

University of California at Berkeley
Department of Mechanical Engineering

ME 233: Advanced Control Systems II

Spring 2012

URL: <http://bspace.berkeley.edu/>

Instructor Richard Conway
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Teaching Assistant (none)

Lectures Tu, Th 3:30-5:00 in 1165 Etcheverry Hall

Discussion TBD

Grading Scheme

Midterm 1	20%
Midterm 2	20%
Final Exam	40%
Homework	20%

Class Notes

ME233 PowerPoint Lectures
(These will be made available on bSpace)

ME233 Class Notes by M. Tomizuka, Part I
(This can be purchased at Copy Central, 2483 Hearst Avenue)

ME233 Class Notes by M. Tomizuka, Part II
(This will be made available on bSpace)

Tentative Schedule (Subject to change):

Week	Topics
1	Probability Theory—Sample Space, Random Variable, Cumulative Distribution and Probability Density Functions
2	Probability Theory—Random Process, Correlation Function, Spectral Density
3	Least Squares Estimation; Stochastic State Estimation (Kalman Filter)
4	Kalman Filter (continued)
5	Properties of the Kalman Filter
6	Dynamic Programming; Discrete-Time LQ problem; Properties of LQ Systems—Return Difference Equality, Robustness, Closed-Loop Eigenvalues and Symmetric Root Locus
7	Linear Stochastic Control (Linear Quadratic Gaussian (LQG) Control)
	Midterm Examination I
8	Minimum Variance Regulation
9	Tracking Control; Feedforward and Preview Control
10	Internal Model Principle and Repetitive Control
11	System Identification and Adaptive Control
	Midterm Examination II
12	Parameter estimation algorithms
13	Stability analysis of adaptive systems
14	Self-tuning regulators

References:

Probability

- D. P. Bertsekas, *Introduction to Probability*, Athena Scientific
- R.D. Yates and D.J. Goodman, *Probability and Stochastic Processes*, second edition, Wiley.
- K. Poolla, *Probability Notes*. The PDF file can be downloaded from the ME233 website
- J. Walran, *EECS126 class notes*. The PDF file can be downloaded from the ME233 website

Linear Quadratic Optimal Control

- B.D.O. Anderson and J.B. Moore, *Optimal Control: Linear Quadratic Methods*, Dover Books on Engineering (paperback), 2007. A PDF can be downloaded from: <http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html>
- Frank L. Lewis, Vassilis L. Syrmos, *Optimal Control*, Wiley-IEEE, 1995.
- E. Bryson and Y-C. Ho, *Applied Optimal Control: Optimization, Estimation, and Control*, Wiley

Stochastic Control Theory and Optimal Filtering

- R. Grover Brown and P. Hwang, *Introduction to Random Signals and Applied Kalman Filtering*, Third Edition, Wiley
- Frank L. Lewis, L. Xie and D. Popa, *Optimal and Robust Estimation*, Second Edition CRC
- M. Grewal and A. Andrews, *Kalman Filter, Theory and Practice*, Prentice Hall
- B.D.O. Anderson and J.B. Moore, *Optimal Filtering*, Dover Books on Engineering (paperback), New York, 2005. A PDF can be downloaded from: <http://users.rsise.anu.edu.au/%7Ejohn/papers/index.html>
- K.J. Astrom, *Introduction to Stochastic Control Theory*, Dover Books on Engineering (paperback), New York, 2006.

Adaptive Control

- Astrom, K. J. and Wittenmark, B., *Adaptive Control*, Addison Wesley, 2nd Ed., 1995.
- G.C. Goodwin and K.S. Sin, *Adaptive Filtering Prediction and Control*, Prentice Hall, 1984.
- S. Sastry and M. Bodson, *Adaptive Control: Stability, Convergence, and Robustness*, Prentice Hall, 1989. (Book can be downloaded from <http://www.ece.utah.edu/~bodson/acscr/>)
- M. Krstic, I. Kanellakopoulos, and P. V. Kokotovic, *Nonlinear and Adaptive Control Design*, Wiley.