

Wireless communications

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Adaptive beamforming

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<https://github.com/BernardoCama/WirelessCommunicationProject>

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2 Project description

In this section, we describe the structure of our project with a brief description of the main points of all the parts composing our work.

2.1 Beamforming techniques

We have implemented 5 beamforming techniques:

1. **Simple beamforming** The phases are selected to steer the array in a particular direction.
2. **Null-steering beamforming** Used to cancel K $j = N-2$ plane waves arriving from known directions.
3. **Minimum variance distortionless response (MVDR) beamforming** This beamformer minimizes the interference-plus-noise power at the output of the beamformer.
4. **Minimum mean square error (MMSE) beamforming** The weights of the antennas are adjusted in a way that the MSE between the output of the beamformer and the reference signal is minimized.
5. **Least mean square (LMS) beamforming** This iterative algorithm adjusts the weights by estimating the gradient of the MSE and moving them in the negative direction of the gradient at each iteration. We have implemented this iterative algorithm both in the time and in the frequency domain.

2.2 Channels

All the 5 beamformers have been tested on 3 different channels:

1. **LOS channel** A simple line of sight channel with no reflections.
2. **Two-ray channel** For each signal, we consider a direct path (LOS) and a single reflection.
3. **Quadrige channel** Here, the scenario we have used is the *QuaDRiGa-UD2D-LOS*.

2.3 Signals

For all the beamformers and in all the channels, the bits we transmit are generated randomly and modulated first with a 4QAM modulation (we have also tested the beamformers with a 16QAM); then, the QAM symbols are modulated with OFDM for transmission.

2.4 Reported results

In this report, we only describe the three most important simulations we have done:

1. Comparison between the SNR at the input and at the output of all the five beamformers in a LOS channel (section 3).
2. Comparison of the performance in terms of constellations revealed, weights of the antennas and BER for all the five beamformers considering different antenna arrays (section 4). This has been done in the quadriga channel and using the LMS beamformer in the time domain.
3. Tracking of two vehicles using LMS beamforming in the frequency domain (section 5).

All the other simulations we have done can be found on the *Github* repository of the project (link in title page).

3 SNR comparison

4 Antenna array comparison

5 Tracking

6 Conclusions

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