

## 1 Probabilistic Graphical Models

Recall that we can represent joint probability distributions with directed acyclic graphs (DAGs). Let  $G$  be a DAG with vertices  $X_1, \dots, X_k$ . If  $P$  is a (joint) distribution for  $X_1, \dots, X_k$  with (joint) probability mass function  $p$ , we say that  $G$  represents  $P$  if

$$p(x_1, \dots, x_k) = \prod_{i=1}^k P(X_i = x_i | \text{pa}(X_i)), \quad (1)$$

where  $\text{pa}(X_i)$  denotes the parent nodes of  $X_i$ . (Recall that in a DAG, node  $Z$  is a parent of node  $X$  iff there is a directed edge going out of  $Z$  into  $X$ .)

Consider the following DAG

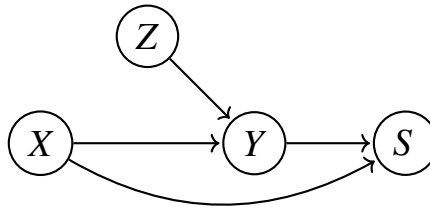


Figure 1:  $G$ , a DAG

(a) Write down the joint factorization of  $P_{S,X,Y,Z}(s, x, y, z)$  implied by the DAG  $G$  shown in Figure 1.

(b) Is  $S \perp Z \mid Y$ ?

(c) Is  $S \perp X \mid Y$ ?

## 2 Hidden Markov Models: Math Review

A Hidden Markov Model is a Markov Process with unobserved (hidden) states.

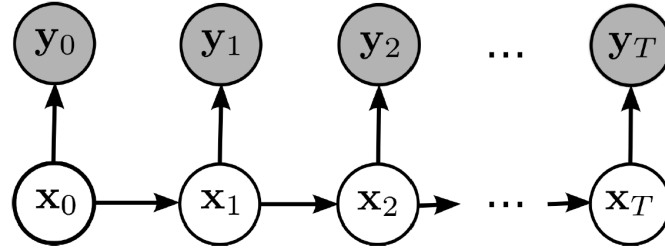


Figure 2: Example Hidden Markov Chain

Consider the following system in  $\mathbb{R}^2$ , where  $X_n$  is the true state at any given time  $n$  and  $Y_n$  is our observation. Given an initial state  $X_0$ , we move to future states by recursively multiplying our current state with transformation matrix  $A$  and adding i.i.d. Standard Normal Gaussian noise. When we take an observation  $Y_n$  of the true state  $X_n$ , we are also exposed to i.i.d. Standard Normal Gaussian Noise.

$$X_{n+1} = AX_n + N(0, I) \quad (2)$$

$$Y_n = X_n + N(0, I) \quad (3)$$

Where we have the 2x2 transformation matrix  $A$  defined as follows:

$$A = \begin{bmatrix} .5 & -.25 \\ -.25 & .75 \end{bmatrix} \quad (4)$$

If we restrict the initial state  $X_0$  to be a unit vector ( $\|X_0\|_2 = 1$ ), determine the following

- (a) What are the eigenvalues of  $A$ ? Is  $A$  a positive semi-definite matrix? (Note that  $\sqrt{5} = 2.236$ )

(b) What is the  $\|E[Y_\infty]\|_2$ ? Prove your assertion.

(c) Consider the Frobenius Norm of an arbitrary  $M \times N$  matrix  $Q$ , defined as  $\|Q\|_F = \sqrt{\sum_i \sum_j |Q_{i,j}|^2}$ , which indicates the “magnitude” or “largeness” of a matrix. Is  $\|Var[Y_\infty]\|_F$  finite or infinite? Prove your assertion.

You may find the following facts to be useful:

(i) Triangle Inequality:  $\|X + Y\| \leq \|X\| + \|Y\|$

(ii) Cauchy Schwarz:  $\|XY\| \leq \|X\| \|Y\|$

(iii) Geometric Sum:  $\sum_{i=0}^{\infty} ar^i = \frac{1}{1-r} \quad \forall r \text{ s.t. } 0 < r < 1; a, r \in \mathbb{R}$