

Lecture 2 Posterior Distributions and Inference

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The Road Ahead...

- ▶ Choice of likelihood function
- ▶ Multiparameter case
- ▶ Bayesian updating
- ▶ Large-sample posterior
- ▶ Identification
- ▶ Posterior estimates: point & interval
- ▶ Model comparison
- ▶ Prediction

Choice of Likelihood Function

- ▶ Bayesian approaches: transparent finite-sample inference but must specify likelihood function
- ▶ Such specification is part of prior information and requires justification, e.g.

$$y_i = \mu + u_i, \quad u_i \sim_{i.i.d.} t_\nu(0, \sigma^2), \quad i = 1, \dots, n$$

- ▶ distributional assumption: normal ($\nu = \infty$) vs. Student- t
 - ▶ posterior odds comparison w.r.t. ν
- ▶ Frequentist approaches: MLE also requires distribution; GMM is free of distribution but relies on large sample

Vector Case: $\theta = (\theta_1, \dots, \theta_d)$

Marginal vs. conditional posterior

$$\underbrace{\pi(\theta_1|y)}_{\text{marginal}} = \int \underbrace{\pi(\theta_1|\theta_2, \dots, \theta_d, y)}_{\text{conditional}} \underbrace{\pi(\theta_2, \dots, \theta_d|y)}_{\text{weight}} d\theta_2 \cdots d\theta_d$$

where $\pi(\theta_1|\theta_2, \dots, \theta_d, y) = \underbrace{\pi(\theta_1, \theta_2, \dots, \theta_d|y)}_{\text{joint}} / \pi(\theta_2, \dots, \theta_d|y)$

- ▶ From joint to marginal posteriors
 - ▶ $\pi(\theta_1|y)$ accounts for uncertainty over $(\theta_2, \dots, \theta_d)$ by averaging $\pi(\theta_1|\theta_2, \dots, \theta_d, y)$ weighted by $\pi(\theta_2, \dots, \theta_d|y)$
 - ▶ analytical vs. numerical integral
- ▶ Focus on one/two-dim marginals (readily graphed)

Die-Tossing Example

- ▶ Multinomial joint likelihood: $(y_1, \dots, y_d) \sim \mathbb{M}_d(\theta, n)$

$$f(y_1, \dots, y_d | \theta_1, \dots, \theta_d) = \frac{n!}{\prod_{i=1}^d y_i!} \prod_{i=1}^d \theta_i^{y_i}$$

- ▶ d outcomes: probabilities $\sum \theta_i = 1$, counts $\sum y_i = n$
- ▶ Bernoulli ($d = 2, n = 1$), binomial ($d = 2, n > 1$)
- ▶ Dirichlet joint prior: $\theta \sim \mathbb{D}(\alpha_1, \dots, \alpha_d)$

$$\pi(\theta) = \frac{\Gamma(\sum_{i=1}^d \alpha_i)}{\prod_{i=1}^d \Gamma(\alpha_i)} \prod_{i=1}^d \theta_i^{\alpha_i - 1}, \quad \sum \theta_i = 1, \quad \alpha_i > 0$$

- ▶ Dirichlet joint posterior: $\theta | y \sim \mathbb{D}(y_1 + \alpha_1, \dots, y_d + \alpha_d)$
- ▶ Beta marginal posterior: $\theta_j | y \sim \mathbb{B}(y_j + \alpha_j, \sum_{i \neq j} y_i + \alpha_i)$

Bayesian Updating

Bayes theorem

$$\text{Old data } y_1: \underbrace{\pi(\theta|y_1)}_{\text{posterior}} \propto \underbrace{f(y_1|\theta)}_{\text{likelihood}} \underbrace{\pi(\theta)}_{\text{prior}}$$

$$\text{New data } y_2: \underbrace{\pi(\theta|y_1, y_2)}_{\text{posterior}} \propto \underbrace{f(y_2|y_1, \theta)}_{\text{likelihood}} \underbrace{\pi(\theta|y_1)}_{\text{prior}}$$

- ▶ Consider coin-tossing example
 - ▶ prior: $\theta \sim \mathbb{B}(\alpha_0, \beta_0)$
 - ▶ posterior after initial n_1 tosses: $\theta|y_1 \sim \mathbb{B}(\alpha_1, \beta_1)$, where $\alpha_1 = \alpha_0 + \sum y_{1,i}$, $\beta_1 = \beta_0 + n_1 - \sum y_{1,i}$
 - ▶ posterior after another n_2 tosses: $\theta|y_1, y_2 \sim \mathbb{B}(\alpha_2, \beta_2)$, where $\alpha_2 = \alpha_1 + \sum y_{2,i}$, $\beta_2 = \beta_1 + n_2 - \sum y_{2,i}$
- ▶ For sequential data, Bayesian updates ‘prior’ with new information to obtain ‘posterior’

Large Samples

Posterior with independent data

$$\pi(\theta|y) \propto \pi(\theta) \exp[n\bar{l}(\theta|y)], \quad \bar{l}(\theta|y) = \frac{1}{n} \sum_{i=1}^n \log[f(y_i|\theta)]$$

- ▶ Effects of large n on posterior
 - ▶ data/likelihood dominates prior
 - ▶ ‘consistency’: $\bar{l}(\theta|y) \rightarrow_{n \rightarrow \infty} \bar{l}(\theta_0|y)$ so posterior degenerates to point mass at true value of θ
 - ▶ ‘asymptotic normality’: take 2nd-order Taylor expansion around MLE $\hat{\theta}$

$$\pi(\theta|y) \propto \pi(\theta) \underbrace{\exp \left[-\frac{n}{2v} (\theta - \hat{\theta})^2 \right]}_{\text{Gaussian kernel}}, \quad v = -\bar{l}''(\hat{\theta}|y)^{-1} > 0$$

provided $\pi(\hat{\theta}) \neq 0$ (exercise: multiparameter case)

Identification

- ▶ Identification through data/likelihood
 - ▶ model A & model B are observationally equivalent if $f(y|\theta_A) = f(y|\theta_B)$ for *all* $y \Rightarrow \theta$ not identified
 - ▶ no observational equivalence $\Rightarrow \theta$ identified
- ▶ Important special case: $f(y|\theta_1, \theta_2) = f(y|\theta_1)$
 - ▶ θ_2 not identified, e.g. linear regression with both constant and complete set of dummies
 - ▶ Identification through prior: if $\pi(\theta_2|\theta_1) \neq \pi(\theta_2)$

$$\pi(\theta_2|y) = \int \pi(\theta_1|y)\pi(\theta_2|\theta_1)d\theta_1 \neq \pi(\theta_2)$$

- ▶ Be cautious when interpreting difference between prior-posterior for unidentified parameters

Posterior Estimates

- ▶ Bayes estimator minimizes expected loss

$$\arg \min_{\hat{\theta}} \mathbb{E}[L(\hat{\theta}, \theta)] = \arg \min_{\hat{\theta}} \int L(\hat{\theta}, \theta) \pi(\theta|y) d\theta$$

- ▶ quadratic loss $L(\hat{\theta}, \theta) = (\hat{\theta} - \theta)^2 \Rightarrow \hat{\theta} = \mathbb{E}(\theta|y)$
 - ▶ frequentist criteria: unbiasedness, consistency, efficiency
 - ▶ \mathbb{E} operator: Bayesian $f(\theta)|y$ vs. frequentist $f(y)|\theta$
- ▶ Credible interval: e.g. $\mathbb{P}(\theta_l \leq \theta \leq \theta_u) = 0.9$
 - ▶ $\min(\theta_u - \theta_l) \Rightarrow$ highest probability density (HPD) interval
 - ▶ frequentist confidence intervals entail all possible y

Model Comparison

Posterior odd & marginal likelihood

$$\underbrace{\frac{\pi(M_1|y)}{\pi(M_2|y)}}_{\text{posterior odds}} = \underbrace{\frac{\pi(M_1)}{\pi(M_2)}}_{\text{prior odds}} \underbrace{\frac{m(y|M_1)}{m(y|M_2)}}_{\text{Bayes factor}}$$

where $\underbrace{m(y|M_i)}_{\text{marginal likelihood}} = \int f(y|\theta_i, M_i) \pi(\theta_i|M_i) d\theta_i$

- Effects of large n on log Bayes factor

$$\log(B_{12}) \approx \underbrace{\log\left(\frac{f(\hat{\theta}_1|y)}{f(\hat{\theta}_2|y)}\right)}_{\text{log likelihood ratio}} - \underbrace{\frac{d_1 - d_2}{2} \log(n)}_{\text{penalty on dim}(\theta)} + \underbrace{C}_{\text{free of } n}$$

- Jeffreys guideline vs. frequentist hypothesis test
- nested vs. non-nested model comparison

Prediction

Predicting new data

$$f(y_f|y) = \int f(y_f|\theta, y) \pi(\theta|y) d\theta$$

- ▶ Recall coin-tossing example
 - ▶ posterior: $\theta|y \sim \mathbb{B}(\alpha_1, \beta_1)$, where $\alpha_1 = \alpha_0 + \sum y_i$,
 $\beta_1 = \beta_0 + n - \sum y_i$
 - ▶ exercise: verify $f(y_{n+1} = 1|y) = \frac{\alpha_0 + \sum y_i}{\alpha_0 + \beta_0 + n} = \mathbb{E}(\theta|y)$
- ▶ Prediction with multiple models via model averaging

$$f(y_f|y) = \sum_{i=1}^m \pi(M_i|y) f(y_f|y, M_i)$$

Readings

- ▶ Jeffreys (1961), "*Theory of Probability*," Clarendon Press