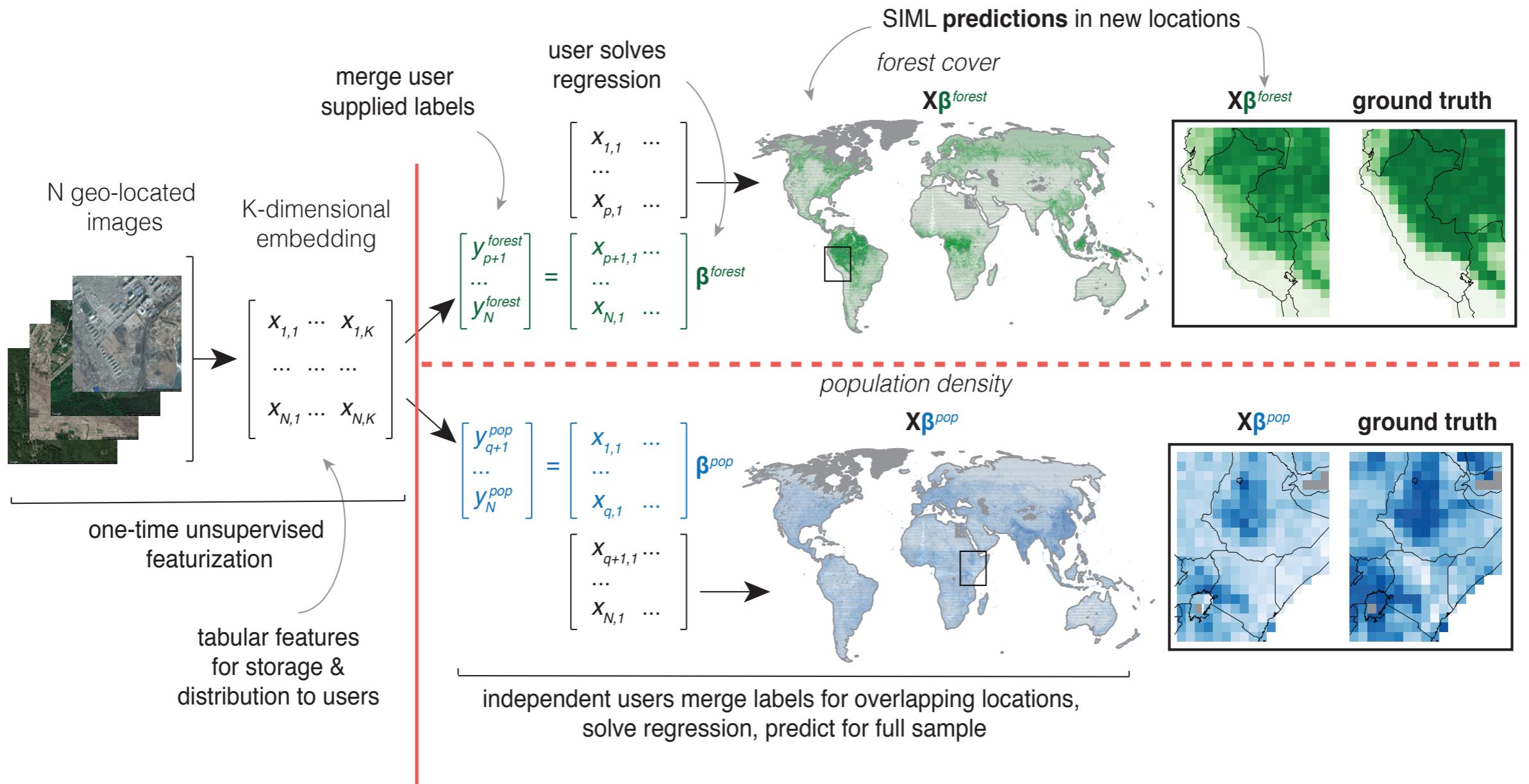
Generalizability

Without sacrificing accuracy or applicability.

MOSAIKS design

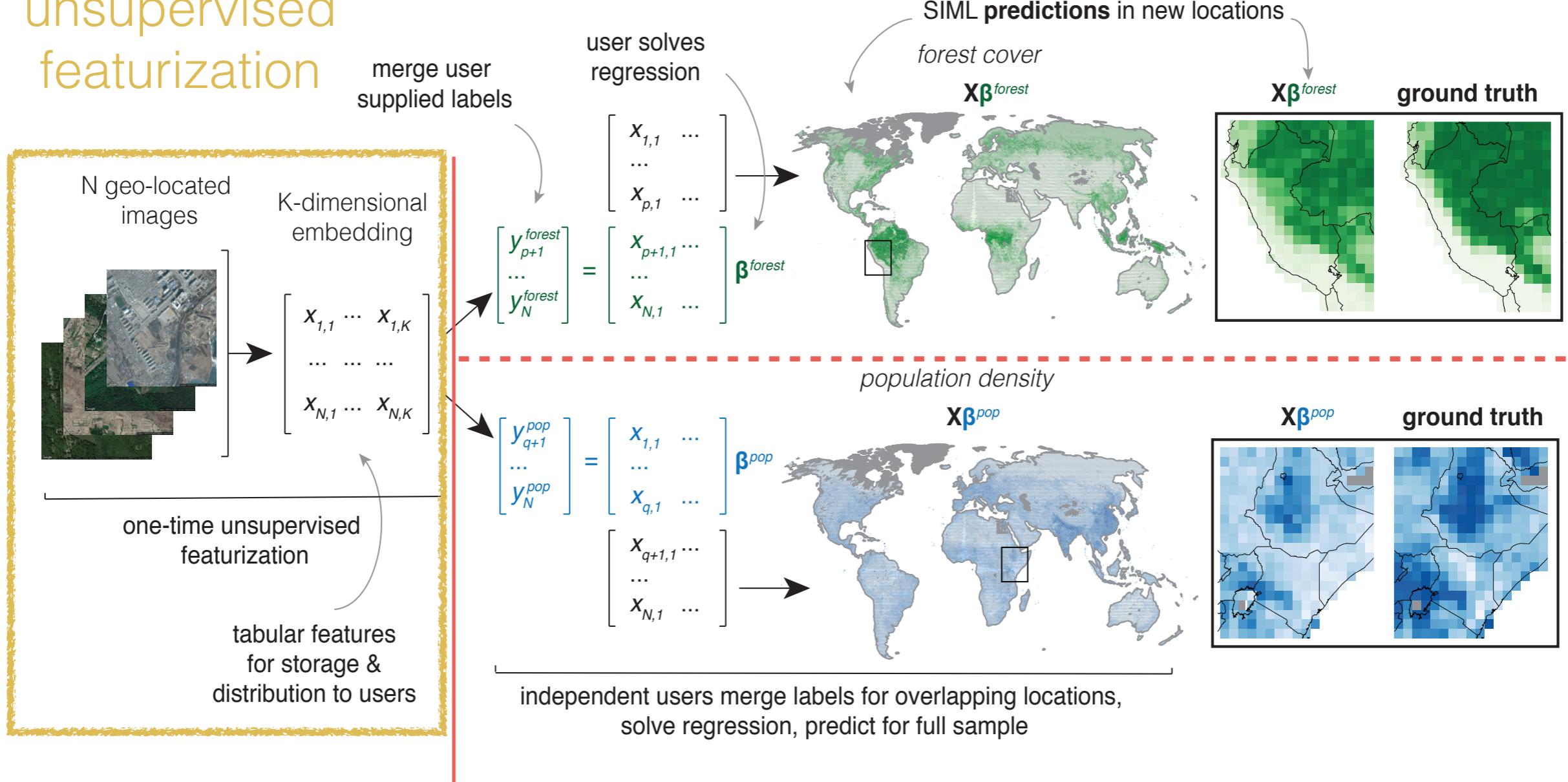


MOSAIKS design



MOSAIKS design

unsupervised featurization

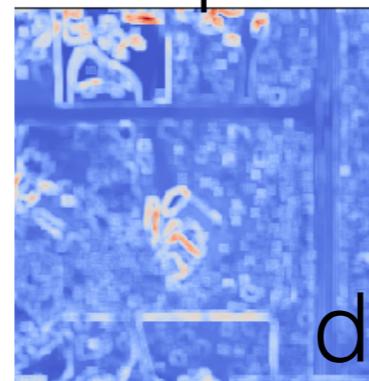
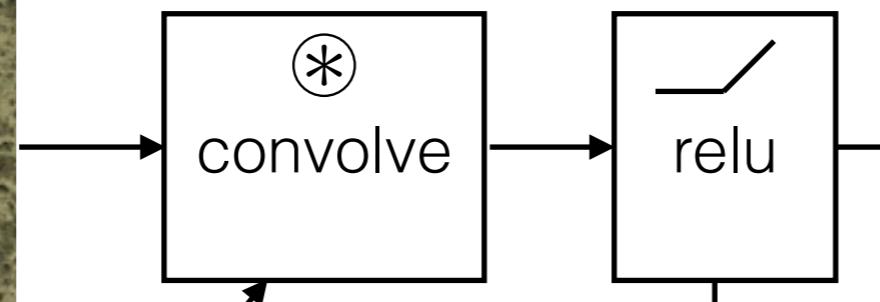


Random Convolutional Features

Sample Image



Random Filters
extracted from data set



Feature Responses

Feature Vector

$$\begin{bmatrix} x_0 \\ \vdots \\ x_d \end{bmatrix}$$

Based on “random kitchen sinks” (Rahimi & Recht 2008)

Random convolutional features have been applied to:

- classifying photographs
 - (Coates & Ng, 2011)
- encoding genomic sequences
 - (Morrow et al., 2017)
- predicting solar flares
 - (Jonas et al., 2018)

Prediction with Random convolutional features (RCF)

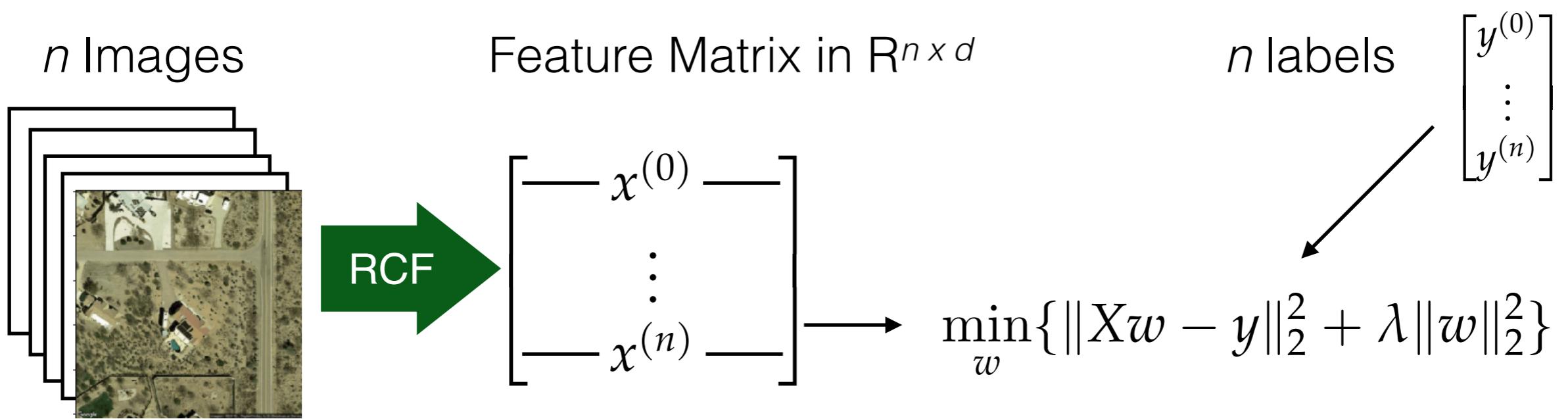
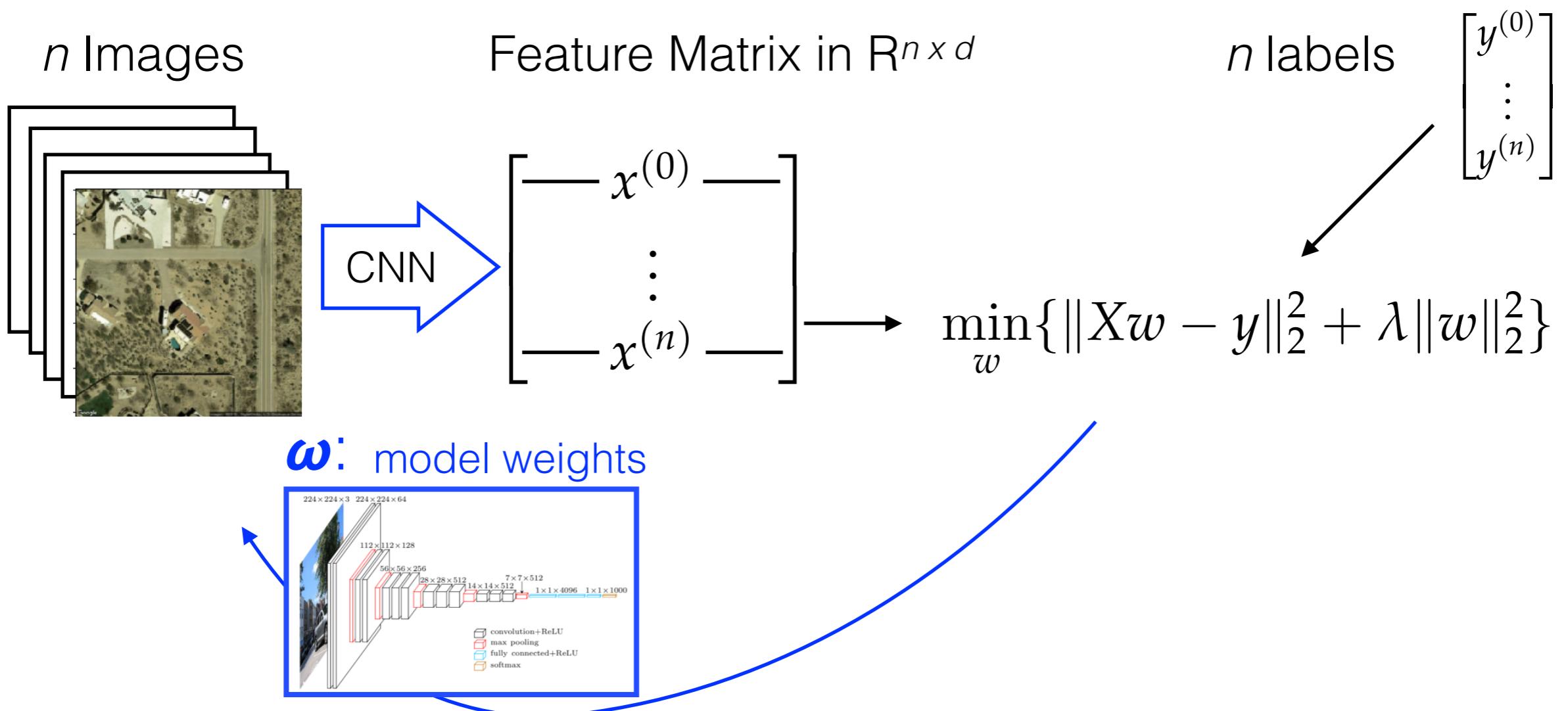


Image features are created without knowledge of labels!

Prediction with unsupervised features

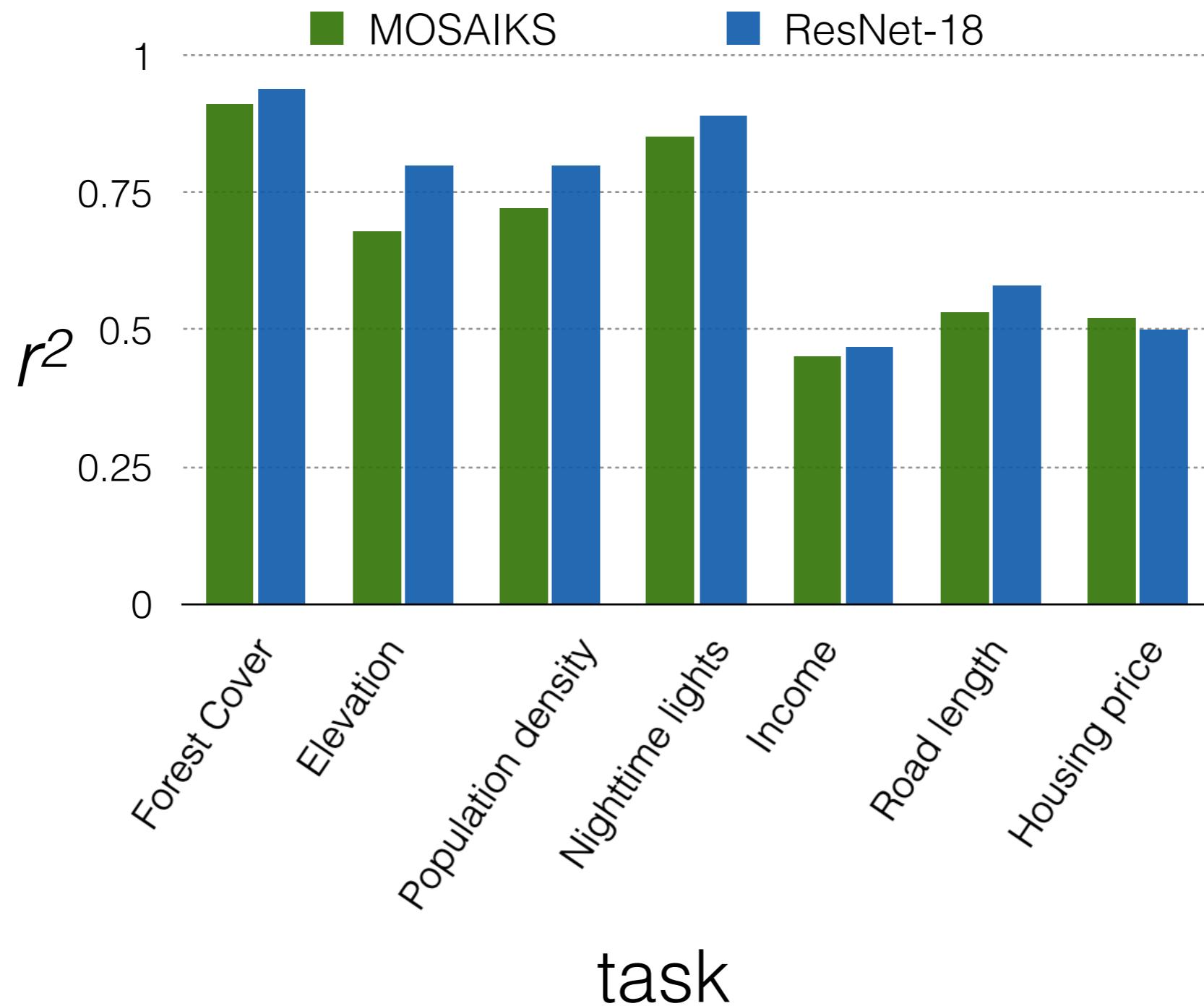


In contrast, Convolutional Neural Networks (CNNs)
learn domain-specific image features

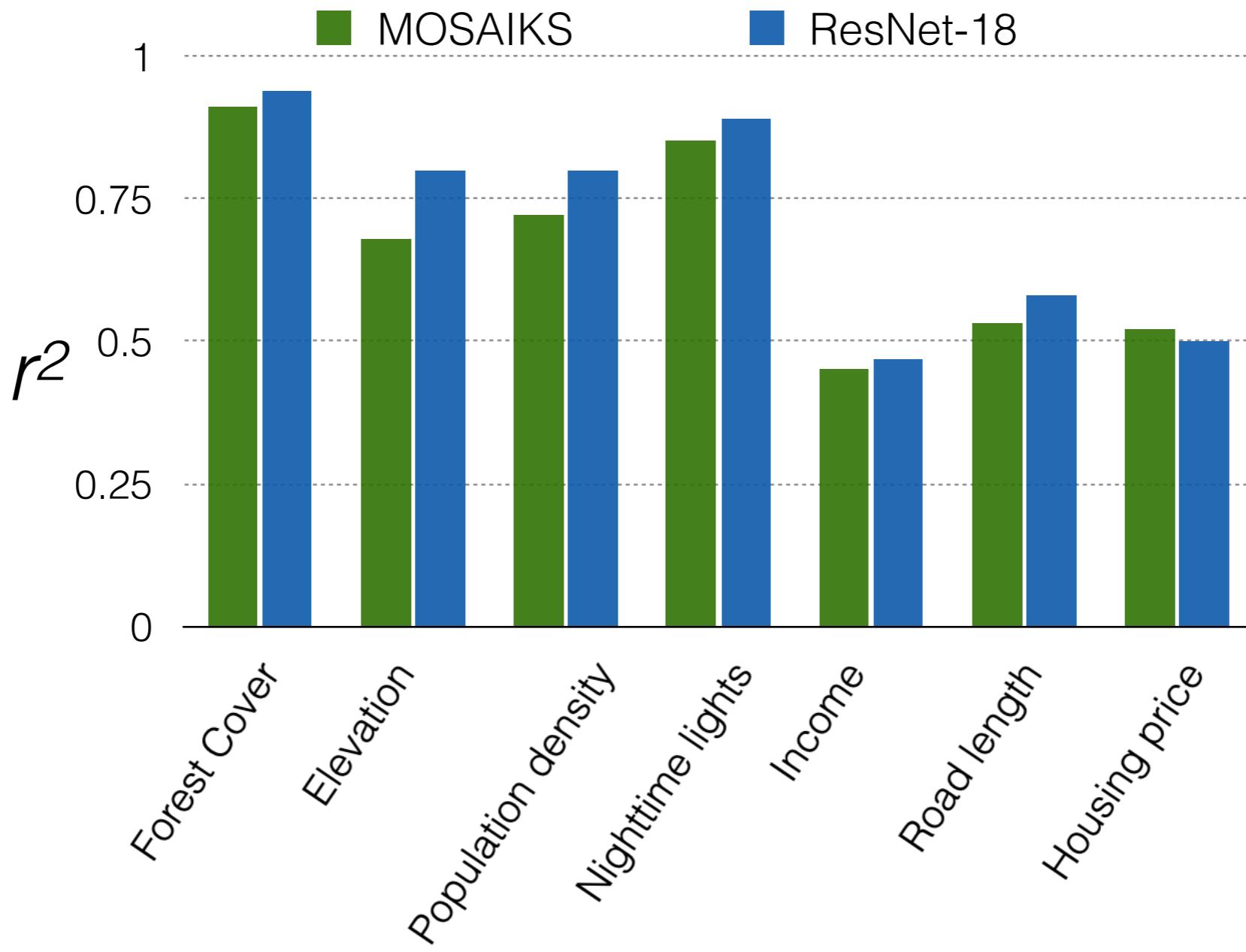
Prediction Domains

- Forest Cover
- Elevation
- Population
- Nighttime Luminosity
- Income
- Road Length
- Housing Price

MOSAIKS compared to fine-tuned ResNet-18 (within US)



MOSAIKS compared to fine-tuned ResNet-18 (within US)



Training times:

MOSAIKS: 1 minute
(CPU, 10 cores)
Esther Rolf (UC Berkeley)

Fully trained ResNet-18: 7.9 hours
(AWS EC2 p3.xlarge, Tesla V100 GPU)

The most commonly used CNNs are designed for classification of “natural imagery”



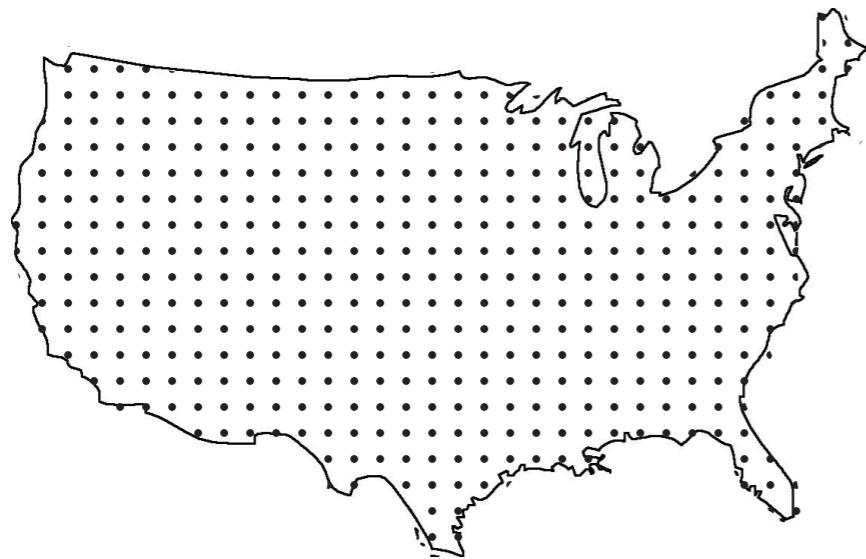
Satellite images are largely **scale** and **orientation** invariant.



The structures in satellite imagery can explain why performance of simpler methods would match that of more complex methods.

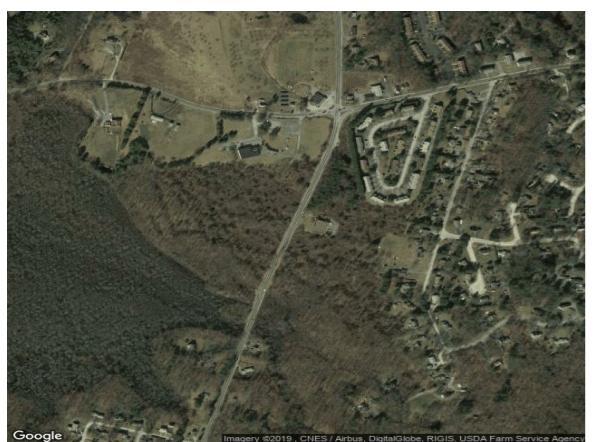
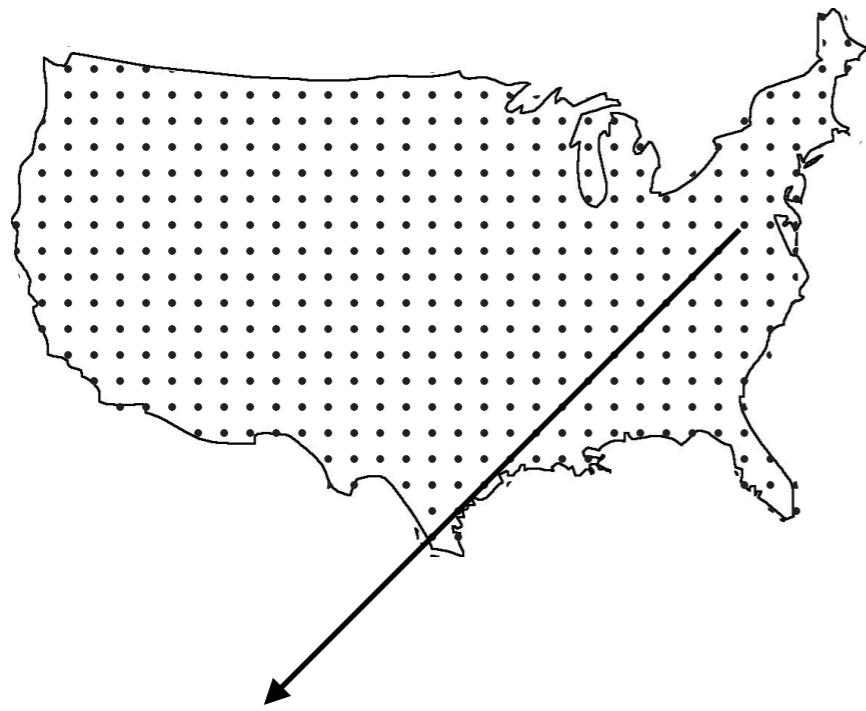
Methods

1. Grid the U.S.



Methods

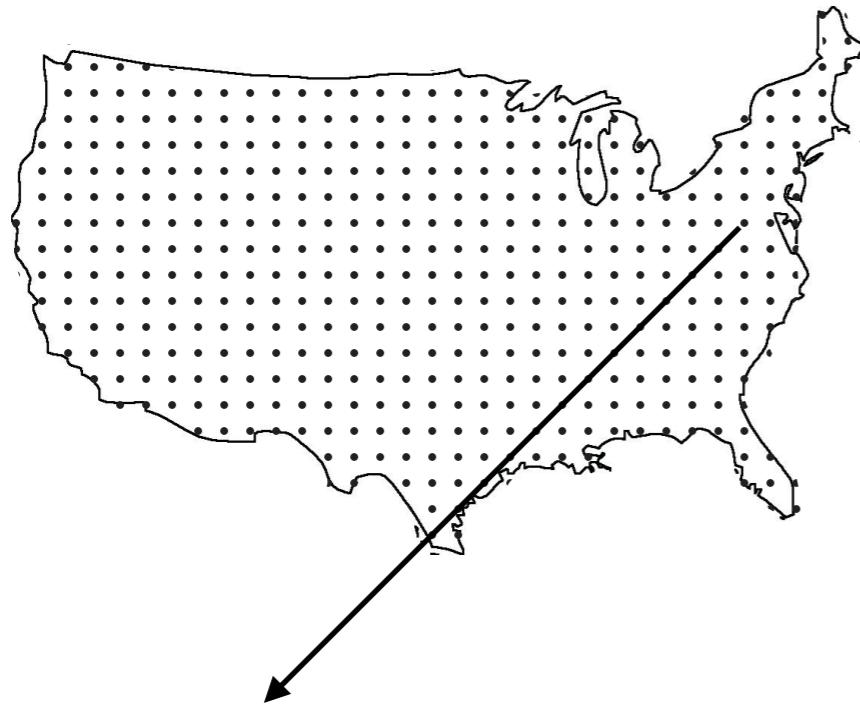
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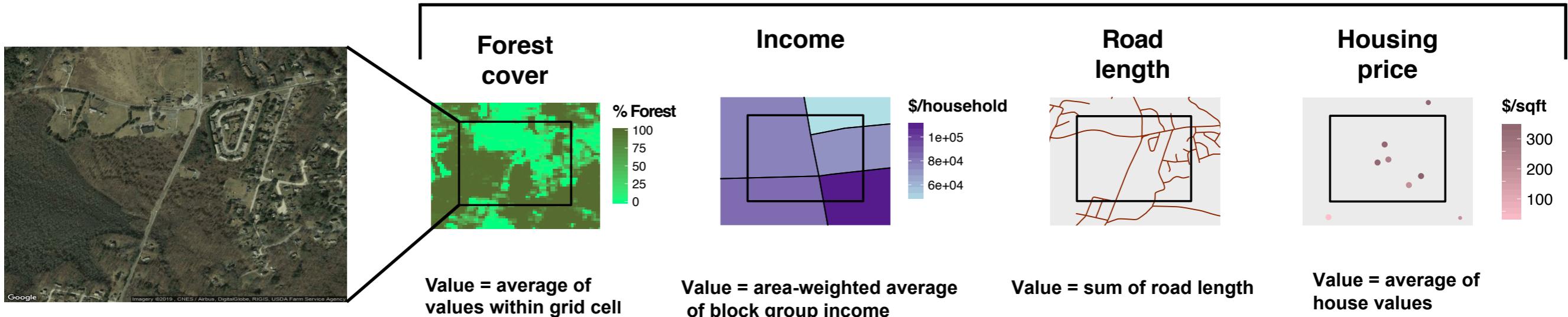
~1km x 1km

Methods

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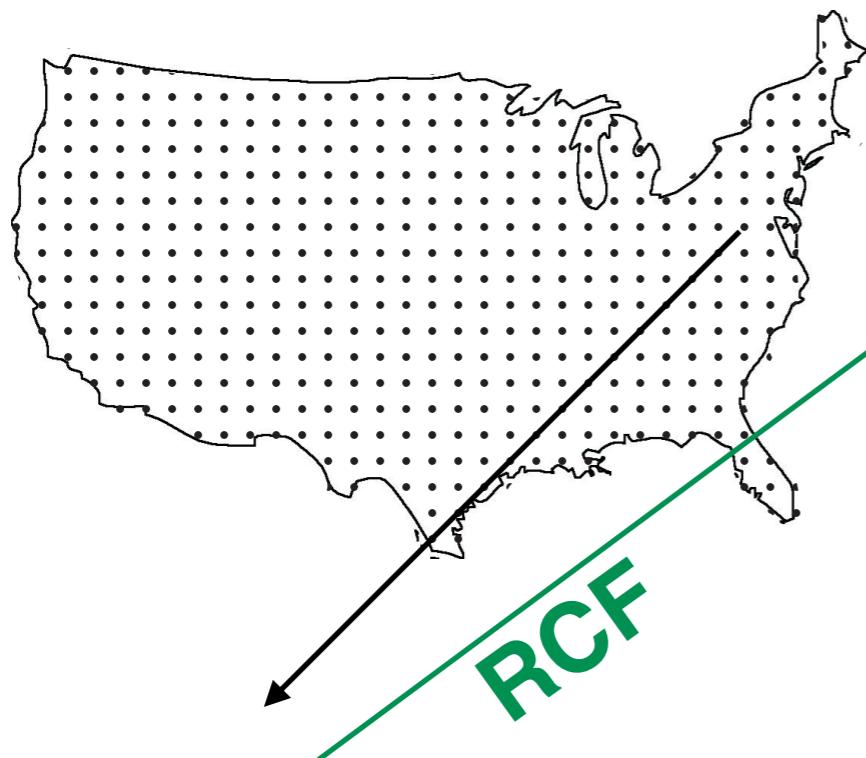
format and spatial resolution
of the labeled data varies across tasks



~1km x 1km

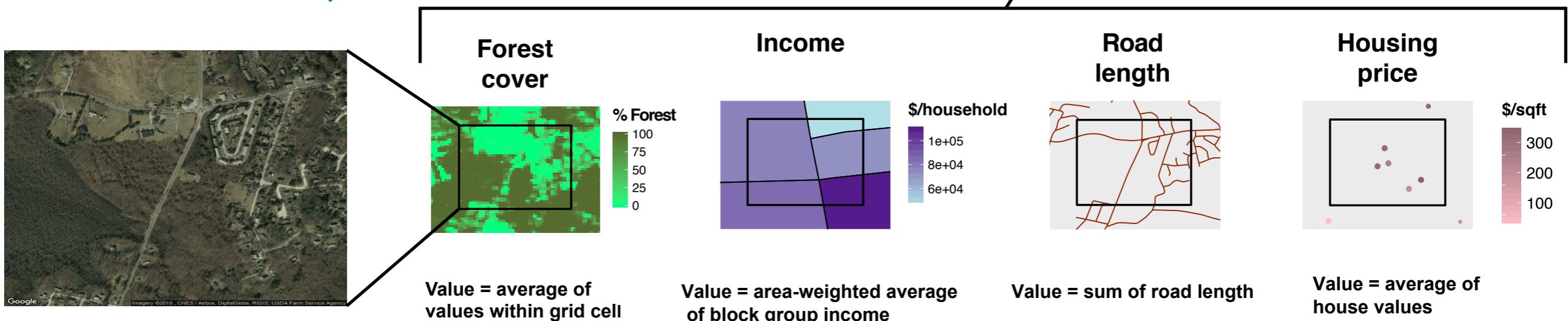
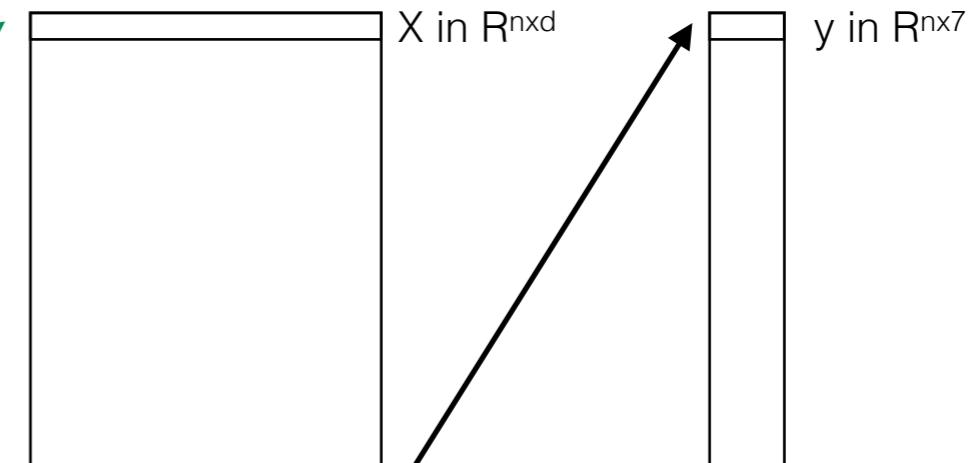
Methods

1. Grid the U.S.



2. Download and featurize Images (RCF)

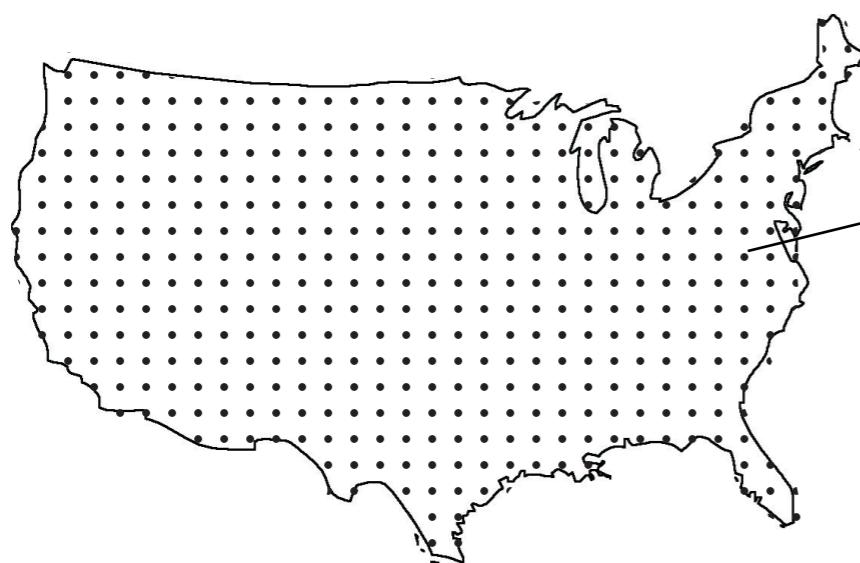
3. Associate with each grid point each of 7 labels



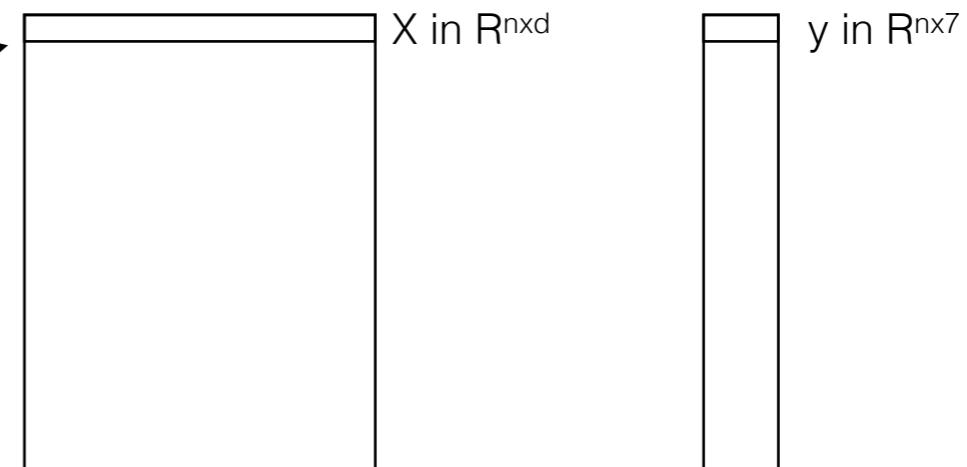
~1km x 1km

Methods

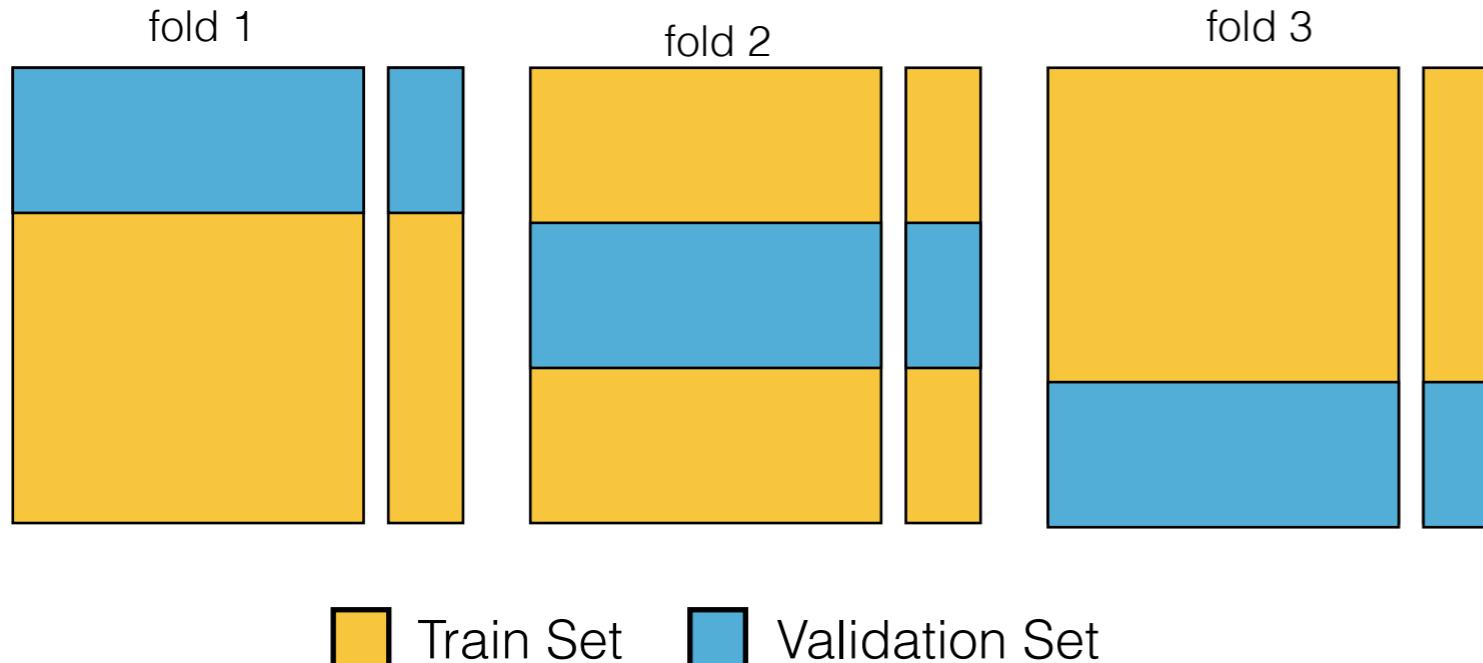
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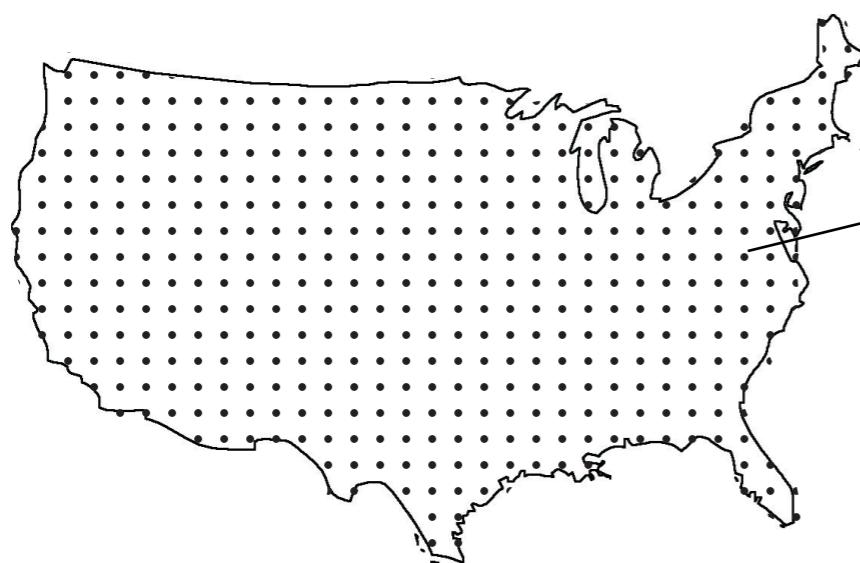


4. k-fold cross validation; pick model parameters



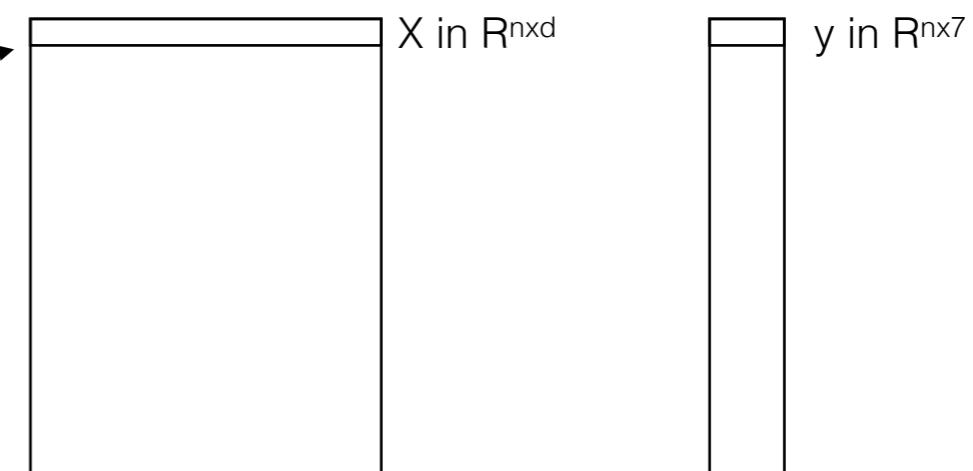
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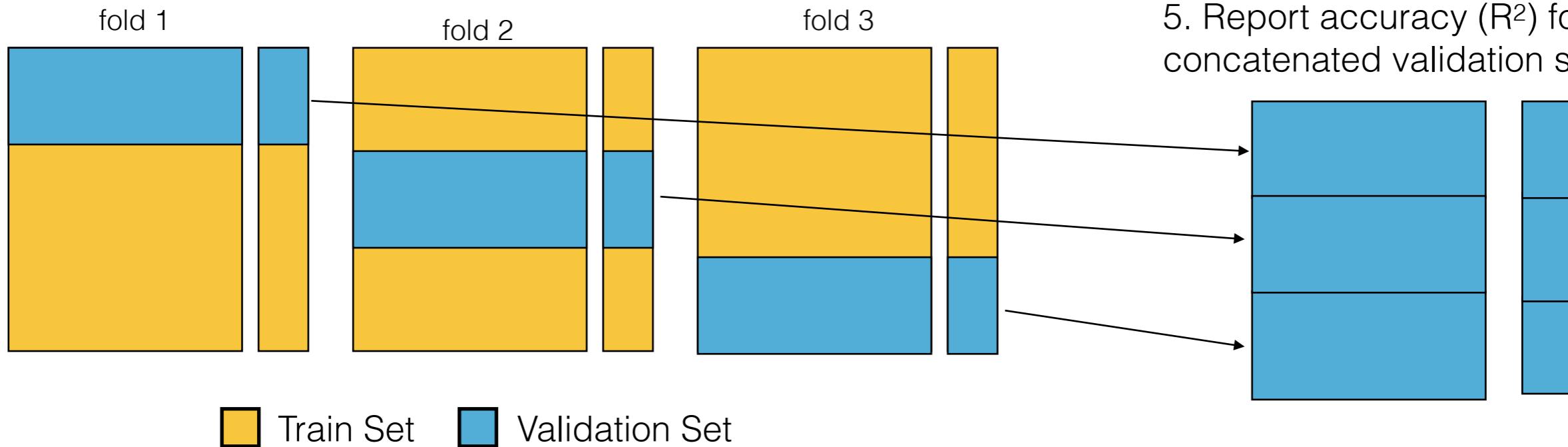


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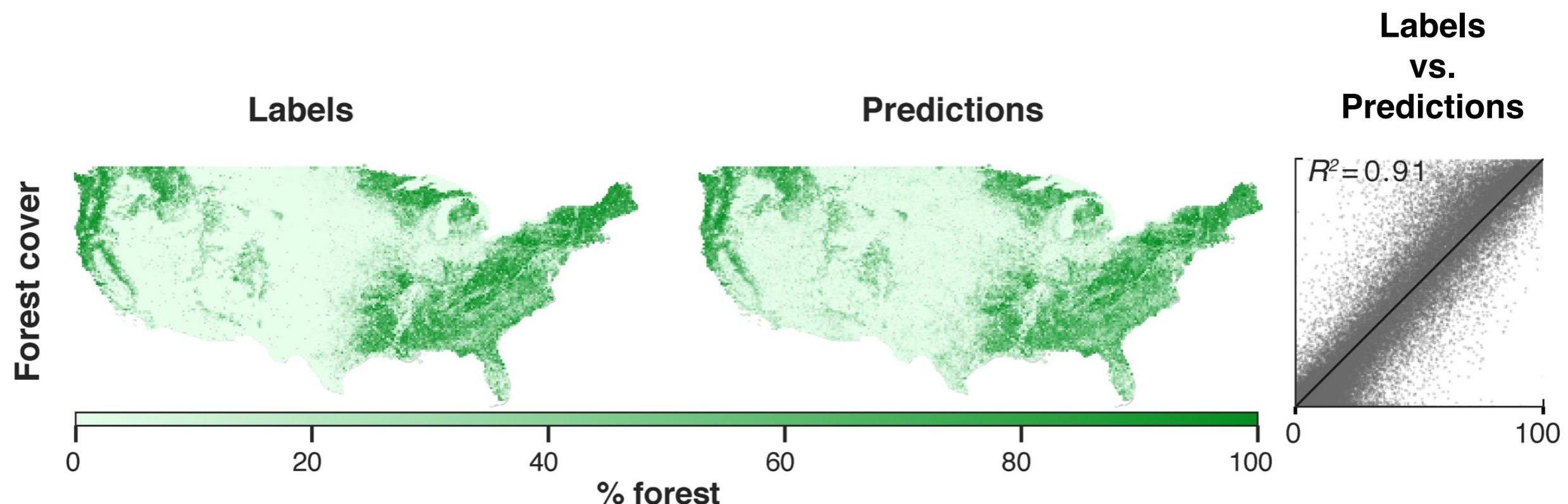


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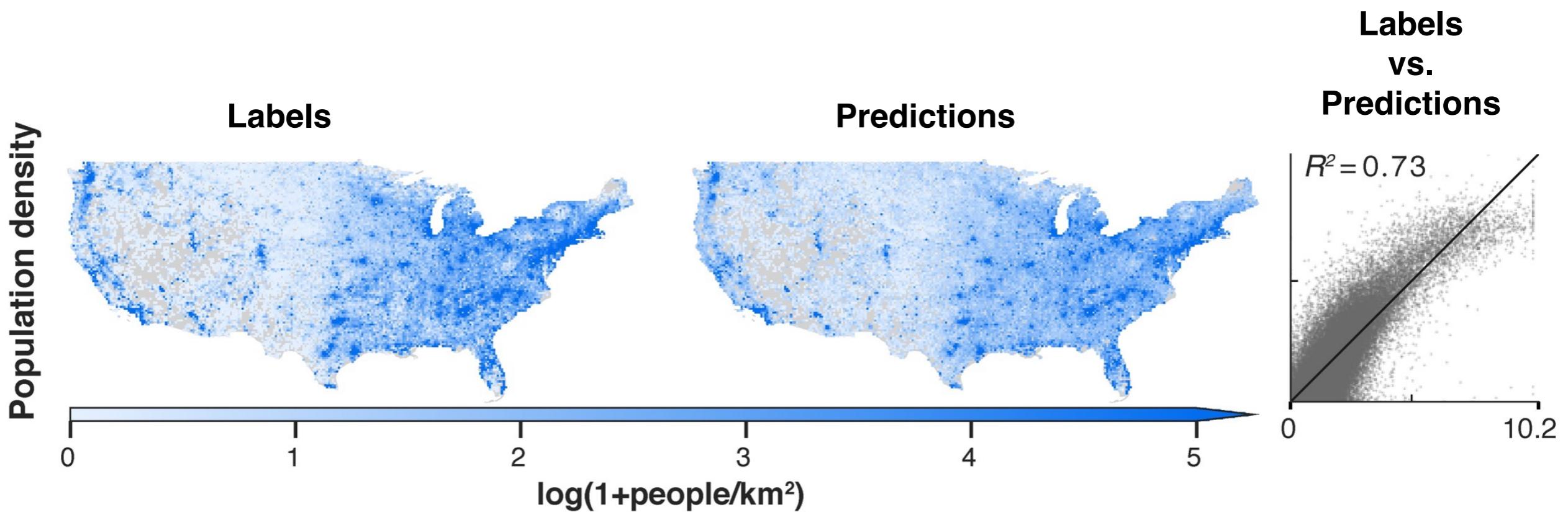


5. Report accuracy (R^2) for concatenated validation sets.

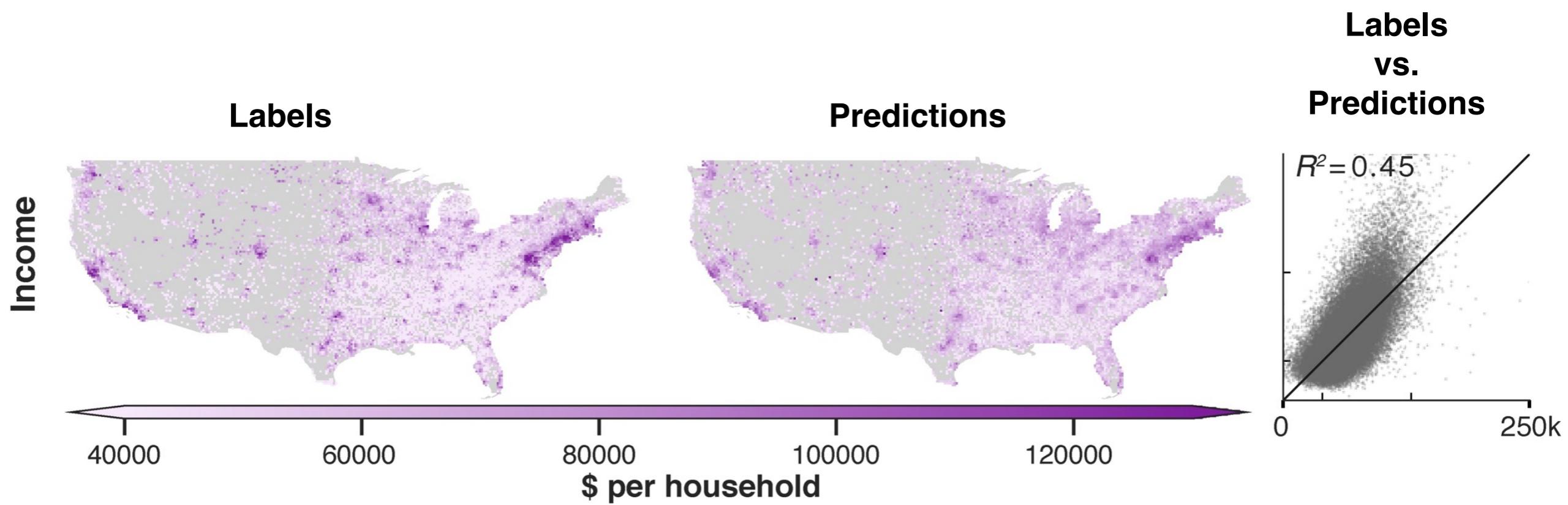
US Outcome #1: Forest Cover



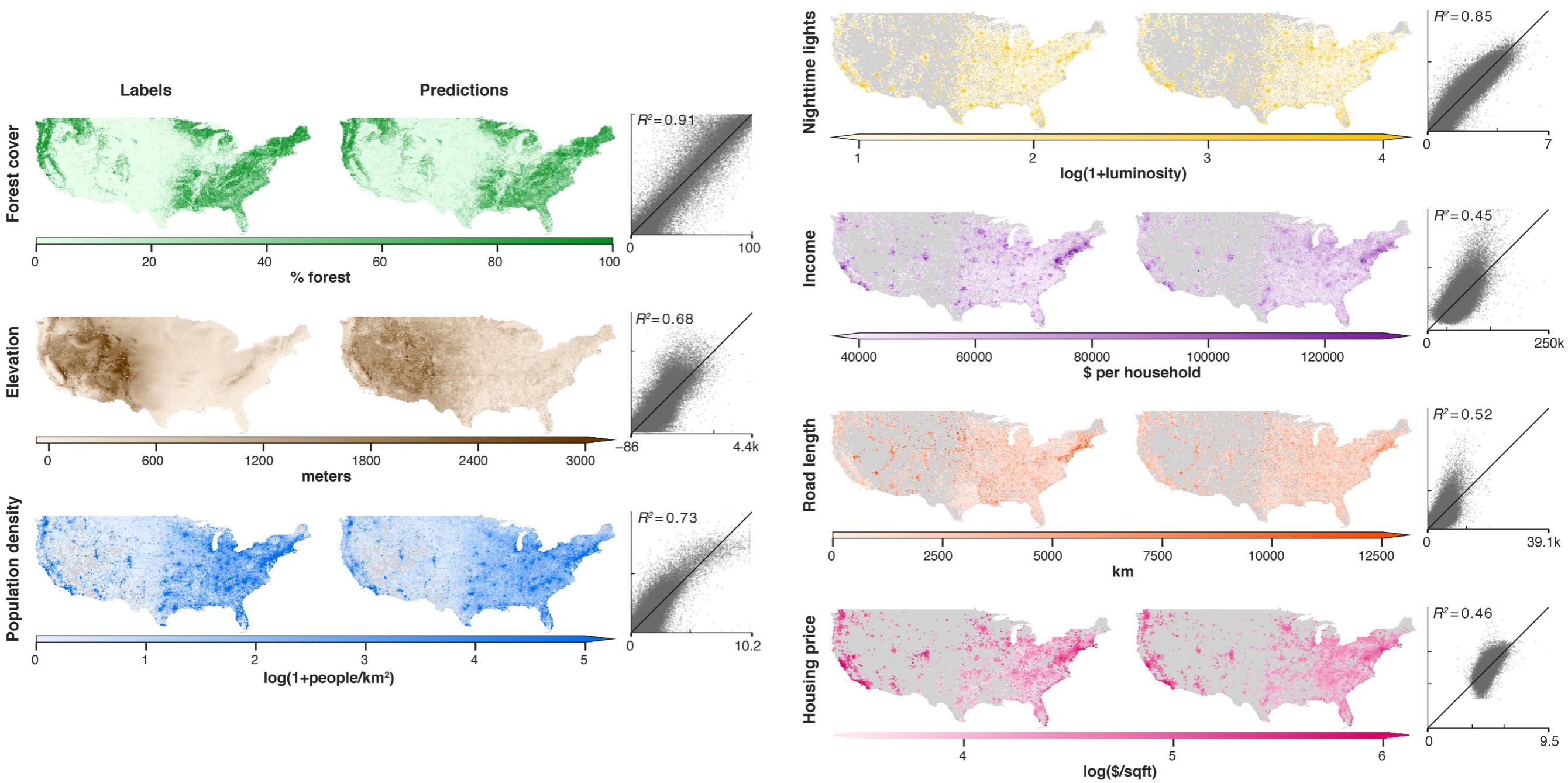
US Outcome #3: Population Density



Outcome #5: Income (per household)



A common featurization allows use to directly compare performance across outcomes.



Global Results

- Forest cover, nighttime luminosity, elevation
- Train on ~700k image label pairs, test on ~100k
 - Using the exact same featurization as in the U.S.
 - Report accuracy (R^2) on test set.

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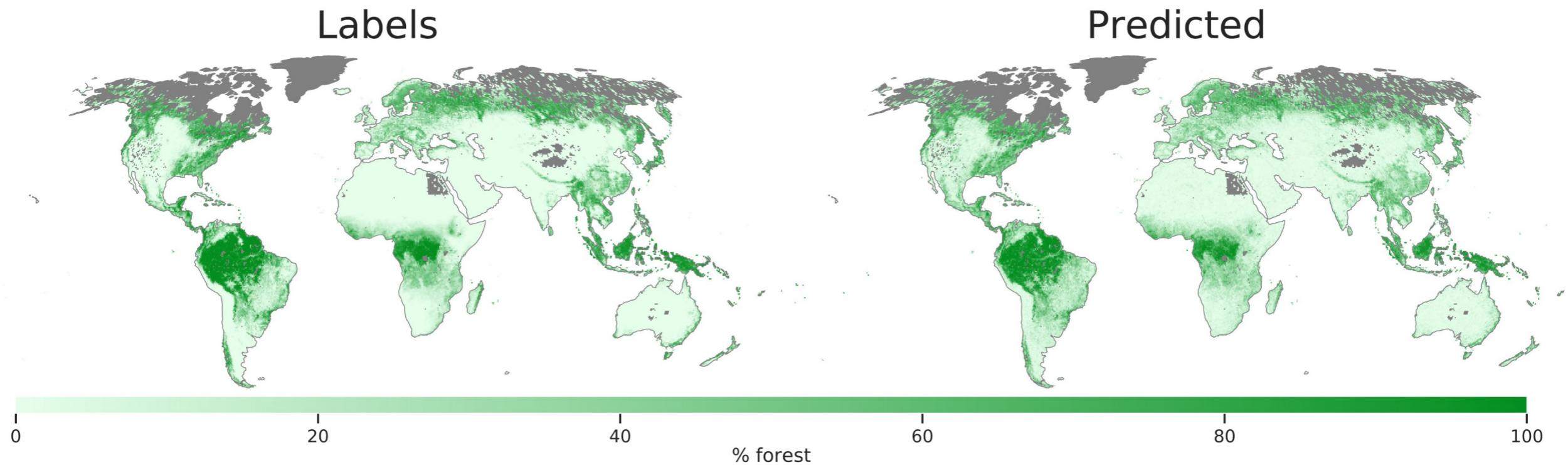
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challenges to scaling globally:

- more imagery
- label distribution mismatch U.S. to global
- images differing quality, many are “missing”

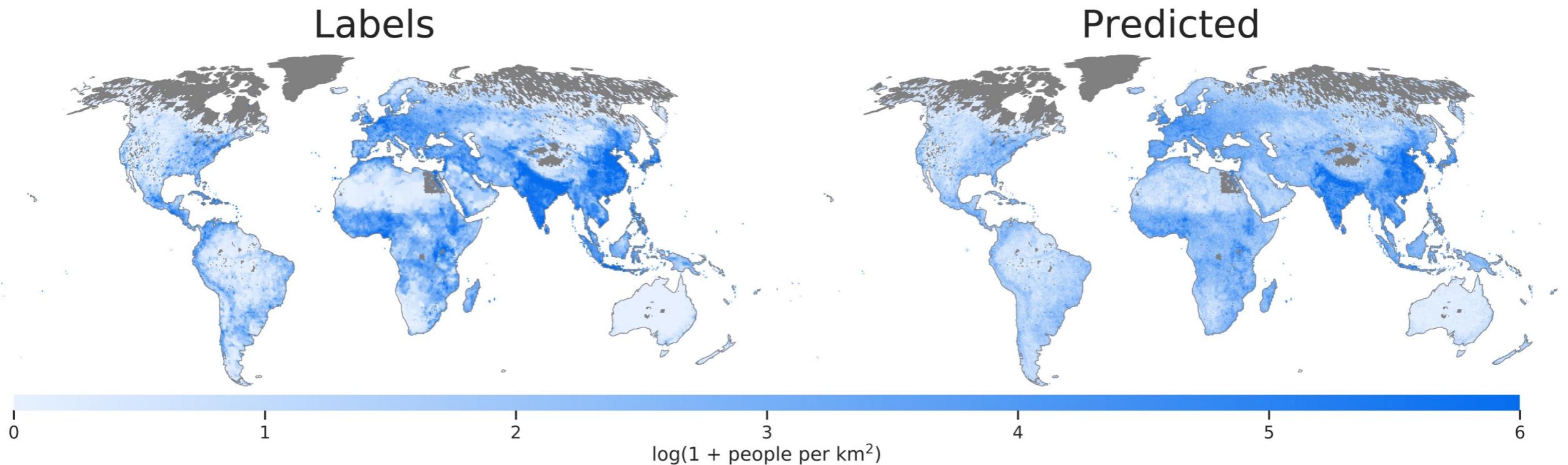
Global Outcome #1: Forest Cover

$$r^2 = 0.85$$



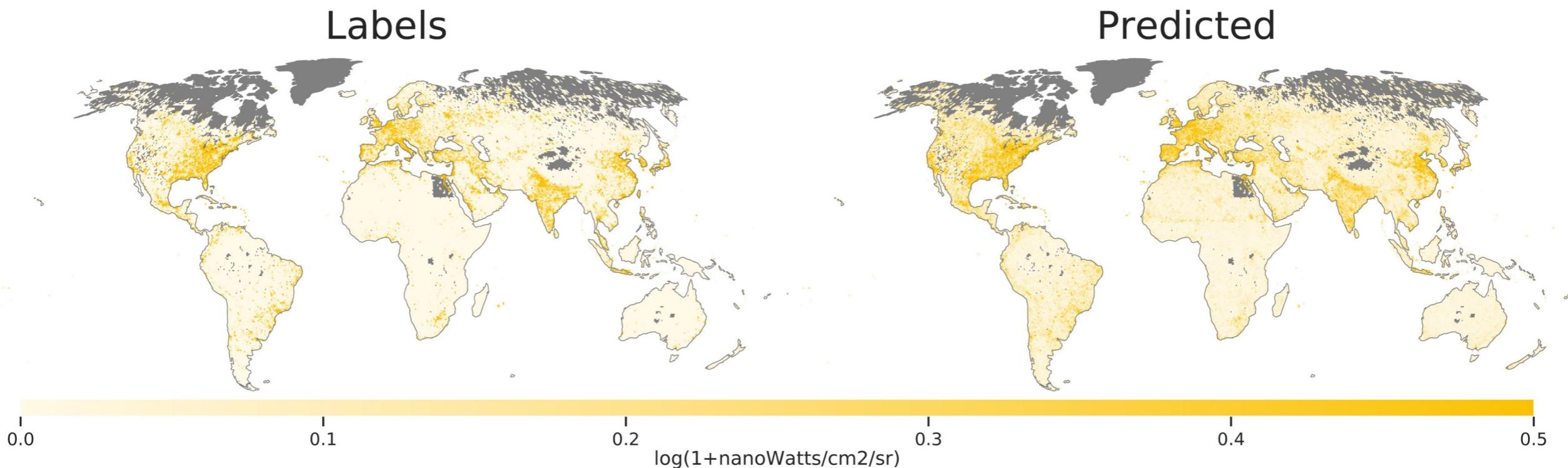
Global Outcome #2: Population Density

$$r^2 = 0.62$$



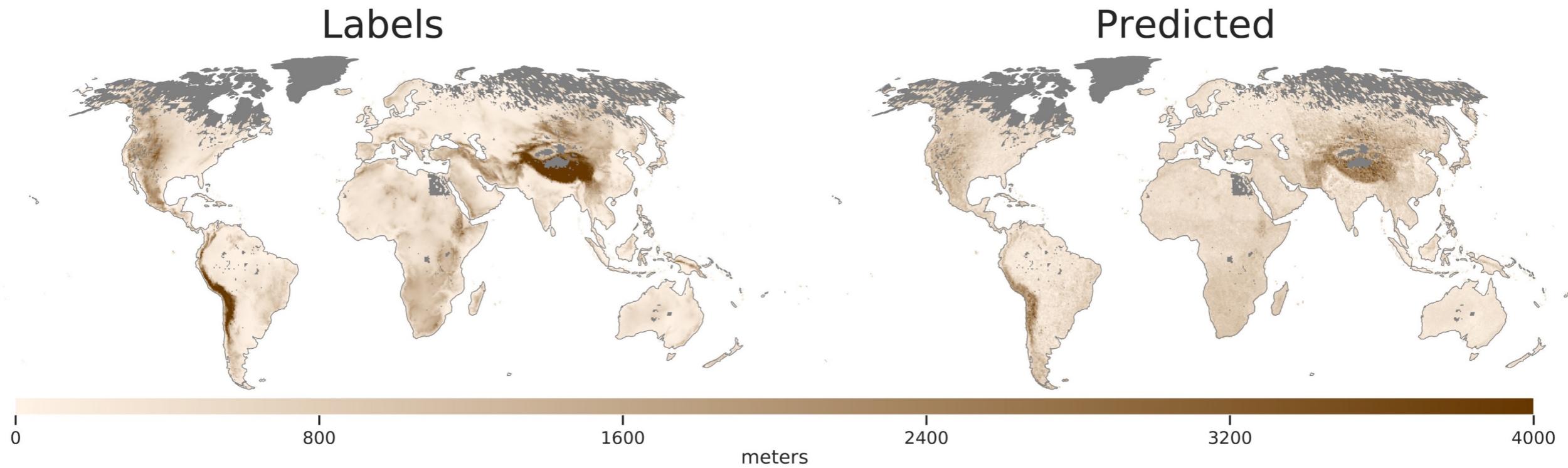
Global Outcome #3: **Nighttime Lights**

$$r^2 = 0.49$$

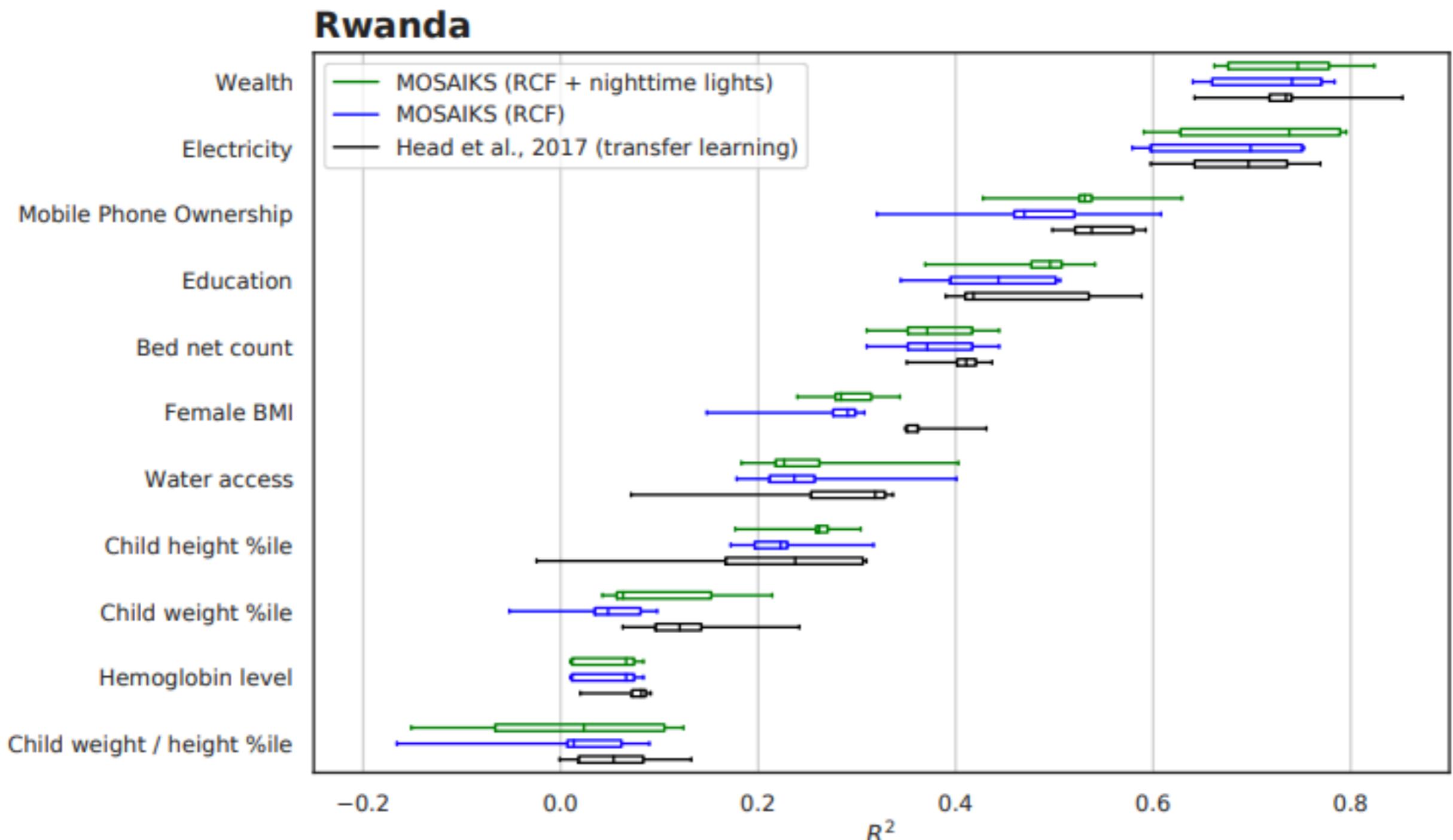


Global Outcome #4: Elevation

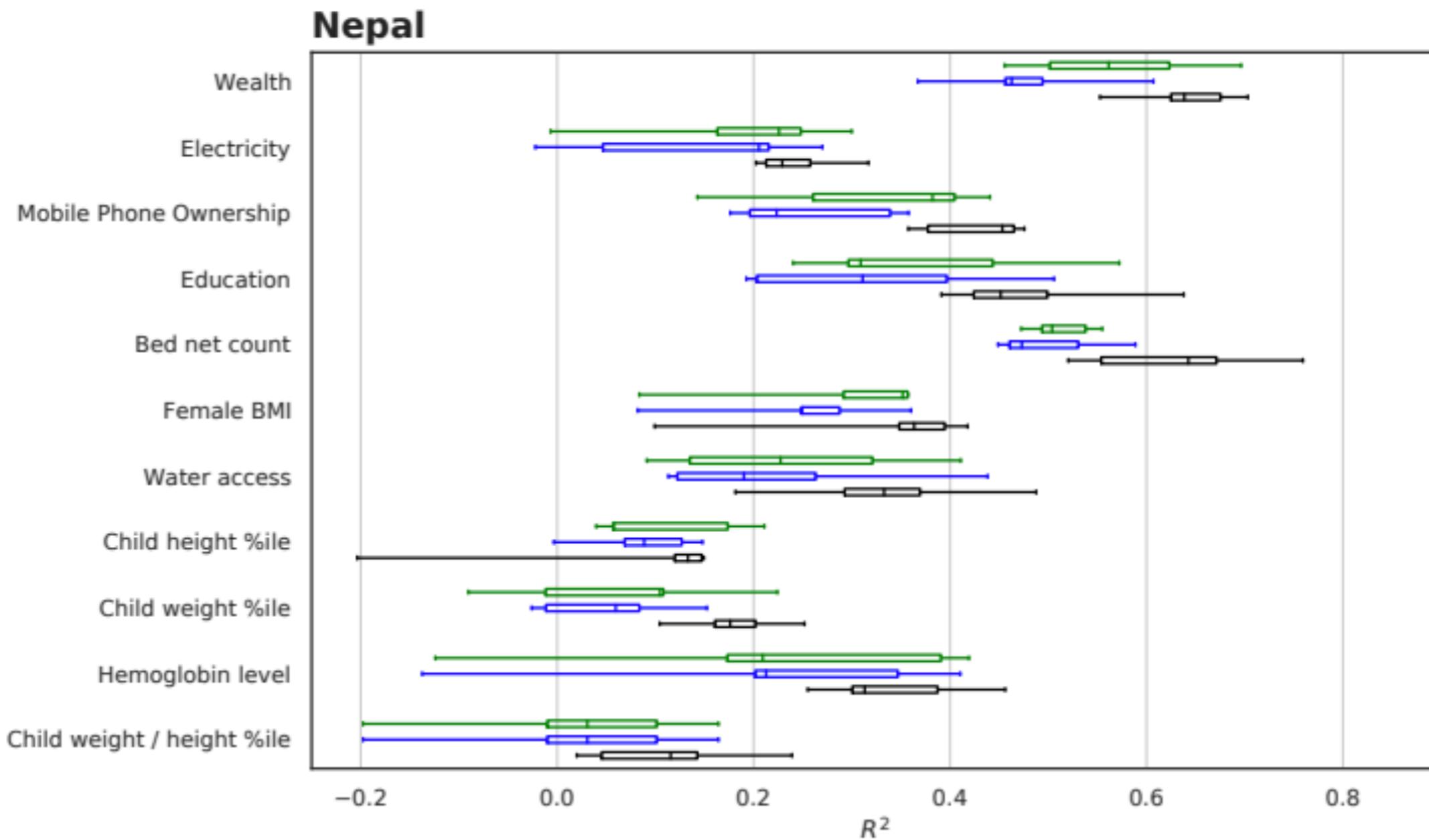
$$r^2 = 0.45$$



MOSAIKS for measuring human development



MOSAIKS for measuring human development



Many analyses end here.

Our fixed featurization allows further exploration of our predictions, and their use in practice

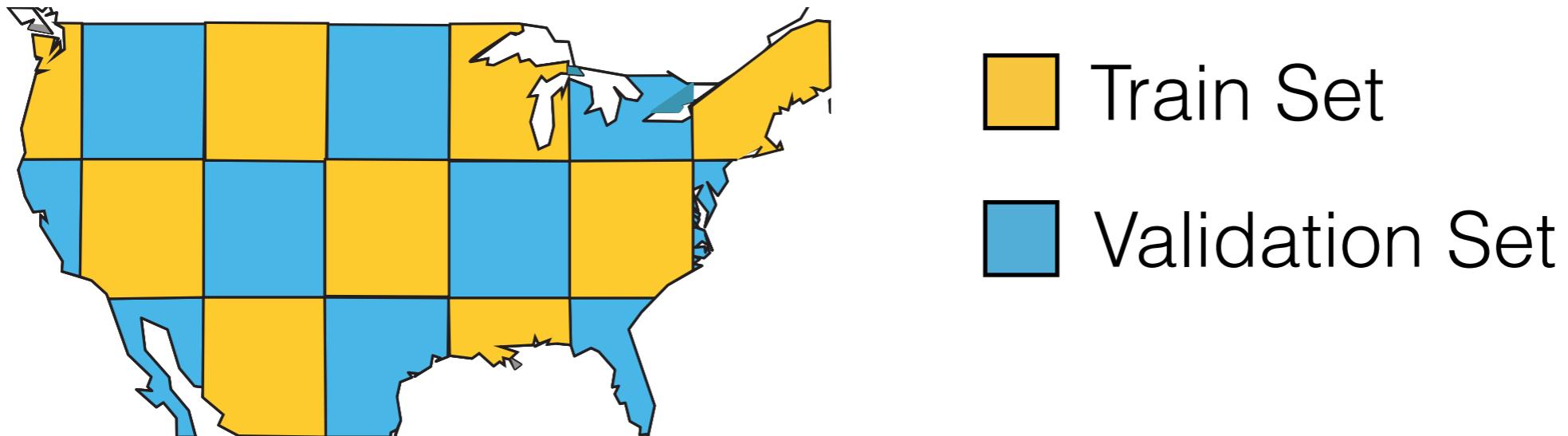
Generalizing across space

Goal: assess whether our method is generalizing over space, or just learning locality.

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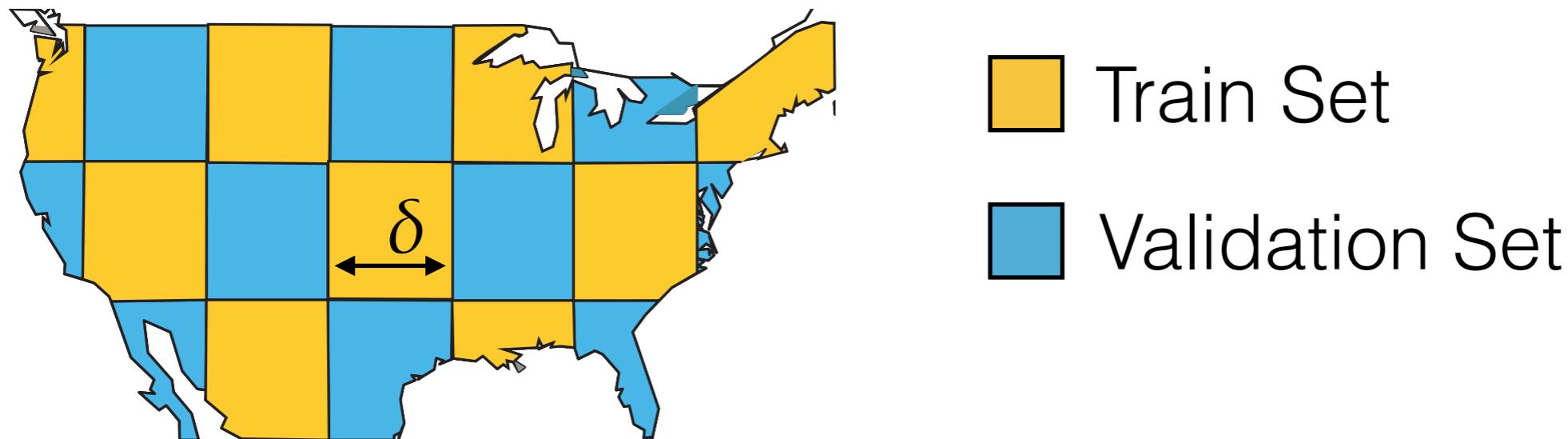
- Procedure: Split up the U.S. into geographically disjoint train and validation sets:



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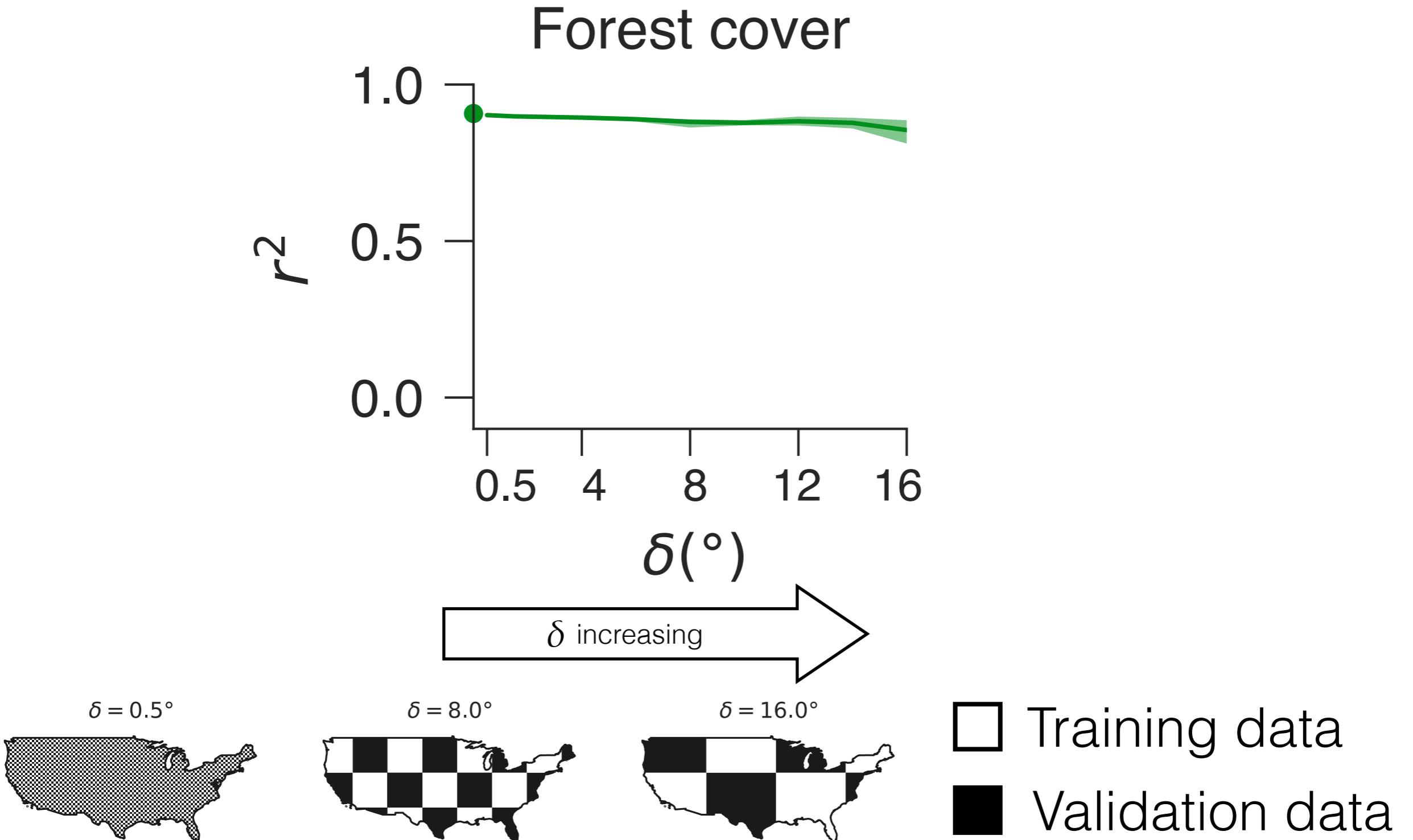
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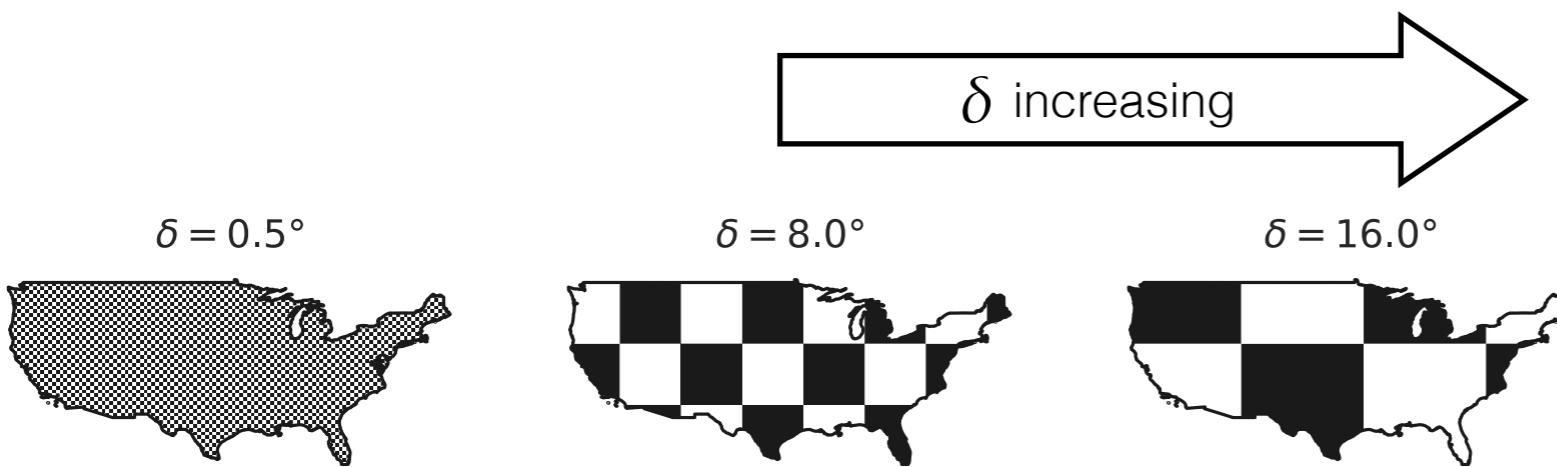
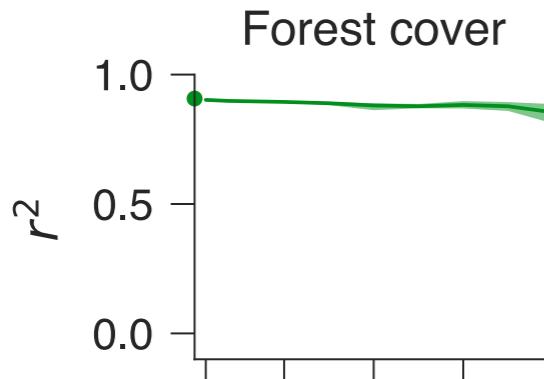


- Vary δ ; at what distance from the training set can we predict points in the validation set?

As degree of spatial extrapolation (δ) increases, performance degrades differently across domains.

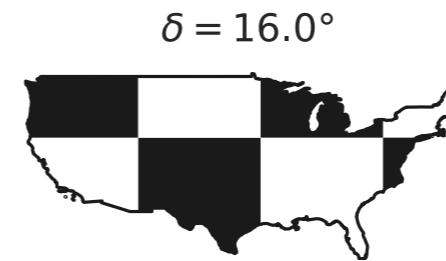
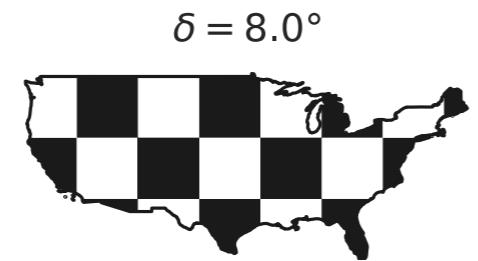
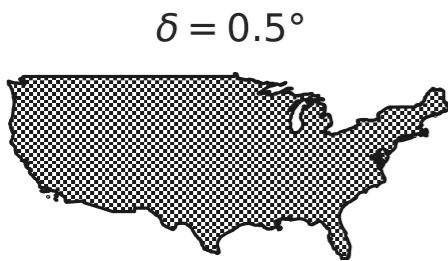
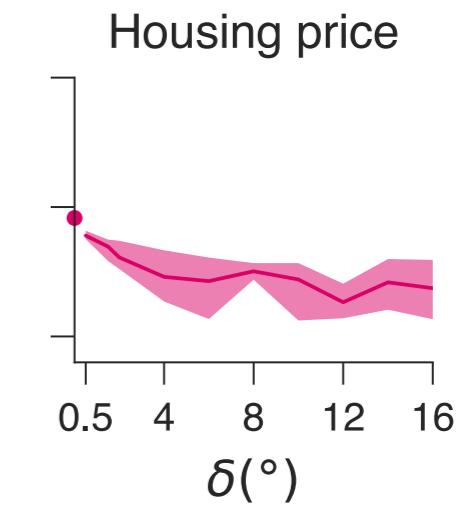
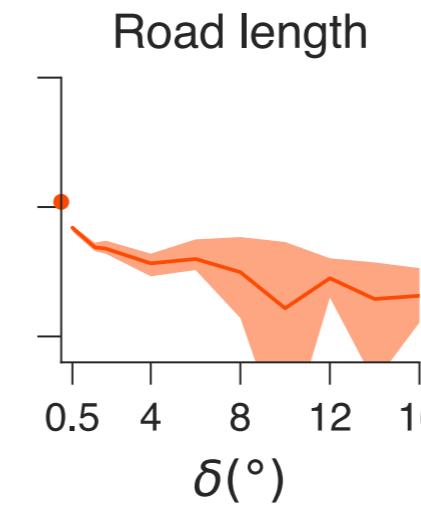
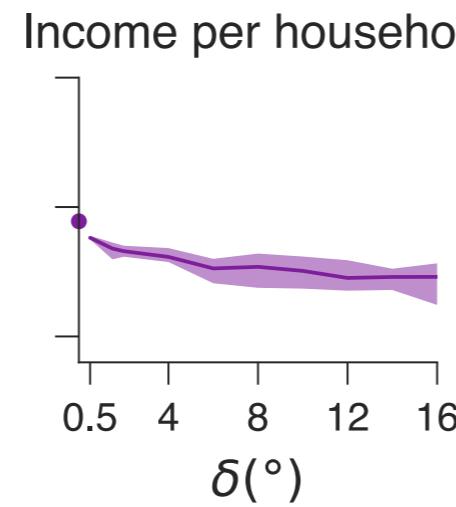
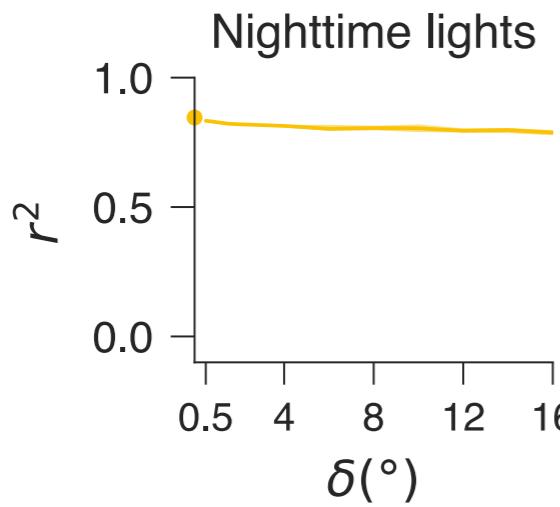
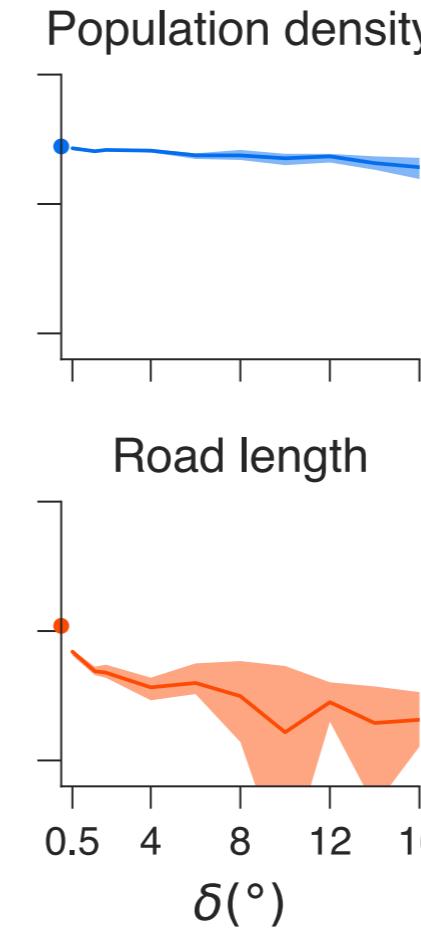
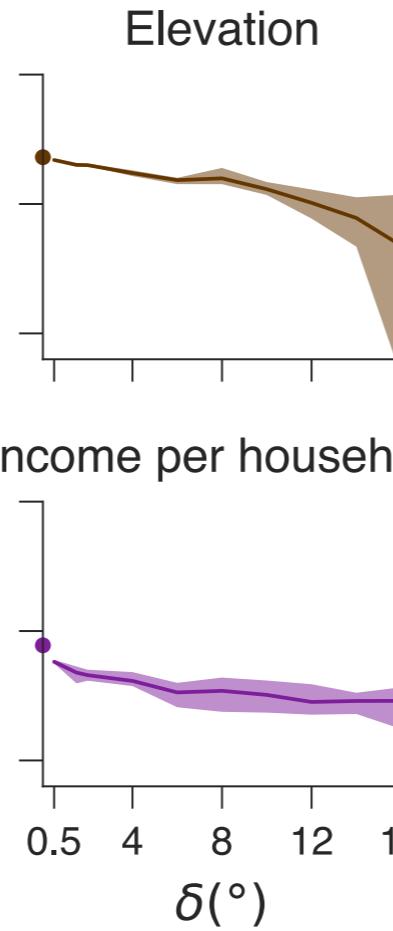
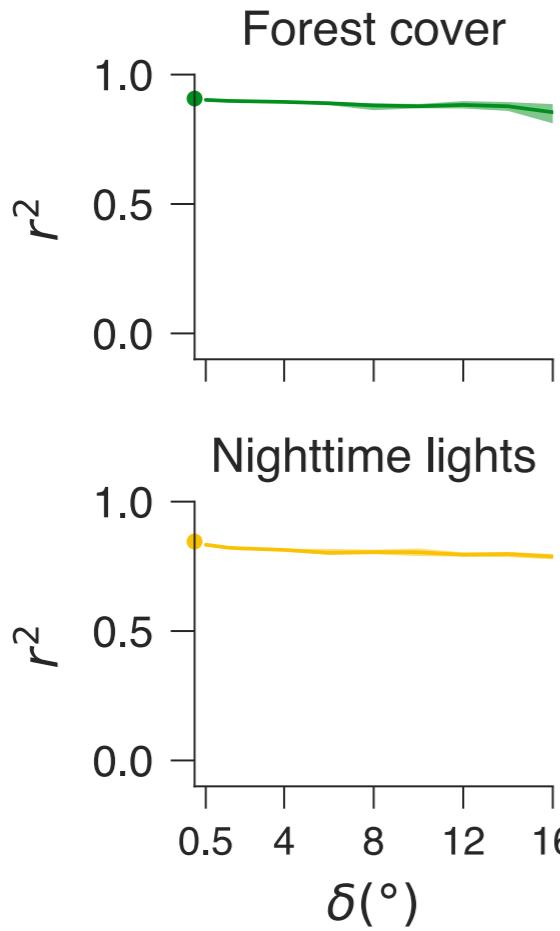


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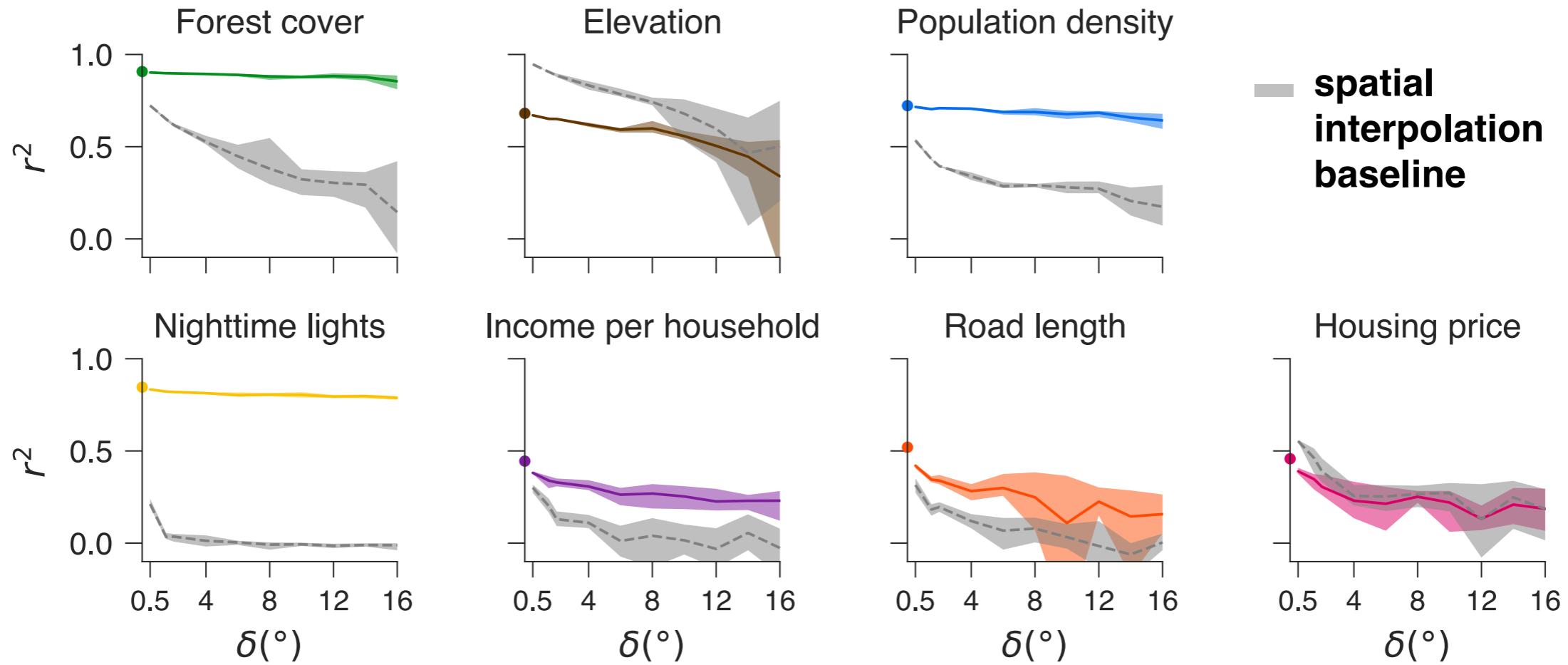
- Training data
- Validation data

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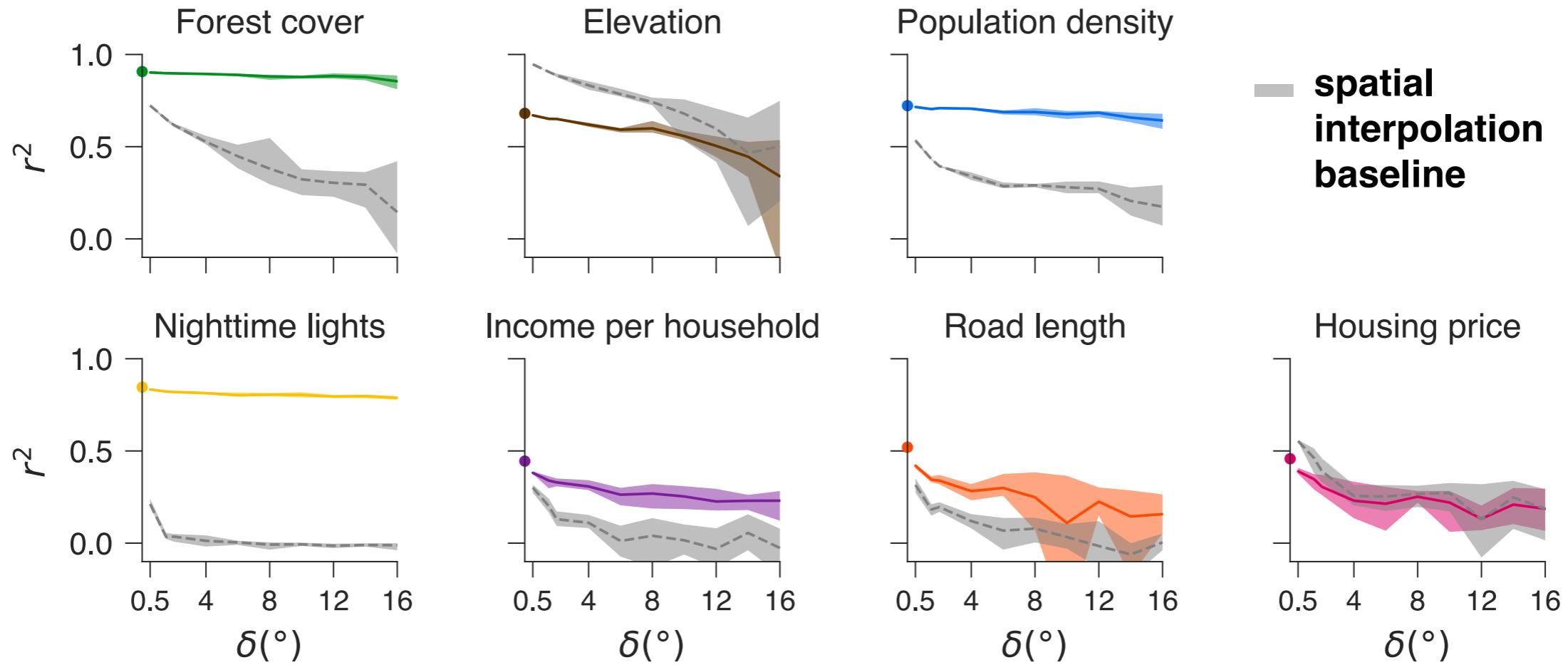


- Training data
- Validation data

Compared to a **spatial interpolation** baseline, our predictions have higher performance on 5/7 tasks.



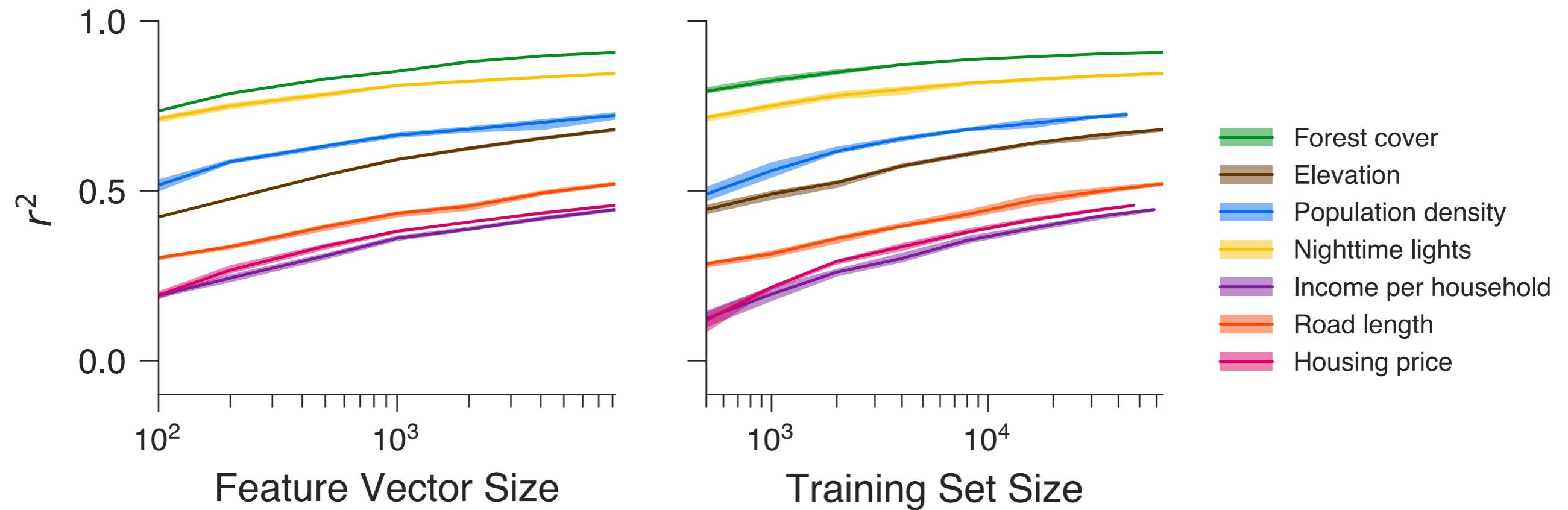
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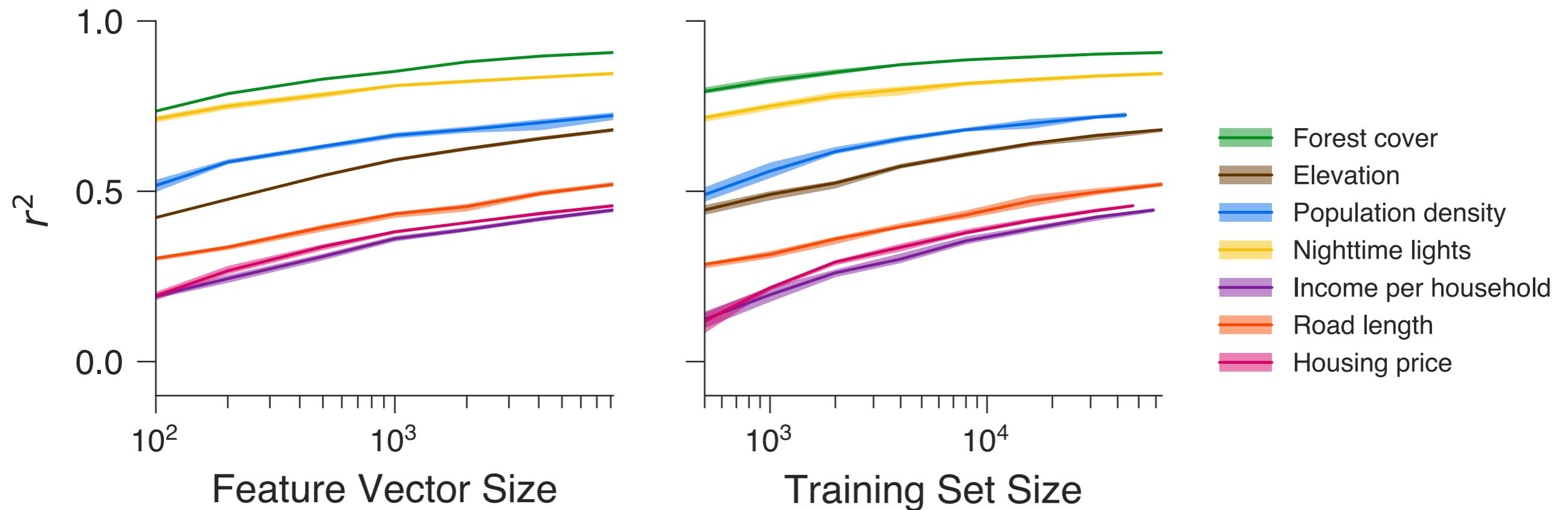
Domains where performance is worse than the baseline are known to exhibit high spatial correlation.

Takeaway: for certain domains, augmenting with location could be beneficial.

Model Diagnostics



Model Diagnostics



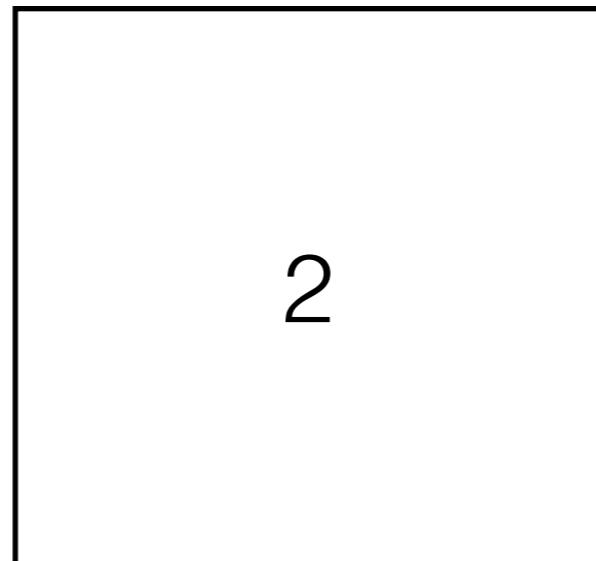
reiterate: with standard neural nets,
we would need to **retrain for each horizontal datapoint**.

Context switch:
we've expanded to global scale,
but can we get finer resolution?

super-resolution

Can we predict variables at *sub-image* resolution?

predicted road length (km):



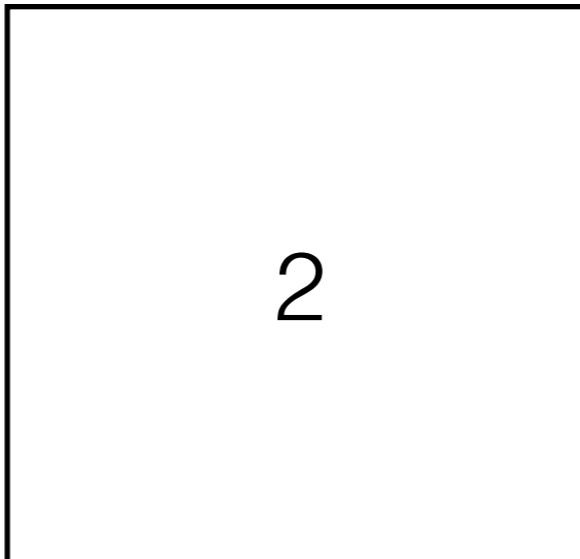
what we've done so far

super-resolution

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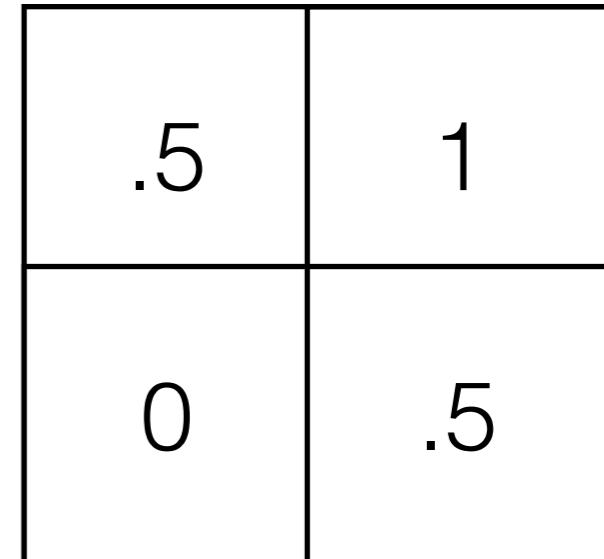


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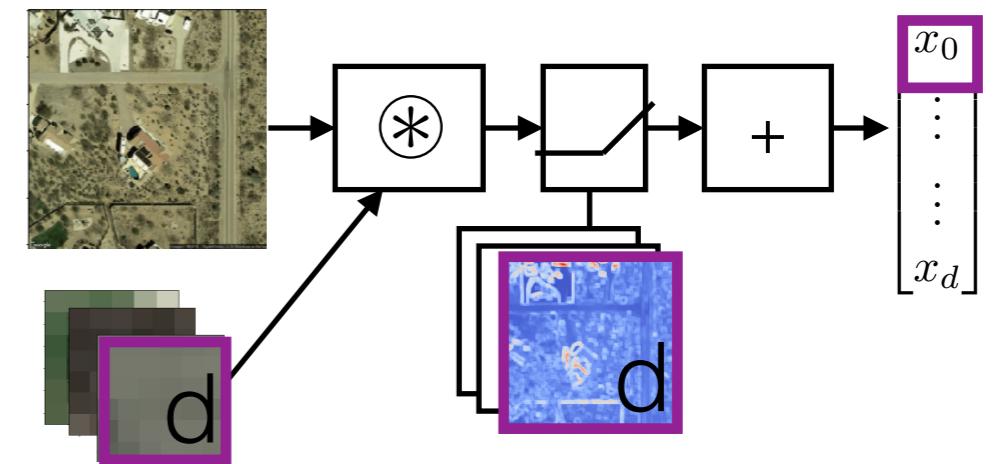
predicted road length (km):



↑
superresolution

super-resolution

$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

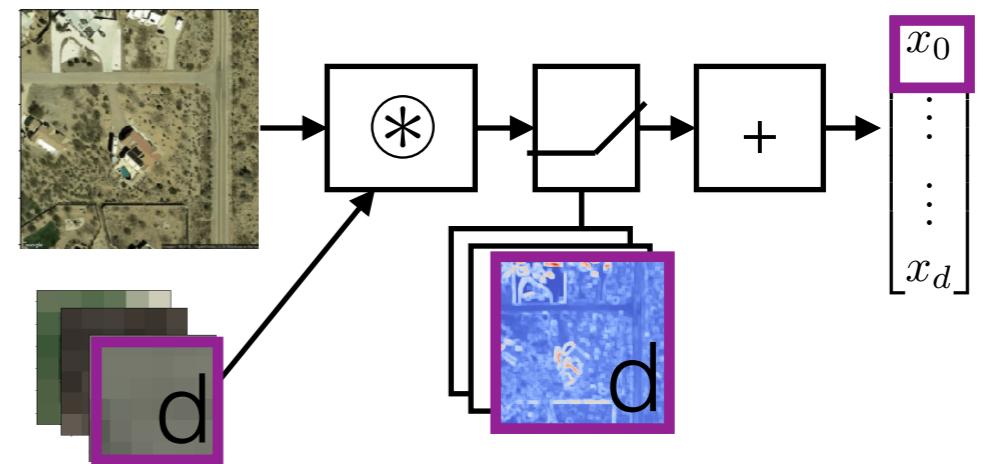


super-resolution

$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

$$\hat{y} = x^T w$$

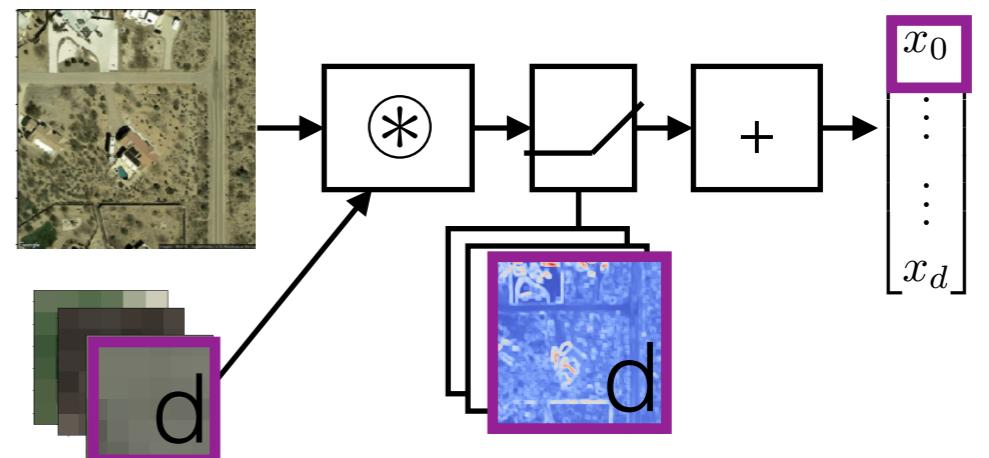
optimal regression weights



super-resolution

$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

$$\begin{aligned}\hat{y} &= x^\top w \quad \text{optimal regression weights} \\ &= \sum_{j=1}^d w_j x_j\end{aligned}$$



super-resolution

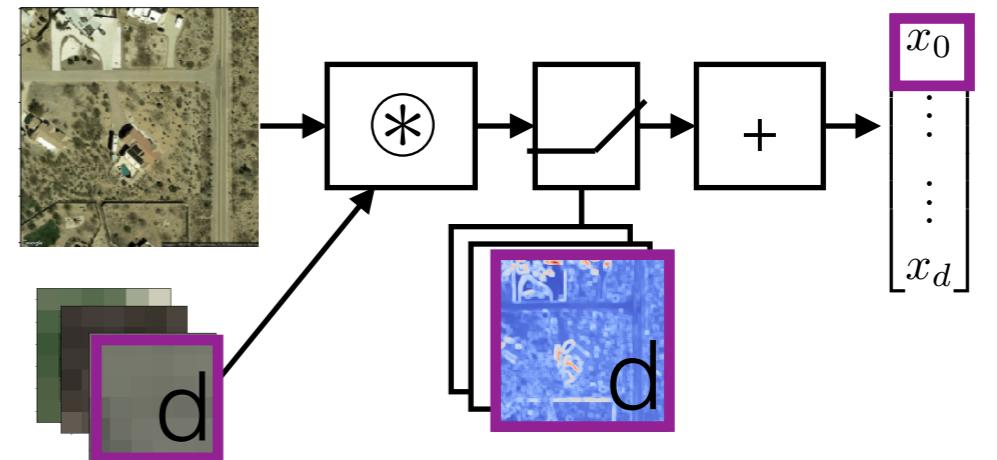
$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

$$\hat{y} = x^\top w$$

optimal regression weights

$$= \sum_{j=1}^d w_j x_j$$

$$= \sum_{j=1}^d w_j \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$



super-resolution

$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

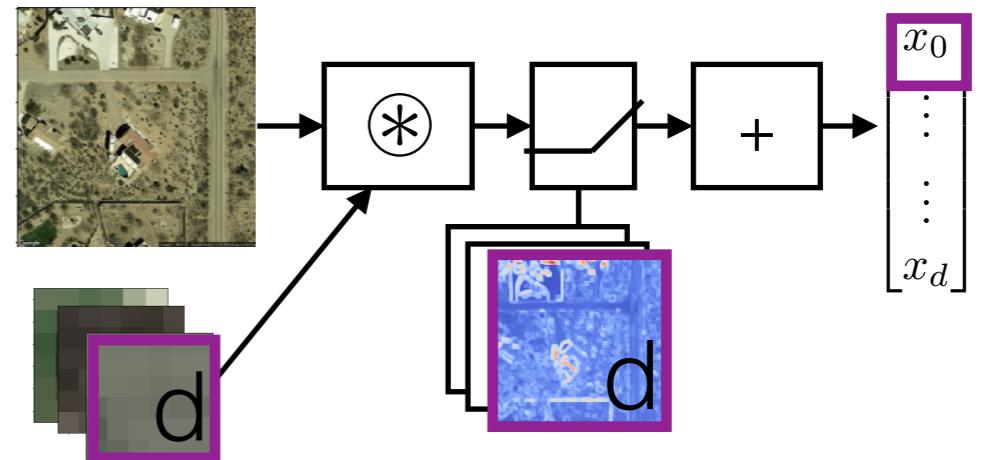
$$\hat{y} = x^\top w$$

optimal regression weights

$$= \sum_{j=1}^d w_j x_j$$

$$= \sum_{j=1}^d w_j \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

$$= \sum_{p \in \text{pixels}} \sum_{j=1}^d (w_j \cdot \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j]))$$



super-resolution

$$x_j = \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

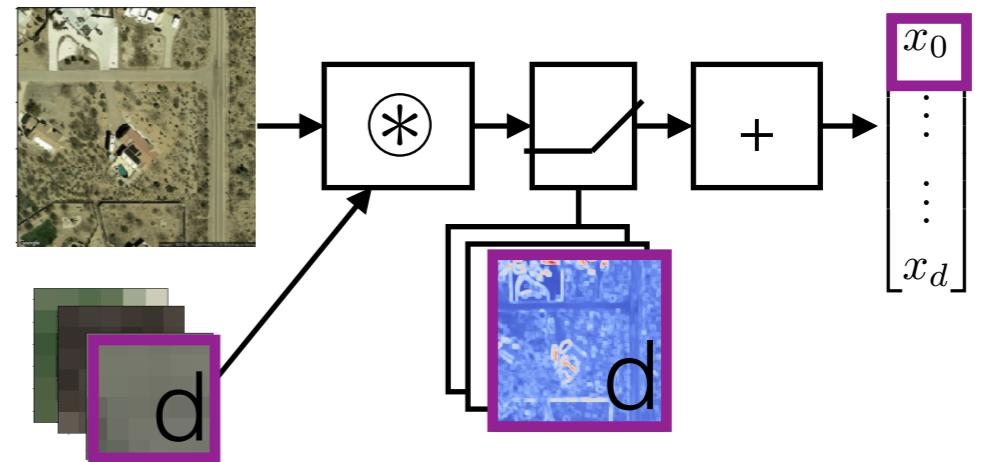
$$\hat{y} = x^\top w$$

optimal regression weights

$$= \sum_{j=1}^d w_j x_j$$

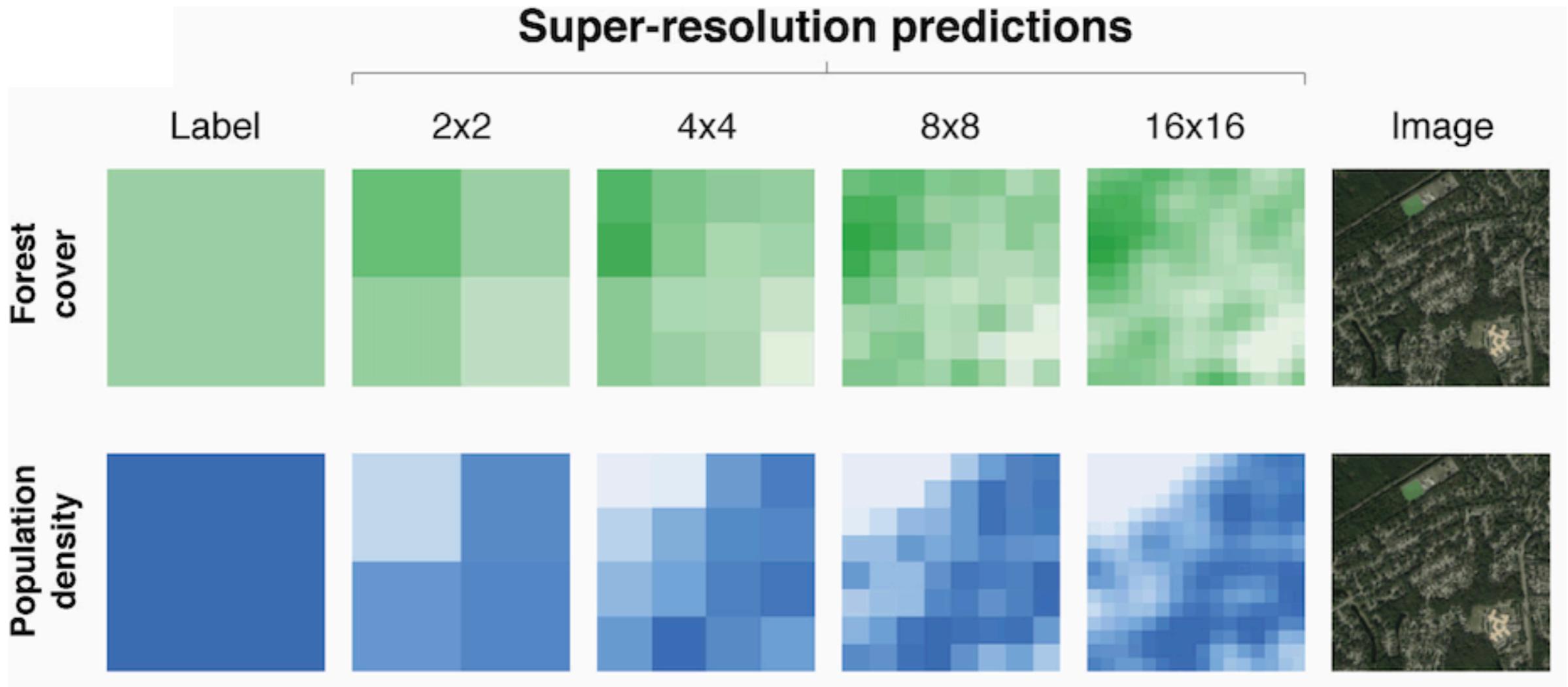
$$= \sum_{j=1}^d w_j \sum_{p \in \text{pixels}} \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j])$$

$$= \sum_{p \in \text{pixels}} \sum_{j=1}^d (w_j \cdot \text{ReLU}(\text{Image}[p] \circledast \text{Filter}[j]))$$

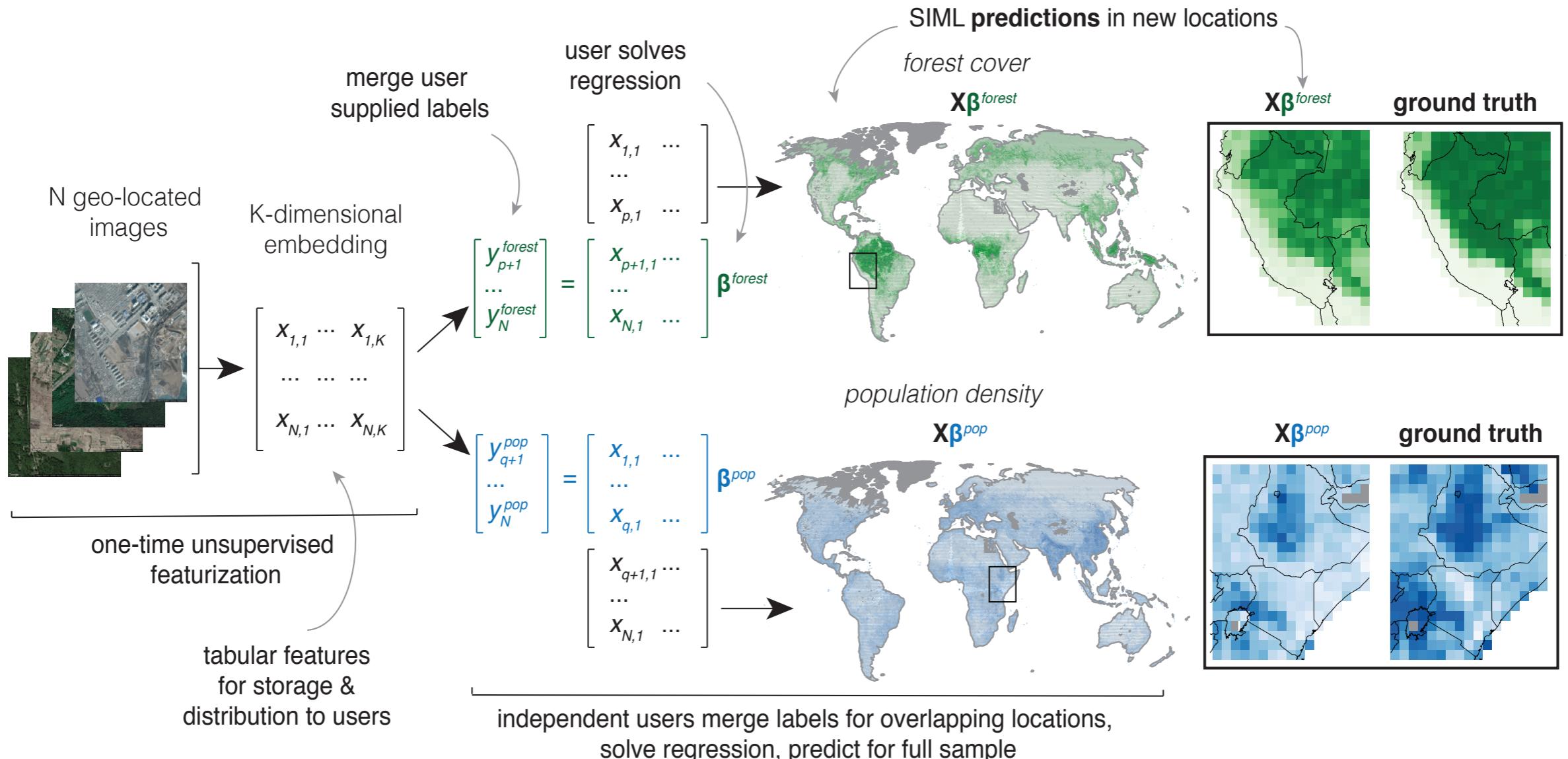


per-pixel predictions!
a sum of filter responses
scaled by regression
weights

Bonus: “super-label-resolution predictions”



Recap



In progress: a public API where users can query for features to run their own scientific analyses.

web-based UI



RCF

$$\begin{bmatrix} x^{(0)} \\ \vdots \\ x^{(n)} \end{bmatrix}$$

File Upload
For when you have a clearly selected and specific set of coordinates (generated from shapefile, geoJSON, etc) that you want to query.
 Choose File No file chosen

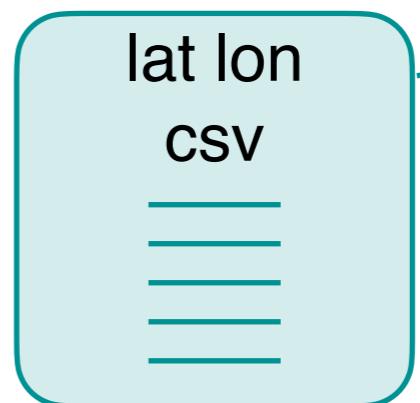
Select Bounding Boxes
For when you would like to select some coarsely defined bounding boxes to query.

Upper Right Lon:
Upper Left Lat: Lower Right Lon:
Lower Right Lat: Add Bbox

Map showing bounding boxes for Central America and the Caribbean. Three blue boxes are drawn on the map: one around Cuba and The Bahamas, one around Honduras and Nicaragua, and one around Colombia and Venezuela.

Clear All Bounding Boxes
Upper left lon: -86.4843750000001
Upper left lat: 25.11455670484684
Lower right lon: -72.33398437500001
Lower right lat: 18.348185439926455
Delete Bounding Box

Upper left lon: -76.55272901058198
Upper left lat: 13.199450407240874
Lower right lon: -53.87694776058197
Lower right lat: 1.9052916224608751
Delete Bounding Box



Summary: unsupervised RCF features enable a generalizable and accessible system for SIML.

What's next:

- Better unsupervised/self-supervised representations for satellite imagery.
- Adapting MOSAIKS design principles to other SIML prediction settings (segmentation, etc).

General SIML resources:

- MOSAIKS code, data, and tutorials: <http://www.globalpolicy.science/mosaiks>
- Torchgeo (<https://torchgeo.readthedocs.io/en/latest/>)
- Thorough list of resources at <https://github.com/robmarkcole/satellite-image-deep-learning>

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