



11. Introducing HANK

Adv. Macro: Heterogenous Agent Models

Jeppe Druedahl

2023



Introduction

- **Previously:** Non-linear transition path and perfect foresight

Introduction

- **Previously:** Non-linear transition path and perfect foresight
- **Today:**
 1. Linearized Impulse Response Function (IRF)
 2. Linearized simulation with aggregate risk

Introduction

- **Previously:** Non-linear transition path and perfect foresight
- **Today:**
 1. Linearized Impulse Response Function (IRF)
 2. Linearized simulation with aggregate risk
- **Relevance:** Business cycle analysis

- **Previously:** Non-linear transition path and perfect foresight
- **Today:**
 1. Linearized Impulse Response Function (IRF)
 2. Linearized simulation with aggregate risk
- **Relevance:** Business cycle analysis
- **Literature:**
 1. Auclert et. al. (2021), »Using the Sequence-Space Jacobian to Solve and Estimate Heterogeneous-Agent Models«
 2. Boppart et. al. (2018), »Exploiting MIT shocks in heterogeneous-agent economies: The impulse response as a numerical derivative«
 3. Documentation for GEModelTools

IRFs and simulation

Reminder of model class

- Unknowns: U
- Shock: Z
- Additional variables: X
- Target equation system:

$$H(U, Z) = 0$$

- Auxiliary model equations:

$$X = M(U, Z)$$

- **Today:** Just consider the *first order solution*

Linearized IRFs

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(\mathbf{U}, \mathbf{Z}) = 0 \Rightarrow \mathbf{H}_U d\mathbf{U} + \mathbf{H}_Z d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{U} = \underbrace{-\mathbf{H}_U^{-1} \mathbf{H}_Z}_{\equiv \mathbf{G}_U} d\mathbf{Z}$$

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(\mathbf{U}, \mathbf{Z}) = 0 \Rightarrow \mathbf{H}_U d\mathbf{U} + \mathbf{H}_Z d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{U} = \underbrace{-\mathbf{H}_U^{-1} \mathbf{H}_Z d\mathbf{Z}}_{\equiv \mathbf{G}_U}$$

2. Derive all other IRFs for

$$\begin{aligned} \mathbf{X} = \mathbf{M}(\mathbf{U}, \mathbf{Z}) &\Rightarrow d\mathbf{X} = \mathbf{M}_U d\mathbf{U} + \mathbf{M}_Z d\mathbf{Z} \\ &= \underbrace{(-\mathbf{M}_U \mathbf{H}_U^{-1} \mathbf{H}_Z + \mathbf{M}_Z) d\mathbf{Z}}_{\equiv \mathbf{G}} \end{aligned}$$

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(\mathbf{U}, \mathbf{Z}) = 0 \Rightarrow \mathbf{H}_U d\mathbf{U} + \mathbf{H}_Z d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{U} = \underbrace{-\mathbf{H}_U^{-1} \mathbf{H}_Z}_{\equiv \mathbf{G}_U} d\mathbf{Z}$$

2. Derive all other IRFs for

$$\begin{aligned} \mathbf{X} = \mathbf{M}(\mathbf{U}, \mathbf{Z}) &\Rightarrow d\mathbf{X} = \mathbf{M}_U d\mathbf{U} + \mathbf{M}_Z d\mathbf{Z} \\ &= \underbrace{(-\mathbf{M}_U \mathbf{H}_U^{-1} \mathbf{H}_Z + \mathbf{M}_Z)}_{\equiv \mathbf{G}} d\mathbf{Z} \end{aligned}$$

- **Computation:** Same for \mathbf{Z} as for \mathbf{U}

Linearized IRFs

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(\mathbf{U}, \mathbf{Z}) = 0 \Rightarrow \mathbf{H}_U d\mathbf{U} + \mathbf{H}_Z d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{U} = \underbrace{-\mathbf{H}_U^{-1} \mathbf{H}_Z}_{\equiv \mathbf{G}_U} d\mathbf{Z}$$

2. Derive all other IRFs for

$$\begin{aligned} \mathbf{X} = \mathbf{M}(\mathbf{U}, \mathbf{Z}) &\Rightarrow d\mathbf{X} = \mathbf{M}_U d\mathbf{U} + \mathbf{M}_Z d\mathbf{Z} \\ &= \underbrace{(-\mathbf{M}_U \mathbf{H}_U^{-1} \mathbf{H}_Z + \mathbf{M}_Z)}_{\equiv \mathbf{G}} d\mathbf{Z} \end{aligned}$$

- **Computation:** Same for \mathbf{Z} as for \mathbf{U}
- **Limitations:**

Linearized IRFs

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(\mathbf{U}, \mathbf{Z}) = 0 \Rightarrow \mathbf{H}_U d\mathbf{U} + \mathbf{H}_Z d\mathbf{Z} = 0 \Leftrightarrow d\mathbf{U} = \underbrace{-\mathbf{H}_U^{-1} \mathbf{H}_Z}_{\equiv \mathbf{G}_U} d\mathbf{Z}$$

2. Derive all other IRFs for

$$\begin{aligned} \mathbf{X} = \mathbf{M}(\mathbf{U}, \mathbf{Z}) &\Rightarrow d\mathbf{X} = \mathbf{M}_U d\mathbf{U} + \mathbf{M}_Z d\mathbf{Z} \\ &= \underbrace{(-\mathbf{M}_U \mathbf{H}_U^{-1} \mathbf{H}_Z + \mathbf{M}_Z)}_{\equiv \mathbf{G}} d\mathbf{Z} \end{aligned}$$

- **Computation:** Same for \mathbf{Z} as for \mathbf{U}
- **Limitations:**
 1. Imprecise for *large* shocks

- **Today:** Just consider the *first order solution*

1. Solve for Impulse Response Functions (IRFs) for unknowns

$$H(U, Z) = 0 \Rightarrow H_U dU + H_Z dZ = 0 \Leftrightarrow dU = \underbrace{-H_U^{-1} H_Z}_{\equiv G_U} dZ$$

2. Derive all other IRFs for

$$\begin{aligned} X = M(U, Z) &\Rightarrow dX = M_U dU + M_Z dZ \\ &= \underbrace{(-M_U H_U^{-1} H_Z + M_Z)}_{\equiv G} dZ \end{aligned}$$

- **Computation:** Same for Z as for U

- **Limitations:**

1. Imprecise for *large* shocks
2. Imprecise in models with *aggregate non-linearities*
(direct in aggregate equations or through micro-behavior)

Aggregate risk

- **Aggregate stochastic variables:** \mathbf{Z} follow some known process with innovations ϵ . *State space form:* RHS is what is known today

$$\begin{bmatrix} \underline{D}_{t+1} \\ X_t \\ Z_t \end{bmatrix} = \mathcal{M} \left(\begin{bmatrix} \underline{D}_t \\ X_{t-1} \\ Z_{t-1} \end{bmatrix}, \epsilon_t \right)$$

\neq perfect foresight wrt. future agg. variables in *sequence-space*

Aggregate risk

- **Aggregate stochastic variables:** \mathbf{Z} follow some known process with innovations ϵ . *State space form:* RHS is what is known today

$$\begin{bmatrix} \underline{\mathbf{D}}_{t+1} \\ \mathbf{X}_t \\ \mathbf{Z}_t \end{bmatrix} = \mathcal{M} \left(\begin{bmatrix} \underline{\mathbf{D}}_t \\ \mathbf{X}_{t-1} \\ \mathbf{Z}_{t-1} \end{bmatrix}, \epsilon_t \right)$$

\neq perfect foresight wrt. future agg. variables in *sequence-space*

- **Observation:** Linearization of aggregate variables imply *certainty equivalence* with respect to these

$$\begin{bmatrix} \underline{\mathbf{D}}_{t+1} \\ \mathbf{X}_t \\ \mathbf{Z}_t \end{bmatrix} = \mathbf{A} \begin{bmatrix} \underline{\mathbf{D}}_t \\ \mathbf{X}_{t-1} \\ \mathbf{Z}_{t-1} \end{bmatrix} + \mathbf{B}\epsilon_t$$

Aggregate risk

- **Aggregate stochastic variables:** \mathbf{Z} follow some known process with innovations ϵ . *State space form:* RHS is what is known today

$$\begin{bmatrix} \underline{\mathbf{D}}_{t+1} \\ \mathbf{X}_t \\ \mathbf{Z}_t \end{bmatrix} = \mathcal{M} \left(\begin{bmatrix} \underline{\mathbf{D}}_t \\ \mathbf{X}_{t-1} \\ \mathbf{Z}_{t-1} \end{bmatrix}, \epsilon_t \right)$$

\neq perfect foresight wrt. future agg. variables in *sequence-space*

- **Observation:** Linearization of aggregate variables imply *certainty equivalence* with respect to these

$$\begin{bmatrix} \underline{\mathbf{D}}_{t+1} \\ \mathbf{X}_t \\ \mathbf{Z}_t \end{bmatrix} = \mathbf{A} \begin{bmatrix} \underline{\mathbf{D}}_t \\ \mathbf{X}_{t-1} \\ \mathbf{Z}_{t-1} \end{bmatrix} + \mathbf{B}\epsilon_t$$

- **Insight:** *The IRF from an MIT shock is equivalent to the IRF in a model with aggregate risk, which is linearized in the aggregate variables (Boppart et. al., 2018)*

Comparisons

- **State-space approach with linearization:** Ahn et al. (2018); Bayer and Luetticke (2020); Bhandari et al. (2023); Bilal (2023)

Con:

1. Harder to implement in my view
2. Valuable to be able to interpret Jacobians

Pro:

1. More similar to standard approaches for RBC and NK models
 2. Easier path to 2nd and higher order approximations
- **Global solution:** The distribution of households is a state variable for each household \Rightarrow *explosion in complexity*
 1. Original: Krusell and Smith (1997, 1998); Algan et al. (2014);
 2. Deep learning: Fernández-Villaverde et al. (2021); Maliar et al. (2021); Han et al. (2021); Kase et al. (2022); Azinovic et al. (2022); Gu et al. (2023); Chen et al. (2023)
 - **Discrete aggregate risk:** Lin and Peruffo (2023)

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):
 1. Draw time series of innovations, $\tilde{\epsilon}_t$

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):
 1. Draw time series of innovations, $\tilde{\epsilon}_t$
 2. Calculate the time series of shocks as $d\tilde{\mathbf{Z}}_t = \sum_{s=0}^{T-1} d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$
Note: $d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$ = effect of shock s periods ago today

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):
 1. Draw time series of innovations, $\tilde{\epsilon}_t$
 2. Calculate the time series of shocks as $d\tilde{\mathbf{Z}}_t = \sum_{s=0}^{T-1} d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$
Note: $d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$ = effect of shock s periods ago today
 3. Calculate the time series of other aggregate variables as

$$d\tilde{\mathbf{X}}_t = \sum_{s=0}^{T-1} d\mathbf{X}_s \tilde{\epsilon}_{t-s}$$

where $d\mathbf{X}_s$ is the IRF to a *unit-shock* after s periods

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):
 1. Draw time series of innovations, $\tilde{\epsilon}_t$
 2. Calculate the time series of shocks as $d\tilde{\mathbf{Z}}_t = \sum_{s=0}^{T-1} d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$
Note: $d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$ = effect of shock s periods ago today
 3. Calculate the time series of other aggregate variables as

$$d\tilde{\mathbf{X}}_t = \sum_{s=0}^{T-1} d\mathbf{X}_s \tilde{\epsilon}_{t-s}$$

where $d\mathbf{X}_s$ is the IRF to a *unit-shock* after s periods

- **Intuition:** Sum of first order effects from all previous shocks

Basic linearized simulation

- **Shocks:** Write the shocks as an $MA(\infty)$ with coefficients $d\mathbf{Z}_s$ for $s \in \{0, 1, \dots\}$ driven by the innovation ϵ_t .
- **Linearized simulation** (with truncation):
 1. Draw time series of innovations, $\tilde{\epsilon}_t$
 2. Calculate the time series of shocks as $d\tilde{\mathbf{Z}}_t = \sum_{s=0}^{T-1} d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$
Note: $d\mathbf{Z}_s \tilde{\epsilon}_{t-s}$ = effect of shock s periods ago today
 3. Calculate the time series of other aggregate variables as

$$d\tilde{\mathbf{X}}_t = \sum_{s=0}^{T-1} d\mathbf{X}_s \tilde{\epsilon}_{t-s}$$

where $d\mathbf{X}_s$ is the IRF to a *unit-shock* after s periods

- **Intuition:** Sum of first order effects from all previous shocks
- **Equivalence:** Same result if we linearize all aggregated equations and write the model in $MA(\infty)$ form

Generalized linearized simulation [advanced]

- **Generality:** Add auxiliary variables (incl. distributional moments) to calculate additional IRFs and simulations

Generalized linearized simulation [advanced]

- **Generality:** Add auxiliary variables (incl. distributional moments) to calculate additional IRFs and simulations
- **Full distribution:**

Generalized linearized simulation [advanced]

- **Generality:** Add auxiliary variables (incl. distributional moments) to calculate additional IRFs and simulations
- **Full distribution:**
 1. The IRF for grid point i_g in a policy function can be calculated as

$$da_{i_g,s}^* = \sum_{s'=s}^{T-1} \sum_{X^{hh} \in \mathbf{X}^{hh}} \frac{\partial a_{i_g}^*}{\partial X_{s'-s}^{hh}} dX_{s'-s}^{hh}.$$

where $\partial a_{i_g}^* / \partial X_k^{hh}$ is the derivative to a k -period ahead shock to input X^{hh} (calculated in fake news algorithm)

Generalized linearized simulation [advanced]

- **Generality:** Add auxiliary variables (incl. distributional moments) to calculate additional IRFs and simulations
- **Full distribution:**
 1. The IRF for grid point i_g in a policy function can be calculated as

$$da_{i_g,s}^* = \sum_{s'=s}^{T-1} \sum_{X^{hh} \in \mathbf{X}^{hh}} \frac{\partial a_{i_g}^*}{\partial X_{s'-s}^{hh}} dX_{s'}^{hh}.$$

where $\partial a_{i_g}^* / \partial X_k^{hh}$ is the derivative to a k -period ahead shock to input X^{hh} (calculated in fake news algorithm)

2. The policy function can there be simulated as

$$a_{i_g,t}^* = \sum_{s=0}^{T-1} da_{i_g,s}^* \tilde{\epsilon}_{t-s}$$

Generalized linearized simulation [advanced]

- **Generality:** Add auxiliary variables (incl. distributional moments) to calculate additional IRFs and simulations
- **Full distribution:**
 1. The IRF for grid point i_g in a policy function can be calculated as

$$da_{i_g,s}^* = \sum_{s'=s}^{T-1} \sum_{X^{hh} \in \mathbf{X}^{hh}} \frac{\partial a_{i_g}^*}{\partial X_{s'-s}^{hh}} dX_{s'-s}^{hh}.$$

where $\partial a_{i_g}^* / \partial X_k^{hh}$ is the derivative to a k -period ahead shock to input X^{hh} (calculated in fake news algorithm)

2. The policy function can there be simulated as

$$a_{i_g,t}^* = \sum_{s=0}^{T-1} da_{i_g,s}^* \tilde{\epsilon}_{t-s}$$

3. Distribution can then be simulated forwards

Calculating moments - variance

- **Identical and independent distributed innovations:**

$$\mathbb{E} \left[\epsilon_t^i \epsilon_{t'}^j \right] = \begin{cases} \sigma_i & \text{if } t = t' \text{ and } i = j \\ 0 & \text{el} \end{cases}$$

Calculating moments - variance

- **Identical and independent distributed innovations:**

$$\mathbb{E} \left[\epsilon_t^i \epsilon_{t'}^j \right] = \begin{cases} \sigma_i & \text{if } t = t' \text{ and } i = j \\ 0 & \text{el} \end{cases}$$

- **Calculating moments such as $\text{var}(dC_t)$ from the IRFs:**

$$\begin{aligned} \text{var}(dC_t) &= \mathbb{E} \left[\left(\sum_{i \in \mathcal{Z}} \sum_{s=0}^{T-1} dC_s \epsilon_{t-s}^i \right)^2 \right] \\ &= \sum_{i \in \mathcal{Z}} \sum_{s=0}^{T-1} \mathbb{E} \left[\epsilon_{t-s}^i \epsilon_{t-s}^i \right] (dC_s^i)^2 \\ &= \sum_{i \in \mathcal{Z}} \sigma_i^2 \sum_{s=0}^{T-1} (dC_s^i)^2 \end{aligned}$$

where dC_s^i is the IRF to a unit-shock to i after s periods
and σ_i is the standard deviation of shock i

Calculating moments - covariance

- **Covariances:**

$$\text{cov}(dC_t, dY_{t+k}) = \sum_{i \in \mathcal{Z}} \sigma_i^2 \sum_{s=0}^{T-1-k} dC_s^i dY_{s+k}^i$$

Calculating moments - covariance

- **Covariances:**

$$\text{cov}(dC_t, dY_{t+k}) = \sum_{i \in \mathcal{Z}} \sigma_i^2 \sum_{s=0}^{T-1-k} dC_s^i dY_{s+k}^i$$

- **Covariance decomposition:**

$$\frac{\text{contribution from one shock}}{\text{contributions from all shocks}} = \frac{\sigma_j^2 \sum_{s=0}^{T-1-k} dC_s^j dY_{s+k}^j}{\sum_{i \in \mathcal{Z}} \sigma_i^2 \sum_{s=0}^{T-1-k} dC_s^i dY_{s+k}^i}$$

- **The simplest approaches:**

1. Impulse Response Function (IRF) matching
2. Minimum distance / simulated method of moments (SMM)

- **The simplest approaches:**
 1. Impulse Response Function (IRF) matching
 2. Minimum distance / simulated method of moments (SMM)
- **Also possible:** *Bayesian likelihood estimation* (see [SSJ](#))

- **The simplest approaches:**
 1. Impulse Response Function (IRF) matching
 2. Minimum distance / simulated method of moments (SMM)
- **Also possible:** *Bayesian likelihood estimation* (see [SSJ](#))
- **Speed:** For a new set of parameters?
 1. Only shock processes change \Rightarrow *same Jacobians* (\mathbf{G}_U, \mathbf{G})
 2. Only need to re-compute Jacobian of aggregate variables?
(only single block?)
 3. Also need to re-compute Jacobian of household problem?
 4. Also need to find stationary equilibrium again?

Sticky prices

- **Households:**

1. Differ by stochastic idiosyncratic productivity and savings
2. Supply labor and choose consumption
3. Subject to a borrowing constraint

- **Households:**

1. Differ by stochastic idiosyncratic productivity and savings
2. Supply labor and choose consumption
3. Subject to a borrowing constraint

- **Intermediary goods firms (continuum)**

1. Produce differentiated goods with labor
2. Set price under monopolistic competition
3. Pay dividends to households

- **Households:**
 1. Differ by stochastic idiosyncratic productivity and savings
 2. Supply labor and choose consumption
 3. Subject to a borrowing constraint
- **Intermediary goods firms (continuum)**
 1. Produce differentiated goods with labor
 2. Set price under monopolistic competition
 3. Pay dividends to households
- **Final goods firms (representative)**
 1. Produce final good with intermediary goods
 2. Take price as given under perfect competition

- **Households:**

1. Differ by stochastic idiosyncratic productivity and savings
2. Supply labor and choose consumption
3. Subject to a borrowing constraint

- **Intermediary goods firms** (continuum)

1. Produce differentiated goods with labor
2. Set price under monopolistic competition
3. Pay dividends to households

- **Final goods firms** (representative)

1. Produce final good with intermediary goods
2. Take price as given under perfect competition

- **Government:**

1. Collect taxes from households
2. Pays interest on government debt and choose public consumption

- **Households:**
 1. Differ by stochastic idiosyncratic productivity and savings
 2. Supply labor and choose consumption
 3. Subject to a borrowing constraint
- **Intermediary goods firms** (continuum)
 1. Produce differentiated goods with labor
 2. Set price under monopolistic competition
 3. Pay dividends to households
- **Final goods firms** (representative)
 1. Produce final good with intermediary goods
 2. Take price as given under perfect competition
- **Government:**
 1. Collect taxes from households
 2. Pays interest on government debt and choose public consumption
- **Central bank:** Set nominal interest rate

Final goods firms

- Intermediary goods indexed by $j \in [0, 1]$

Final goods firms

- Intermediary goods indexed by $j \in [0, 1]$
- **Static** problem for representative final good firm:

$$\max_{y_{jt} \forall j} P_t Y_t - \int_0^1 p_{jt} y_{jt} dj \text{ s.t. } Y_t = \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu}$$

for given output price, P_t , and input prices, p_{jt}

Final goods firms

- Intermediary goods indexed by $j \in [0, 1]$
- **Static** problem for representative final good firm:

$$\max_{y_{jt} \forall j} P_t Y_t - \int_0^1 p_{jt} y_{jt} dj \text{ s.t. } Y_t = \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu}$$

for given output price, P_t , and input prices, p_{jt}

- **Demand curve** derived from FOC wrt. y_{jt}

$$\forall j : y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

Final goods firms

- Intermediary goods indexed by $j \in [0, 1]$
- **Static** problem for representative final good firm:

$$\max_{y_{jt} \forall j} P_t Y_t - \int_0^1 p_{jt} y_{jt} dj \text{ s.t. } Y_t = \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu}$$

for given output price, P_t , and input prices, p_{jt}

- **Demand curve** derived from FOC wrt. y_{jt}

$$\forall j : y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

- **Note:** Zero profits (can be used to derive price index)

Derivation of demand curve

- FOC wrt. y_{jt}

$$0 = P_t \mu \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu-1} \frac{1}{\mu} y_{jt}^{\frac{1}{\mu}-1} - p_{jt} \Leftrightarrow$$

$$\frac{p_{jt}}{P_t} = \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu-1} y_{jt}^{\frac{1-\mu}{\mu}} \Leftrightarrow$$

$$\left(\frac{p_{jt}}{P_t} \right)^{\frac{\mu}{\mu-1}} = \left(\int_0^1 y_{jt}^{\frac{1}{\mu}} dj \right)^{\mu} y_{jt}^{-1} \Leftrightarrow$$

$$y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

- **Dynamic problem for intermediary goods firms:**

$$J_t(p_{jt-1}) = \max_{y_{jt}, p_{jt}, n_{jt}} \left\{ \frac{p_{jt}}{P_t} y_{jt} - w_t n_{jt} - \Omega(p_{jt}, p_{jt-1}) Y_t + \frac{J_{t+1}(p_{jt})}{1 + r_{t+1}} \right\}$$

$$\text{s.t. } y_{jt} = Z_t n_{jt}, \quad y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

$$\Omega(p_{jt}, p_{jt-1}) = \frac{\mu}{\mu-1} \frac{1}{2\kappa} \left[\log \left(\frac{p_{jt}}{p_{jt-1}} \right) \right]^2$$

- **Dynamic problem for intermediary goods firms:**

$$J_t(p_{jt-1}) = \max_{y_{jt}, p_{jt}, n_{jt}} \left\{ \frac{p_{jt}}{P_t} y_{jt} - w_t n_{jt} - \Omega(p_{jt}, p_{jt-1}) Y_t + \frac{J_{t+1}(p_{jt})}{1 + r_{t+1}} \right\}$$

$$\text{s.t. } y_{jt} = Z_t n_{jt}, \quad y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

$$\Omega(p_{jt}, p_{jt-1}) = \frac{\mu}{\mu-1} \frac{1}{2\kappa} \left[\log \left(\frac{p_{jt}}{p_{jt-1}} \right) \right]^2$$

- **Symmetry:** In equilibrium all firms set the same price, $p_{jt} = P_t$

- **Dynamic problem for intermediary goods firms:**

$$J_t(p_{jt-1}) = \max_{y_{jt}, p_{jt}, n_{jt}} \left\{ \frac{p_{jt}}{P_t} y_{jt} - w_t n_{jt} - \Omega(p_{jt}, p_{jt-1}) Y_t + \frac{J_{t+1}(p_{jt})}{1 + r_{t+1}} \right\}$$

$$\text{s.t. } y_{jt} = Z_t n_{jt}, \quad y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

$$\Omega(p_{jt}, p_{jt-1}) = \frac{\mu}{\mu-1} \frac{1}{2\kappa} \left[\log \left(\frac{p_{jt}}{p_{jt-1}} \right) \right]^2$$

- **Symmetry:** In equilibrium all firms set the same price, $p_{jt} = P_t$
- **NKPC** derived from FOC wrt. p_{jt} and envelope condition:

$$\log(1 + \pi_t) = \kappa \left(\frac{w_t}{Z_t} - \frac{1}{\mu} \right) + \frac{Y_{t+1}}{Y_t} \frac{\log(1 + \pi_{t+1})}{1 + r_{t+1}}, \quad \pi_t \equiv P_t / P_{t-1} - 1$$

- **Dynamic problem for intermediary goods firms:**

$$J_t(p_{jt-1}) = \max_{y_{jt}, p_{jt}, n_{jt}} \left\{ \frac{p_{jt}}{P_t} y_{jt} - w_t n_{jt} - \Omega(p_{jt}, p_{jt-1}) Y_t + \frac{J_{t+1}(p_{jt})}{1 + r_{t+1}} \right\}$$
$$\text{s.t. } y_{jt} = Z_t n_{jt}, \quad y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$
$$\Omega(p_{jt}, p_{jt-1}) = \frac{\mu}{\mu-1} \frac{1}{2\kappa} \left[\log \left(\frac{p_{jt}}{p_{jt-1}} \right) \right]^2$$

- **Symmetry:** In equilibrium all firms set the same price, $p_{jt} = P_t$
- **NKPC** derived from FOC wrt. p_{jt} and envelope condition:

$$\log(1 + \pi_t) = \kappa \left(\frac{w_t}{Z_t} - \frac{1}{\mu} \right) + \frac{Y_{t+1}}{Y_t} \frac{\log(1 + \pi_{t+1})}{1 + r_{t+1}}, \quad \pi_t \equiv P_t / P_{t-1} - 1$$

- **Implied production:** $Y_t = y_{jt}$, $N_t = n_{jt}$ (from symmetry)

Intermediary goods firms

- **Dynamic problem for intermediary goods firms:**

$$J_t(p_{jt-1}) = \max_{y_{jt}, p_{jt}, n_{jt}} \left\{ \frac{p_{jt}}{P_t} y_{jt} - w_t n_{jt} - \Omega(p_{jt}, p_{jt-1}) Y_t + \frac{J_{t+1}(p_{jt})}{1 + r_{t+1}} \right\}$$

$$\text{s.t. } y_{jt} = Z_t n_{jt}, \quad y_{jt} = \left(\frac{p_{jt}}{P_t} \right)^{-\frac{\mu}{\mu-1}} Y_t$$

$$\Omega(p_{jt}, p_{jt-1}) = \frac{\mu}{\mu-1} \frac{1}{2\kappa} \left[\log \left(\frac{p_{jt}}{p_{jt-1}} \right) \right]^2$$

- **Symmetry:** In equilibrium all firms set the same price, $p_{jt} = P_t$
- **NKPC** derived from FOC wrt. p_{jt} and envelope condition:

$$\log(1 + \pi_t) = \kappa \left(\frac{w_t}{Z_t} - \frac{1}{\mu} \right) + \frac{Y_{t+1}}{Y_t} \frac{\log(1 + \pi_{t+1})}{1 + r_{t+1}}, \quad \pi_t \equiv P_t / P_{t-1} - 1$$

- **Implied production:** $Y_t = y_{jt}$, $N_t = n_{jt}$ (from symmetry)
- **Implied dividends:** $d_t = Y_t - w_t N_t - \frac{\mu}{\mu-1} \frac{1}{2\kappa} [\log(1 + \pi_t)]^2 Y_t$

- FOC wrt. p_{jt} :

$$0 = \left(1 - \frac{\mu}{\mu - 1}\right) \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{P_t} + \frac{\mu}{\mu - 1} \frac{w_t}{Z_t} \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{p_{jt}} \\ - \frac{\mu}{\mu - 1} \frac{1}{\kappa} \frac{\log\left(\frac{p_{jt}}{p_{jt-1}}\right)}{p_{jt}} Y_t + \frac{J'_{t+1}(p_{jt})}{1 + r_{t+1}}$$

- FOC wrt. p_{jt} :

$$0 = \left(1 - \frac{\mu}{\mu - 1}\right) \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{P_t} + \frac{\mu}{\mu - 1} \frac{w_t}{Z_t} \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{p_{jt}} \\ - \frac{\mu}{\mu - 1} \frac{1}{\kappa} \frac{\log\left(\frac{p_{jt}}{p_{jt-1}}\right)}{p_{jt}} Y_t + \frac{J'_{t+1}(p_{jt})}{1 + r_{t+1}}$$

- Envelope condition: $J'_{t+1}(p_{jt}) = \frac{\mu}{\mu-1} \frac{1}{\kappa} \frac{\log\left(\frac{p_{jt+1}}{p_{jt}}\right)}{p_{jt}} Y_{t+1}$

Derivation of NKPC

- FOC wrt. p_{jt} :

$$0 = \left(1 - \frac{\mu}{\mu - 1}\right) \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{P_t} + \frac{\mu}{\mu - 1} \frac{w_t}{Z_t} \left(\frac{p_{jt}}{P_t}\right)^{-\frac{\mu}{\mu-1}} \frac{Y_t}{p_{jt}} \\ - \frac{\mu}{\mu - 1} \frac{1}{\kappa} \frac{\log\left(\frac{p_{jt}}{p_{jt-1}}\right)}{p_{jt}} Y_t + \frac{J'_{t+1}(p_{jt})}{1 + r_{t+1}}$$

- Envelope condition: $J'_{t+1}(p_{jt}) = \frac{\mu}{\mu-1} \frac{1}{\kappa} \frac{\log\left(\frac{p_{jt+1}}{p_{jt}}\right)}{p_{jt}} Y_{t+1}$
- FOC + Envelope + Symmetry + $\pi_t = P_t/P_{t-1} - 1$

$$0 = \left(1 - \frac{\mu}{\mu - 1}\right) \frac{Y_t}{P_t} + \frac{\mu}{\mu - 1} \frac{w_t}{Z_t} \frac{Y_t}{P_t} \\ + \frac{\mu}{\mu - 1} \frac{1}{\kappa} \log(1 + \pi_t) \frac{Y_t}{P_t} + \frac{\frac{\mu}{\mu-1} \frac{1}{\kappa} \log(1 + \pi_{t+1}) \frac{Y_{t+1}}{P_t}}{1 + r_{t+1}}$$

- **Household problem:** Distribution, \mathbf{D}_t , over z_t and a_{t-1}

$$v_t(z_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} - \varphi \frac{\ell_t^{1+\nu}}{1+\nu} + \beta \mathbb{E}[v_{t+1}(z_{t+1}, a_t) | z_t, a_t]$$

$$\text{s.t. } a_t = (1 + r_t)a_{t-1} + (w_t \ell_t - \tau_t + d_t)z_t - c_t \geq 0$$

$$\log z_{t+1} = \rho_z \log z_t + \psi_{t+1}, \psi_t \sim \mathcal{N}(\mu_\psi, \sigma_\psi), \mathbb{E}[z_t] = 1$$

- **Household problem:** Distribution, \mathbf{D}_t , over z_t and a_{t-1}

$$v_t(z_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} - \varphi \frac{\ell_t^{1+\nu}}{1+\nu} + \beta \mathbb{E}[v_{t+1}(z_{t+1}, a_t) | z_t, a_t]$$

$$\text{s.t. } a_t = (1 + r_t)a_{t-1} + (w_t \ell_t - \tau_t + d_t)z_t - c_t \geq 0$$

$$\log z_{t+1} = \rho_z \log z_t + \psi_{t+1}, \psi_t \sim \mathcal{N}(\mu_\psi, \sigma_\psi), \mathbb{E}[z_t] = 1$$

- **Dividends:** Distributed proportional to productivity (ad hoc)

- **Household problem:** Distribution, \mathbf{D}_t , over z_t and a_{t-1}

$$v_t(z_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} - \varphi \frac{\ell_t^{1+\nu}}{1+\nu} + \beta \mathbb{E}[v_{t+1}(z_{t+1}, a_t) | z_t, a_t]$$

$$\text{s.t. } a_t = (1 + r_t)a_{t-1} + (w_t \ell_t - \tau_t + d_t)z_t - c_t \geq 0$$

$$\log z_{t+1} = \rho_z \log z_t + \psi_{t+1}, \psi_t \sim \mathcal{N}(\mu_\psi, \sigma_\psi), \mathbb{E}[z_t] = 1$$

- **Dividends:** Distributed proportional to productivity (ad hoc)
- **Taxes:** Collected proportional to productivity (ad hoc)

- **Household problem:** Distribution, \mathbf{D}_t , over z_t and a_{t-1}

$$v_t(z_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} - \varphi \frac{\ell_t^{1+\nu}}{1+\nu} + \beta \mathbb{E}[v_{t+1}(z_{t+1}, a_t) | z_t, a_t]$$

$$\text{s.t. } a_t = (1 + r_t)a_{t-1} + (w_t \ell_t - \tau_t + d_t)z_t - c_t \geq 0$$

$$\log z_{t+1} = \rho_z \log z_t + \psi_{t+1}, \psi_t \sim \mathcal{N}(\mu_\psi, \sigma_\psi), \mathbb{E}[z_t] = 1$$

- **Dividends:** Distributed proportional to productivity (ad hoc)
- **Taxes:** Collected proportional to productivity (ad hoc)
- **Optimality conditions:**

$$\text{FOC wrt. } c_t : 0 = c_t^{-\sigma} - \beta \mathbb{E}_t[v_{a,t+1}(z_{t+1}, a_t)]$$

$$\text{FOC wrt. } \ell_t : 0 = w_t z_t \beta \mathbb{E}_t[v_{a,t+1}(z_{t+1}, a_t)] - \varphi \ell_t^\nu$$

$$\text{Envelope condition: } v_{a,t}(z_t, a_{t-1}) = (1 + r_t)c_t^{-\sigma}$$

- **Household problem:** Distribution, \mathbf{D}_t , over z_t and a_{t-1}

$$v_t(z_t, a_{t-1}) = \max_{c_t} \frac{c_t^{1-\sigma}}{1-\sigma} - \varphi \frac{\ell_t^{1+\nu}}{1+\nu} + \beta \mathbb{E}[v_{t+1}(z_{t+1}, a_t) | z_t, a_t]$$

$$\text{s.t. } a_t = (1 + r_t)a_{t-1} + (w_t \ell_t - \tau_t + d_t)z_t - c_t \geq 0$$

$$\log z_{t+1} = \rho_z \log z_t + \psi_{t+1}, \psi_t \sim \mathcal{N}(\mu_\psi, \sigma_\psi), \mathbb{E}[z_t] = 1$$

- **Dividends:** Distributed proportional to productivity (ad hoc)
- **Taxes:** Collected proportional to productivity (ad hoc)
- **Optimality conditions:**

$$\text{FOC wrt. } c_t : 0 = c_t^{-\sigma} - \beta \mathbb{E}_t[v_{a,t+1}(z_{t+1}, a_t)]$$

$$\text{FOC wrt. } \ell_t : 0 = w_t z_t \beta \mathbb{E}_t[v_{a,t+1}(z_{t+1}, a_t)] - \varphi \ell_t^\nu$$

$$\text{Envelope condition: } v_{a,t}(z_t, a_{t-1}) = (1 + r_t) c_t^{-\sigma}$$

- **Effective labor-supply:** $n_t = z_t \ell_t$

- **Beginning-of-period value function:**

$$\underline{v}_{a,t}(z_{t-1}, a_{t-1}) = \mathbb{E}_t [v_{a,t}(z_t, a_{t-1})] = \mathbb{E} [(1 + r_t)c_t^{-\sigma}]$$

- **Beginning-of-period value function:**

$$\underline{v}_{a,t}(z_{t-1}, a_{t-1}) = \mathbb{E}_t [v_{a,t}(z_t, a_{t-1})] = \mathbb{E} [(1 + r_t)c_t^{-\sigma}]$$

- **Endogenous grid method:** Vary z_t and a_t to find

$$c_t = (\beta \underline{v}_{a,t+1}(z_t, a_t))^{-\frac{1}{\sigma}}$$

$$\ell_t = \left(\frac{w_t z_t}{\varphi} c_t^{-\sigma} \right)^{\frac{1}{\nu}}$$

$$m_t = c_t + a_t - (w_t \ell_t - \tau_t + d_t) z_t$$

- **Beginning-of-period value function:**

$$\underline{v}_{a,t}(z_{t-1}, a_{t-1}) = \mathbb{E}_t [v_{a,t}(z_t, a_{t-1})] = \mathbb{E} [(1 + r_t)c_t^{-\sigma}]$$

- **Endogenous grid method:** Vary z_t and a_t to find

$$c_t = (\beta \underline{v}_{a,t+1}(z_t, a_t))^{-\frac{1}{\sigma}}$$

$$\ell_t = \left(\frac{w_t z_t}{\varphi} c_t^{-\sigma} \right)^{\frac{1}{\nu}}$$

$$m_t = c_t + a_t - (w_t \ell_t - \tau_t + d_t) z_t$$

- **Consumption and labor supply:** Use linear interpolation to find

$$c^*(z_t, a_{t-1}) \text{ and } \ell^*(z_t, a_{t-1}) \text{ with } m_t = (1 + r_t)a_{t-1}$$

- **Beginning-of-period value function:**

$$\underline{v}_{a,t}(z_{t-1}, a_{t-1}) = \mathbb{E}_t [\underline{v}_{a,t}(z_t, a_{t-1})] = \mathbb{E} [(1 + r_t)c_t^{-\sigma}]$$

- **Endogenous grid method:** Vary z_t and a_t to find

$$c_t = (\beta \underline{v}_{a,t+1}(z_t, a_t))^{-\frac{1}{\sigma}}$$

$$\ell_t = \left(\frac{w_t z_t}{\varphi} c_t^{-\sigma} \right)^{\frac{1}{\nu}}$$

$$m_t = c_t + a_t - (w_t \ell_t - \tau_t + d_t) z_t$$

- **Consumption and labor supply:** Use linear interpolation to find

$$c^*(z_t, a_{t-1}) \text{ and } \ell^*(z_t, a_{t-1}) \text{ with } m_t = (1 + r_t)a_{t-1}$$

- **Savings:** $a^*(z_t, a_{t-1}) = (1 + r_t)a_{t-1} - c_t^* + (w_t \ell_t^* - \tau_t + d_t)z_t$

- **Problem:** $a^*(z_t, a_{t-1}) < 0$ violate borrowing constraint

- **Problem:** $a^*(z_t, a_{t-1}) < 0$ violate borrowing constraint
- **Refinement if $a^*(z_t, a_{t-1}) < 0$ by:**
Find ℓ^* (and c^* and n^*) with *Newton solver* assuming $a^* = 0$

- **Problem:** $a^*(z_t, a_{t-1}) < 0$ violate borrowing constraint
- **Refinement if $a^*(z_t, a_{t-1}) < 0$ by:**

Find ℓ^* (and c^* and n^*) with *Newton solver* assuming $a^* = 0$

1. Stop if $f(\ell^*) = \ell^* - \left(\frac{w_t z_t}{\varphi}\right)^{\frac{1}{\nu}} (c^*)^{-\frac{\sigma}{\nu}} < \text{tol.}$ where

$$c^* = (1 + r_t)a_{t-1} + (w_t \ell^* - \tau_t + d_t)z_t$$

$$n^* = z_t \ell^*$$

- **Problem:** $a^*(z_t, a_{t-1}) < 0$ violate borrowing constraint
- **Refinement if $a^*(z_t, a_{t-1}) < 0$ by:**

Find ℓ^* (and c^* and n^*) with *Newton solver* assuming $a^* = 0$

1. Stop if $f(\ell^*) = \ell^* - \left(\frac{w_t z_t}{\varphi}\right)^{\frac{1}{\nu}} (c^*)^{-\frac{\sigma}{\nu}} < \text{tol.}$ where

$$c^* = (1 + r_t)a_{t-1} + (w_t \ell^* - \tau_t + d_t)z_t$$

$$n^* = z_t \ell^*$$

2. Set

$$\ell^* = \frac{f(\ell^*)}{f'(\ell^*)} = \frac{f(\ell^*)}{1 - \left(\frac{w_t z_t}{\varphi}\right)^{\frac{1}{\nu}} \left(-\frac{\sigma}{\nu}\right) (c^*)^{-\frac{\sigma}{\nu}} w_t z_t}$$

- **Problem:** $a^*(z_t, a_{t-1}) < 0$ violate borrowing constraint
- **Refinement if $a^*(z_t, a_{t-1}) < 0$ by:**

Find ℓ^* (and c^* and n^*) with *Newton solver* assuming $a^* = 0$

1. Stop if $f(\ell^*) = \ell^* - \left(\frac{w_t z_t}{\varphi}\right)^{\frac{1}{\nu}} (c^*)^{-\frac{\sigma}{\nu}} < \text{tol.}$ where

$$c^* = (1 + r_t)a_{t-1} + (w_t \ell^* - \tau_t + d_t)z_t$$

$$n^* = z_t \ell^*$$

2. Set

$$\ell^* = \frac{f(\ell^*)}{f'(\ell^*)} = \frac{f(\ell^*)}{1 - \left(\frac{w_t z_t}{\varphi}\right)^{\frac{1}{\nu}} \left(-\frac{\sigma}{\nu}\right) (c^*)^{-\frac{\sigma}{\nu}} w_t z_t}$$

3. Return to step 1

- **Monetary policy:** Follow Taylor-rule:

$$i_t = i_t^* + \phi \pi_t$$

where i_t^* is a shock

- **Monetary policy:** Follow Taylor-rule:

$$i_t = i_t^* + \phi \pi_t$$

where i_t^* is a shock

- **Fisher relationship:**

$$r_t = (1 + i_{t-1}) / (1 + \pi_t) - 1$$

- **Monetary policy:** Follow Taylor-rule:

$$i_t = i_t^* + \phi \pi_t$$

where i_t^* is a shock

- **Fisher relationship:**

$$r_t = (1 + i_{t-1}) / (1 + \pi_t) - 1$$

- **Government:** Choose τ_t to keep debt constant and finance exogenous public consumption

$$\tau_t = r_t B_{ss} + G_t$$

Market clearing

1. Assets: $B_{ss} = \int a_t^*(z_t, a_{t-1}) d\mathbf{D}_t$
2. Labor: $N_t = \int n_t^*(z_t, a_{t-1}) d\mathbf{D}_t$ (in effective units)
3. Goods: $Y_t = \int c_t^*(z_t, a_{t-1}) d\mathbf{D}_t + G_t + \frac{\mu}{\mu-1} \frac{1}{2\kappa} [\log(1 + \pi_t)]^2 Y_t$

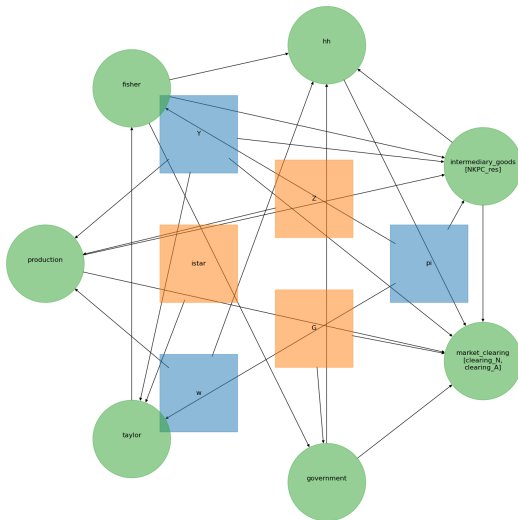
As an equation system

$$\begin{aligned} H(\pi, w, Y, i^*, Z, \underline{D}_0) &= 0 \\ \left[\begin{array}{c} \log(1 + \pi_t) - \left[\kappa \left(\frac{w_t}{Z_t} - \frac{1}{\mu} \right) + \frac{Y_{t+1}}{Y_t} \frac{\log(1 + \pi_{t+1})}{1 + r_{t+1}} \right] \\ N_t - \int n_t^*(z_t, a_{t-1}) d\mathbf{D}_t \\ B_{ss} - \int a_t^*(z_t, a_{t-1}) d\mathbf{D}_t \end{array} \right] &= 0 \end{aligned}$$

The rest of the model is given by

$$\mathbf{X} = \mathbf{M}(\pi, w, Y, i^*, Z)$$

As a DAG



Steady state

- **Chosen:** B_{ss} , G_{ss} , r_{ss}
- **Analytically:**
 1. **Normalization:** $Z_{ss} = N_{ss} = 1$
 2. **Zero-inflation:** $\pi_{ss} = 0 \Rightarrow i_{ss} = i_{ss}^* = (1 + r_{ss})(1 + \pi_{ss}) - 1$
 3. **Firms:** $Y_{ss} = Z_{ss}N_{ss}$, $w_{ss} = \frac{Z_{ss}}{\mu}$ and $d_{ss} = Y_{ss} - w_{ss}N_{ss}$
 4. **Government:** $\tau_{ss} = r_{ss}B_{ss} + G_{ss}$
 5. **Assets:** $A_{ss} = B_{ss}$
- **Numerically:** Choose β and φ to get market clearing

Transmission mechanism to monetary policy shock

1. **Monetary policy shock:** $i_t^* \downarrow \Rightarrow i_t = i_t^* + \phi\pi_t \downarrow$
2. **Real interest rate:** $r_t = \frac{1+i_t-1}{1+\pi_t} \downarrow$
3. **Taxes:** $\tau_t = r_t B_{ss} \downarrow$
4. **Household consumption,** $C_t^{hh} \uparrow$, due to $r_t \downarrow$ and $\tau_t \downarrow$
5. **Firms production,** $Y_t \uparrow$, and **labor demand,** $N_t \uparrow$
6. **Inflation,** $\pi_t \uparrow$, and **wage,** $w_t \uparrow$ and **dividends,** $d_t \downarrow$
7. **Household labor supply,** $N_t^{hh} \uparrow$, due to $w_t \uparrow$ and $d_t \downarrow$,
but dampened $\tau_t \downarrow$
8. **Nominal rate,** $i_t \uparrow$ due to $\pi_t \uparrow$ implying $r_t \uparrow$
9. **Household consumption,** $C_t^{hh} \uparrow$, due to $w_t \uparrow$
but dampened by $d_t \downarrow$ and $r_t \uparrow$

Summary

- **Today:**

1. Aggregate risk and linearized dynamics (IRF and simulation)
2. Calculating aggregate moments (for calibration or estimation)
3. HANK with sticky prices

Exercise

Exercise

1. Compute the non-linear response to a temporary increase in government spending
2. Compute the linearized IRF to the same shock and compare
3. Sketch the transmission mechanism of government spending
4. Analyze how the aggressiveness of monetary policy affects the effectiveness of fiscal policy
5. Compare you previous results with the effects of a public transfer

Summary

Summary and next week

- **Today:**

1. Aggregate risk and linearized dynamics (IRF and simulation)
2. Calculating aggregate moments (for calibration or estimation)
3. A baseline HANK (sticky prices)

- **Next week:** More on HANK models

- **Homework:**

1. Work on exercise
2. Skim-read Auclert et al. (2023),
»The Intertemporal Keynesian Cross«