

# A Primer on Bayesian Econometrics with Macroeconomic Applications

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# Frequentist v.s. Bayesian

## Probability axioms

1.  $0 \leq \mathbb{P}(A) \leq 1$  for any event  $A$
2.  $\mathbb{P}(A) = 1$  if event  $A$  represents logical truth
3.  $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B)$  for disjoint events  $A$  and  $B$
4.  $\mathbb{P}(A|B) = \mathbb{P}(A \cap B)/\mathbb{P}(B)$  (conditional probability)

- ▶ Any assignment of probabilities must satisfy above axioms
  - ▶ Frequentists assign probabilities to events that describe outcome of *repeated* experiment
  - ▶ Bayesians assign 'subjective' probability to any uncertain event (de Finetti's (1990) coherency principle)
- ▶ How likely it rains tomorrow?

# What Is the Lecture About?

- ▶ Introduce Bayesian computational devices applicable in macroeconomics and related fields
- ▶ Why Bayesian paradigm
  - ▶ handle sophisticated economic models
  - ▶ uncertainty in forecasting & policymaking
- ▶ Main references
  - ▶ Greenberg (2008), *"Introduction to Bayesian Econometrics"*, Cambridge University Press
  - ▶ Herbst & Schorfheide (2015), *"Bayesian Estimation of DSGE Models"*, Princeton University Press
  - ▶ An & Schorfheide (2007), *"Bayesian Analysis of DSGE Models"*, Econometric Reviews

# The Road Ahead...

- ▶ Part I: Fundamentals of Bayesian econometrics
  - ▶ prior, likelihood, and posterior
  - ▶ posterior inference
  - ▶ classical simulation methods
  - ▶ Markov chain Monte Carlo methods
- ▶ Part II: Macroeconomic applications
  - ▶ solving linearized DSGE model
  - ▶ prior distribution and likelihood function
  - ▶ tailored randomized block algorithm
  - ▶ selected further readings

## Part I: Fundamentals of Bayesian econometrics

# Prior, Likelihood, and Posterior

## Bayes Theorem

$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)} \propto p(y|\theta)p(\theta)$$

- ▶ Learning of random vector  $Y = [Y_1, \dots, Y_n]'$ 
  - ▶ call their realizations  $y = [y_1, \dots, y_n]'$  *data*
  - ▶ parametric distribution  $\mathbb{P}_\theta$
  - ▶ learning of unknown parameter  $\theta$
- ▶ Bayesian approach treats  $\theta$  as being random
  - ▶ start with *prior* density  $p(\theta)$
  - ▶ update by *likelihood* function  $p(y|\theta)$
  - ▶ *posterior* density  $p(\theta|y)$  proportional to prior  $\times$  likelihood

# Coin-Tossing Example

- ▶ Likelihood function

- ▶ single toss:  $y_i = 1$  if head or 0 if tail

$$y_i \sim \text{Bernoulli}(\theta) \Rightarrow p(y_i|\theta) = \theta^{y_i}(1 - \theta)^{1-y_i}$$

- ▶  $n$  independent tosses

$$p(y_1, \dots, y_n|\theta) = \theta^{\sum y_i} (1 - \theta)^{n - \sum y_i}$$

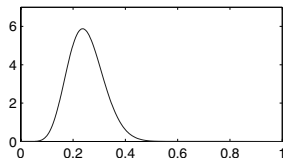
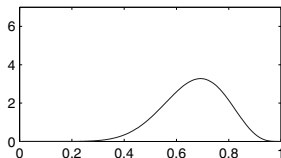
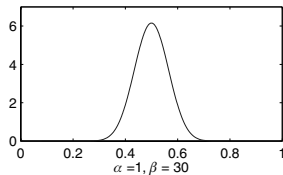
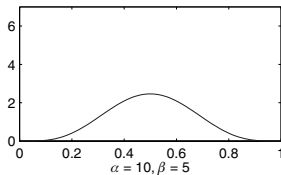
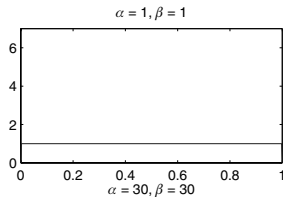
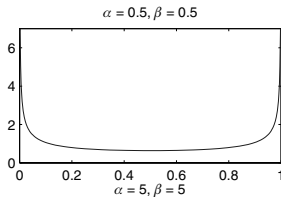
- ▶ Prior density:  $\theta \sim \text{Beta}(\alpha, \beta)$

$$p(\theta) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha-1} (1 - \theta)^{\beta-1}, \quad 0 \leq \theta \leq 1, \quad \alpha, \beta > 0$$

- ▶ Posterior density:  $\theta \sim \text{Beta}(\alpha + \sum y_i, \beta + n - \sum y_i)$

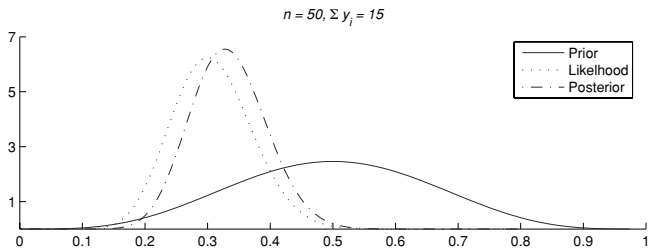
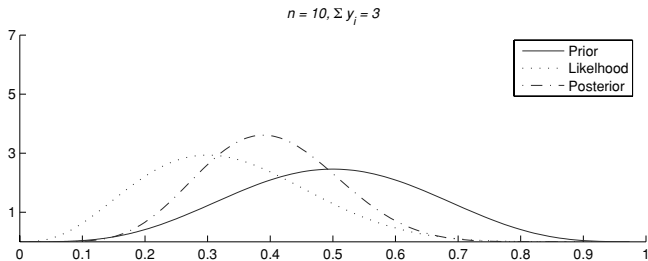
$$p(\theta|y) \propto \theta^{\alpha + \sum y_i - 1} (1 - \theta)^{\beta + n - \sum y_i - 1}$$

# Beta Distribution





# Sample Size



# Posterior Inference

- Identification
  - observational equivalence:  $p(y|\theta_1) = p(y|\theta_2)$  for all  $y$
  - identification through data v.s. prior
- Posterior estimates
  - point estimate:  $\hat{\theta} = \arg \max \int L(\hat{\theta}, \theta) p(\theta|y) d\theta$
  - interval estimate:  $\mathbb{P}(\theta_L \leq \theta \leq \theta_U) = .95$
- Prediction:  $p(y_{n+1}|y) = \int p(y_{n+1}|\theta, y) p(\theta|y) d\theta$
- Model comparison (& averaging)

$$\underbrace{\frac{p(\mathcal{M}_1|y)}{p(\mathcal{M}_2|y)}}_{\text{posterior odd}} = \underbrace{\frac{p(\mathcal{M}_1)}{p(\mathcal{M}_2)}}_{\text{prior odd}} \underbrace{\frac{p(y|\mathcal{M}_1)}{p(y|\mathcal{M}_2)}}_{\text{Bayes factor}}$$

where

$$\underbrace{p(y|\mathcal{M}_i)}_{\text{marginal likelihood}} = \int p(y|\theta_i, \mathcal{M}_i) p(\theta_i|\mathcal{M}_i) d\theta_i$$

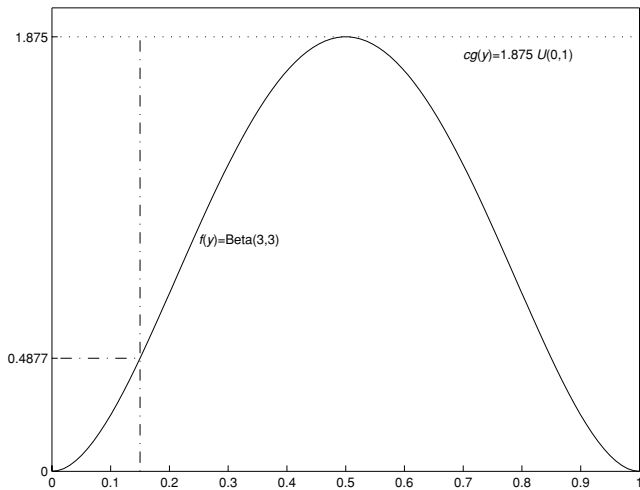
# Method 1: Probability Integral Transform

- ▶ Goal: represent  $f(y)$  with  $\mathbb{P}(Y \leq y) = F(y)$  by simulating *independent* samples
  - ▶ step 1: draw  $u \sim \text{Uniform}(0, 1)$
  - ▶ step 2: return  $y = F^{-1}(u)$  as a draw from  $f(y)$
- ▶ Example:  $f(y) = \frac{3}{8}y^2$  for  $0 \leq y \leq 2$  and 0 otherwise
  - ▶ compute distribution function  $F(y) = \frac{1}{8}y^3$
  - ▶ draw  $u \sim \text{Uniform}(0, 1) \Rightarrow y = 2u^{\frac{1}{3}} \sim f(y)$
- ▶ Remark: inefficient in multivariate case

## Method 2: Accept-Reject

- ▶ Goal: represent target  $f(y)$  by simulating *independent* samples from proposal  $g(y)$  with  $f(y) \leq cg(y)$  for some  $c \geq 1$ 
  - ▶ step 1: draw  $y \sim g(y)$
  - ▶ step 2: draw  $u \sim \text{Uniform}(0, 1)$
  - ▶ step 3: accept  $y$  as a draw from  $f(y)$  if  $u \leq \frac{f(y)}{cg(y)}$ ; otherwise reject and return to step 1
- ▶ Example: sample from  $\text{Beta}(3, 3)$ 
  - ▶ choose proposal  $\text{Uniform}(0, 1)$
  - ▶ set  $c = 1.875$
- ▶ Remark: difficult to find proposal in multivariate case

## Method 2: Accept-Reject (Cont'd)



## Method 3: Importance Sampling

- ▶ Goal: estimate  $\mathbb{E}[g(X)] = \int g(x)f(x)dx$  by simulating *independent* samples from proposal  $h(x)$ 
  - ▶ step 1: draw a sample  $\{x_i\}_{i=1}^M$  from  $h(x)$
  - ▶ step 2: compute

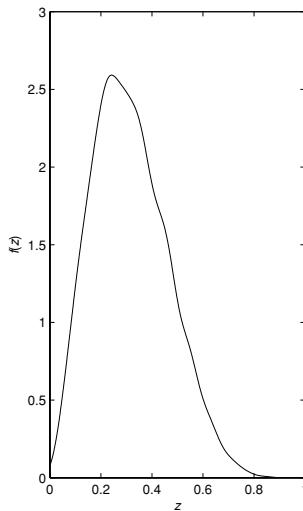
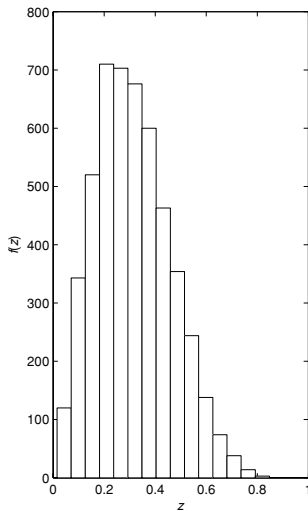
$$\mathbb{E}[g(X)] \approx \frac{1}{M} \sum_{i=1}^M g(x_i) \underbrace{f(x_i)/h(x_i)}_{\text{importance weight}}$$

- ▶ Example:  $\mathbb{E}[1/(1+x^2)]$  where  $x \sim \text{Exp}(1)$  truncated to  $[0, 1]$ 
  - ▶ step 1: draw a sample  $\{x_i\}_{i=1}^M$  from  $\text{Beta}(2, 3)$
  - ▶ step 2: compute

$$\frac{1}{M} \sum_{i=1}^M \frac{1}{1+x_i^2} \frac{e^{-x_i}}{1-e^{-1}} \frac{\text{Beta}(2, 3)}{x_i(1-x_i^2)}$$

- ▶ Remark: difficult to find proposal in multivariate case

# Using Simulated Output



- ▶  $\{x_i\}_{i=1}^M \sim \text{Beta}(3, 3)$ ,  $\{y_i\}_{i=1}^M \sim \text{Beta}(5, 3)$ ,  $z_i = x_i y_i$
- ▶  $\{z_i\}_{i=1}^M$  represent distribution of  $Z = XY$

# MCMC Algorithm: Big Picture

## A central equation

$$\int_A \int_{\mathbb{R}^d} p(x, y) \pi^*(x) dx dy = \int_A \pi^*(y) dy, \quad \forall A \in \mathcal{B}(\mathbb{R}^d)$$

- ▶ What is Markov chain theory doing? Know transition kernel  $p(\cdot, \cdot)$ , find invariant distribution  $\pi^*(\cdot)$

$$\int_A \int_{\mathbb{R}^d} p(x, y) \pi^{(n-1)}(x) dx dy = \int_A \pi^{(n)}(y) dy \rightarrow \int_A \pi^*(y) dy$$

- ▶ Markov chain Monte Carlo (MCMC) is doing opposite: know  $\pi^*(\cdot)$ , find corresponding  $p(\cdot, \cdot)$  such that

$$\pi^*(x)p(x, y) = \pi^*(y)p(y, x) \quad (\text{reversibility})$$

- ▶ Remark: greatly broaden scope of Bayesian methods though at cost of simulating *dependent* samples



# Metropolis-Hastings Algorithm

- ▶ Generic MH algorithm

- ▶ initialization: set  $\theta^{(0)} = \arg \max p(y|\theta)p(\theta)$
- ▶ recursion: for  $k = 1, \dots, N$ 
  - step 1: draw  $\vartheta \sim q(\theta^{(k-1)}, \cdot)$  (proposal density)
  - step 2: set  $\theta^{(k)} = \vartheta$  with probability of move

$$\alpha(\theta^{(k-1)}, \vartheta) = \min \left\{ \frac{p(y|\vartheta)p(\vartheta)}{p(y|\theta^{(k-1)})p(\theta^{(k-1)})} \frac{q(\vartheta, \theta^{(k-1)})}{q(\theta^{(k-1)}, \vartheta)}, 1 \right\}$$

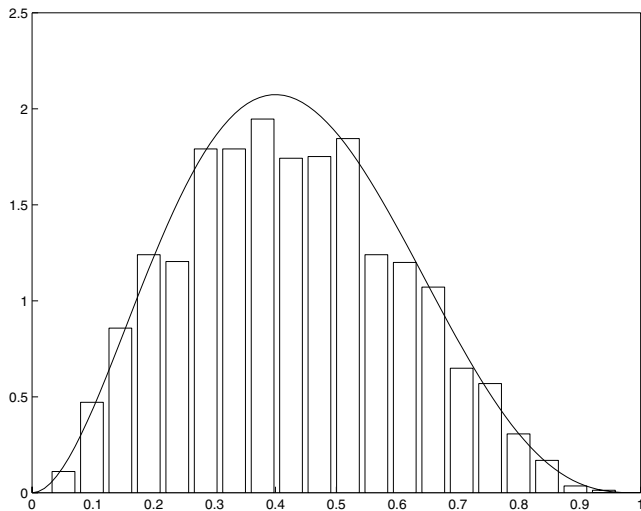
otherwise set  $\theta^{(k)} = \theta^{(k-1)}$

- ▶ discard burn-in phase
- ▶ MH's choice of  $p(\cdot, \cdot)$

$$p_{\text{MH}}(\theta^{(k-1)}, \vartheta) \equiv q(\theta^{(k-1)}, \vartheta) \alpha(\theta^{(k-1)}, \vartheta)$$

satisfies reversibility with invariant distribution  $p(\theta|y)$

# MH Output



- ▶ Target  $\text{Beta}(3, 4)$ , proposal  $\text{Uniform}(0, 1)$
- ▶  $M = 5,000$  after initial 500 burn-in

# Random Walk MH

## MATLAB pseudo-code

```
function [chain,rej] = RandomWalk_MH(c,Sigma)
[...]  
for k = 1:N  
    theta = mvt_rnd(chain(k-1,:),c^2*Sigma,inf,1);  
    pk_next = PostKer(theta);  
    alpha = min([exp(pk_next-pk_last) 1]);  
    if rand > alpha % reject  
        chain(k,:) = chain(k-1,:);  
        rej = rej+1;  
    else % accept  
        chain(k,:) = theta;  
        pk_last = pk_next;  
    end  
end
```

# Block-at-a-Time Algorithm

## Conditional invariant distributions

$$\int_{A_1} \int_{\mathbb{R}^{d_1}} p_1(x_1, y_1 | x_2) \pi_{1|2}^*(x_1 | x_2) dx_1 dy_1 = \int_{A_1} \pi_{1|2}^*(y_1 | x_2) dy_1$$

$$\int_{A_2} \int_{\mathbb{R}^{d_2}} P_2(x_2, y_2 | x_1) \pi_{2|1}^*(x_2 | x_1) dx_2 dy_2 = \int_{A_2} \pi_{2|1}^*(y_2 | x_1) dy_2$$

- ▶ Product of kernels principle
  - ▶  $p_1(x_1, y_1 | x_2) p_2(x_2, y_2 | y_1)$  has invariant density  $\pi^*(x_1, x_2)$
  - ▶ underlying Gibbs, MH within Gibbs, & TaRB
- ▶ Reference: Chib & Greenberg (1995), “*Understanding Metropolis-Hastings Algorithm*”, American Statistician

## Part II: Macroeconomic Applications

# Simple New Keynesian Model

- Dynamic IS relation

$$\hat{y}_t = \mathbb{E}_t \hat{y}_{t+1} + \hat{g}_t - \mathbb{E}_t \hat{g}_{t+1} - \frac{1}{\tau} (\hat{R}_t - \mathbb{E}_t \hat{\pi}_{t+1} - \mathbb{E}_t \hat{z}_{t+1})$$

- New Keynesian Phillips curve

$$\hat{\pi}_t = \beta \mathbb{E}_t \hat{\pi}_{t+1} + \kappa (\hat{y}_t - \hat{g}_t)$$

- Monetary policy rule

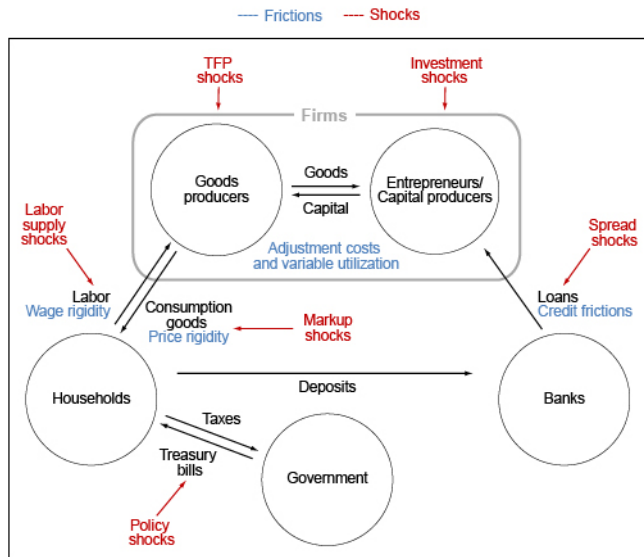
$$\hat{R}_t = \rho_R \hat{R}_{t-1} + (1 - \rho_R) \psi_1 \hat{\pi}_t + (1 - \rho_R) \psi_2 (\hat{y}_t - \hat{g}_t) + \epsilon_{R,t}$$

- Exogenous driving processes

$$\hat{g}_t = \rho_G \hat{g}_{t-1} + \epsilon_{G,t}, \quad \hat{z}_t = \rho_Z \hat{z}_{t-1} + \epsilon_{Z,t}$$

# FRB-NY Model

## A Stylized Description of the Model



# State Space Form

- ▶ Solving linear rational expectations models

- ▶ time domain (our focus), e.g. Sims (2001)

$$s_t = C(\theta) + G(\theta)s_{t-1} + M(\theta)\epsilon_t$$

- ▶ frequency domain, e.g. Walker & Tan (2015)

$$s_t = \sum_{k=0}^{\infty} C_{\theta,k} \epsilon_{t-k} \equiv C_{\theta}(L) \epsilon_t$$

- ▶ Measurement equations

$$\underbrace{\begin{pmatrix} \text{YGR}_t \\ \text{INF}_t \\ \text{INT}_t \end{pmatrix}}_{y_t} = \underbrace{\begin{pmatrix} \gamma^{(Q)} \\ \pi^{(A)} \\ \pi^{(A)} + r^{(A)} + 4\gamma^{(Q)} \end{pmatrix}}_{D(\theta)} + \underbrace{\begin{pmatrix} \hat{y}_t - \hat{y}_{t-1} + \hat{z}_t \\ 4\hat{\pi}_t \\ 4\hat{R}_t \end{pmatrix}}_{Z(\theta)s_t} + u_t$$

- ▶ Distributional assumption:  $\epsilon_t \sim \mathcal{N}(0, \Sigma_{\epsilon})$ ,  $u_t \sim \mathcal{N}(0, \Sigma_u)$



# Sims' Method

## MATLAB pseudo-code

```
function [C,G,M,eu] = SolveModel(para,ssp,P,V)
[...]  
% Input equations  
j = j+1;           % new Keynesian Phillips curve  
G0(j,V.model.pi) = 1;  
G0(j,V.model.E_pi) = -ssp(P.beta);  
G0(j,V.model.y) = -para(P.kappa);  
G0(j,V.model.g) = para(P.kappa);  
j = j+1;           % trend shock  
G0(j,V.model.z) = 1;  
G1(j,V.model.z) = para(P.rho_Z);  
Psi(j,V.shock.eps_Z) = 1;  
j = j+1;           % E_pi error  
G0(j,V.model.pi) = 1;  
G1(j,V.model.E_pi) = 1;  
Pi(j,V.fore.pi) = 1;  
% Solve model (see Chris Sims' webpage)  
[G,C,M,~,~,~,~,eu] = gensys(G0,G1,CC,Psi,Pi);
```

# Prior Distribution

Name	Domain	Density	Mean	S.D.
$\tau$	$\mathbb{R}^+$	G	2.00	0.50
$\kappa$	$\mathbb{R}^+$	G	0.20	0.10
$\psi_1$	$(1, \infty)$	G	1.50	0.25
$\psi_2$	$\mathbb{R}^+$	G	0.50	0.25
$r^{(A)}$	$\mathbb{R}^+$	G	0.50	0.50
$\pi^{(A)}$	$\mathbb{R}^+$	G	7.00	2.00
$\gamma^{(Q)}$	$\mathbb{R}$	N	0.40	0.20
$\rho_R$	$[0, 1)$	B	0.50	0.20
$\rho_G$	$[0, 1)$	B	0.80	0.10
$\rho_Z$	$[0, 1)$	B	0.66	0.15
$\sigma_R$	$\mathbb{R}^+$	IG	0.50	0.26
$\sigma_G$	$\mathbb{R}^+$	IG	1.25	0.65
$\sigma_Z$	$\mathbb{R}^+$	IG	0.63	0.33

# Prior Evaluation

## MATLAB pseudo-code

```
function logprior = prior_pdf(x,mean,sd,type)

switch type
    case 'G'          % Gamma distribution
        a = mean^2/sd^2;
        b = sd^2/mean;
        logprior = log(gampdf(x,a,b));
    case 'N'          % Normal distribution
        logprior = log(normpdf(x,mean,sd));
    case 'B'          % Beta distribution
        a = -mean*(sd^2+mean^2-mean)/sd^2;
        b = (mean-1)*(sd^2+mean^2-mean)/sd^2;
        logprior = log(betapdf(x,a,b));
    case 'I1'         % Inv-Gamma type-1 distribution
        [...]
end
```

# Likelihood Function

## ► Generic filter

► initialization: set  $p(s_0|y_0, \theta) = p(s_0|\theta)$

► recursion: for  $t = 1, \dots, T$

step 1: forecasting  $s_t$  via model solution

$$p(s_t|y_{1:t-1}, \theta) = \int p(s_t|s_{t-1}, \cancel{y_{1:t-1}}, \theta) p(s_{t-1}|y_{1:t-1}, \theta) ds_{t-1}$$

step 2: forecasting  $y_t$  via measurement equations

$$p(y_t|y_{1:t-1}, \theta) = \int p(y_t|s_t, \cancel{y_{1:t-1}}, \theta) p(s_t|y_{1:t-1}, \theta) ds_t$$

step 3: filtering  $s_t$  via Bayes' Theorem

$$p(s_t|y_{1:t}, \theta) = \frac{p(y_t|s_t, \cancel{y_{1:t-1}}, \theta) p(s_t|y_{1:t-1}, \theta)}{p(y_t|y_{1:t-1}, \theta)}$$

► Likelihood evaluation:  $p(y_{1:T}|\theta) = \prod_{t=1}^T p(y_t|y_{1:t-1}, \theta)$

# Kalman Filter

## MATLAB pseudo-code

```
function [m_fs,V_fs,loglik] = KalmanFilter(Y,SSR)
[...]  
for t = 1:T  
    % Period-(t-1) predictive density  
    m_ps = C+G*m_fs(:,t-1);  
    V_ps = G*V_fs(:, :, t-1)*G'+M*V_e*M';  
  
    % Period-t log likelihood  
    m_py = D+Z*m_ps;  
    V_py = Z*V_ps*Z'+V_u;  
    loglik(t) = mvt_pdf(Y(t,:),m_py',V_py,inf);  
  
    % Period-t filtering density  
    gain = (V_ps*Z')/V_py;  
    m_fs(:,t) = m_ps+gain*(Y(t,:)'-m_py);  
    V_fs(:, :, t) = V_ps-gain*Z*V_ps;  
end
```

# TaRB-MH Algorithm

- ▶ A powerful and highly efficient MCMC approach
  - ▶ randomize number & components of blocks
  - ▶ tailor proposal to posterior location & curvature
- ▶ Tailored randomized block (TaRB) algorithm
  - ▶ initialization: set  $\theta^{(0)} = \arg \max p(y|\theta)p(\theta)$
  - ▶ recursion: for  $k = 1, \dots, N$ 
    - step 1: randomize blocks  $(\theta_{k,1}, \theta_{k,2}, \dots, \theta_{k,B_k})$
    - step 2: tailor proposal density by optimization routine

$$q_l(\theta_{k,l}|\theta_{k,-l}, y) = t(\theta_{k,l}|\hat{\theta}_{k,l}, V_{k,l}, \nu)$$

step 3: update each block with  $\alpha_l(\theta_{k,l}, \vartheta_{k,l}|\theta_{k,-l}, y)$

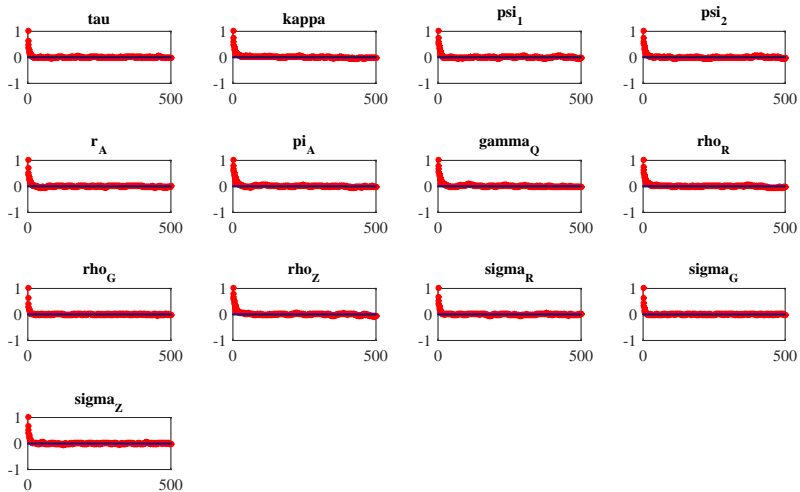
- ▶ discard burn-in phase
- ▶ Chib & Ramamurthy (2010), “*TaRB MCMC Methods with Application to DSGE Models*”, Journal of Econometrics

## Posterior Distribution

Name	Mean	90% interval	lneff.
$\tau$	2.435	[1.712, 3.314]	8.1
$\kappa$	0.543	[0.362, 0.758]	16.7
$\psi_1$	1.738	[1.400, 2.093]	10.1
$\psi_2$	0.570	[0.198, 1.088]	13.7
$r^{(A)}$	0.388	[0.038, 0.869]	9.4
$\pi^{(A)}$	3.379	[2.789, 3.968]	16.6
$\gamma^{(Q)}$	0.605	[0.399, 0.806]	16.4
$\rho_R$	0.791	[0.735, 0.841]	17.1
$\rho_G$	0.963	[0.933, 0.987]	7.4
$\rho_Z$	0.924	[0.890, 0.956]	18.0
$\sigma_R$	0.208	[0.173, 0.247]	10.2
$\sigma_G$	0.736	[0.637, 0.856]	7.0
$\sigma_Z$	0.209	[0.172, 0.249]	9.3

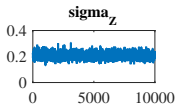
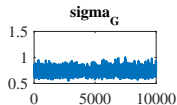
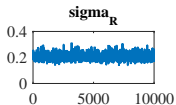
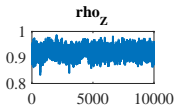
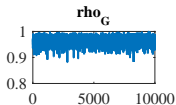
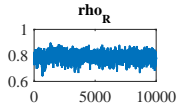
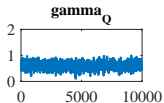
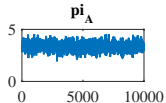
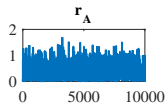
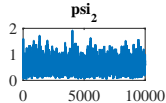
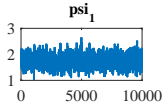
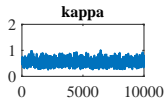
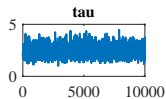
NOTES: number of draws = 10,000 after first 1,000 burn-in; computational time = 17m:32s; rejection rate = 45.9%; average number of blocks = 3.4

# Autocorrelation Function





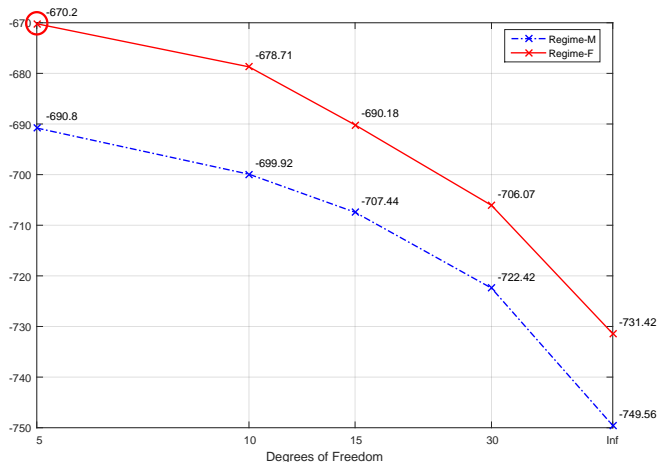
# Trace Plot



# Monetary-Fiscal Policy Interaction

- ▶ Macro policies have two essential tasks to perform
  - ▶ determining inflation/price level
  - ▶ stabilizing government debt
- ▶ Conventional theory (regime-M)
  - ▶ MP 'actively' targets inflation by Taylor principle
  - ▶ FP 'passively' targets debt by fiscal adjustments
- ▶ Fiscal theory (regime-F)
  - ▶ FP 'actively' determines inflation
  - ▶ MP 'passively' maintains real value of debt
- ▶ Fundamental understandings of how macro economy works hinge on determining policy regime, e.g.
  - ▶ inflation monetary or fiscal phenomenon?
  - ▶ appropriate MP response to deflation?

# Leeper-Traum-Walker Model



- ▶ Truth: regime-F with 5 degrees of freedom and 100 observations; 33 parameters, 48 equations, 8 observables
- ▶ True model yields highest marginal likelihood

## Selected Further Readings

- ▶ Student-t shocks: Chib & Ramamurthy (2014), "*DSGE Models with Student-t Errors*", *Econometric Reviews*
- ▶ Stochastic volatility: Justiniano & Primiceri (2008), "*Time-Varying Volatility of Macro Fluctuations*", *AER*
- ▶ Regime-switching: Schorfheide (2005), "*Learning and Monetary Policy Shifts*", *RED*
- ▶ DSGE-VAR: Del Negro & Schorfheide (2004), "*Priors from General Equilibrium Models for VARs*", *IER*
- ▶ Prediction pool: Del Negro, Hasegawa & Schorfheide (2016), "*Dynamic Prediction Pools*", *JoE*
- ▶ Asset pricing: Rapach & Tan (2018), "*Asset Pricing with Recursive Preferences and Stochastic Volatility*", *Manuscript*