

$$w^{(n-1)} \quad (n-1) \times P$$

$$\begin{bmatrix} \vdots \\ \vdots \end{bmatrix}_{x_{n-1}} \quad \begin{bmatrix} \vdots \\ \vdots \end{bmatrix}_{y_{n-1}}$$

$$W^{(n-1)} = (x_{n-1}^T x_{n-1})^{-1} x_{n-1}^T y_{n-1} \Rightarrow P \times 1$$

$$X_n = \begin{bmatrix} x_{n-1} \\ x_n \end{bmatrix} \begin{matrix} \nearrow G \\ \nwarrow \end{matrix} \begin{matrix} R_{n-1} \times P \\ (n-1+1) \end{matrix}$$

$$R_{n-1} = X_{n-1}^T X_{n-1} \quad (P \times P) \quad \leftarrow n-1 \text{ data}$$

$$R_n = X_n^T X_n \quad \leftarrow n \text{ data}$$

$$R_n = R_{n-1} + x_n x_n^T \quad (P \times P) \quad \downarrow \quad (P \times 1) \cdot (1 \times P)$$

rank one update.

$$(A + x x^T)^{-1} = A^{-1} - \frac{A^{-1} x x^T A^{-1}}{1 + x^T A^{-1} x}$$

$$R_n^{-1} x_n^T y \quad G R^P \times 1$$

$$z_n = x_n^T y_n \quad G R^P \times 1$$

Goal:
time n: $W^{(n)} = R_n^{-1} z_n$ from $W^{(n-1)}$

Error: $e_{n-1} = W^T x_{n-1} - y_{n-1}$
(each data)

$$W_{n-1} = \sum_{i=0}^{n-1} \lambda^{(n-1)-i} e_i^2 \quad \text{forgetting (past)}$$

$$R_{n-1} = \sum_{i=0}^{n-1} \lambda^{(n-1)-i} x_i x_i^T \quad (P \times P)$$

$$z_{n-1} = \sum_{i=0}^{n-1} \lambda^{(n-1)-i} x_i y_i \quad (P \times 1)$$

$$R_n = \sum_{i=0}^{n-1} \lambda^{(n-1)-i} x_i x_i^T + x_n x_n^T$$

$$\left(\sum_{i=0}^{n-1} \lambda^{(n-1)-i} x_i x_i^T \right)$$

$$= \lambda \left[\sum_{i=0}^{n-1} \lambda^{(n-1)-i-1} x_i x_i^T \right] + x_n x_n^T$$

$$= \lambda R_{n-1} + x_n x_n^T$$

$$\left(A^{-1} - \frac{A^{-1} x x^T A^{-1}}{1 + x^T A^{-1} x} \right) (A + x x^T)$$

rank one update

$$I + A^{-1} x x^T A^{-1} = A^{-1} x x^T A^{-1} x x^T$$

$$R_n^{-1} = \frac{1}{\lambda} R_{n-1}^{-1} - \frac{\frac{1}{\lambda} R_{n-1}^{-1} x_n x_n^T R_{n-1}^{-1}}{1 + x_n^T \frac{1}{\lambda} R_{n-1}^{-1} x_n}$$

$$\begin{aligned} L^T A X X^T A^T &= \frac{1}{\lambda} X X^T A^T A X \\ &= \frac{1}{\lambda} X X^T A^T X \\ &= \frac{1}{\lambda} X X^T A^T X \\ &= I. \end{aligned}$$

Define: $P_n = R_n^{-1}$, $P_{n-1} = R_{n-1}^{-1}$

$$P_n = \frac{1}{\lambda} P_{n-1} - \frac{\frac{1}{\lambda} P_{n-1} x_n x_n^T P_{n-1}}{1 + x_n^T \frac{1}{\lambda} P_{n-1} x_n} = \frac{1}{\lambda} P_{n-1} - \frac{1}{\lambda} K_n x_n^T P_{n-1}$$

$$K_n = \frac{\frac{1}{\lambda} P_{n-1} x_n}{1 + x_n^T \frac{1}{\lambda} P_{n-1} x_n}$$

$$\begin{aligned} z_n &= \sum_{i=0}^n \lambda^{n-i} x_i y_i = \sum_{i=0}^{n-1} \lambda^{n-i} x_i y_i + x_n y_n \\ &= \lambda \sum_{i=0}^{n-1} \lambda^{n-1-i} x_i y_i + x_n y_n \\ &= \lambda z_{n-1} + x_n y_n \end{aligned}$$

homework

$$K_n = \left[\frac{1}{\lambda} P_{n-1} - \frac{1}{\lambda} K_n x_n^T P_{n-1} \right] x_n = P_n x_n$$

$$\downarrow \quad z_n + K_n x_n^T \frac{1}{\lambda} P_{n-1} x_n = \frac{1}{\lambda} P_{n-1} x_n.$$

$$K_n = \frac{1}{\lambda} P_{n-1} x_n - \frac{1}{\lambda} K_n x_n^T P_{n-1} x_n.$$

Goal: update w at time n

$$w^n = P_n z_n = P_n [\lambda z_{n-1} + k_n y_n] = \lambda P_n z_{n-1} + P_n k_n y_n$$

$$= \lambda \left[\frac{1}{\lambda} P_{n-1} - \frac{1}{\lambda} k_n x_n^T P_{n-1} \right] z_{n-1} + P_n k_n y_n$$

$$= \underbrace{P_{n-1} z_{n-1}}_{(w^{n-1})} - k_n x_n^T \underbrace{(P_{n-1} z_{n-1})}_{(w^{n-1})} + \underbrace{P_n k_n}_{(k_n)} y_n$$

$$= w^{n-1} - k_n (x_n^T w^{n-1} - y_n)$$

Gain \times Prediction error.

Starting Point: Linear Regression

- Data: $\{x_n, y_n\}_{n=1}^N$, $x \in \mathcal{R}^p$, $y_n \in \mathcal{R}$
- Usually $N > p$, Offset / bias term absorbed into w .
- Model: $y = w^T x$
- Linear model on fixed nonlinear basis functions:

$$y = w^T \Phi(x)$$

where $\Phi(\cdot)$ is from a set of fixed transforms e.g. Radial Basis Functions (RBF), with some hyperparameters in them.

- We minimize error: $E = \|y - Xw\|^2$
- X is an $N \times p$ matrix; y is $N \times 1$ vector.
- There is a closed form solution: $w = (X^T X)^{-1} X^T y$
- We can estimate w by a gradient descent algorithm:

$$w^{(k+1)} = w^{(k)} - \eta \nabla_w E$$

- $\nabla_w E$ is a vector, dimension p , derivative of E with respect to each of the weights:

$$\nabla_w E = 2 X^T (y - Xw) \quad (\text{少负号})$$

- This gradient is sum over all the data; we could also perform sample by sample update: Stochastic Gradient Descent

$$w^{(k+1)} = w^{(k)} + \eta (y(n) - w^T x_n) x_n$$

- Structure: Constant \times Error \times Input

Introduction

In online estimation of a regression problem defined by $\{\mathbf{x}_n, y_n\}_{n=1}^N$ where the inputs $\mathbf{x}_n \in \mathcal{R}^p$ and the target y_n is scalar, we consider the arrival of data to be sequential

$$\dots \{\mathbf{x}_{n-1}, y_{n-1}\}, \{\mathbf{x}_n, y_n\}, \{\mathbf{x}_{n+1}, y_{n+1}\}, \dots$$

Our task is to update the solution for the parameters \mathbf{w}_{n-1} we have at time $(n-1)$ upon the arrival of data $\{\mathbf{x}_n, y_n\}$ at time n *without* referring back to data seen in the past: $\{\mathbf{x}_i, y_i\}_{i=1}^{n-1}$. What summary information do we carry with us is the basic question underlying this topic.

The RLS algorithm achieves this by updating an inverse of a matrix (inverse covariance matrix, P_{n-1}) sequentially. The algorithm is as follows:

$$\begin{aligned} \mathbf{k}_n &= \frac{\frac{1}{\lambda} P_{n-1} \mathbf{x}_n}{1 + \frac{1}{\lambda} \mathbf{x}_n^T P_{n-1} \mathbf{x}_n} \\ e(n) &= y_n - \mathbf{w}_{n-1}^T \mathbf{x}_n \\ \mathbf{w}_n &= \mathbf{w}_{n-1} + \mathbf{k}_n e(n) \\ P_n &= \frac{1}{\lambda} P_{n-1} - \frac{1}{\lambda} \mathbf{k}_n \mathbf{x}_n^T P_{n-1} \end{aligned}$$

← 设 P_{n-1} 为初值.

Note several aspects of the algorithm:

- There is no matrix inversion at each step, the update of P_{n-1} uses the matrix inversion lemma.
- There is a gain term \mathbf{k}_n which gives a structure: the new values of parameters being the old values to which we add a term given by the error and this gain.
- $0 < \lambda < 1$ is a user defined parameter that controls how fast the contribution of data seen in the past decays.

伪代码:

$$P_{n-1} = I / \lambda \quad (X[0])$$

$$\mathbf{w}_{n-1} = \text{np.zeros}((P_{n-1}))$$

for n in range(N):

$$\mathbf{k}_n = \frac{1}{\lambda} P_{n-1} \mathbf{x}_n / (1 + \frac{1}{\lambda} \mathbf{x}_n^T P_{n-1} \mathbf{x}_n)$$

$$e(n) = y_n - \mathbf{w}_{n-1}^T \mathbf{x}_n$$

$$\mathbf{w}_n = \mathbf{w}_{n-1} + \mathbf{k}_n e(n)$$

$$P_n = \frac{1}{\lambda} P_{n-1} - \frac{1}{\lambda} \mathbf{k}_n \mathbf{x}_n^T P_{n-1}$$

更新 $P_{n-1}, \mathbf{w}_{n-1}$