```
x(k+1)=Ax(k)+Bu(k), y(k)=Cx(k)
y_{d[0,N]} = \{ y_d(0), y_d(1), \dots, y_d(N) \}
J = \frac{1}{2} [y_d(N) - y(N)]^T S[y_d(N) - y(N)] + \frac{1}{2} \sum_{k=0}^{N-1} \{ [y_d(k) - y(k)]^T T[y_d(k) - y(k)] + u^T(k) R u(k) \}
J^{o}[x(k), k] = \min_{u(k)} \{L[x(k), u(k), k] + J^{o}[x(k+1), k+1]\}
L[x(k), u(k), k] = \frac{1}{2} \{ [y_d(k) - y(k)]^T T[y_d(k) - y(k)] + u^T(k) R u(k) \}
2L[x(k), u(k), k] = [y_d^T(k) - y^T(k)]Ty_d(k) - [y_d^T(k) - y^T(k)]Ty(k) + u^T(k)Ru(k)
2L[x(k), u(k), k] = v_d^T(k)T v_d(k) - v_d^T(k)T v_d(k) - v_d^T(k)T v(k) + v_d^T(k)T v(k)
v^{T}(k)T y_{d}(k) is a scalar so y^{T}(k)T y_{d}(k) = [y^{T}(k)T y_{d}(k)]^{T} = y_{d}^{T}(k)T y(k)
2L[x(k), u(k), k] = v_d^T(k)T v_d(k) - 2v^T(k)T v_d(k) + v^T(k)T v(k) + u^T(k)Ru(k)
2L[x(k), u(k), k] = y_d^T(k)Ty_d(k) - 2x^T(k)C^TTy_d(k) + x^T(k)C^TTCx(k) + u^T(k)Ru(k)
J^{o}[x(N), N] = \frac{1}{2} [y_{d}(N) - y(N)]^{T} S[y_{d}(N) - y(N)]
2J^{o}[x(N), N] = [y_{d}^{T}(N) - y_{d}^{T}(N)]Sy_{d}(N) - [y_{d}^{T}(N) - y_{d}^{T}(N)]Sy(N)
2J^{o}[x(N), N] = y_{d}^{T}(N)Sy_{d}(N) - y_{d}^{T}(N)Sy_{d}(N) - y_{d}^{T}(N)Sy(N) + y_{d}^{T}(N)Sy(N)
2J^{o}[x(N), N] = y_{d}^{T}(N)Sy_{d}(N) - 2y^{T}(N)Sy_{d}(N) + y^{T}(N)Sy(N)
2J^{o}[x(N), N] = y_{d}^{T}(N)Sy_{d}(N) - 2x^{T}(N)C^{T}Sy_{d}(N) + x^{T}(N)C^{T}SCx(N)
J^{o}[x(N), N] = \frac{1}{2} y_{d}^{T}(N) S y_{d}(N) - x^{T}(N) C^{T} S y_{d}(N) + \frac{1}{2} x^{T}(N) C^{T} S C x(N)
Using the form J^{o}[x(k), k] = \frac{1}{2}x^{T}(k)P(k)x(k) + x^{T}(k)b(k) + c(k)
We have final conditions P(N) = C^T S C, b(N) = -C^T S y_d(N), c(N) = \frac{1}{2} y_d^T(N) S y_d(N)
Using the same assumed form at k+1:
2J^{o}[x(k+1), k+1] = x^{T}(k+1)P(k+1)x(k+1) + 2x^{T}(k+1)b(k+1) + 2c(k+1)
   = [Ax(k) + Bu(k)]^{T} P(k+1) [Ax(k) + Bu(k)] + 2[Ax(k) + Bu(k)]^{T} b(k+1) + 2c(k+1)
   = [x^{T}(k)A^{T} + u^{T}(k)B^{T}]P(k+1)[Ax(k) + Bu(k)] + 2[x^{T}(k)A^{T} + u^{T}(k)B^{T}]b(k+1) + 2c(k+1)
   = x^{T}(k)A^{T}P(k+1)Ax(k) + 2u^{T}(k)B^{T}P(k+1)Ax(k) + u^{T}(k)B^{T}P(k+1)Bu(k)
        +2x^{T}(k)A^{T}b(k+1)+2u^{T}(k)B^{T}b(k+1)+2c(k+1)
  = x^{T}(k)A^{T}P(k+1)Ax(k) + u^{T}(k)B^{T}P(k+1)Bu(k) + 2u^{T}(k)B^{T}[P(k+1)Ax(k) + b(k+1)]
        +2x^{T}(k)A^{T}b(k+1)+2c(k+1)
J^{o}[x(k), k] = \min\{L[x(k), u(k), k] + J^{o}[x(k+1), k+1]\}
2J^{o}[x(k), k] = \min_{u(k)} \{y_{d}^{T}(k)T y_{d}(k) - 2x^{T}(k)C^{T}T y_{d}(k) + x^{T}(k)C^{T}T C x(k) + u^{T}(k)R u(k)\}
        +x^{T}(k)A^{T}P(k+1)Ax(k)+u^{T}(k)B^{T}P(k+1)Bu(k)+2u^{T}(k)B^{T}[P(k+1)Ax(k)+b(k+1)]
        +2x^{T}(k)A^{T}b(k+1)+2c(k+1)
  = \min_{u(k)} \{ y_d^T(k) T y_d(k) - 2 x^T(k) [C^T T y_d(k) - A^T b(k+1)] + x^T(k) [C^T T C + A^T P(k+1) A] x(k) \}
        +u^{T}(k)[R+B^{T}P(k+1)B]u(k)+2u^{T}(k)B^{T}[P(k+1)Ax(k)+b(k+1)]+2c(k+1)
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Minimum achieved for u^{o}(k) such that \frac{\partial J[x(k), k]}{\partial u(k)}|_{u^{o}(k)} = 0
\frac{\partial J[x(k),k]}{\partial u(k)}\Big|_{u^{o}(k)} = [R + B^{T}P(k+1)B]u^{o}(k) + B^{T}[P(k+1)Ax(k) + b(k+1)] = 0
u^{o}(k) = -[R + B^{T} P(k+1) B]^{-1} B^{T} [P(k+1) A x(k) + b(k+1)]
Let K_2(k+1) = [R+B^T P(k+1)B]^{-1}B^T, and K_1(k+1) = K_2(k+1)P(k+1)A
u^{o}(k) = -K_{1}(k+1)x(k) - K_{2}(k+1)b(k+1)
2J^{o}[x(k), k] = 2c(k+1) - 2x^{T}(k)[C^{T}Tv_{d}(k) - A^{T}b(k+1)] + x^{T}(k)[C^{T}TC + A^{T}P(k+1)A]x(k)
     +u^{o}(k)^{T}[R+B^{T}P(k+1)B]u^{o}(k)+2u^{o}(k)^{T}B^{T}[P(k+1)Ax(k)+b(k+1)]+v_{d}^{T}(k)Tv_{d}(k)
2J^{o}[x(k), k] = 2c(k+1) - 2x^{T}(k)[C^{T}Ty_{d}(k) - A^{T}b(k+1)] + x^{T}(k)[C^{T}TC + A^{T}P(k+1)A]x(k)
     +[K_1(k+1)x(k)+K_2(k+1)b(k+1)]^T[R+B^TP(k+1)B][K_1(k+1)x(k)+K_2(k+1)b(k+1)]
    -2[K_1(k+1)x(k)+K_2(k+1)b(k+1)]^TB^T[P(k+1)Ax(k)+b(k+1)]+y_d^T(k)Ty_d(k)
2J^{o}[x(k), k] = 2c(k+1) - 2x^{T}(k)[C^{T}Ty_{d}(k) - A^{T}b(k+1)] + x^{T}(k)[C^{T}TC + A^{T}P(k+1)A]x(k)
     +x^{T}(k)K_{1}^{T}(k+1)[R+B^{T}P(k+1)B]K_{1}(k+1)x(k)
     +2x^{T}(k)K_{1}^{T}(k+1)[R+B^{T}P(k+1)B]K_{2}(k+1)b(k+1)
     +b^{T}(k+1)K_{2}^{T}(k+1)[R+B^{T}P(k+1)B]K_{2}(k+1)b(k+1)
     -2x^{T}(k)K_{1}^{T}(k+1)B^{T}P(k+1)Ax(k)-2x^{T}(k)K_{1}^{T}(k+1)B^{T}b(k+1)
     -2b^{T}(k+1)K_{2}^{T}(k+1)B^{T}P(k+1)Ax(k)-2b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1)+y_{d}^{T}(k)Ty_{d}(k)
2J^{o}[x(k), k] = 2c(k+1) - 2x^{T}(k)[C^{T}Ty_{d}(k) - A^{T}b(k+1)] + x^{T}(k)[C^{T}TC + A^{T}P(k+1)A]x(k)
     +x^{T}(k)K_{1}^{T}(k+1)B^{T}P(k+1)Ax(k)
     +2x^{T}(k)A^{T}P^{T}(k+1)BK_{2}(k+1)b(k+1)
     +b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1)
     -2x^{T}(k)K_{1}^{T}(k+1)B^{T}P(k+1)Ax(k)-2x^{T}(k)K_{1}^{T}(k+1)B^{T}b(k+1)
     -2b^{T}(k+1)K_{2}^{T}(k+1)B^{T}P(k+1)Ax(k)-2b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1)+v_{d}^{T}(k)Tv_{d}(k)
2J^{o}[x(k), k] = 2c(k+1) - 2x^{T}(k)[C^{T}Ty_{d}(k) - A^{T}b(k+1)] + x^{T}(k)[C^{T}TC + A^{T}P(k+1)A]x(k)
     -x^{T}(k)K_{1}^{T}(k+1)B^{T}P(k+1)Ax(k)-b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1)
     -2x^{T}(k)K_{1}^{T}(k+1)B^{T}b(k+1)+y_{d}^{T}(k)Ty_{d}(k)
2J^{o}[x(k), k] = 2c(k+1) - b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1) + y_{d}^{T}(k)Ty_{d}(k)
     +x^{T}(k)[C^{T}TC+A^{T}P(k+1)A-K_{1}^{T}(k+1)B^{T}P(k+1)A]x(k)
     +2x^{T}(k)[(A^{T}-K_{1}^{T}(k+1)B^{T})b(k+1)-C^{T}Ty_{d}(k)]
Since J^{o}[x(k), k] = \frac{1}{2}x^{T}(k)P(k)x(k) + x^{T}(k)b(k) + c(k) we can equate coefficients:
P(k) = C^{T}TC + A^{T}P(k+1)A - K_{1}^{T}(k+1)B^{T}P(k+1)A
P(k) = C^{T} T C + A^{T} P(k+1) A - A^{T} P^{T}(k+1) B ([R+B^{T} P(k+1)B]^{-1})^{T} B^{T} P(k+1) A
(M^{-1})^T = (M^T)^{-1} so:
P(k) = C^{T} T C + A^{T} P(k+1) A - A^{T} P^{T} (k+1) B [R + B^{T} P(k+1) B]^{-1} B^{T} P(k+1) A
b(k) = [A^{T} - K_{1}^{T}(k+1)B^{T}]b(k+1) - C^{T}T v_{d}(k)
b(k) = [A^{T} - A^{T} P^{T} (k+1) B [R + B^{T} P (k+1) B]^{-1} B^{T}] b(k+1) - C^{T} T y_{d}(k)
c(k) = c(k+1) - \frac{1}{2}b^{T}(k+1)K_{2}^{T}(k+1)B^{T}b(k+1) + \frac{1}{2}y_{d}^{T}(k)Ty_{d}(k)
c(k) = c(k+1) - \frac{1}{2}b^{T}(k+1)B[R + B^{T}P(k+1)B]^{-1}B^{T}b(k+1) + \frac{1}{2}y_{d}^{T}(k)Ty_{d}(k)
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$$\begin{aligned} & (2) \\ & U_o^* = |u^*(0), \ u^*(1), \dots, \ u^*(N-1) | \\ & U_o^* = |u^*(0), \ u^*(1), \dots, \ u^*(N-1) | \\ & u^*(k) \ge 0, \ x(N) = L \\ & J = \prod_{k=0}^{N-1} u(k) = u(0)u(1) \cdots u(N-1) \\ & J_o^* [x(m)] = \max_{u(m)} \prod_{k=0}^{N-1} u(k) \\ & U_m = [u(m), u(m+1), \dots, u(N-1)] \\ & J_o^* [x(m)] = \max_{u(m)} \left[ u(m) \max_{u(m)} \sum_{k=0}^{N-1} u(k) \right] \\ & J_o^* [x(m)] = \max_{u(m)} \left[ u(m) J_o^* [x(m+1)] \right] \\ & J_o^* [x(N-1)] = u^*(N-1) = L - x(N-1) \\ & J_o^* [x(N-2)] = \max_{u(N-2)} \left[ u(N-2) J_o^* [x(N-1)] \right] = \max_{u(N-2)} \left[ u(N-2) (L - x(N-1)) \right] \\ & x(N-1) = x(N-2) + u(N-2), \text{ so } J_o^* [x(N-2)] = \max_{u(N-2)} \left[ u(N-2) (L - x(N-2) - u(N-2)) \right] \\ & \text{Maximum achieved for } u^*(N-2) \text{ such that } \frac{\partial J_0 [x(N-2)]}{\partial u(N-2)} \Big|_{u^*(N-2)} = 0 \\ & \frac{\partial J_0 [x(N-2)]}{\partial u(N-2)} \Big|_{u^*(N-2)} = L - x(N-2) - 2 u^*(N-2) = 0 \\ & u^*(N-2) = \frac{1}{2} (L - x(N-2)), \ J^o [x(N-2)] = \frac{1}{2} \frac{1}{2} (L - x(N-2))^2 \\ & J^o [x(N-3)] = \max_{u(N-3)} \left[ u(N-3) J_o^* [x(N-2)] \right] = \max_{u(N-3)} \left[ u(N-3) \frac{1}{2} (L - x(N-3) - u(N-3))^2 \right] \\ & \frac{\partial J_0 [x(N-3)]}{\partial u(N-3)} \Big|_{u^*(N-3)} = \frac{1}{2} \frac{1}{2} (L - x(N-3) - u^*(N-3)) = 0 \\ & x(N-2) \neq L \text{ so } L - x(N-3) - u^*(N-3) \neq 0 \\ & \frac{1}{2} (L - x(N-3) - u^*(N-3)) - u^*(N-3) = 0 \\ & u^*(N-3) = \frac{1}{3} (L - x(N-3)), \ J^o [x(N-3)] = \frac{1}{3} (L - x(N-3))^3 \\ & \text{Propose general form: } u^*(N-k) = \frac{1}{k} (L - x(N-k)), \ J^o (x(N-k)) = u^*(N-k) \frac{1}{k} (L - x(N-k))^k \right] \\ & J^o [x(N-k-1)] = \max_{u(N-k-1)} \left[ u(N-k-1) \frac{1}{k} (L - x(N-k-1) - u^*(N-k-1))^k - u^*(N-k-1) \frac{1}{k} (L - x(N-k-1))^{k-1} \end{aligned}$$

For 
$$k \neq 0$$
,  $(L-x(N-k-1)-u^o(N-k-1))^{k-1} \neq 0$   
 $0 = (L-x(N-k-1)-u^o(N-k-1))-k u^o(N-k-1)$   
 $u^o(N-k-1) = \frac{1}{k+1}(L-x(N-k-1))$  so proposed general form holds by induction.

3. 
$$x(k+1) = Ax(k) + Bu(k), \ x(0) \neq 0$$

$$J[x_m, m, S, N] = \frac{1}{2}x^T(N)Sx(N) + \frac{1}{2}\sum_{k=m}^{N-1} \{x^T(k)Qx(k) + u^T(k)Ru(k)\}$$

$$J^o[x_m, m, S, N] = \min_{U_m} J[x_m, m, S, N]$$

$$U_m = \{u(m), u(m+1), \dots, u(N-1)\}$$

$$J[x_m, m, 0, N+1] = \frac{1}{2}\sum_{k=m}^{N} \{x^T(k)Qx(k) + u^T(k)Ru(k)\}$$

$$J[x_m, m, 0, N+1] = \frac{1}{2}\{x^T(N)Qx(N) + u^T(N)Ru(N)\} + J[x_m, m, 0, N]$$

$$J[x_m, m, 0, N] \geq J^o[x_m, m, 0, N], \text{ so:}$$

$$J[x_m, m, 0, N+1] \geq \frac{1}{2}\{x^T(N)Qx(N) + u^T(N)Ru(N)\} + J^o[x_m, m, 0, N]$$

$$Q \geq 0 \text{ and } R > 0 \text{ so } J[x_m, m, 0, N+1] \geq J^o[x_m, m, 0, N]$$

$$J^o[x_m, m, 0, N+1] = \min_{U_m, u(N)} J[x_m, m, 0, N+1] \geq J^o[x_m, m, 0, N]$$