Lecture 10 Bayesian DSGE Models

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Introduction

- DYNARE has played a large role in the practical fitting of DSGE models
- However, it cannot handle high-dimensional DSGE models or models with
 - ► Student-*t* shocks, e.g., Chib & Ramamurthy (2014)
 - stochastic volatility, e.g., Justiniano & Primiceri (2008)
- ► Chib, Shin, & Tan (2021) provide a user-friendly MATLAB toolbox for such models that contains
 - training sample priors
 - efficient sampling of parameters by the TaRB-MH algorithm of Chib & Ramamurthy (2010)
 - ► fast computation of the marginal likelihood by the method of Chib (1995) and Chib & Jeliazkov (2001)
 - post-estimation tools, e.g., point and density forecasts

The Road Ahead...

- ▶ DSGE model
- Prior distribution
- ► Posterior distribution
- Marginal likelihood
- ► Prediction

Illustration

Dynamic IS relation

$$\hat{y}_t = \mathbb{E}_t \hat{y}_{t+1} + \hat{g}_t - \mathbb{E}_t \hat{g}_{t+1} - \frac{1}{\tau} (\hat{R}_t - \mathbb{E}_t \hat{\pi}_{t+1} - \mathbb{E}_t \hat{z}_{t+1})$$

► New Keynesian Phillips curve

$$\hat{\pi}_t = \beta \mathbb{E}_t \hat{\pi}_{t+1} + \kappa (\hat{y}_t - \hat{g}_t)$$

Monetary policy rule

$$\hat{R}_{t} = \rho_{R}\hat{R}_{t-1} + (1 - \rho_{R})\psi_{1}\hat{\pi}_{t} + (1 - \rho_{R})\psi_{2}(\hat{y}_{t} - \hat{g}_{t}) + \epsilon_{R,t}$$

Exogenous shocks

$$\hat{g}_t = \rho_G \hat{g}_{t-1} + \epsilon_{G,t}, \quad \hat{z}_t = \rho_Z \hat{z}_{t-1} + \epsilon_{Z,t}$$

▶ t-innovation with SV: for $s \in \{R, G, Z\}$

$$\epsilon_{s,t} \sim t_{\scriptscriptstyle V}(0,e^{h_{\scriptscriptstyle S},t}), \quad h_{\scriptscriptstyle S,t} = (1-\phi_{\scriptscriptstyle S})\mu_{\scriptscriptstyle S} + \phi_{\scriptscriptstyle S}h_{\scriptscriptstyle S,t-1} + \eta_{\scriptscriptstyle S,t}, \quad \eta_{\scriptscriptstyle S,t} \sim N(0,\omega_{\scriptscriptstyle S}^2)$$

State Space Form

- We rely on Sims' (2001) method to solve for the solution of the structural model, for *each* value of θ
- ► After (log) linearizing around the steady state, the structural model is expressed in canonical form as

$$\Gamma_0(\theta)x_t = \Gamma_1(\theta)x_{t-1} + \Psi\epsilon_t + \Pi\eta_t$$

Applying Sims' method, the unique, bounded solution takes the form

$$x_t = G(\theta)x_{t-1} + M(\theta)\epsilon_t$$

where $G(\theta)$ and $M(\theta)$ are non-linear unspecified functions of θ determined by the solve step

State Space Form

▶ Model completed by the measurement equations

$$egin{pmatrix} \mathsf{YGR}_t \ \mathsf{INF}_t \ \mathsf{INT}_t \end{pmatrix} = egin{pmatrix} \gamma^{(\mathcal{Q})} & & & \\ \pi^{(A)} & & & \\ \pi^{(A)} + r^{(A)} + 4\gamma^{(\mathcal{Q})} \end{pmatrix} + egin{pmatrix} \hat{y}_t - \hat{y}_{t-1} + \hat{z}_t \ 4\hat{\pi}_t \ 4\hat{R}_t \end{pmatrix}$$

▶ We show results for an extended version of this model that has 51 parameters, 21 variables, 8 shocks, 8 observables, and 1,494 non-Gaussian and nonlinear latent variables

Example

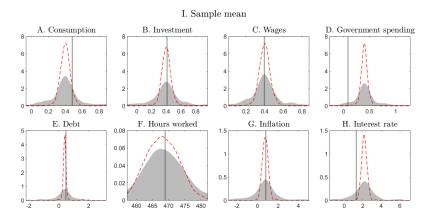
- Set MATLAB directory to the 'DSGE-SVt' folder
- Specify the model, data, and save directories

```
%% Housekeeping
clear
close all
clc
%% User search path & mex files
modpath = ['user' filesep 'ltw17'];
datpath = ['user' filesep 'ltw17' filesep '
   data.txt']:
savepath = ['user' filesep 'ltw17'];
spec = tarb_spec([], 'modpath', modpath, 'datpath
    ', datpath, 'savepath', savepath);
OneFileToMexThemAll
```

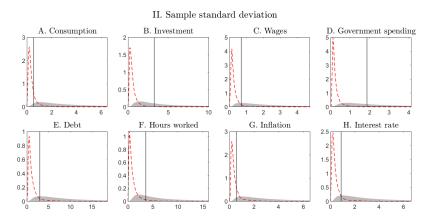
Training Sample Prior

- ▶ In high dimensions, formulating an appropriate prior is difficult due to the complex mapping from θ to $G(\theta)$ and $M(\theta)$
- ▶ Standard choices often produce prior-sample conflict
- We supply two ways of dealing with this: training sample priors and Student-t family of distributions for location-type parameters
- ► A sampling the prior function is available to calculate the implied distribution of the outcomes

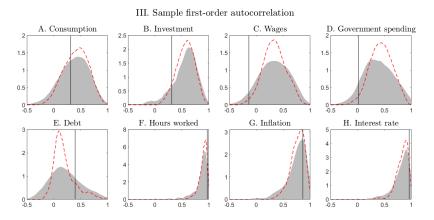
Prior Predictive Distribution



Prior Predictive Distribution



Prior Predictive Distribution



Estimation

► The centerpiece of the estimation procedure is the TaRB-MH algorithm of Chib & Ramamurthy (2010)

▶ Used to draw samples of $(\theta, z_{1:T})$ from

$$\pi(\theta, z_{1:T}|y_{1:T}) \propto f(y_{1:T}, z_{1:T}|\theta) \cdot \pi(\theta) \cdot \mathbf{1}\{\theta \in \Theta_D\}$$

► TaRB-MH is coded up in DYNARE, but the implementation there is somehow not efficient

TaRB-MH MCMC

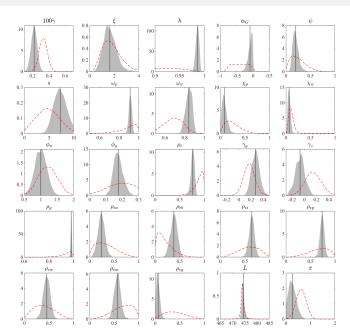
- Two hallmarks of TaRB-MH
 - randomize the number and components of blocks
 - ▶ tailor the proposal density to the posterior location and curvature, i.e., $q_b(\theta_b|y_{1:T},z_{1:T},\theta_{-b})=t_v(\theta_b|\hat{\theta}_b,\hat{V}_b)$, $b=1,\ldots,B$, using simulated annealing and Chris Sims' csminwel
- ▶ The toolbox provides a fast implementation of these steps by
 - randomly tailoring proposal every few iterations
 - ► MEX loop-intensive functions from C/C++ code
 - lacktriangle csminwel to get \hat{V}_b as output
- ► Although intensive it all happens seamlessly

Example

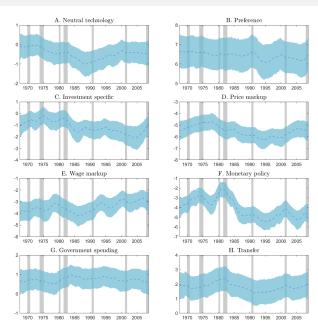
► Set up the TaRB-MH algorithm

► The estimation results are stored in the MATLAB data file tarb_full.mat

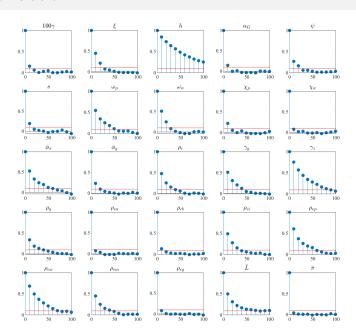
Prior-Posterior



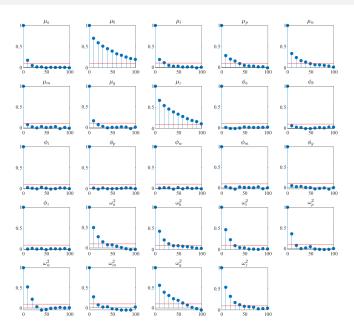
Stochastic Volatility



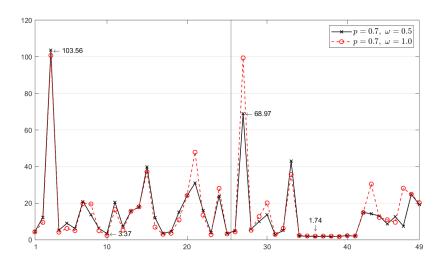
Autocorrelation



Autocorrelation



Inefficiency Factor



Model Comparison

 Marginal likelihood is computed by a fast implementation of the Chib & Jeliazkov (2001) estimator

▶ This estimator is based on the identity of Chib (1995)

$$m(y_{1:T}) = \frac{f(y_{1:T}|\theta^*)\pi(\theta^*)}{\pi(\theta^*|y_{1:T})}, \quad \forall \theta^*$$

Model Comparison

► With multiple block sampling, the posterior ordinate is estimated from the decomposition

$$\pi(\theta^*|y_{1:T}) = \pi(\theta_1^*|y_{1:T})\pi(\theta_2^*|y_{1:T},\theta_1^*)\cdots\pi(\theta_B^*|y_{1:T},\theta_1^*,\ldots,\theta_{B-1}^*)$$
 using several reduced TaRB-MH runs

Key point: all reduced runs can be parallelized for the cost of only one reduced run, regardless of the number of blocks

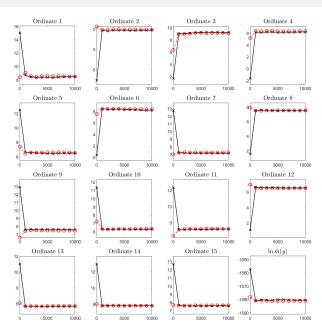
► This speeds up the calculation enormously

Example

► Set up the TaRB-MH reduced run

► The estimation results are stored in the MATLAB data file tarb_reduce.mat

Marginal Likelihood



Simulation Evidence

Table 1: Chib-Jeliazkov estimator

DGP 1: regime-M with $\nu = 15$			DGP 2: regime-F with $\phi=0.5$		
ν	М	F	φ	М	F
30 (light)	4	0	0.1 (weak)	0	9
15 (fat)	15	0	0.5 (moderate)	0	10
5 (heavy)	1	0	0.9 (strong)	0	1

NOTES: Number of picks for each model specification.

Table 2: Modified harmonic mean estimator

DGP 1: regime-M with $\nu=15$			DGP 2: regime-F with $\phi=0.5$		
ν	М	F	φ	М	F
30 (light)	0	0	0.1 (weak)	0	0
15 (fat)	0	0	0.5 (moderate)	0	0
5 (heavy)	20	0	0.9 (strong)	0	20

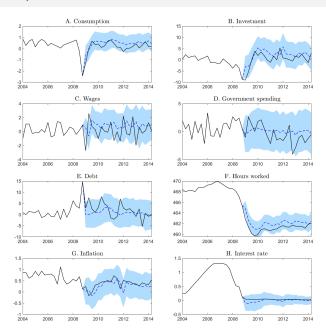
Post-Estimation Tools

- Toolbox includes post-estimation tools, e.g., functions for conducting impulse response, variance decomposition, and prediction
- ► For instance, suppose we want the one-quarter-ahead prediction density

$$p(y_{T+1}|y_{1:T}) = \int p(y_{T+1}|y_{1:T},\theta,z_{T+1}) \cdot \pi(\theta,z_{T+1}|y_{1:T})d(\theta,z_{1:T})$$

▶ This is available through the TaRB-MH specification

Out-of-Sample Forecast



Outroduction

- Going beyond DYNARE for Next-Gen DSGE models
- Efficient and fast estimation via TaRB-MH and parallel computing
- MATLAB toolbox: publicly available at sites.google.com/a/slu.edu/tanf/research
- Readily applied. Current application in progress, an open economy DSGE model that is about twice as big as the largest DSGE model estimated to date

References

- Chib & Ramamurthy (2010), "Tailored Randomized Block MCMC Methods with Application to DSGE Models," Journal of Econometrics
- ► Chib, Shin, & Tan (2021), "DSGE-SVt: An Econometric Toolkit for High-Dimensional DSGE Models with SV and t Errors," Computational Economics
- Sims (2001), "Solving Linear Rational Expectations Models,"
 Computational Economics