

ME 233 Advanced Control II

Lecture 22

Parameter Convergence in Least Squares Estimation and Persistence of Excitation

Estimation of ARMA model

$$A(q^{-1})y(k) = q^{-d}B(q^{-1})u(k)$$

Where

- $u(k)$ known **bounded** input
- $y(k)$ measured output

Estimation of ARMA model

$$A(q^{-1})y(k) = q^{-d}B(q^{-1})u(k)$$

Where

$$A(q^{-1}) = 1 + a_1q^{-1} + \dots + a_nq^{-n} \quad \text{(anti-Schur)}$$

$$B(q^{-1}) = b_o + b_1q^{-1} + \dots + b_mq^{-m}$$

- Orders n and m are known
- Relative degree d is known
- a 's and b 's are unknown but constant coefficients

ARMA Model

$$y(k) = \phi^T(k-1)\theta$$

Unknown
parameter vector:

$$\theta = \left[\begin{array}{c} a_1 \\ \vdots \\ a_n \\ b_o \\ \vdots \\ b_m \end{array} \right] \left\{ \begin{array}{l} n \\ m+1 \end{array} \right.$$

Known regressor vector:

$$\phi(k-1) = \left[\begin{array}{c} -y(k-1) \\ \vdots \\ -y(k-n) \\ u(k-d) \\ \vdots \\ u(k-d-m) \end{array} \right] \left\{ \begin{array}{l} n+m+1 \end{array} \right.$$

ARMA series-parallel estimation

- A-priori output

$$\hat{y}^o(k) = \phi^T(k-1) \hat{\theta}(k-1)$$

$$\hat{\theta}(k) = [\hat{a}_1(k) \ \cdots \ \hat{a}_n(k) \ \hat{b}_o(k) \ \cdots \ \hat{b}_m(k)]^T$$

- A-priori error

$$e^o(k) = y(k) - \hat{y}^o(k)$$

ARMA series-parallel estimation

- A-priori error

$$e^o(k) = y(k) - \hat{y}^o(k)$$

$$e^o(k) = \phi^T(k-1) \tilde{\theta}(k-1)$$

- Parameter error

$$\tilde{\theta}(k) = \theta - \hat{\theta}(k)$$

RLS Estimation Algorithm

$$e^o(k+1) = y(k+1) - \phi^T(k) \hat{\theta}(k)$$

$$e(k+1) = \frac{\lambda_1(k)}{\lambda_1(k) + \phi^T(k) F(k) \phi(k)} e^o(k+1)$$

$$\hat{\theta}(k+1) = \hat{\theta}(k) + \frac{1}{\lambda_1(k)} F(k) \phi(k) e(k+1)$$

$$F(k+1) = \frac{1}{\lambda_1(k)} \left[F(k) - \lambda_2(k) \frac{F(k) \phi(k) \phi^T(k) F(k)}{\lambda_1(k) + \lambda_2(k) \phi^T(k) F(k) \phi(k)} \right]$$

Overview

- In Lecture 21 we learned how to analyze the stability of adaptive systems and proved:

- Convergence of the output error

$$e^o(k) \rightarrow 0 \quad e(k) \rightarrow 0$$

- Today we will provide conditions on the input sequence $u(k)$ that guarantee that

$$\tilde{\theta}(k) = \theta - \hat{\theta}(k)$$

also converges to zero.

Parameter error convergence

- Remember that $e^o(k) \rightarrow 0$

It can be shown that the $n+m+1$ parameter error also converges:

$$\lim_{k \rightarrow \infty} \tilde{\theta}(k) = \bar{\theta}$$


$$\lim_{k \rightarrow \infty} \tilde{\theta}(k) = \bar{\theta} = \left[\begin{array}{c} \bar{a}_1 \\ \vdots \\ \bar{a}_n \\ \bar{b}_o \\ \vdots \\ \bar{b}_m \end{array} \right] = \left. \begin{array}{c} \left. \begin{array}{c} \bar{a}_1 \\ \vdots \\ \bar{a}_n \end{array} \right\} \right\} n \\ \left. \begin{array}{c} \bar{b}_o \\ \vdots \\ \bar{b}_m \end{array} \right\} m+1 \end{array} \right\}$$

Excitation matrix

Given and input sequence $u(k) \in \mathcal{R}$

Define the u -regressor of order n :

$$\phi_{u_n}(k) = \begin{bmatrix} u(k) \\ u(k-1) \\ \vdots \\ u(k-n+1) \end{bmatrix} \in \mathcal{R}^n$$

 only present and past values of $u(k)$ are used

Excitation matrix

Given and input sequence $u(k) \in \mathcal{R}$

$$\phi_{u_n}(k) = \begin{bmatrix} u(k) \\ u(k-1) \\ \vdots \\ u(k-n+1) \end{bmatrix} \in \mathcal{R}^n$$

Define the $n \times n$ excitation matrix:

$$C_n = \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N \phi_{u_n}(k) \phi_{u_n}^T(k) \right\}$$

Time average of $\phi_{u_n}(k) \phi_{u_n}^T(k)$

Persistence of Excitation (PE)

The input sequence $u(k)$

is **persistently exciting** of order n if the $n \times n$ excitation matrix is **positive definite**

$$C_n \succ 0$$

$$\phi_{u_n}(k) = \begin{bmatrix} u(k) \\ u(k-1) \\ \vdots \\ u(k-n+1) \end{bmatrix} \in \mathcal{R}^n$$

PE inputs in FIR models

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Theorem:

$u(k)$ is persistently exciting (PE) of order n iff the following holds **for all** nonzero polynomials

$A(q^{-1})$ of order at most $n-1$

$$U = \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N w^2(k) \right\} > 0$$

where $w(k) = A(q^{-1})u(k)$

$w(k)$ is PE of order 1

PE inputs in FIR models

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Alternate statement of Theorem:

The following are equivalent:

- $u(k)$ is PE of order n
- $A(q^{-1})u(k)$ is PE of order 1 for all nonzero polynomials $A(q^{-1})$ of degree at most $n-1$

PE inputs in FIR models

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Proof: Let

$$A(q^{-1}) = a_0 + a_1 q^{-1} + \dots + a_{n-1} q^{n-1}$$

Then

$$A(q^{-1})u(k) = \underbrace{\begin{bmatrix} a_0 & a_1 & \dots & a_{n-1} \end{bmatrix}}_{a^T} \underbrace{\begin{bmatrix} u(k) \\ u(k-1) \\ \vdots \\ u(k-n+1) \end{bmatrix}}_{\phi(k)}$$

$$w(k) = A(q^{-1})u(k) = a^T \phi(k) = \phi^T(k)a$$

PE inputs in FIR models

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Proof (cont'd):

$$\begin{aligned} U &= \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N w^2(k) \right\} \\ &= \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N a^T \phi(k) \phi^T(k) a \right\} \\ &= a^T \left[\lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N \phi(k) \phi^T(k) \right\} \right] a \\ &= a^T C_n a \end{aligned}$$

PE inputs in FIR models

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Proof (cont'd):

Since $U = a^T C_n a$, we see that $U > 0, \forall a \neq 0$ if and only if $C_n \succ 0$.

Therefore, $U > 0$ for all nonzero polynomials $A(q^{-1})$ of order at most $n-1$ if and only if $C_n \succ 0$



PE inputs in FIR models

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To determine the PE order of a sequence $u(k)$

1. Find a nonzero polynomial $A(q^{-1})$ of order n such that $A(q^{-1})u(k)$ is not PE of order 1

this means that $u(k)$ is PE of order at most n

2. Compute the excitation matrix C_n and verify that it is positive definite.

Conditions for PE

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Examples: Constant input

$$u(k) = 1, \quad \forall k$$

$$(1 - q^{-1})u(k) = 0 \implies u(k) \text{ is not PE of order 2}$$

$$C_1 = \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{j=-N}^{j=N} u^2(k) \right\} = 1 > 0$$

$$\implies \boxed{u(k) \text{ is PE of order 1}}$$

Conditions for PE in FIR Models

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Examples: Sinusoid input

Consider the pure sinusoid input

$$u(k) = \sin(\omega k), \quad 0 < \omega < \pi$$

$$[1 - 2 \cos(\omega)q^{-1} + q^{-2}]u(k) = 0$$

$$\implies u(k) \text{ is not PE of order 3}$$

Conditions for PE in FIR Models

Examples: Sinusoid input

$$\text{Let } \phi(k) = \begin{bmatrix} u(k) & u(k-1) \end{bmatrix}^T, \quad u(k) = \sin(\omega k).$$

$$C_2 = \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N \phi(k) \phi^T(k) \right\}$$

$$= \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \begin{bmatrix} \sum_{k=-N}^N u^2(k) & \sum_{k=-N}^N u(k)u(k-1) \\ \sum_{k=-N}^N u(k)u(k-1) & \sum_{k=-N}^N u^2(k-1) \end{bmatrix} \right\}$$

$$C_2 = \frac{1}{2} \begin{bmatrix} 1 & \cos(\omega) \\ \cos(\omega) & 1 \end{bmatrix} \succ 0 \quad 0 < \omega < \pi$$

Conditions for PE in FIR Models

Examples: Sinusoid input

$$[1 - 2 \cos(\omega)q^{-1} + q^{-2}]u(k) = 0 \Rightarrow u(k) \text{ is not PE of order 3}$$

$$C_2 = \frac{1}{2} \begin{bmatrix} 1 & \cos(\omega) \\ \cos(\omega) & 1 \end{bmatrix} \succ 0 \Rightarrow u(k) \text{ is PE of order 2}$$

Conditions for PE in FIR Models

Examples: Sum of Sinusoids

Consider an input that is a sum of m sinusoids, with m distinct frequencies

$$u(k) = \sum_{i=1}^m \sin(\omega_i k), \quad \begin{matrix} 0 < \omega_i < \pi \\ \omega_i \neq \omega_j \end{matrix}$$

$u(k)$ is PE of order $n = 2m$.

Conditions for PE in FIR Models

Examples: Random process

Consider a colored random process

$$u(k) = G(q)w(k)$$

where $w(k)$ is white noise and $G(q)$ is nonzero.

$u(k)$ is PE of any order.

PE in Filtered Signals

Theorem

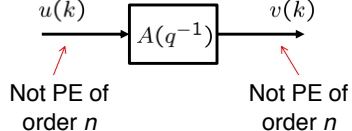
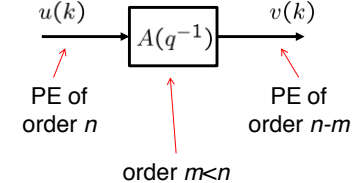
Let $v(k)$ be the output of the model

$$v(k) = A(q^{-1})u(k)$$

where $A(q^{-1})$ is a nonzero polynomial

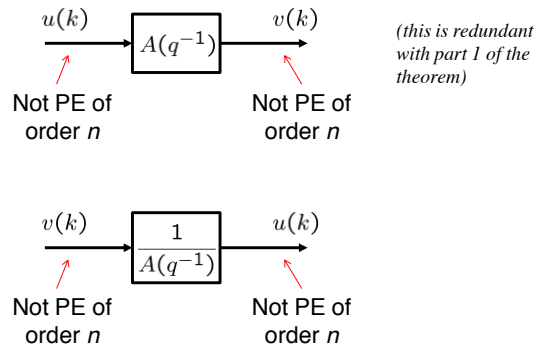
1. If $u(k)$ is not PE of order n , then $v(k)$ is not PE of order n
2. If $u(k)$ is PE of order n and $A(q^{-1})$ has degree $m < n$, then $v(k)$ is PE of order $n-m$
3. If $A(q^{-1})$ is anti-Schur, then $u(k)$ is PE of order n if and only if $v(k)$ is PE of order n

Interpretation of Theorem

1. 
2. 

Interpretation of Theorem

3. When $A(q^{-1})$ anti-Schur



PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Preliminary result 1:

If $u(k)$ is not PE of order 1, then $v(k)$ is not PE of order 1

Proof:

$$\text{Let } A(q^{-1}) = a_0 + a_1 q^{-1} + \dots + a_{n-1} q^{-n+1}$$

$$\Rightarrow A(q^{-1})u(k) = \underbrace{\begin{bmatrix} a_0 & a_1 & \dots & a_{n-1} \end{bmatrix}}_{a^T} \underbrace{\begin{bmatrix} u(k) \\ u(k-1) \\ \vdots \\ u(k-n+1) \end{bmatrix}}_{\phi(k)}$$

PE in Filtered Signals

Proof of preliminary result 1 (continued):

$$v(k) = A(q^{-1})u(k) = a^T \phi(k)$$

$$U = \lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N v^2(k) \right\}$$

$$= a^T \left(\lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{k=-N}^N \phi(k) \phi^T(k) \right\} \right) a = a^T C_n a$$

Since $u(k)$ is not PE of order 1, $C_1 = 0$

\Rightarrow The diagonal elements of C_n are zero

Since $C_n \succeq 0$, this implies that $C_n = 0$

$\Rightarrow U = 0$, which implies that $v(k)$ is not PE of order 1



PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Preliminary result 2:

If $A(q^{-1})$ is anti-Schur and $v(k)$ is not PE of order 1,

then $\frac{1}{A(q^{-1})}v(k)$ is not PE of order 1

The proof is based on frequency domain techniques for deterministic signals that are analogous to power spectral density techniques for wide sense stationary random signals

(see the additional material at the end of this lecture)

PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Proof of (1):

Let $u(k)$ not be PE of order n

Choose nonzero $B(q^{-1})$ of degree at most $n-1$ such that $w(k) = B(q^{-1})u(k)$ is not PE of order 1

$$B(q^{-1})v(k) = A(q^{-1})B(q^{-1})u(k) = A(q^{-1})w(k)$$

By the preliminary result, $A(q^{-1})w(k)$ is not PE of order 1, which implies that $B(q^{-1})v(k)$ is not PE of order 1

$\Rightarrow v(k)$ is not PE of order n



PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Proof of (2):

Let $u(k)$ be PE of order n and $A(q^{-1})$ have degree $m < n$

Suppose $B(q^{-1})v(k)$ is not PE of order 1 where $B(q^{-1})$ has order at most $n-m-1$

$\Rightarrow B(q^{-1})A(q^{-1})u(k)$ is not PE of order 1

Since $B(q^{-1})A(q^{-1})$ has order at most $n-1$ and $u(k)$ is PE of order n , $B(q^{-1})A(q^{-1})$ is the zero polynomial

Since $A(q^{-1})$ is a nonzero polynomial, $B(q^{-1})$ is the zero polynomial

$\Rightarrow v(k)$ is PE of order $n-m$



PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Proof of (3):

By statement (1) of the theorem, if $u(k)$ is not PE of order n , then $v(k)$ is not PE of order n

It only remains to show that if $v(k)$ is not PE of order n , then $u(k)$ is not PE of order n

Let $v(k)$ not be PE of order n and choose nonzero $B(q^{-1})$ of order at most $n-1$ such that $w(k) = B(q^{-1})v(k)$ is not PE of order 1

This implies that $A(q^{-1})B(q^{-1})u(k)$ is not PE of order 1

PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Proof of (3), continued:

$A(q^{-1})B(q^{-1})u(k)$ is not PE of order 1

Since $A(q^{-1})$ is anti-Schur, we use preliminary result 2 to see that $B(q^{-1})u(k)$ is not PE of order 1

Since $B(q^{-1})$ is a nonzero polynomial of order at most $n-1$

$\Rightarrow u(k)$ is not PE of order n



ARMA Model (review)

$$A(q^{-1})y(k) = q^{-d}B(q^{-1})u(k)$$

Where

$$A(q^{-1}) = 1 + a_1q^{-1} + \dots + a_nq^{-n} \quad (\text{anti-Schur})$$

$$B(q^{-1}) = b_0 + b_1q^{-1} + \dots + b_mq^{-m}$$

- Orders n and m are known
- Relative degree d is known
- a 's and b 's are unknown but constant coefficients

ARMA Model (review)

$$y(k) = \phi^T(k-1)\theta$$

Unknown parameter vector:

$$\theta = \left[\begin{array}{c} a_1 \\ \vdots \\ a_n \\ b_0 \\ \vdots \\ b_m \end{array} \right] \left\{ \begin{array}{l} n \\ m+1 \end{array} \right.$$

Known regressor vector:

$$\phi(k-1) = \left[\begin{array}{c} -y(k-1) \\ \vdots \\ -y(k-n) \\ u(k-d) \\ \vdots \\ u(k-d-m) \end{array} \right] \left\{ \begin{array}{l} n+m+1 \end{array} \right.$$

PE in ARMA models

Theorem:

Consider the parameter estimation of the ARMA system using the LS estimation algorithm. If

- $A(q^{-1})$ is anti-Schur
- $A(q^{-1})$ and $B(q^{-1})$ are co-prime
- $u(k)$ is PE of order $n + m + 1$

Parameter estimates convergence to the true values

PE in ARMA models - Proof

Simplifying assumption: the parameter error converges

$$\bar{\theta} = \lim_{k \rightarrow \infty} \tilde{\theta}(k) = [\bar{a}_1 \ \cdots \ \bar{a}_n \ \bar{b}_0 \ \cdots \ \bar{b}_m]^T$$

Define: the LS output estimation error by

$$e(k) = \phi(k-1)^T \bar{\theta}$$

We know that

$$e(k) \rightarrow 0$$

PE in ARMA models - Proof

Notice that

$$e(k) = q^{-d} \bar{B}(q^{-1}) u(k) - \bar{A}(q^{-1}) y(k)$$

where

$$\begin{aligned} \bar{A}(q^{-1}) &= A(q^{-1}) - \hat{A}(q^{-1}) \\ &= \bar{a}_1 q^{-1} + \cdots + \bar{a}_n q^{-n} \end{aligned}$$

$$\begin{aligned} \bar{B}(q^{-1}) &= B(q^{-1}) - \hat{B}(q^{-1}) \\ &= \bar{b}_0 + \cdots + \bar{b}_m q^{-m} \end{aligned}$$

PE in ARMA models - Proof

From

$$e(k) = q^{-d} \bar{B}(q^{-1}) u(k) - \bar{A}(q^{-1}) y(k)$$

$$y(k) = \frac{q^{-d} B(q^{-1})}{A(q^{-1})} u(k)$$

We obtain

$$\begin{aligned} e(k) &= q^{-d} \bar{B}(q^{-1}) u(k) - \bar{A}(q^{-1}) \frac{q^{-d} B(q^{-1})}{A(q^{-1})} u(k) \\ &= q^{-d} [\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})] \frac{1}{A(q^{-1})} u(k). \end{aligned}$$

PE in ARMA models - Proof

$$e(k) = q^{-d} \underbrace{[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})]}_{\text{Polynomial of order } n+m} \underbrace{\frac{1}{A(q^{-1})} u(k)}_{v(k)}.$$

Notice that since $A(q^{-1})$ is anti-Schur and

$$v(k) = \frac{1}{A(q^{-1})} u(k)$$

$u(k)$ is PE of order $n + m + 1$



$v(k)$ is PE of order $n + m + 1$

PE in ARMA models - Proof

So far, we know that if

$u(k)$ is PE of order $n + m + 1$,

then

$$[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})] = 0$$

where $A(q^{-1})$ and $B(q^{-1})$ are co-prime

$$\bar{A}(q^{-1}) = A(q^{-1}) - \hat{A}(q^{-1})$$

$$\bar{B}(q^{-1}) = B(q^{-1}) - \hat{B}(q^{-1})$$

PE in ARMA models - Proof

$$e(k) = q^{-d} \underbrace{[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})]}_{\text{Polynomial of order } n+m} \underbrace{\frac{1}{A(q^{-1})} u(k)}_{v(k)}.$$

- $v(k)$ is PE of order $n + m + 1$
- $e(k)$ is PE of order 1 **unless**
 $[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})] = 0$

Since $e(k) = 0$, it cannot be PE of order 1

Therefore, $[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})] = 0$

PE in ARMA models - Proof

$$[\bar{B}(q^{-1}) A(q^{-1}) - \bar{A}(q^{-1}) B(q^{-1})] = 0$$

This equation can be written as follows:

$$D \bar{\theta}^* = 0$$

where

$$\bar{\theta}^* = [\bar{b}_0 \cdots \bar{b}_m \quad -\bar{a}_1 \quad \cdots \quad -\bar{a}_n]^T \in \mathcal{R}^{n+m+1}$$

and: $\bar{a}_i = a_i - \hat{a}_i$

$$\bar{b}_i = b_i - \hat{b}_i$$

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PE in ARMA models - Proof

$$D = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ a_1 & 1 & \ddots & \vdots \\ a_2 & a_1 & \ddots & 0 \\ \vdots & a_2 & \ddots & 1 \\ a_{n-1} & \vdots & \ddots & a_1 \\ a_n & a_{n-1} & \ddots & a_2 \\ 0 & a_n & \ddots & \vdots \\ \vdots & \ddots & \ddots & a_{n-1} \\ 0 & \cdots & 0 & a_n \end{bmatrix} \begin{bmatrix} 0 & 0 & \cdots & 0 & 0 \\ b_0 & 0 & \cdots & 0 & 0 \\ b_1 & b_0 & \ddots & \vdots & \vdots \\ \vdots & b_1 & \ddots & 0 & 0 \\ b_{m-1} & \vdots & \ddots & b_0 & 0 \\ b_m & b_{m-1} & \ddots & b_1 & b_0 \\ 0 & b_m & \ddots & \vdots & b_1 \\ 0 & 0 & \ddots & b_{m-1} & \vdots \\ \vdots & \vdots & \ddots & b_m & b_{m-1} \\ 0 & 0 & \ddots & 0 & b_m \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{m+1} \quad \underbrace{\hspace{10em}}_n$

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PE in ARMA models - Proof

$$D \bar{\theta}^* = 0$$

$A(q^{-1})$ and $B(q^{-1})$ are co-prime

 D is nonsingular and $\bar{\theta}^* = 0$

Therefore, when $u(k)$ is PE of order $n + m + 1$
Parameter estimates convergence to the true values

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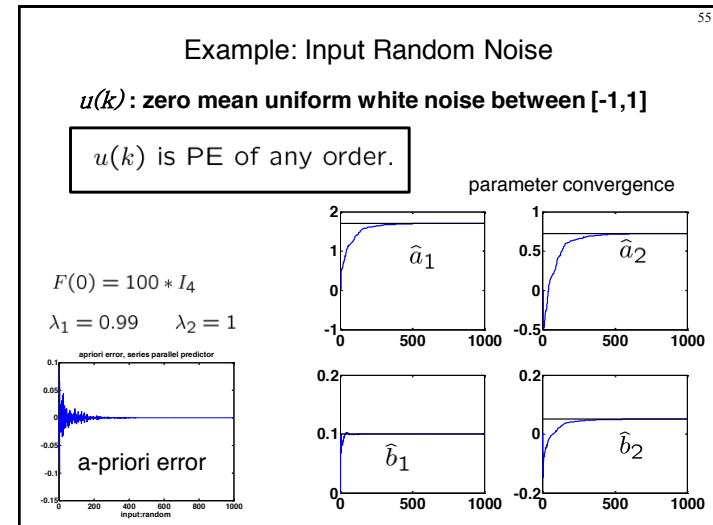
Example

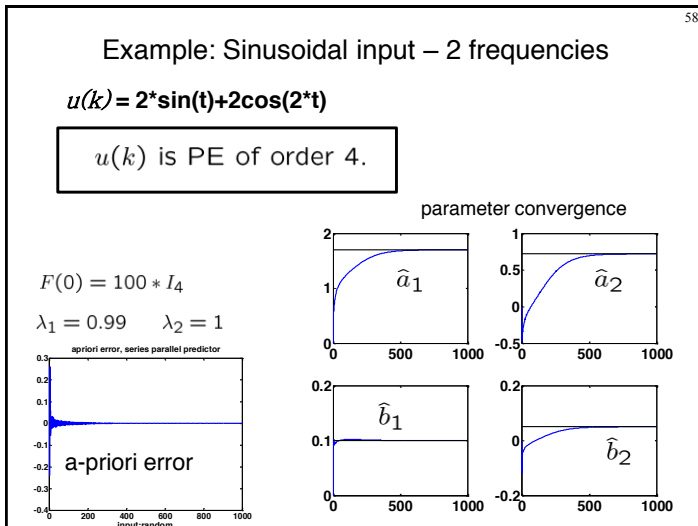
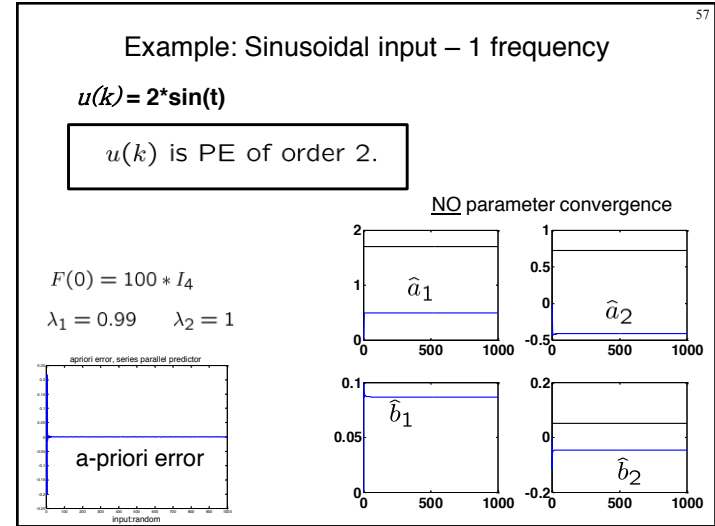
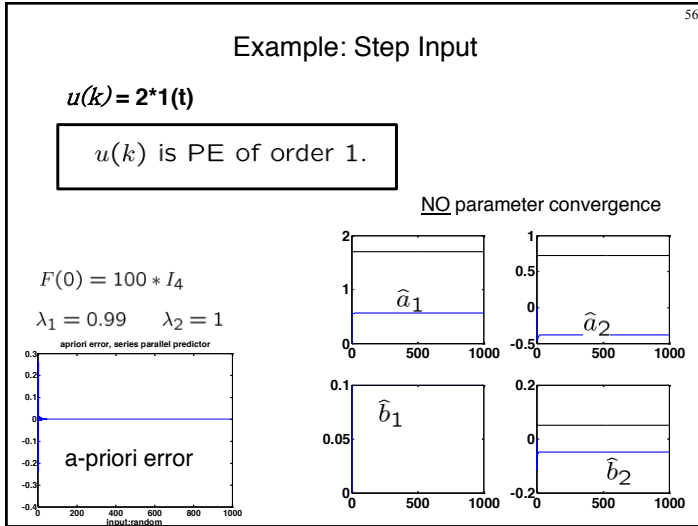
- Plant:

$$y(k) = \frac{q^{-1} 0.1(1 + 0.5q^{-1})}{(1 + 0.9q^{-1})(1 + 0.8q^{-1})} u(k)$$

$$y(k+1) = \theta^T \phi(k)$$

$$\theta = \begin{bmatrix} 1.7 \\ 0.72 \\ 0.1 \\ 0.05 \end{bmatrix} \in \mathcal{R}^4 \quad \phi(k) = \begin{bmatrix} -y(k) \\ -y(k-1) \\ u(k) \\ u(k-1) \end{bmatrix} \in \mathcal{R}^4$$
- We need $u(k)$ to be a PE sequence of order 4 to guarantee parameter convergence





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Additional Material

(you are not responsible for this)

- Proof of preliminary result 2

PE in Filtered Signals

$$v(k) = A(q^{-1})u(k)$$

Preliminary result 2:

If $A(q^{-1})$ is anti-Schur and $v(k)$ is not PE of order 1,

then $\frac{1}{A(q^{-1})}v(k)$ is not PE of order 1

The proof is based on frequency domain techniques for deterministic signals that are analogous to power spectral density techniques for wide sense stationary random signals

Stochastic and Deterministic Signals

WSS zero-mean random signals, $X(k)$ and $Y(k)$

$$\Lambda_{XY}(j) = E\{X(k+j)Y^T(k)\}$$

$$\Phi_{XX}(\omega) = \mathcal{F}\{\Lambda_{XX}(\cdot)\}$$

$$\Lambda_{XX}(0) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \Phi_{XX}(\omega) d\omega$$

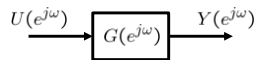
Deterministic signals, $x(k)$ and $y(k)$

$$\Gamma_{xy}(j) = \lim_{N \rightarrow \infty} \underbrace{\left(\frac{1}{2N+1} \sum_{k=-N}^N x(k+j)y^T(k) \right)}_{\text{Average value of } x(k+j)y^T(k) \text{ over } k}$$

$$\Psi_{xx}(\omega) = \mathcal{F}\{\Gamma_{xx}(\cdot)\}$$

$$\Gamma_{xx}(0) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \Psi_{xx}(\omega) d\omega$$

Stochastic and Deterministic Signals



where $G(z)$ is stable

WSS zero-mean random signals, $U(k)$ and $Y(k)$

$$\Phi_{YY}(\omega) = G(e^{j\omega})\Phi_{UU}(\omega)G^*(e^{j\omega})$$

↓ Scalar $U(k)$ and $Y(k)$

$$\Phi_{YY}(\omega) = |G(e^{j\omega})|^2 \Phi_{UU}(\omega)$$

Deterministic signals, $u(k)$ and $y(k)$

$$\Psi_{YY}(\omega) = G(e^{j\omega})\Psi_{UU}(\omega)G^*(e^{j\omega})$$

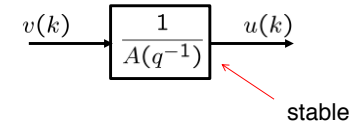
↓ Scalar $u(k)$ and $y(k)$

$$\Psi_{YY}(\omega) = |G(e^{j\omega})|^2 \Psi_{UU}(\omega)$$

Proof of Preliminary Result 2

Let

- $A(q^{-1})$ be anti-Schur
- $v(k)$ not be PE of order 1
- $u(k)$ be generated by



Choose M such that $\left| \frac{1}{A(e^{-j\omega})} \right|^2 \leq M, \quad \forall \omega \in [0, 2\pi]$

Proof of Preliminary Result 2

$$v(k) \rightarrow \boxed{\frac{1}{A(q^{-1})}} \rightarrow u(k) \quad \left| \frac{1}{A(e^{-j\omega})} \right|^2 \leq M, \quad \forall \omega \in [0, 2\pi]$$

$$\begin{aligned} \Gamma_{uu}(0) &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \Psi_{uu}(\omega) d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left[\left| \frac{1}{A(e^{-j\omega})} \right|^2 \Psi_{vv}(\omega) \right] d\omega \\ &\leq M \frac{1}{2\pi} \int_{-\pi}^{\pi} \Psi_{vv}(\omega) d\omega = M \Gamma_{vv}(0) \end{aligned}$$

Therefore, we have

$$0 \leq \Gamma_{uu}(0) \leq M \Gamma_{vv}(0)$$

Proof of Preliminary Result 2

$$0 \leq \Gamma_{uu}(0) \leq M \Gamma_{vv}(0)$$

$$v(k) \text{ not PE of order 1} \Rightarrow \Gamma_{vv}(0) = 0$$

$$\Rightarrow 0 \leq \Gamma_{uu}(0) \leq 0$$

$$\Rightarrow \Gamma_{uu}(0) = 0$$

$$\Rightarrow u(k) \text{ not PE of order 1}$$

