CORDIC

Introduction to digital Low-Level Radio Frequency Controls in Accelerators

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1 Introduction

This lab will guide you through the CORDIC (COordinate Rotation DIgital Computer) introduced in the lecture. Much of the code is derived from Berkeley Lab's bedrock/cordic repository.

We use Berkeley Lab's cordic module for the following lab.

The unit under test is cordicg_b22.v, which is generated by cordicgx.py with 22 bits internal data path width.

Input data width of xin, yin is configurable as a parameter of testbench, defined by DW in Makefile. The number of stages NSTG is also an parameter of the test bench.

We will test both Polar to Rectangular, and Rectangular to Polar conversion.

Use make to build test bench, run simulation and print results for analysis. Details check Makefile

2 Exercises

2.1 Polar to Rectangular

To get an ordinary P->R set yin to zero. It's also possible to use that mode for general vector rotation of the input (xin, yin) vector by angle phasein, which is the case using the test bench.

Note that the CORDIC propagation delay of NSTG cycles are already taken care of, so that the printed data is an aligned row of "T [ns]", "phasein", "xin", "yin", "xout", "yout", "phaseout" at every clock cycle.

Pay attention to the full scale of phasein and phaseout ports, which has DW+1 data width. The full scale of these two signals are $[0, 2\pi]$.

Check the CORDIC accuracy by comparing the expected vector after rotation and its output (xout, yout) for all data. What's the peak to peak and RMS error percentage?

2.2 Rectangular to Polar

To get an ordinary R->P computation set phasein to zero. A non-zero phasein in that mode will simply be added to the answer.

The test bench will work in the prior case. Check the CORDIC accuracy by comparing the expected amplitude and angle of (xin, yin) and the CORDIC output xout, phaseout respectively. What's the peak to peak and RMS error percentage?

2.3 Change data width and observe the difference

2.4 Change number of stages and observe the difference