### University of California at Berkeley Department of Mechanical Engineering

#### ME 233: Advanced Control Systems II

Spring 2010

URL: http://bspace.berkeley.edu/

**Instructor**: Roberto Horowitz

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**Teaching Assistant**: Name: TBD

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Office Hours: TBDA

Lectures: Tu, Th 11:30-12:00 in Rm. 109 Dwinelle Hall

**Discussion**: TBD

**Grading Scheme**: 2 Midterm Exams (20% each) 50 %

Final Examination 40 % Homework 10 %

Class Notes: ME233 Class Notes by M. Tomizuka (Parts I and II)

Part I may be purchased at Copy Central, 2483 Hearst Avenue

ME233 Power Point Class Notes by R. Horowitz

(Will be distributed weekly electronically)

Tentative Schedule (Subject to change):

Week	Topics
1	Dynamic Programming, Discrete Time LQ problem, Properties of LQ Systems; Return Difference
	Equality, Robustness, Closed Loop Eigenvalues and Symmetric Root Locus (ME232 Class Notes)
2	Review of Probability Theory; Sample Space, Random Variable, Probability Distribution and
	Density Functions.
3	Continuation of Probability Theory: Random Process, Correlation Function, Spectral Density.
4	Principle of Least Squares estimation; Stochastic State Estimation (Kalman Filter).
5	Stochastic Estimation (continuation).
6	Kalman Filter properties; Linear Stochastic Control (Linear Quadratic Gaussian (LQG) Problem).
7	Midterm Examination I; Loop Transfer Recovery
8	Minimum Variance Regulation.
9	Tracking Control; Feedforward and Preview Control.
10	Internal Model Principle and Repetitive Control.
11	System Identification and Adaptive Control
12	Parameter Estimation Algorithms
13	Stability analysis of adaptive systems. Midterm Examination II.
14	Self-tuning Regulators.
15	Review, catching up.

### **References:**

# **Liner Quadratic Optimal Control:**

- B.D.O. Anderson and J.B. Moore, *Optimal Control: Linear Quadratic Methods*, Dover Books on Engineering (paperback), 2007. A PDF can be downloaded from: <a href="http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html">http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html</a>
- Frank L. Lewis, Vassilis L. Syrmos, *Optimal Control*, Wiley-IEEE, 1995. An electronic preview can be obtained at: http://books.google.com/books?id=jkD37elP6NIC
- E. Bryson and Y-C. Ho, Applied Optimal Control: Optimization, Estimation, and Control, Wiley

## **Probability**

- D. P. Bertsekas, Introduction to Probability, Athena Scientific
- R.D. Yates and D.J. Goodman, *Probability and Stochastic Processes*, second edition, Willey.
- K. Poolla, *Probability Notes*. The PDF file can be downloaded from the ME233 website
- J. Walran, EECS126 class notes. The PDF file can be downloaded from the ME233 website

## Stochastic Control Theory and Optimal Filtering

- R. Grover Brown and P. Hwang, *Introduction to Random Signals and Applied Kalman Filtering*, Third Edition, Willey
- Frank L. Lewis, L. Xie and D. Popa, Optimal and Robust Estimation, Second Edition CRC
- M. Grewal and A. Andrews, Kalman Filter, Theory and Practice, Prentice Hall
- B.D.O. Anderson and J.B. Moore, *Optimal Filtering*, Dover Books on Engineering (paperback), New York, 2005. A PDF can be downloaded from: <a href="http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html">http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html</a>
- K.J. Astrom, *Introduction to Stochastic Control Theory*, Dover Books on Engineering (paperback), New York, 2006.

## **Adaptive Control**

- Astrom, K. J. and Wittenmark, B., Adaptive Control, Addison Wesley, 2nd Ed., 1995.
- G.C. Goodwin and K.S. Sin, Adaptive Filtering Prediction and Control, Prentice Hall, 1984.
- S. Sastry and M. Bodson, *Adaptive Control: Stability, Convergence, and Robustness*, Prentice Hall, 1989.(Book can be downloaded from <a href="http://www.ece.utah.edu/~bodson/acscr/">http://www.ece.utah.edu/~bodson/acscr/</a>)
- M. Krstic, I. Kanellakopoulos, and P. V. Kokotovic, *Nonlinear and Adaptive Control Design*, Willey.