

CS294-248 Special Topics in Database Theory

Unit 5 (Part 2): Database Constraints

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Outline

- Classical constraints: FDs, MVDs, CIs
- The basics, and a modern approach

Functional Dependencies

Fix a relation schema $R(\mathbf{X})$.

A **Functional Dependency**, FD, is an expression $\mathbf{U} \rightarrow \mathbf{V}$ for $\mathbf{U}, \mathbf{V} \subseteq \mathbf{X}$.

We say that an instance R^D **satisfies** the FD σ , and write $R^D \models \sigma$, if:

$$\forall t, t' \in R^D : t.\mathbf{U} = t'.\mathbf{U} \Rightarrow t.\mathbf{V} = t'.\mathbf{V}$$

If Σ is a set of FDs, then we write $R^D \models \Sigma$ if $R^D \models \sigma$ for all $\sigma \in \Sigma$.

Example

X	Y	Z
123	12	23
321	32	21
125	12	25
323	32	23
637	63	37
283	28	83

Then:

$$\begin{aligned}R^D &\models X \rightarrow Y, \\ &\quad X \rightarrow Z, \\ &\quad X \rightarrow YZ, \\ &\quad YZ \rightarrow X\end{aligned}$$

But:

$$R^D \not\models Y \rightarrow X$$

The Implication Problem

We say that a set of FDs Σ **implies** and FD σ if $\forall R^D, R^D \models \Sigma$ implies $R^D \models \sigma$.

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Example: $AB \rightarrow C, CD \rightarrow E \models ABD \rightarrow E$.

Proof:

<i>A</i>	<i>B</i>	<i>C</i>	<i>D</i>	<i>E</i>
		...		
<i>a</i>	<i>b</i>	<i>y</i>	<i>d</i>	?
		...		
<i>a</i>	<i>b</i>	<i>v</i>	<i>d</i>	?
		...		

Armstrong's Axioms

Many minor variations. My favorite:

Trivial: $\models UV \rightarrow U$

Transitivity: $U \rightarrow V, V \rightarrow W \models U \rightarrow W$

Splitting/combining: $U \rightarrow VW$ iff $U \rightarrow V, U \rightarrow W$

However, cumbersome to use: Can we check $\Sigma \models \sigma$ in PTIME?

The Closure Operator

Fix Σ . The **closure** of a set U is $U^+ \stackrel{\text{def}}{=} \{Z \mid \Sigma \models U \rightarrow Z\}$

Note that Σ is implicit in defining U^+ .

Databases 101 (to discuss in class):

- Given U , one can compute the closure U^+ in PTIME
- $\Sigma \models U \rightarrow V$ iff $V \subseteq U^+$.
- Example: $\Sigma = \{AB \rightarrow C, CD \rightarrow E\};$
 $AD^+ = ?$

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$ABD^+ =? ABCD$.

2-Tuple Relation

Fact

If $\Sigma \not\models \sigma$ then there exists a 2-tuple relation R s.t. $R \models \Sigma$ and $R \not\models \sigma$.

Example: $AB \rightarrow C, CD \rightarrow E \not\models CD \rightarrow A$.

Find a counterexample with 2 tuples (use values 0, 1):

	A	B	C	D	E
$R =$?	?	?	?	?
	?	?	?	?	?

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$$CD^+ = CDE$$

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0	0	0	0	0
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To refute $\mathbf{U} \rightarrow \mathbf{V}$: Tuple 1: $(0, 0, \dots, 0)$, Tuple 2: $\mathbf{U}^+ := 0$, rest $:= 1$.

Armstrong Relation

- We can refute a single implication $\Sigma \models \sigma$ using a 2-tuple relation.
- **Armstrong relation** for Σ is a relation R_Σ that refutes *all* FDs not implied by Σ .
- Equivalently, $\Sigma \models \sigma$ iff $R_\Sigma \models \sigma$.
- The construction of R_Σ is more interesting than the application. Next.

The Direct Product

[Fagin, 1982]

The **direct product**¹ of two tuples $t = (a_1, \dots, a_n)$ and $t' = (b_1, \dots, b_n)$ is:

$$t \otimes t' \stackrel{\text{def}}{=} ((a_1, b_1), \dots, (a_n, b_n))$$

¹A.k.a. **domain product**.

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The **direct product** of two relations $R(\mathbf{X}), R'(\mathbf{X})$ (same attributes!) is

$$R \otimes R' \stackrel{\text{def}}{=} \{t \otimes t' \mid t \in R, t' \in R'\}$$

¹A.k.a. **domain product**.

Example: Cartesian Product v.s. Direct Product

 $T =$

<i>A</i>	<i>B</i>
1	5
1	6

 $S =$

<i>X</i>	<i>Y</i>	<i>Z</i>
<i>a</i>	<i>b</i>	<i>c</i>
<i>f</i>	<i>b</i>	<i>d</i>
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 $T \times S =$

<i>A</i>	<i>B</i>	<i>X</i>	<i>Y</i>	<i>Z</i>
1	5	<i>a</i>	<i>b</i>	<i>c</i>
1	6	<i>a</i>	<i>b</i>	<i>c</i>
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...				

 $R =$

X	Y	Z
1	5	m
1	6	m

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1a	5b	mc
1a	6b	mc
2a	6b	nc
1f	5b	md
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Given prob. distributions with entropies h_R, h_S , what is $h_{R \otimes S}$?
In class.

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Given prob. distributions with entropies h_R, h_S , what is $h_{R \otimes S}$?

In class. $h_R + h_S$ (sum of two vectors).

h_T, h_S cannot be added, since they have $2^2, 2^3$ dimensions.

Armstrong's Relation

Lemma

For any FD σ , $R \otimes R' \models \sigma$ iff $R \models \sigma$ and $R' \models \sigma$.

Proof in class (it's straightforward).

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Theorem (Armstrong's Relation)

For any set of FDs Σ there exists R_Σ s.t., for any FD σ , $\Sigma \models \sigma$ iff $R_\Sigma \models \sigma$.

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Proof Let $\sigma_i, i = 1, n$ be all FDs not implied by Σ .

Since $\Sigma \not\models \sigma_i$, there exists a 2-tuple R_i such that $R_i \models \Sigma$ and $R_i \not\models \sigma_i$.

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Then $R_\Sigma \stackrel{\text{def}}{=} R_1 \otimes \dots \otimes R_n$ satisfies the theorem.

Why?

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Why?

How large is R_Σ ?

Discussion

Next:

- Defining the FDs is equivalent to defining the closure operator \mathbf{U}^+ .
- In turn, this is equivalent to defining the *closed* sets, i.e. those that satisfy $\mathbf{U} = \mathbf{U}^+$.
- And this is equivalent to defining the lattice of closed elements.

The Closure Operator: Properties

Monotone: If $U \subseteq V$, then $U^+ \subseteq V^+$.

Why??

Expansive: $U \subseteq U^+$

Why??

Idempotent: $(U^+)^+ = U^+$

Why??

Wikipedia calls these properties **increasing**, **extensive**, **idempotent**.

Discussion

The **closure operator**, and its associated **closure system** occur in many areas of math and CS.

- For any subset $S \subseteq \mathbb{R}^d$, its **linear span**, $\text{span}(S)$, is the smallest vector space containing S ; span is a closure operator.
- For any subset $S \subseteq \mathbb{R}^d$, let $\text{convex}(S) \subseteq \mathbb{R}^d$ be its convex closure; convex is a closure operator.
- The **topological closure** of a subset $S \subseteq \mathbb{R}^d$ is the set \bar{S} consisting of all limits $\lim_n x_n$, where the sequence x_n is in S .
- Fix an algebra A . The **algebra generated** by a subset S is the smallest sub-algebra containing S .

Detour: Closure Operators

Fix a set Ω .

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Definition (Closure Operator)

A **closure operator** is $cl : \mathcal{P}(\Omega) \rightarrow \mathcal{P}(\Omega)$ that is:

- monotone $A \subseteq B \Rightarrow cl(A) \subseteq cl(B)$
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- for any $\mathcal{S} \subseteq \mathcal{C}$, $\bigcap \mathcal{S} \in \mathcal{C}$.

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Therefore $cl(A) \subseteq \bigcap \{X \mid X \in \mathcal{S}\} = A$.

From FDs to the Lattice of Closed Sets

A set of FDs for $R(\mathbf{X})$ is equivalent to a closure system on \mathbf{X} .

Moreover, a closure system \mathcal{C} forms a **lattice**, $(\mathcal{C}, \wedge, \vee)$:

$$X \wedge Y \stackrel{\text{def}}{=} X \cap Y$$

$$X \vee Y \stackrel{\text{def}}{=} (X \cup Y)^+$$

From FDs to the Lattice of Closed Sets

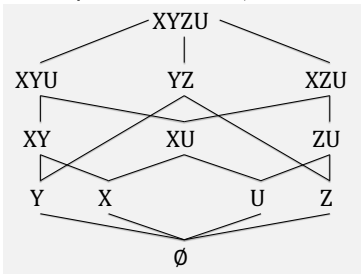
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Example: $YU \rightarrow X, XZ \rightarrow U$



Discussion

- Functional dependencies are a key concept in CS, beyond databases.
- In databases, they have two traditional applications:
 - ▶ Database normalization: BCNF, 3NF
 - ▶ Keys/foreign keys; “semantic pointers”
- More recent applications: discover FDs from data, approximate FDs, repairing for FDs (data imputation).

Multivalued Dependencies

Relation Decomposition

Take a relation R , partition its variables into $\mathbf{U}, \mathbf{V}, \mathbf{W}$.

Instead of storing $R(\mathbf{U}, \mathbf{V}, \mathbf{W})$ we store its projections:

$$R_1(\mathbf{U}, \mathbf{V}) \stackrel{\text{def}}{=} \Pi_{UV}(R), \quad R_2(\mathbf{U}, \mathbf{W}) \stackrel{\text{def}}{=} \Pi_{UW}(R)$$

Can we always recover R from $R_1 \bowtie R_2$?

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Lossless decomposition: when $R = R_1 \bowtie R_2$.

Fact If $\mathbf{U} \rightarrow \mathbf{V}$ holds then the decomposition is lossless. This is the basis of *database normalization* (BCNF, 3NF).

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We will always denote the MVD by $U \twoheadrightarrow V; W$ ($W \stackrel{\text{def}}{=}$ the rest of attrs).

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$$R = \Pi_{UV}(R) \bowtie \Pi_{UW}(R)$$

We will always denote the MVD by $U \twoheadrightarrow V; W$ ($W \stackrel{\text{def}}{=}$ the rest of attrs).

Equivalently: if $(u, v_1, w_2), (u, v_2, w_2) \in R$ then $(u, v_1, w_2) \in R$ (and, by symmetry, $(u, v_2, w_1) \in R$).

Examples

1. Fix $R(X, Y, Z)$. If $Z \rightarrow X$, then $Z \twoheadrightarrow (X; Y)$.

Why?

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Why? Because $R = R_1(X, Z) \bowtie R_2(Y, Z)$ is lossless.

2. If $R(X, Y) = R_1(X) \times R_2(Y)$, then $R \models \emptyset \twoheadrightarrow (X; Y)$.

Examples

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Why? Because $R = R_1(X, Z) \bowtie R_2(Y, Z)$ is lossless.

2. If $R(X, Y) = R_1(X) \times R_2(Y)$, then $R \models \emptyset \twoheadrightarrow (X; Y)$.

3. $R =$

X	Y	Z
a	x	m
a	y	m
b	x	m
b	y	m
a	x	n

Then $R \models Z \twoheadrightarrow (X; Y)$

$R_1(X, Z) =$

X	Z
a	m
b	n
a	n

$R_2(Y, Z) =$

Y	Z
x	m
y	m
x	n

Axiomatization

[Beeri et al., 1977] gave a sound and complete axiomatization for MVDs and FDs (together).

MVD1 (Reflexivity): If $Y \subseteq X$
then $X \twoheadrightarrow Y$.

MVD2 (Augmentation): If $Z \subseteq W$ and
 $X \twoheadrightarrow Y$
then $XW \twoheadrightarrow YZ$.

MVD3 (Transitivity): If $X \twoheadrightarrow Y$ and
 $Y \twoheadrightarrow Z$
then $X \twoheadrightarrow Z$.

MVD4 (Pseudo-transitivity):
If $X \twoheadrightarrow Y$ and $YW \twoheadrightarrow Z$
then $XW \twoheadrightarrow Z$.

MVD5 (Union): If $X \twoheadrightarrow Y_1$ and $X \twoheadrightarrow Y_2$
then $X \twoheadrightarrow Y_1 Y_2$.

MVD6 (Decomposition): If $X \twoheadrightarrow Y_1$ and
 $X \twoheadrightarrow Y_2$
then $X \twoheadrightarrow Y_1 \cap Y_2$,
 $X \twoheadrightarrow Y_1 - Y_2$ and
 $X \twoheadrightarrow Y_2 - Y_1$.

No need to read: we will see a simpler approach to MVDs

Embedded MVD

Recall that an MVD $\sigma = \mathbf{U} \twoheadrightarrow (\mathbf{V}; \mathbf{W})$ includes *all variables*

When σ does not include all the variables then it is called an **Embedded MVD**, or EMVD.

A major breakthrough:

Theorem

[Herrmann, 1995] *The implication problem of EMVDs is undecidable.*

Discussion

- MVDs used to define the 4th Normal Form.
- MVDs are more complex and less intuitive than FDs
- FDs equivalent to a closure system, equivalent to a lattice. No such thing for MVDs.

Conditional Independence

Definition

Fix a joint probability distribution p over variables \mathbf{X} .

\mathbf{V} , \mathbf{W} are **independent** conditioned on \mathbf{U} if $\forall \mathbf{u}, \mathbf{v}, \mathbf{w}$:

$$p(\mathbf{U} = \mathbf{u}, \mathbf{V} = \mathbf{v})p(\mathbf{U} = \mathbf{u}, \mathbf{W} = \mathbf{w}) = p(\mathbf{U} = \mathbf{u})p(\mathbf{U} = \mathbf{u}, \mathbf{V} = \mathbf{v}, \mathbf{W} = \mathbf{w})$$

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$$\boxed{\mathbf{V} \perp \mathbf{W} | \mathbf{U}} \text{ if } \boxed{p(\mathbf{V}, \mathbf{W} | \mathbf{U}) = p(\mathbf{V} | \mathbf{U}) \cdot p(\mathbf{W} | \mathbf{U})}$$

but be careful when $p(\mathbf{U} = \mathbf{u}) = 0$.

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but be careful when $p(\mathbf{U} = \mathbf{u}) = 0$.

X	Y	p
0	0	1/6
0	1	1/6
1	0	1/3
1	1	1/3

$X \perp Y?$:

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0	1	1/6
1	0	1/3
1	1	1/3

$X \perp Y?$

Yes

$$\begin{array}{|c|} \hline X \\ \hline 0 \\ 1 \\ \hline \end{array} \begin{array}{l} p \\ 1/3 \\ 2/3 \end{array} \times \begin{array}{|c|} \hline Y \\ \hline 0 \\ 1 \\ \hline \end{array} \begin{array}{l} p \\ 1/2 \\ 1/2 \end{array}$$

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×

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NO

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Y	p
0	1/2
1	1/2

$X \perp Y?$

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0	1	1/3
1	0	1/6

NO

Observation: if $\mathbf{V} \perp \mathbf{W} | \mathbf{U}$ holds then $\mathbf{U} \rightarrow (\mathbf{V}; \mathbf{W})$.

The Conditional Independence Implication Problem

Introduced by Pearl in the early 80s.

Given a set of CIs Σ and a CI σ , does $\Sigma \models \sigma$ hold?

[Geiger and Pearl, 1993] complete axiomatization for “saturated” CIs (meaning: each CI includes all variables).

Is the CI implication problem decidable?

Open problem for decades. There were two independent claims of proofs last year (I don't know their status).

Discussion

There is an uneasy connection between MVDs and CIs:

- MVDs correspond only to *saturated* CIs, i.e. all variables. The implication problem is the same.
- EMVDs appear to correspond to general CIs, but their implication problem is different.

Connection to Entropy

Entropic Vectors

Fix a relation instance R . [Lee, 1987] observed the following:
Let p be any probability distribution with support R , and h be its entropic vector.

For any p , $R \models \mathbf{U} \rightarrow \mathbf{V}$ iff $h(\mathbf{V}|\mathbf{U}) = 0$

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If p is uniform, then $R \models \mathbf{U} \twoheadrightarrow (\mathbf{V}; \mathbf{W})$ iff $\mathbf{V} \perp \mathbf{W}|\mathbf{U}$ iff $I_h(\mathbf{V}; \mathbf{W}|\mathbf{U}) = 0$.

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then $Z \twoheadrightarrow (X; Y)$
 $X \perp Y|Z$.

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1	0	1/4
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then

$$\begin{aligned} Z &\twoheadrightarrow (X; Y) \\ X &\perp Y|Z. \end{aligned}$$

But, if probabilities are other than 1/4, then

$$\begin{aligned} Z &\twoheadrightarrow (X; Y) \\ \neg(X &\perp Y|Z). \end{aligned}$$

The FD/MVD implication problem can be solved with entropic inequalities!

FD/MVD Implication by Entropic Inequalities

Example: Union Axiom MVD5: $X \twoheadrightarrow Y_1, X \twoheadrightarrow Y_2 \models X \twoheadrightarrow Y_1 Y_2$

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Let Z be the other variables, then:

$(X \twoheadrightarrow Y_1; Y_2 Z), (X \twoheadrightarrow Y_2; Y_1 Z) \models (X \twoheadrightarrow Y_1 Y_2 | Z).$

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We show: $I_h(Y_1; Y_2 Z | X) = I_h(Y_2; Y_1 Z | X) = 0 \Rightarrow I_h(Y_1 Y_2; Z | X) = 0$

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Suffices to show: $I_h(Y_1; Y_2 Z | X) + I_h(Y_2; Y_1 Z | X) \geq I_h(Y_1 Y_2; Z | X)$

Why??

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Why??

$$\begin{aligned}
 I_h(Y_1; Y_2 Z | X) + I_h(Y_2; Y_1 Z | X) &= h(XY_1) + h(XY_2 Z) - h(XY_1 Y_2 Z) - h(X) \\
 &\quad + h(XY_2) + h(XY_1 Z) - h(XY_1 Y_2 Z) - h(X) \\
 I_h(Y_1 Y_2; Z | X) &= h(XY_1 Y_2) + h(XZ) - h(XY_1 Y_2 Z) - h(X)
 \end{aligned}$$

FD/MVD Implication by Entropic Inequalities

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Why??

$$\begin{aligned} I_h(Y_1; Y_2 Z | X) + I_h(Y_2; Y_1 Z | X) &= h(XY_1) + h(XY_2 Z) - h(XY_1 Y_2 Z) - h(X) \\ &\quad + h(XY_2) + h(XY_1 Z) - h(XY_1 Y_2 Z) - h(X) \\ I_h(Y_1 Y_2; Z | X) &= h(XY_1 Y_2) + h(XZ) - h(XY_1 Y_2 Z) - h(X) \end{aligned}$$

Need to show:

$$h(XY_1) + h(XY_2 Z) + h(XY_2) + h(XY_1 Z) \geq h(XY_1 Y_2 Z) + h(X)$$

FD/MVD Implication by Entropic Inequalities

Example: Union Axiom MVD5: $X \twoheadrightarrow Y_1, X \twoheadrightarrow Y_2 \models X \twoheadrightarrow Y_1 Y_2$

Let Z be the other variables, then:

$(X \twoheadrightarrow Y_1; Y_2 Z), (X \twoheadrightarrow Y_2; Y_1 Z) \models (X \twoheadrightarrow Y_1 Y_2 | Z)$.

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Suffices to show: $I_h(Y_1; Y_2 Z | X) + I_h(Y_2; Y_1 Z | X) \geq I_h(Y_1 Y_2; Z | X)$

Why??

$$\begin{aligned} I_h(Y_1; Y_2 Z | X) + I_h(Y_2; Y_1 Z | X) &= h(XY_1) + h(XY_2 Z) - h(XY_1 Y_2 Z) - h(X) \\ &\quad + h(XY_2) + h(XY_1 Z) - h(XY_1 Y_2 Z) - h(X) \\ I_h(Y_1 Y_2; Z | X) &= h(XY_1 Y_2) + h(XZ) - h(XY_1 Y_2 Z) - h(X) \end{aligned}$$

Need to show:

$$h(XY_1) + h(XY_2 Z) + h(XY_2) + h(XY_1 Z) \geq h(XY_1 Y_2 Z) + h(X)$$

Follows from $h(XY_1) + h(XY_2) \geq h(X)$ and $h(XY_2 Z) + h(XY_1 Z) \geq h(XY_1 Y_2 Z)$, which hold by modularity and non-negativity

Discussion

- Every FD/MVD implication can be derived from a Shannon inequality, where all terms are of the form $h(\mathbf{V}|\mathbf{U})$ or $I_h(\mathbf{V}; \mathbf{W}|\mathbf{U})$ [Kenig and Suciu, 2022].
- What about general CIs? Surprisingly, there exists CIs where the conditional implication holds $I_h(\dots) = 0 \Rightarrow I_h(\dots) = 0$, but the corresponding inequality fails [Kaced and Romashchenko, 2013].
- Limitations of the entropic method: restricted to FD/MVDs. Next week: more general constraints, incomplete databases, probabilistic databases.



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